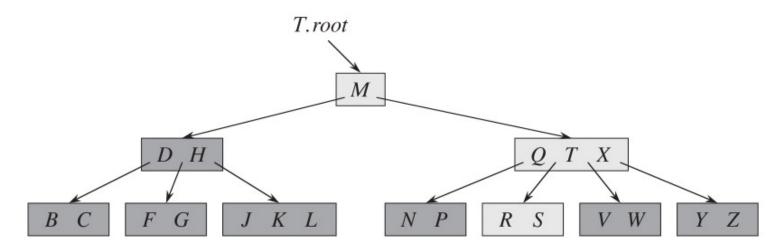
B-Trees

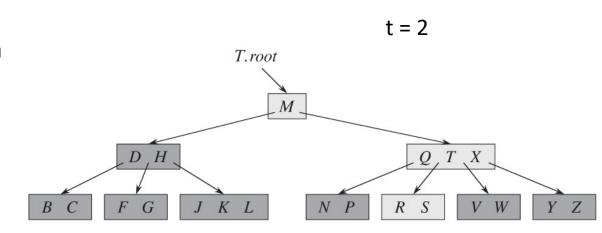
What is a B-Tree?

- Balanced search tree
- Each B-tree node can have many children
 - Branching factor: a few to thousands
- Height: O(lg n)



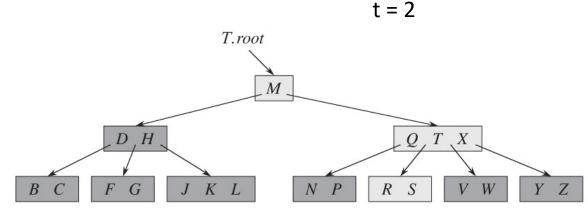
Properties of B-trees

- Keys are stored in non-decreasing order in a node
- All leaves have the same depth tree height h
- For each non-leaf nodes with i elements contains i+1 pointers
- t: minimum degree, integer, t>=2
 - Every non-root node must have >= t-1 keys
 - Every non-root internal node have >= t children
 - Every node contains <= 2t-1 keys
 - Every internal nodes contain <= 2t children



Properties of B-trees

- t: minimum degree, integer, t>=2
 - Every non-root node must have >= t-1 keys
 - Every non-root internal node have >= t children
 - Every node contains <= 2t-1 keys
 - Every internal nodes contain <= 2t children
- Can be summarized in 3 main rules:
 - Every none root node must have $\lceil t/2 \rceil$ (Ceiling of t/2) children
 - Root must have min 2 children
 - All leaf nodes must be at the same level.



B-tree search

```
Search tree rooted at node x for key k
    B-TREE-SEARCH(x, k)
       i = 1
                                                find smallest index i in the tree where key[i] >= k
        while i \le x . n and k > x . key_i
            i = i + 1
        if i \le x . n and k == x . key_i
                                                if k == key[i], found the key and return the results
             return (x, i)
        elseif x.leaf
                                    pointer
                                                   if k != key[i] and x is a leaf, could not find k
             return NIL
        else DISK-READ(x.c_i)
                                                        if k != key[i] and x is not a leaf, recurse and search the subtree of x
             return B-TREE-SEARCH(x.c_i, k)
    9
                                                                                T.root
             height
                                          Search for R in the B-tree:
complexity: O(t h) = O(t log_t n)
                         num of
        minimum
                         keys
        degree
```

Create an empty B-tree

```
B-TREE-CREATE(T)

1 x = \text{ALLOCATE-NODE}()

2 x.leaf = \text{TRUE}

3 x.n = 0

4 \text{DISK-WRITE}(x)

5 T.root = x
```

Insert a key into B-trees — Splitting a node

Before inserting, if the node is full with 2t-1 keys, need to split the node first

```
B-Tree-Split-Child (x, i)
    z = ALLOCATE-NODE()
    y = x.c_i
    z.leaf = y.leaf
    z.n = t - 1
    for j = 1 to t - 1
        z.key_i = y.key_{i+t}
    if not y.leaf
        for j = 1 to t
            z.c_i = y.c_{i+t}
    y.n = t - 1
    for j = x \cdot n + 1 downto i + 1
        x.c_{i+1} = x.c_i
    x.c_{i+1} = z
    for i = x . n downto i
        x.key_{i+1} = x.key_i
    x.key_i = y.key_t
    x.n = x.n + 1
    DISK-WRITE(y)
    DISK-WRITE (z)
    DISK-WRITE(x)
```

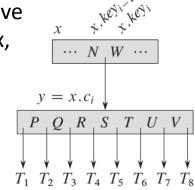
split the full node x.ci, which is y, where x is is a nonfull internal node

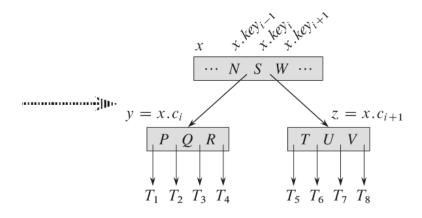
y has 2t-1 elements.

This creates node z and allocate the largest t-1 elements in y into z, and adjust key count for y

complexity: Theta(t)

Assign z as a child of x, move the median key from y to x, and adjust key count of x





Insert a key into B-trees — nonfull node

```
insert a key k into a non-full node x
B-Tree-Insert-Nonfull (x, k)
    i = x.n
    if x.leaf
         while i \ge 1 and k < x . key_i
             x.key_{i+1} = x.key_i
                                          if x is a leaf node, then insert k into x
             i = i - 1
         x.key_{i+1} = k
         x.n = x.n + 1
         DISK-WRITE(x)
    else while i \ge 1 and k < x \cdot key_i
             i = i - 1
10
         i = i + 1
11
         DISK-READ(x.c_i)
         if x.c_i.n == 2t - 1
13
                                              node to insert k into
14
             B-TREE-SPLIT-CHILD (x, i)
             if k > x. key,
15
                 i = i + 1
16
         B-Tree-Insert-Nonfull(x.c_i, k)
17
                                                   child node
```

if x is not a leaf node, and if x.ci is full, then split x.ci, and find which child

> recursively insert k into that nonfull (b) B inserted

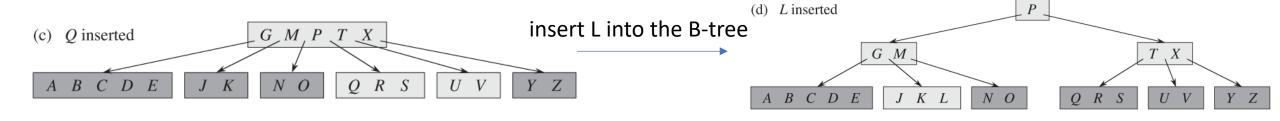
G, M, P, X

N O

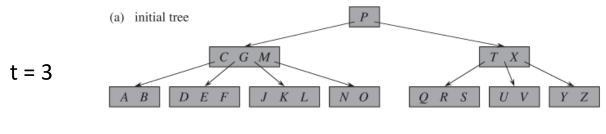
R S T

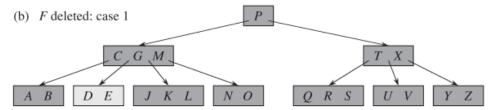
A B C D E

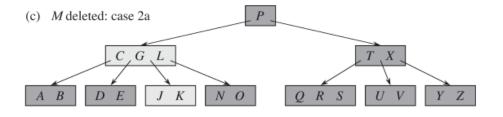
Insert a key into B-trees – general case

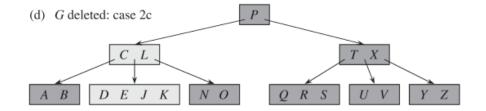


Delete from B-Tree









initial case

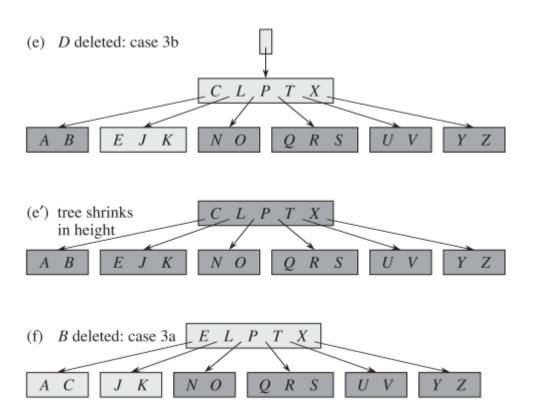
Case 1: simple deletion from leaf node

Case 2a: If child y preceding k has at least t keys, float predecessor k' to replace k, do it recursively

Case 2b: if y has less than t keys, find z that follows k, if z has at least t keys, float the successor of k' of k to replace k, do it recursively

Case 2c: otherwise, merge k and all of z into y and recursively delete k from y

Delete from B-tree continued



Case 3a: if x.ci has only t-1 keys but immediate sibling has at least t keys, move a key from x into ci and move a key from x.ci sibling up into x, and then delete k, recurse on child of x

Case 3b: if x.ci and x.ci's immediate siblings have t-1 keys, merge x.ci with one sibling and move a key from x down to the median of the new node, do it recursively

Reading

• CLRS Book.

Introduction to Algorithms, 3rd Edition, Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein

B-Tree Visualization

https://www.cs.usfca.edu/~galles/visualization/BTree.html