scan 4df16d [1] 1.0 2.0 -0.9 1.5 1.0 -0.8 0.5 motor1 - 0.7 0.0 -0.6 -0.5 ∤ -1.0 -- 0.5 -1.5 0.4 -2.0 -0.100.05 0.10 -0.050.00 motor2