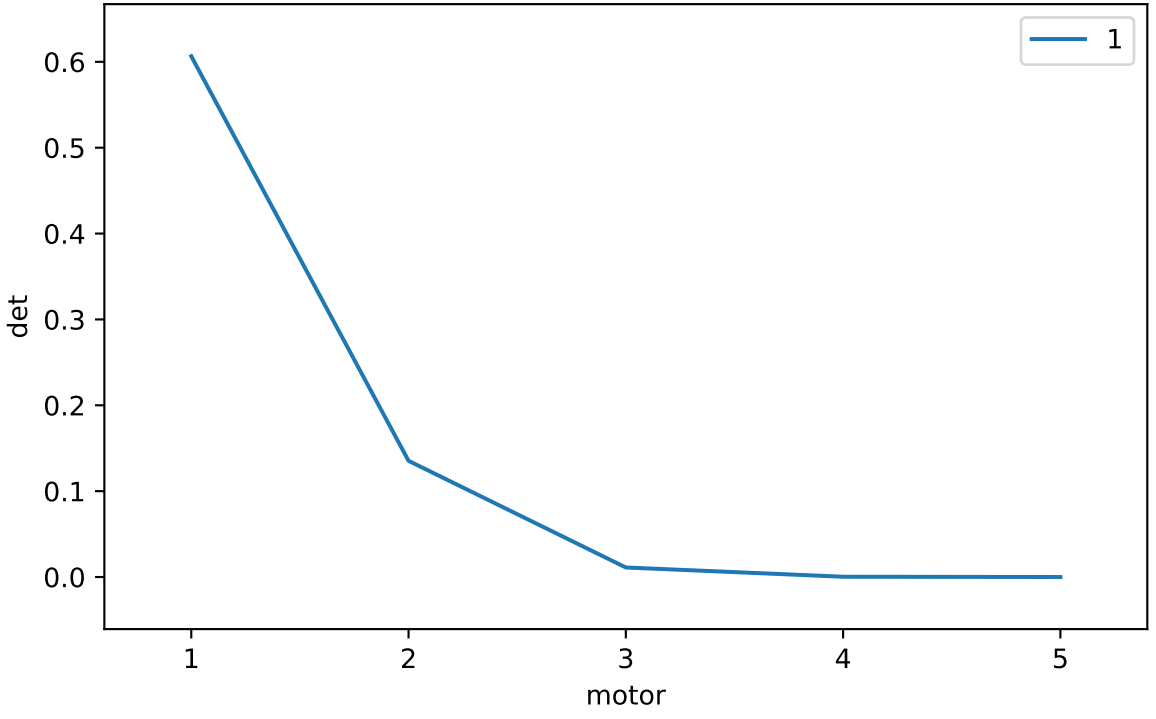
1
0.6
0.5
0.4
0.3
0.2
0.1
0.0
det
1
2
3
4
5
motor