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Training a Spiking Neural Network using R-STDP to perform Autonomous Target Tracking on a Snake Car Robot

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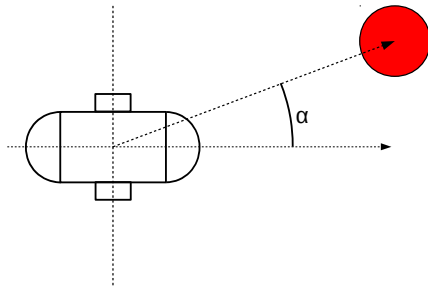
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Planar snake car model

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Figure 1: Angle between robot head module and target.

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[1] R. Munroe.
Number of computers.
https://xkcd.com/1727/.

[2] Nasa.
Nasa photojournal.
https://photojournal.jpl.nasa.gov/.