

Feature effect with variable-size bins

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1 Toy example

A simple toy example for illustrating the importance of variable-size feature effect. Let's say that the correct feature effect for the feature of interest is (see 1):

$$f_{\text{ALE}}(x_s) = c + \begin{cases} 10x_s & , 0 \leq x_s < 5 \\ -10x_s & , 5 \leq x_s < 10 \\ 0 & , 10 \leq x_s < 100 \end{cases} \quad (1)$$

where c is a normalizing constant.

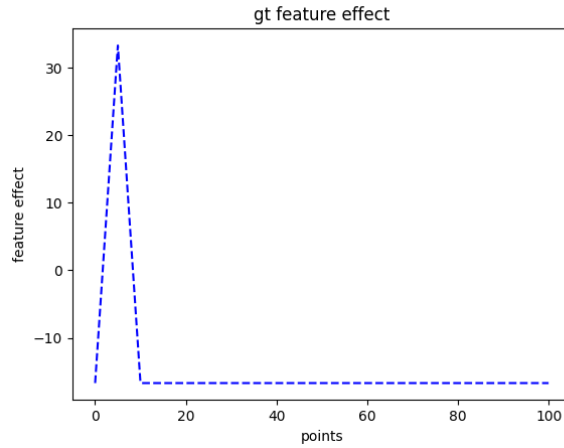


Figure 1: Ground-truth feature effect

We generate $N = 500$ datapoints which are distributed in a special way; $\frac{500}{3}$ are in $[0, 5]$, $\frac{500}{3}$ in $[5, 10]$ and $\frac{500}{3}$ in $[10, 100]$. The points are more dense in the first two piecewise linear parts and more narrow later. We also make

the hypothesis that there are correlations with other features, the local effect computed on each data points gets an added Gaussian noise:

$$\frac{\partial f}{\partial x_s}(x_s) = \epsilon + \begin{cases} 10 & , 0 \leq x_s < 5 \\ -10 & , 5 \leq x_s < 10 \\ 0 & , 10 \leq x_s < 100 \end{cases} \quad (2)$$

where $\epsilon \sim \mathcal{N}(0, 2)$. See the local effect of each data point in figure 1.

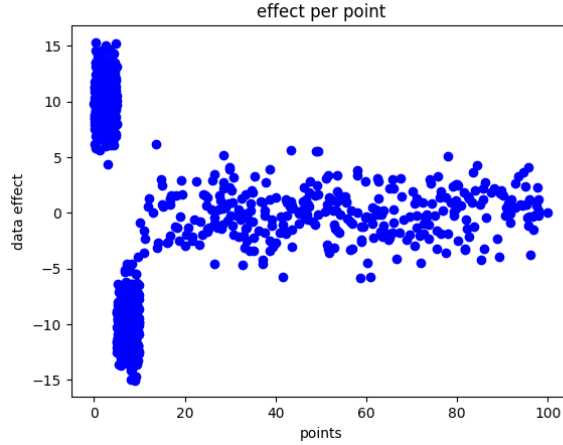


Figure 2: Local effect per point

The example is created to highlight the importance of variable bins; there are two very strong effects in areas $[0, 5]$, $[5, 10]$, and then the effect is zero. Ideally, we would like to create only three bins of different-size, i.e. $[0, 5]$, $[5, 10]$, $[10, 100]$.

2 Fixed-size

With fixed-size bins, there are two solutions; If we create large bins we miss the first two high-resolution effects at the beginning (see fig.3). If we create small bins, we capture the effects at the beginning, but we split effect of $[10, 100]$ in many bins leading to noisy artifacts (see fig 4, 5).

3 Variable-size

With variable-size we can find the optimal bins, given that there is enough resolution i.e. the maximum number of bins is large enough to enable creating small bins in the beginning. For example, with maximum number of bins equal to 10 (see figure 6), it is impossible to capture the effect in the beginning. But

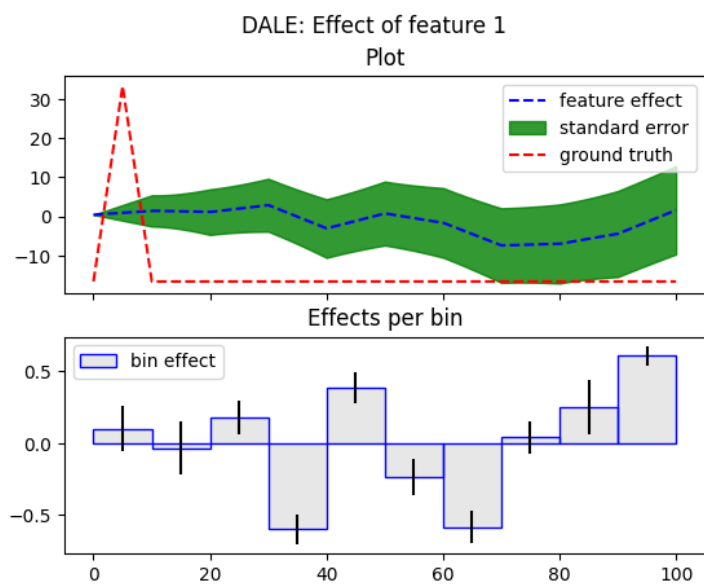


Figure 3: DALE fixed-size with 10 bins

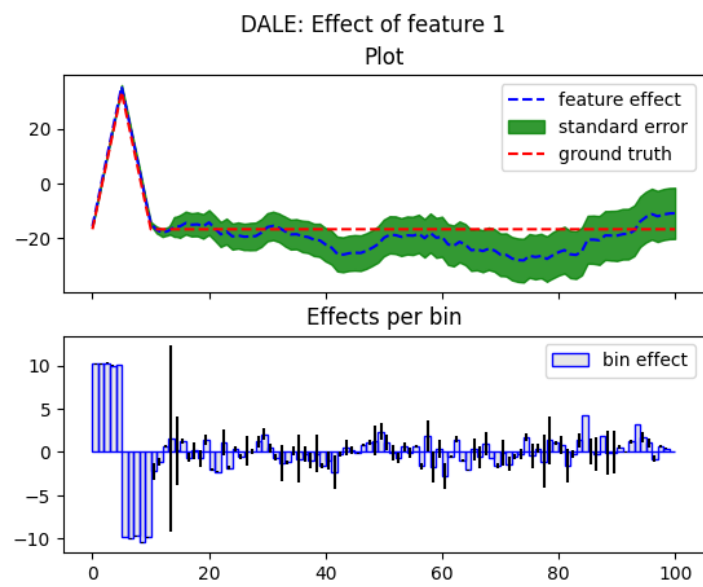


Figure 4: DALE fixed-size with 100 bins

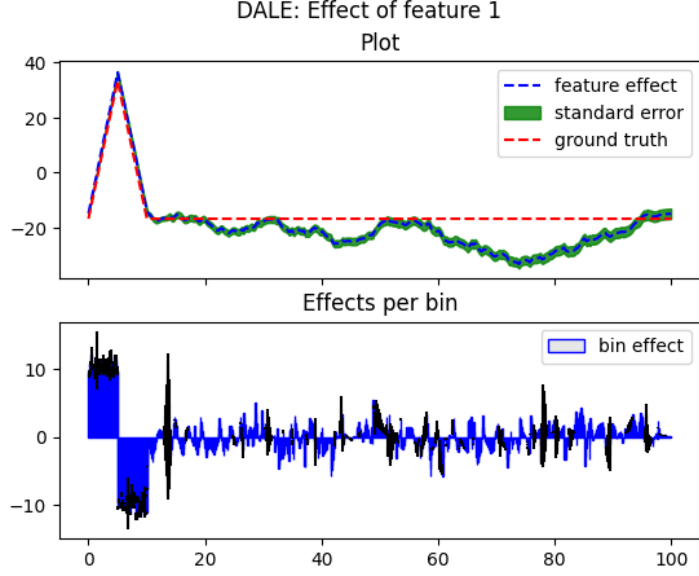


Figure 5: DALE fixed-size with 1000 bins

with maximum number of bins ≥ 20 (see 7 8), the bins are created (almost) perfectly. We also observe that the actual number of the hyperparameter maximum number of bins is not important; all values ≥ 20 give robust results. Finally, we confirm that with create the 'correct' bins, we create perfect feature effect (almost identical with the ground-truth).

4 Comparing fixed-size with Variable-size

We evaluate fixed-size and variable-size with two metrics; Loss and MSE. Loss is the sum of the standard error of each bin and MSE is the Mean squared error between the obtained feature effect plot and the ground-truth. Our goal is to choose the plot with minimum sum of standard errors (loss) as the best feature effect estimation. Therefore, we want to check whether minimising the loss is a good criterion for getting the plot with the smallest MSE. We set a threshold of minimum 10 points per bin for ensuring robust standard error estimations. Therefore we cannot evaluate the loss in cases of large number of fixed-size bins.

For the loss, in figure 9 we observe that:

- for fixed size, the standard error is not a good indicator for choosing the correct number of bins. Firstly, we cannot evaluate it for large number of bins, since there are not enough points inside all bins. Secondly, since the variance inside the bins is big, standard error is dominated by the number of samples.

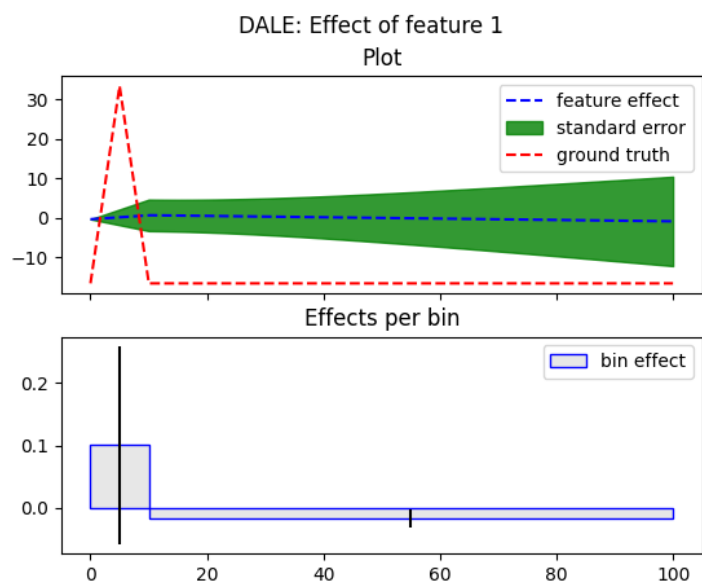


Figure 6: DALE variable-size with 10 bins

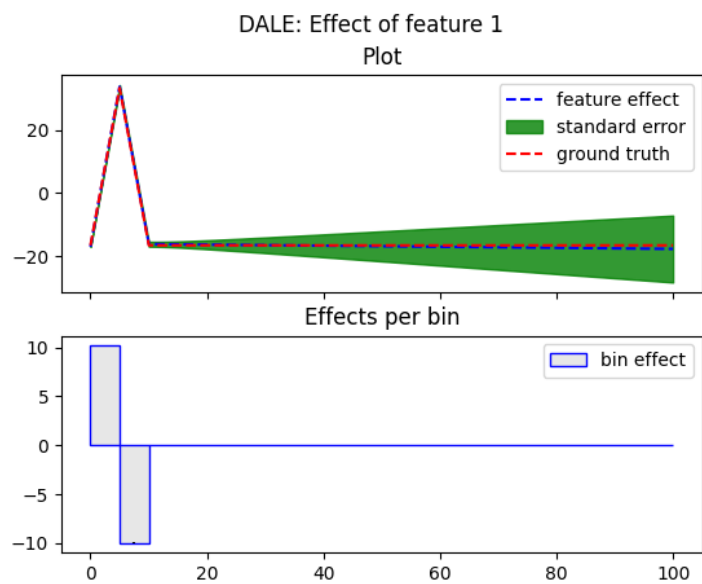


Figure 7: DALE variable-size with 20 bins

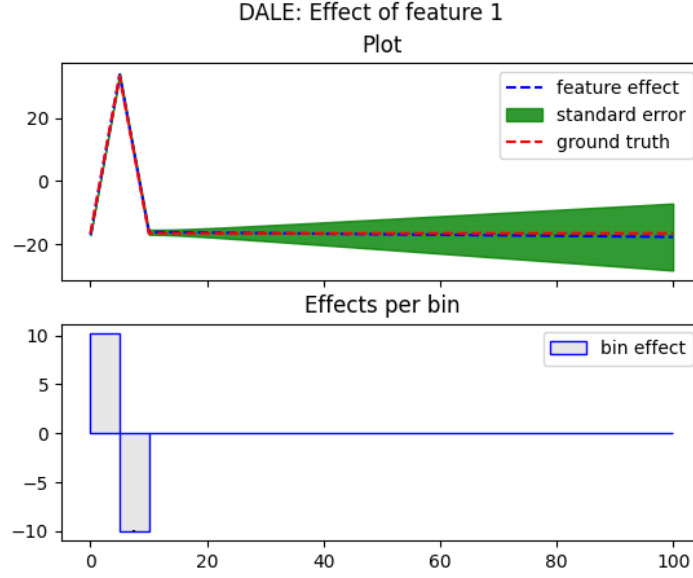


Figure 8: DALE variable-size with 100 bins

- for variable size, the sum of standard errors is a valid indicator indicator. When loss is minimized ($K=20, 40, 60$) the MSE is also minimized.

For the MSE, in figure 10, we observe that:

- for fixed-size, the MSE is smaller for larger number of bins (makes sense)
- for variable-size, the MSE is smaller for larger maximum number of bins (makes sense)
- the variable-size creates in general more accurate feature effect plots
- as the maximum number of bins grows larger we get more robust feature effect plots. For example, $K=21$ leads to large MSE, whereas $K=20$ is almost optimal. In contrast, $K=71$ is very close to $K=70$ which is also almost optimal. In general, for $K \geq 50$ the result is close to perfect independently of the exact value of K .

5 Best solutions based on standard error

In figure 11 we see the best fixed-size feature effect plot based on loss and in figure 12 the best variable-size based on the same criterion.

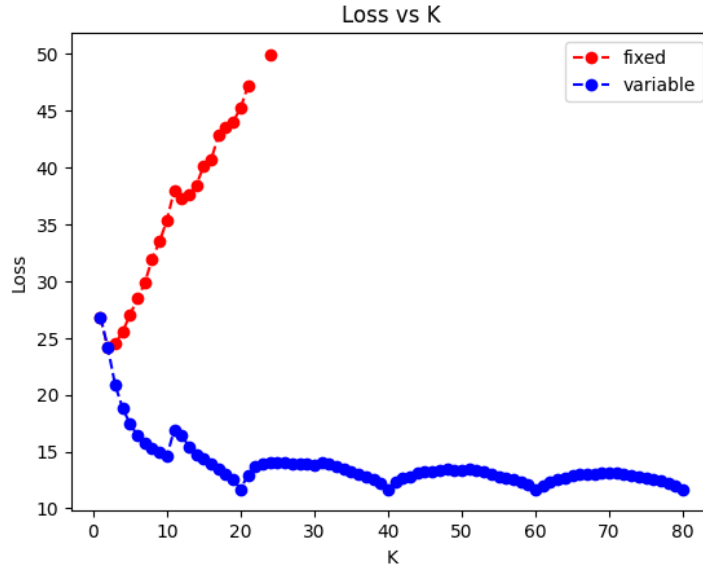


Figure 9: Loss vs number of bins (means number of bins when fixed size, and maximum number of bins when variable size)

6 Conclusion

It is easy to show that it is important to create plots of variable-size bins. Sum of standard errors can be an indicator for choosing the correct plot, but it is not very robust. When the clusters are not very clear, it tends to choose bigger bins (sometimes even allocating all points in a single bin). I am still searching for alternative clustering criteria.

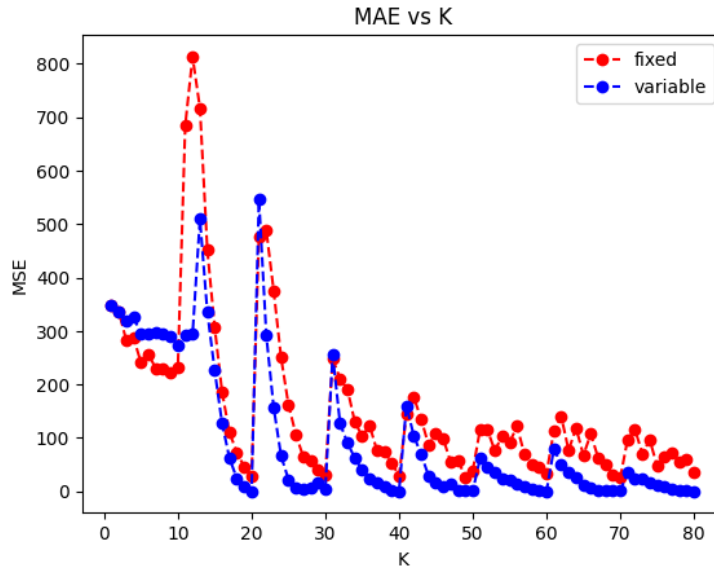


Figure 10: MSE vs number of bins (means number of bins when fixed size, and maximum number of bins when variable size)

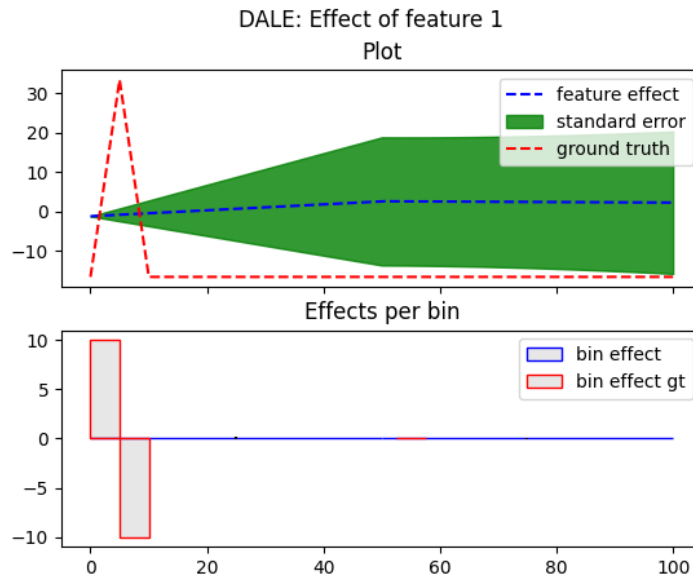


Figure 11: Best solution, based on standard error, for fixed-size bins is the creation of 2 bins

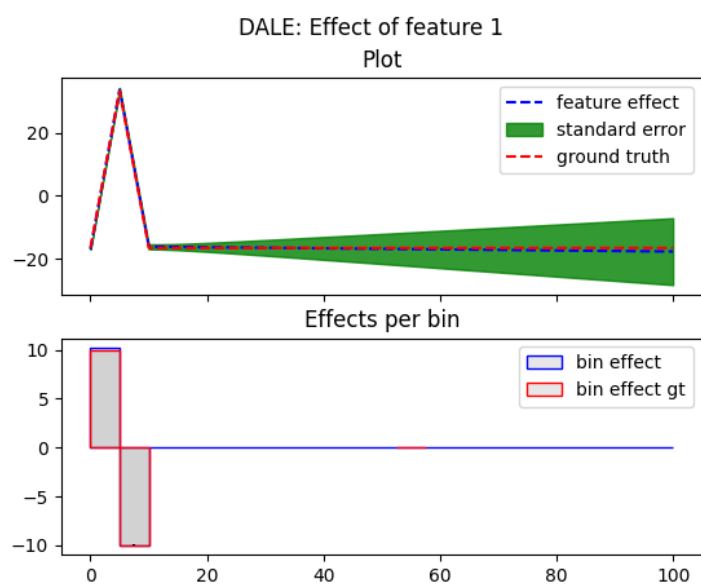


Figure 12: Best solution based on standard error for variable-size bins; it creates the 3 correct bins, with maximum number of bins equal to 80.