HW5 参考答案及常见问题

第一题:

```
1. Note: (i) The argmented matrix

[b<sub>1</sub> b<sub>2</sub> L(u<sub>1</sub>) L(u<sub>2</sub>) L(u<sub>3</sub>)] \Rightarrow \begin{bmatrix} 1 & 2 & 1 & 3 & 0 \\ -1 & 1 & 2 & 0 & -2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -5 & -3 & 4 \\ 0 & 1 & 3 & 3 & -2 \end{bmatrix}

the matrix A = \begin{bmatrix} -5 & -3 & 4 \\ 3 & 3 & -2 \end{bmatrix}

\Rightarrow L(u<sub>1</sub>) = [b<sub>1</sub> b<sub>2</sub>] \begin{bmatrix} -5 \\ 3 \end{bmatrix} L(u<sub>2</sub>) = [b<sub>1</sub> b<sub>2</sub>] \begin{bmatrix} -3 \\ 3 \end{bmatrix} L(u<sub>3</sub>) = [b<sub>1</sub> b<sub>2</sub>] \begin{bmatrix} 4 \\ -2 \end{bmatrix}

(ii) The argmented matrix

[b<sub>1</sub> b<sub>2</sub> L(u<sub>1</sub>) L(u<sub>2</sub>) L(u<sub>3</sub>)] = \begin{bmatrix} 1 & 2 & 0 & 4 & 2 \\ -1 & -1 & -1 & -1 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 2 & -2 & -4 \\ 0 & 1 & -1 & 3 & 3 \end{bmatrix}

the matrix A = \begin{bmatrix} 2 & -2 & -4 \\ -1 & 3 & 3 \end{bmatrix}

\Rightarrow L(u<sub>1</sub>) = [b<sub>1</sub> b<sub>2</sub>] \begin{bmatrix} -1 \\ -1 \end{bmatrix} L(u<sub>2</sub>) = [b<sub>1</sub> b<sub>2</sub>] \begin{bmatrix} -1 \\ 3 \end{bmatrix} L(u<sub>3</sub>) = [b<sub>1</sub> b<sub>2</sub>] \begin{bmatrix} -4 \\ 3 \end{bmatrix}
```

第二题:

转移矩阵S是从 $[1,x,x^2]$ 到 $[2,4x,4x^2-4]$ 。很多同学都弄反了。

$$D(1) = 0 = [1, x, x^{2}] \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$D(x) = 1 = [1, x, x^{2}] \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$D(x^{2}) = 2x = [1, x, x^{2}] \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
thus,
$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$D(2) = 0 = [2,4x,4x^{2}] \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$D(4x) = 4 = [2,4x,4x^{2}] \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$D(4x^{2}-4) = 8x = [2,4x,4x^{2}-4] \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$
thus,
$$B = \begin{bmatrix} 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$1 = \frac{1}{2} \cdot 2 + 0.4x + 0.(4x^{2}-4)$$

$$1 = \frac{1}{2} \cdot 2 + 0.4x + 0.(4x^{2}-4)$$

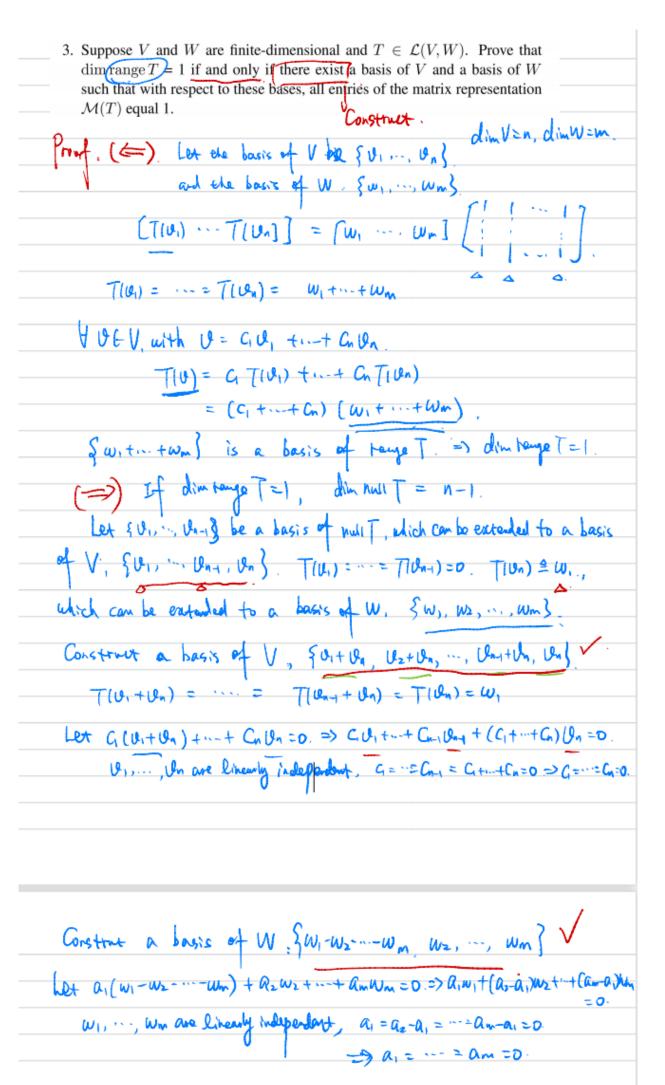
$$1 = \frac{1}{2} \cdot 2 + 0.4x + 0.(4x^{2}-4)$$
thus.
$$1 = \frac{1}{2} \cdot 2 + 0.4x + 0.(4x^{2}-4)$$

U

0

thus.
$$S = \begin{bmatrix} \frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 4 & 0 \end{bmatrix}$$

第三题:



第四题:

4. ci)
$$A^{T}A\hat{x} = A^{T}b \qquad \begin{bmatrix} 6 & 3 \\ 3 & 6 \end{bmatrix} \hat{x} = \begin{bmatrix} 6 \\ 9 \end{bmatrix} \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \end{bmatrix}$$

$$\hat{x} = \begin{bmatrix} 6 & 3 \\ 3 & 6 \end{bmatrix}^{-1} \begin{bmatrix} 6 \\ 9 \end{bmatrix} \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \end{bmatrix}$$

$$A^{T}A\hat{x} = A^{T}b \qquad a basis for C(A) is \begin{cases} \frac{1}{2} \\ -1 \end{cases}$$

$$A^{T} = \begin{bmatrix} \frac{1}{2} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix}$$

$$A^{T} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix}$$

$$A^{T} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad \hat{x} = \begin{bmatrix} \frac{1}{3} \\ -1 \end{bmatrix} \qquad (A^{T})^{T}A^{T} = b \qquad (A^{T})^{T}b = b \qquad (A^{T})^{T}b$$

第五题:

(a)

(a) Suppose V is finite-dimensional and $T \in \mathcal{L}(V)$. Prove that the following statements are equivalent:

(i) T is invertible;

- (ii) T is injective;
- (iii) T is surjective.

Tis invertible (=) Tis injective and surjective

(ii) => ciii) Tis injective, MNUT= fos.

dim V = dim nou T + dim raye T.

= dim range T. (range T is a subspace of V)

=) Nayo T = V

(i'(i) => cii) Tis surjected, range [= V.

dim V= dim nun T + dim nup T = dim nun T + dim V

=) dim nun T = 0. =) null T = {0} =) T is injective.

(b) "=)" Suppose there exists an invertible operator TE ((v) such that Tw = Sw for any ueu, we need to proof that Sis injective Since TEL(v) and Tis invertible, so Tis injective. Assume that for u, uze U, S(u) = S(u), then Itu) = S(u) = S(u) = T(uz) so u1=u2, this proof that S is injective. "E" Suppose that Sis injective Olf dim U = dim V, then SELLV) and S is injective, so S is invertible let T=S, then T satisfies all the items. @ If dim u < dim v, suppose fu, u, umig is a basis of u, and it can be extended to {u, u, ... um umi ... un} which is a basis of V now we need to prove that Scui) Scuil ... Scum) are linearly independen suppose Ciscui) + Ciscui) + ... + Cm Scum) = 0 => S(C, u, + C, u, + m + Cm um) =0 since S is injective, null S = { o} , so c = c = = = = 0 we can extend (Scui) Scui) ... Scum) Unti ... Un as a basis of U Let T(ui) = S(ui) T(us) = S(us) ... T(un) = S(um) T(un) = Vmot "T(un) = Un now we need to proof that I is invertible since dim rangeT = n=dim V, T is surjective suppose T(u) = T(a, u, +a, u, + m + anun) = 0

then a,Tcui) + a, Tcu, + m + a, Tcun) = 0 and {Tcui) Tcui, m Tcun} is a basis of V so a = a, = m = a, null T = {0} so T is injective. So T is invertible.

(c). if part 和 only if part 都需要证明

Druf. ((=). | Y Ut null [1, T_1(V)=0. | S[Z(V)=T_1(V)=0. = S(T_2(V))]

S is invertible, T_2(V) = 0. => U & null [z. => null [z

(=) If null Ti = null Tz, let {4, ", 4r} be a basis of null Ti (null Tz), which Can be extended to a basis of V, Eli, ", Ur, Ury, Jung TI(U1) = ... = TI(U1)=0. Let TI(U1)=W1, ..., TI(Un)=Wn-r T2 (Ux) = "== T2 (Uv) =0. LOT T2 (Ur41) = W1, ", T2 (Un) = Wn.r. Let C, W, + .- + Cn-r Wm+ = 0. => T, (C, br+1+ ... + Cn-r Un) = 0. => CIUrty to Cont Un & MULL Ty => CIUITY TO CONTRACTOR =) W1, ..., Wn-v are likearly independent, which can be exceeded to a basis of W. Similarly, wi, ..., where are linearly judependent, which can be also extended to a basis of W, &w, ..., wn-r, ..., wn). Construct S. $S(w_i) = w_i$, $S(w_m) = w_m$.

(d). 以作业内的题目为准,按照不同题目解答,只要过程正确,也算对。

```
题: T.T.EL(V,W) need to prove: dim null T, = dim null T. = dim null T. = dim null T.
                                                                              RELLU). SELLW)
solution:
                                                                              s.t. TI=STAR.
 € 3 RS St. T,=STAR
       let \{v, \dots v_r\} be a basis of multi, we can extend to it to a basis of V.
        {V. ... Vr, Vr, ..., Vn} => {T, (Vm) .... T, (Vn)} is a basis of rang T.
   since S & ||Z|| are invertible. \{P(V_1), \dots, P(V_n)\} are is a basis of V.
          ST_{\lambda}R(V_{\lambda}) = T_{\lambda}(V_{\lambda}) = 0 ST_{\lambda}R(V_{\lambda}) = T_{\lambda}R(V_{\lambda}) = 0 T_{\lambda}R(V_{\lambda}) = 0 T_{\lambda}R(V_{\lambda}) = 0
           > {AV.) .... , R(V) } & is a bacis of multiple.
         > VeV (s(v) = a, Tx R(V)+ ---+ anTxR(Vn) = are (TxRWree)+---+ anTx R(Vn)
         if Cree Is R(Vree) + --- + CnTeR(Vn) =0. => Cree STeR(Vree) +---+ CnSTeR(Vn)=0
          => CFT1(Vrr1)+---+ CnT1(Vn)=0 => Crr1=---= Cn=0
         we have {T_2P(V_{11}), ..., T_2P(V_n)} is a basis of rougTz.
               din rougt = n-r => dhy rull Tz = r = din rull T,
> if dim null Ti = dim null Tz =r.
     let {v, ..., vr} be a basis of nullTi, and extendit to {vi, ..., vr, vari, ..., vn} a basis of v
           {V', ..., V'} ... null Tz.
                                                                     (vi', ---, vr', vr, --- vn')
                                                                                                              V.
     let R(v,)= v,' --. R(vr) = R(vr') ... R(vn)= vn'
        {Ti(Viri)... Ti(Vi)} is a basis of rangTi, {Ta(Viri), ---, Ta(Vi)} is a basis of $ rog Ta
   let W_i = T_i(V_{ri}) - ... W_{n-r} = T_i(V_n) W_i' = T_i(V_{ri}') - ... W_{n-r} = T_i(V_n') the same of the same of the S(W<sub>i</sub>') = W<sub>i</sub> \{W_i', ..., W_r, W_{ri}, ..., W_n'\} be a basis of W \{W_i', ..., W_r, W_{ri}, ..., W_n'\}
             S(Wm)=Wm
       with S&R
               ¥ i=1,..., r.
                     STLR(V_i) = 0 = T_i(V_i)
```

STER(V;) = STE(V:') = S(W:+) = W:+ = T;(V:)

∀ 1= r+1,...,n.