AutoPylot

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1 Introduction

1.1 Project nature

This is the project nature

1.2 State of the art

This is the state of the art

2 Objectives

2.1 Final objectives

Those are the final objectives

2.2 Optional objectives

Those are the opt objectives

2.3 Motivations

Those are the final requirements

3 Technical specifications

3.1 Hardware

Those are the technical specifications - what we need - data generation / gathering - what will we use ?

3.2 Software

- what software parts we will need

3.3 Constraints

- weight - language: python - autonomous navigation - data ? - framerate, efficiency of the algorithm - safety

4 Planning

5 Task allocation

6 Conclusion