

Hodge Theory, Gelfand Theory, and Clifford Analysis Applied to Tomography

Colin Roberts



Overview

- 1 Introduction
- 2 Clifford analysis
- 3 Hodge theory
- 4 Tomography
- 5 Gelfand theory
- 6 Further results, open questions, conclusion

Section 1

Introduction

Motivating problems

- *Electrical Impedance Tomography (EIT)* asks whether one can determine the conductivity of a medium from the voltage-to-current map.

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- The *Calderón problem* replaces the medium with a manifold M , conductivity with g , and replaces the voltage-to-current map with the Dirichlet-to-Neumann operator Λ .

Other questions

What is the value of α ?

What is the value of β ?

What is the value of γ ?

What is the value of δ ?

What is the value of ϵ ?

What is the value of ζ ?

What is the value of η ?

What is the value of θ ?

What is the value of ι ?

What is the value of κ ?

What is the value of λ ?

What is the value of μ ?

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- Do these functions also contain metric data?
- Can we access these functions from the boundary?

Subsection 1

Preliminaries

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- The associated *Clifford algebra* is the quotient

$$Cl(V, g) := \mathcal{T}(V) / \langle \mathbf{v} \otimes \mathbf{v} - g(\mathbf{v}, \mathbf{v}) \rangle .$$

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- The completely degenerate case is the *exterior algebra*

$$\bigwedge(V) := \text{Cl}(V, 0).$$

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- The bivector part is antisymmetric: $\mathbf{u} \wedge \mathbf{v} = -\mathbf{v} \wedge \mathbf{u}$.

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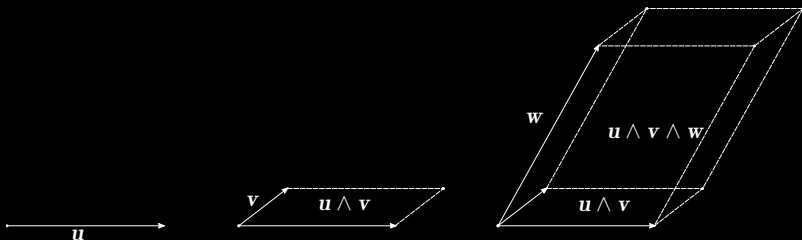
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 - Elements of the even grade subalgebra, \mathcal{G}^+ , are called *spinors*.
- Since $\mathcal{G} = \bigoplus_{r=0}^n \mathcal{G}^r$ a general *multivector* is $A = \sum_{r=0}^n \langle A \rangle_r$.



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- The most important products for us are

$$A_r \wedge B_s := \langle A_r B_s \rangle_{r+s}$$

$$A_r \lrcorner B_s := \langle A_r B_s \rangle_{s-r}$$

Reciprocals and reverses

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$$(\mathbf{v}_1 \mathbf{v}_2 \cdots \mathbf{v}_r)^\dagger = \mathbf{v}_r \cdots \mathbf{v}_2 \mathbf{v}_1.$$

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- The *projection* of A into a subspace U_r by

$$P_{U_r}(A) := A \lrcorner U_r U_r^{-1}.$$

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$$I := \frac{1}{|\boldsymbol{\mu}|} \boldsymbol{\mu}.$$

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- Dual exchanges products $(A \lrcorner B)^\perp = A \wedge B^\perp$.

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 - Standard basis $\mathbf{e}_1, \mathbf{e}_2$, and $\mathbf{e}_{12} := \mathbf{e}_1 \mathbf{e}_2$. Then $\mathbf{e}_{12}^2 = -1$.
 - Right multiplication of vectors by \mathbf{e}_{12} rotates counter-clockwise by $\pi/2$.

Section 2

Clifford analysis

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- Take same naming scheme and notation: $\mathfrak{X}^r(M)$, $\mathfrak{X}^+(M)$, etc.

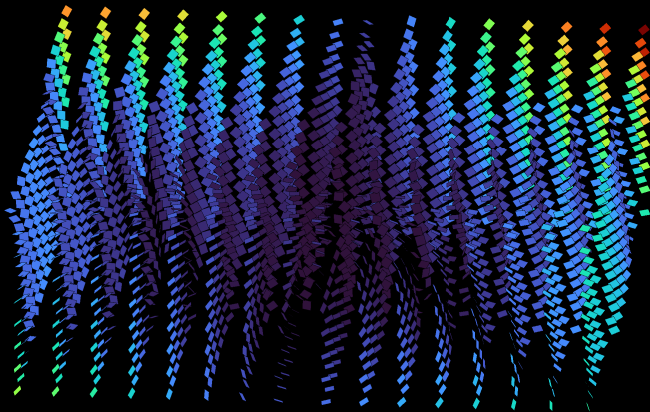
Scalar field

$$\langle p_{(1,0)} + p_{(0,1)} + p_{(1,1)} + p_{(2,0)} + p_{(0,2)} + p_{(3,0)} + p_{(0,3)} + p_{(2,1)}(1 + \mathbf{e}_{31}) + p_{(1,2)}(1 + \mathbf{e}_{31}) \rangle$$



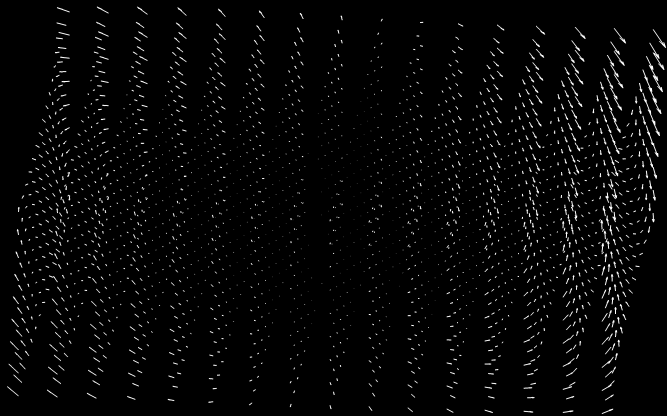
Bivector field

$$\langle p_{(1,0)} + p_{(0,1)} + p_{(1,1)} + p_{(2,0)} + p_{(0,2)} + p_{(3,0)} + p_{(0,3)} + p_{(2,1)}(1 + \mathbf{e}_{31}) + p_{(1,2)}(1 + \mathbf{e}_{31}) \rangle_2$$



Vector field

$$\langle p_{(1,0)} + p_{(0,1)} + p_{(1,1)} + p_{(2,0)} + p_{(0,2)} + p_{(3,0)} + p_{(0,3)} + p_{(2,1)}(1 + \mathbf{e}_{31}) + p_{(1,2)}(1 + \mathbf{e}_{31}) \rangle_2^\perp$$



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- ∇^2 is the Laplace-Beltrami operator.

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- For a vector field $\mathbf{v} \in \mathfrak{X}^1(\mathbb{R}^3)$ we have

$$\nabla \mathbf{v} = \underbrace{\nabla \lrcorner \mathbf{v}}_{\text{divergence}} + \underbrace{\nabla \wedge \mathbf{v}}_{\text{curl}}.$$

where

$$\text{curl}(\mathbf{v}) = (\nabla \wedge \mathbf{v})^\perp$$

Differential forms

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- Algebra and calculus descend to multivector equivalent:

$$\alpha_r \wedge \beta_s = (A_r \wedge B_s) \lrcorner dX_{r+s}^\dagger$$

$$\underbrace{d\alpha_r = (\nabla \wedge A_r) \lrcorner dX_{r+1}^\dagger}_{\text{exterior derivative}}$$

$$\alpha_r \lrcorner \beta_s = (A_r \lrcorner B_s) \lrcorner dX_{r-s}^\dagger$$

$$\underbrace{\delta\alpha_r = (-\nabla \lrcorner A_r) \lrcorner dX_{r-1}^\dagger}_{\text{codifferential}}$$

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- For M this yields $d\mu = \sqrt{|g|} dx^1 \cdots dx^n$

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- Define the *multivector field inner product on R* by

$$\langle\langle A, B \rangle\rangle_R := \int_R A * B d\mu_R$$

Green's formulas

- From [Hestenes, Sobczyk: 1984] and [Booß-Bavnbek, Wojciechowski: 1993]

$$\langle \nabla A, B \rangle = (-1)^n \langle A, \nabla B \rangle + \langle A, B \rangle_{\partial M}$$

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- Following from the above

$$\langle \nabla A, B \rangle = -\langle A, \nabla B \rangle + \langle A, \nu B \rangle.$$

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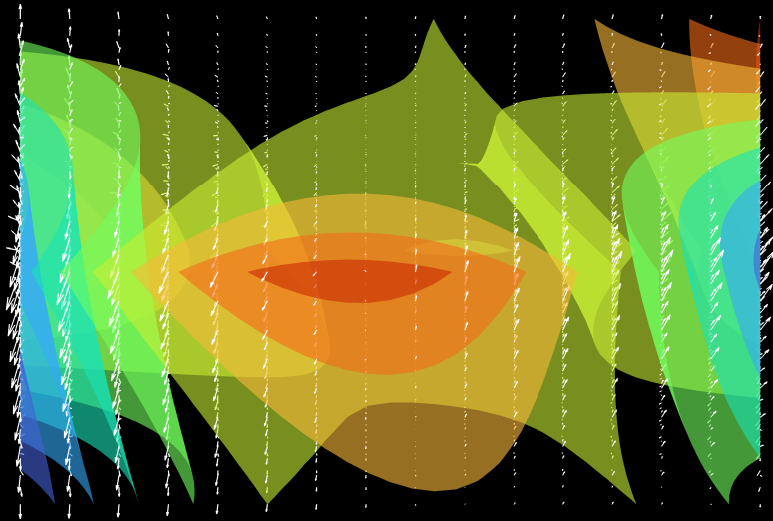
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$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}.$$

- Field $p_{(1,0)} + p_{(0,1)} + \cdots$ is monogenic (or quaternion harmonic).



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- have **harmonic components**.

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- [Calderbank: 1995], this map is an isomorphism.

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- **Scalar part of the above is the double layer potential.**

Inversion

- [Calderbank: 1995] Can solve the equation $\nabla A = B$ by

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- In a region $M \subset \mathbb{R}^3$ take a vector field \mathbf{J} ,

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Inversion

- [Calderbank: 1995] Can solve the equation $\nabla A = B$ by

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- **This is the Biot–Savart operator.** [Cantarella, et al.: 2001]

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Proposition

Monogenic fields can be written as a power series in z_{ij} and the coefficients are computed with a Cauchy integral.

Section 3

Hodge theory

Idea

Hodge theory relates analysis to topology.

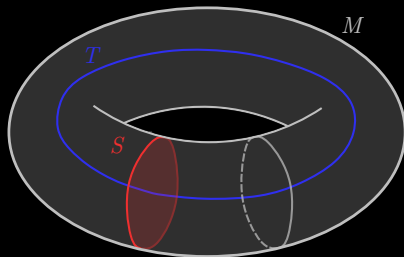
Idea

Hodge theory relates analysis to topology.

■ **Theorem (Hodge Isomorphisms).**

$$H^r(M) \cong \mathcal{M}_N^r(M)$$

$$H^r(M, \partial M) \cong \mathcal{M}_D^r(M, \partial M).$$



Product on cohomologies

We know $\wedge: H^r(X) \times H^s(X) \rightarrow H^{r+s}(X)$.

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The contraction \lrcorner is a product on cohomologies by:

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- $\lrcorner: H^r(M, \partial M) \times H^s(M, \partial M) \rightarrow H^{s-r}(M, \partial M)$;
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- This product is equivalent to the mixed cup product in [Shonkwiler, 2009].

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- But, $\mathcal{M}(M) \neq \bigoplus_{j=1}^n \mathcal{M}^j(M)$.

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Theorem: Clifford–Hodge Decomposition

The space of multivector fields $\mathfrak{X}(M)$ has the orthogonal decomposition

$$\mathfrak{X}(M) = \mathcal{M}(M) \oplus \nabla\mathfrak{X}(M).$$

Comparing to Hodge–Morrey

- From Hodge–Morrey

$$\mathfrak{X}(M) = \sum_{r=0}^n \underbrace{\mathcal{E}_D^r(M)}_{\operatorname{im}(\nabla \wedge)} \oplus \underbrace{\mathcal{C}_N^r(M)}_{\operatorname{im}(\nabla \lrcorner)} \oplus \underbrace{\mathcal{M}^r(M)}_{\operatorname{ker}(\nabla)}.$$

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- But the Clifford–Hodge is not filtered by grades

$$\mathfrak{X}(M) = \underbrace{\mathcal{M}(M)}_{\ker \nabla} \oplus \underbrace{\nabla \mathfrak{X}(M)}_{\operatorname{im} \nabla}.$$

Section 4

Tomography

EIT forward problem

Given σ and \mathbf{J} , find \mathbf{E} and \mathbf{V}

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EIT inverse problem

• σ is unknown

• σ is piecewise constant

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• σ is piecewise constant and linear with noise and regularization

• σ is piecewise constant and linear with noise and regularization and a priori information

• σ is piecewise constant and linear with noise and regularization and a priori information and a posteriori information

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- The *electric Dirichlet-to-Neumann (DN) operator*

$$\Lambda_E: \mathfrak{t}\mathfrak{X}^0(M) \rightarrow \mathfrak{t}\mathfrak{X}^0(M) \quad \text{by} \quad \Lambda_E \phi = \boldsymbol{\nu} \lrcorner \boldsymbol{\nabla} \wedge u = \frac{\partial u}{\partial \boldsymbol{\nu}}.$$

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- Question: Can we determine (M, g) from Λ_E ?

Magnetic analog

- Magnetic bivector field B solves the forward problem

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- Question: What can we get from Λ_B ?

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- The smooth cases is still unsolved.

Electromagnetic tomography

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Electromagnetic tomography

- **Can combine to monogenic spinor $A_+ = u + B$.**
- Can we recover the space of monogenic fields from the DN operators?
- If the space of monogenic fields contained geometric data, this would be a step forward in the Calderón problem...

Geometric generalization

In arbitrary dimension:

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- $\Lambda_E \times \Lambda_B$ is equivalent to **complete DN operator** [Shonkwiler, Sharafutdinov: 2013].

Spinor DN operator

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Theorem

$$\ker \mathcal{J} = \text{tr}\mathcal{M}^\pm(M).$$

Section 5

Gelfand theory

Open questions

- How can we make the model more expressive?
- How can we make the model more robust to adversarial perturbations?
- How can we make the model more interpretable?
- How can we make the model more efficient?
- How can we make the model more scalable?
- How can we make the model more robust to distribution shifts?
- How can we make the model more robust to model misspecification?
- How can we make the model more robust to model overfitting?
- How can we make the model more robust to model underfitting?
- How can we make the model more robust to model bias?
- How can we make the model more robust to model variance?
- How can we make the model more robust to model noise?
- How can we make the model more robust to model outliers?
- How can we make the model more robust to model anomalies?
- How can we make the model more robust to model errors?
- How can we make the model more robust to model failures?
- How can we make the model more robust to model crashes?
- How can we make the model more robust to model downtime?
- How can we make the model more robust to model security breaches?
- How can we make the model more robust to model data breaches?
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- We will prove this is true for arbitrary regions.

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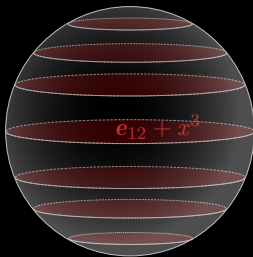
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- Find g that conformal with the complex structure.

Subsurface spinor fields

- For O convex, let $\boldsymbol{B} \in \mathfrak{X}(O)$ be parallel translation of a unit 2-blade.

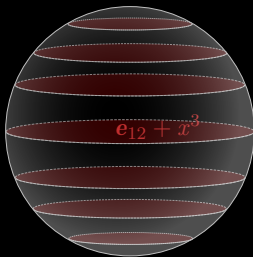
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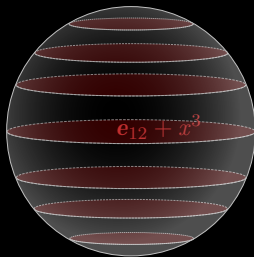
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- **Algebra is a commutative Banach algebra.**

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- **We show these are the only elements in the spectrum.**

Idea

By linearity, we can note that for $\delta \in \mathfrak{M}(M)$

$$\delta[A_+] = \sum_{j=0}^{\infty} \left(\sum_{\substack{j_2 \cdots j_n \\ j_2 + \cdots + j_n = j}} \delta[p_{j_2 \cdots j_n}] a_{j_2 \cdots j_n} \right)$$

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by the multiplicativity of δ . Then $z_{ij} \in \mathcal{A}_{\mathbf{e}_{ij}}(O)$.

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Lemma: Point evaluation

For $\delta \in \mathfrak{M}(M)$ we have $\delta(z_{ij}) = z_{ij}(x_\delta)$ for some $x_\delta \in \mathbb{R}^n$.

Necessary lemmas

For regions $M \subset \mathbb{R}^n$:

Lemma: Density

The space $\mathcal{M}^{\mathcal{P}}(M)$ is dense in $\mathcal{M}(M)$.

Lemma: Point evaluation

For $\delta \in \mathfrak{M}(M)$ we have $\delta(z_{ij}) = z_{ij}(x_\delta)$ for some $x_\delta \in \mathbb{R}^n$.

Lemma: Identification

Let $A_+ \in \mathcal{M}^+(M)$, then $\delta(A_+) = A_+(x_\delta)$ for some $x_\delta \in M$.

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Theorem: Clifford-algebraic Gelfand theorem

With the weak-* topology on $\mathfrak{M}(M)$, the map

$$\gamma: \mathfrak{M}(M) \rightarrow M, \quad \delta \mapsto x_\delta$$

is a homeomorphism. The Gelfand transform $\widehat{A}_+(\delta) = \delta[A_+]$ is an isometric isomorphism so $\mathcal{M}^+(M) \cong \widehat{\mathcal{M}^+(M)}$.

Section 6

Further results, open questions, conclusion

A Stone–Weierstrass theorem

- Using continuation from a z_{ij} :

Lemma

The space $\overline{\mathcal{M}^+(M)}$ separates points.

A Stone–Weierstrass theorem

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Lemma

The space $\overline{\mathcal{M}^+(M)}$ separates points.

- Using [Laville, Ramadanoff: 1996]:

Theorem: Stone–Weierstrass

$\overline{\mathcal{M}^+(M)}$ is dense in $C(M; \mathcal{G}^+)$.

Sheaf theory

- Using unique continuation:

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Theorem

The sheaf \mathcal{M}_M is Hausdorff and the map $\pi: \mathcal{M}_M \rightarrow M$ is a local homeomorphism.

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Sheaf theory

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Theorem

The sheaf \mathcal{M}_M is Hausdorff and the map $\pi: \mathcal{M}_M \rightarrow M$ is a local homeomorphism.

- Can one find a component of \mathcal{M}_M that is homeomorphic to M ?
- This would be helpful in using technique of [Lassas, Uhlmann: 2001].

Future work and open questions

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- The DN operator determines $\text{tr} \mathcal{M}^+(M)$.
- The map $\text{tr}: \vee \mathcal{M}^+(M) \rightarrow \text{tr} \vee \mathcal{M}^+(M)$ is an isometric isomorphism of algebras.
- The space $\mathcal{M}^+(M)$ determines the metric structure of M up to isometry.

Future work and open questions

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- Many of these approaches use the Hilbert transform which is also used by Belishev, Sharafutdinov, and Shonkwiler to study the Calderón problem.
- The Hilbert transform is also a classical part of Clifford analysis.
- [Lassas, Uhlmann: 2001] use sheaf theory to solve the analytic Calderón problem.
- [Santacesaria: 2019] proposes another method for solving the Calderón problem using Clifford algebras and complex geometric optics.

Conclusion

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- Able to describe DN operators and extract homological information and boundary values of monogenic fields.
- Monogenic fields are uniquely determined by boundary traces via Cauchy integral.
- Monogenic fields are able to tell us the topology of the manifold they are defined on.

Thank you!