

The Calderón Problem

on Riemannian Manifolds

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Outline

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- Discuss some of the current results and issues.
- Rephrase the problem in a geometrical way.
- Prove the problem in 2 dimensions using the boundary control method.
- What can and can't we do to generalize this method?

Section 1

Introduction

Subsection 1

Calderón Problem

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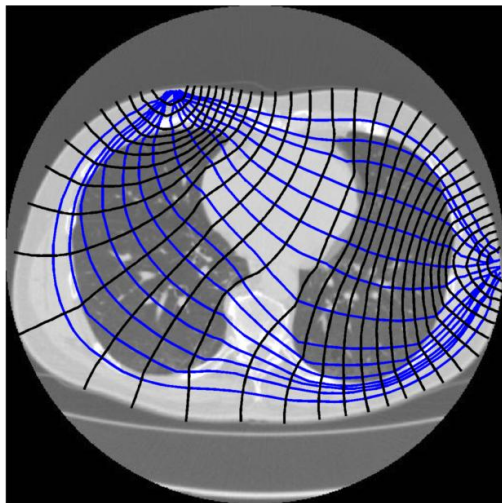
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- This problem sparked interest due to its usefulness in geophysical and medical imaging.



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- Can we determine the conductivity matrix γ from Λ ?

Section 2

The Calderón Problem on Riemannian Manifolds

Subsection 1

Preliminaries

Geometry

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- *Smooth n -dimensional manifold*: A space that locally looks like (is C^∞ diffeomorphic to) an open subset of \mathbb{R}^n .

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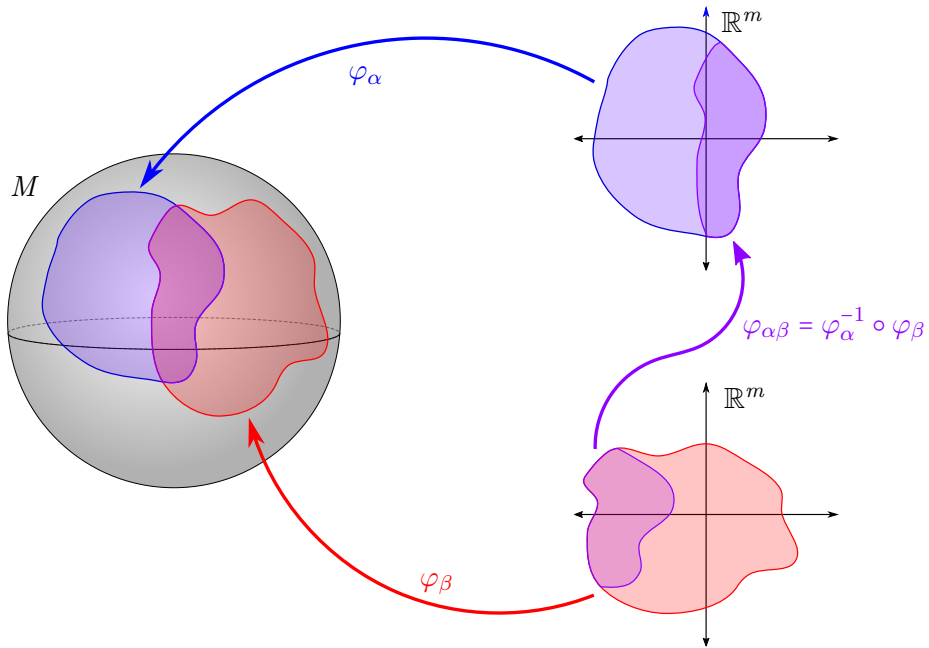
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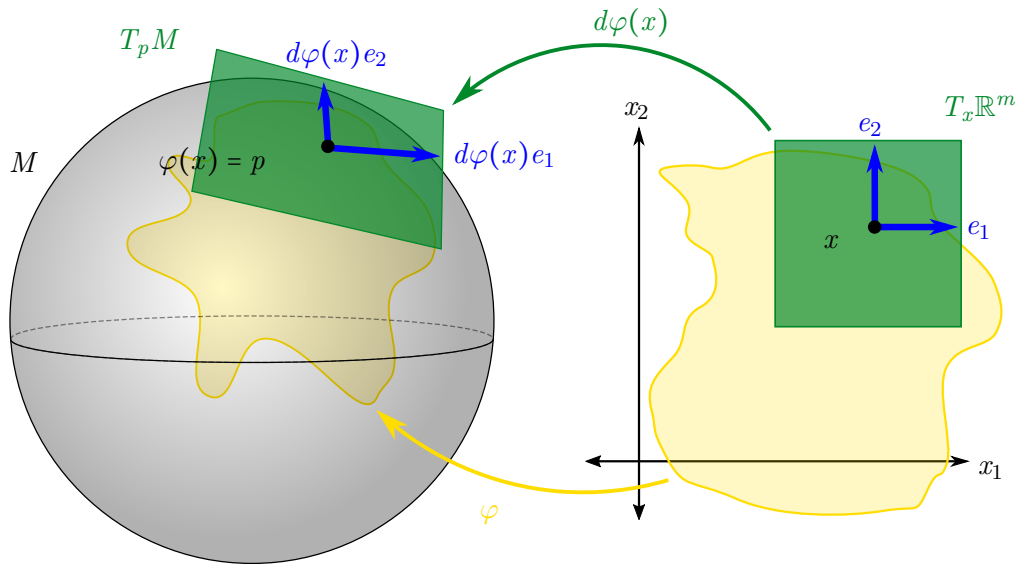
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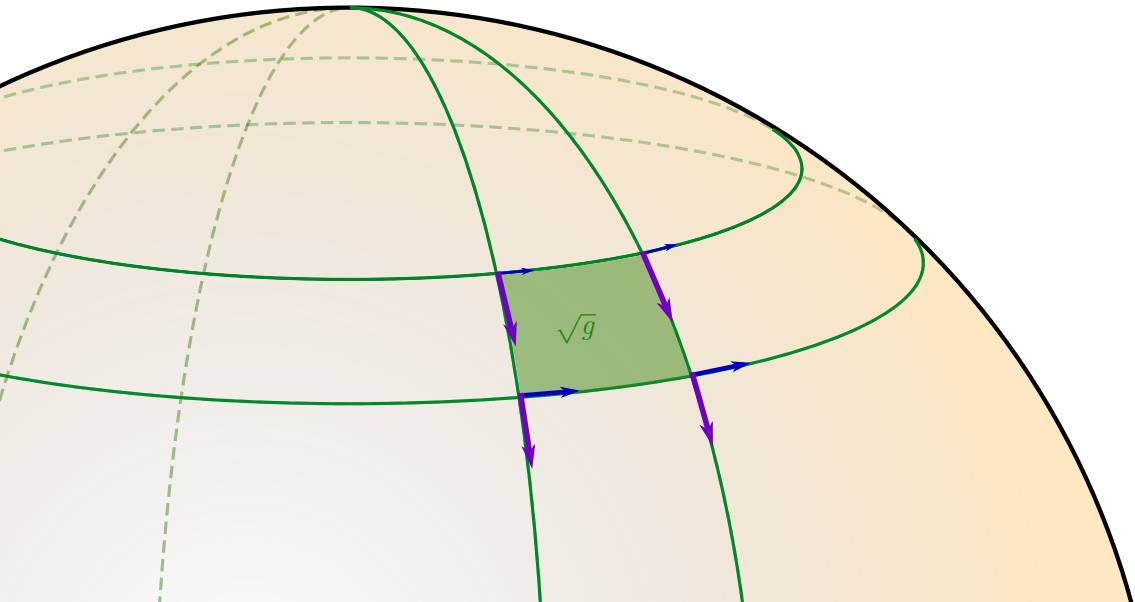
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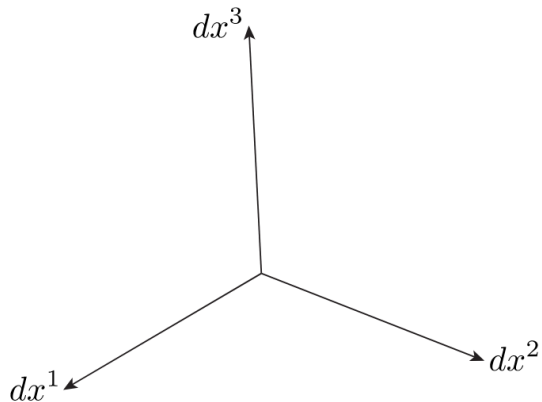
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- *Exterior algebra*: Differential forms with the wedge product \wedge .
- *Hodge Star*: Attached to the exterior algebra when we also have a Riemannian metric. Gives an isomorphism between k and $n - k$ -forms.



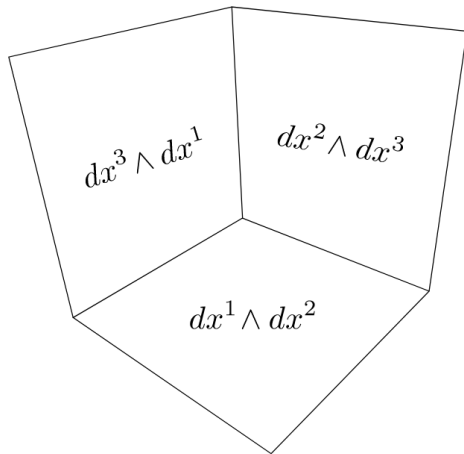




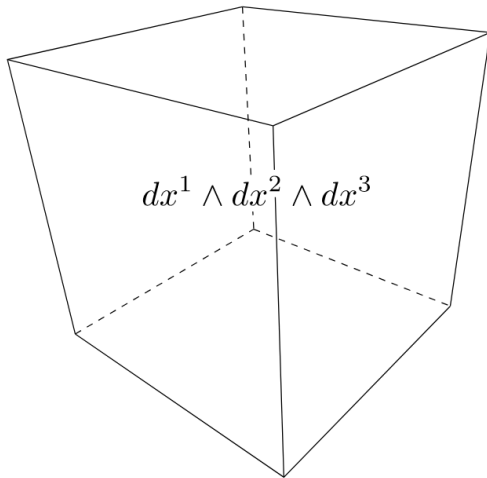
1-Forms



2-Forms



3-Forms



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- *Codifferential*: Formal adjoint to d written as δ .
- *Dirac Operator*: $D = d + \delta$.
- *Laplace-Beltrami Operator*: $\Delta = d\delta + \delta d = D^2$ and in coordinates

$$\Delta f = \frac{1}{\sqrt{|g|}} \sum_{j=1}^n \sum_{k=1}^n \frac{\partial}{\partial x^i} \sqrt{|g|} g^{ij} \frac{\partial}{\partial x^j} f$$

Subsection 2

Raphrasing EIT Problem in a Geometrical Language

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- Recover g from knowing Λ .

Subsection 3

Expected and Current Results

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So, g is a function of n variables that needs to be determined by the kernel λ which is $2n - 2$ variables.

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- $n \geq 3$ is overdetermined.

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Indeed, let $\tilde{g} = e^{2\phi}g$, then

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When $n = 2$, the extra term cancels.

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- Can only know the total impedance between the two electrodes.

Isotropic Case

For g isotropic and $n \geq 3$ one can determine g from Λ .

(*Sylvester-Uhlmann 1987*)

2 Dimensional Anisotropic

- Can recover g up to conformal class and can't do better.
- Proven by Lassas and Uhlmann in *On Determining the Riemannian manifold from the Dirichlet to Neumann map*.

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- Can determine the boundary C^∞ -jet of g in Lee and Uhlmann's *Determining anisotropic real-analytic conductivities by boundary measurements*.
- For smooth manifolds, the anisotropic problem is open. The goal is to recover the metric up to isometry.

Section 3

Boundary Control Method in 2 Dimensions

Theorem

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Two 2-dimensional compact orientable manifolds with single common boundary are conformally equivalent iff their DN-maps coincide.

Belishev's *The Calderón Problem for Two-Dimensional Manifolds by the BC-Method.*

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- Gelfand transform relates an algebra \mathcal{A} to the algebra of continuous functions on the spectrum of that algebra, $C(\text{spec}\mathcal{A})$.
- This gives us a way to realize Ω from functions defined on Ω that we have access to.

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- Represent the trace algebra with the DN map. (Lemma 3)
- Construct the manifold. (Theorem)

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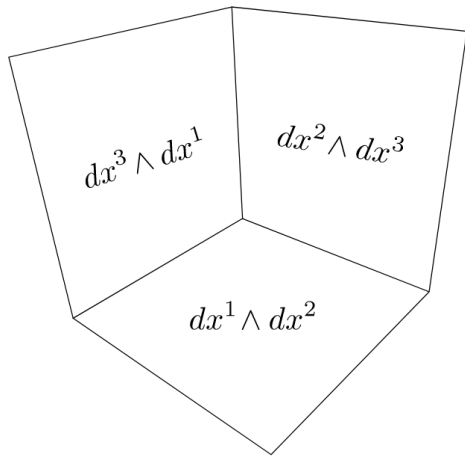
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- Λ maps boundary k -forms to boundary $n - k - 1$ forms.



Subsection 1

Lemma 1

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- $\dim \operatorname{Ran} \left[\Lambda + d\Lambda^{-1}d \right] = \beta_1(\Omega).$

Corollary

Λ completely determines the topology of Ω .

Proof

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- Since Ω is a single connected component, $\beta_0(\Omega) = 1$.
- We have $\beta_1(\Omega)$ from before.
- Since Ω is a surface with boundary, $\beta_2(\Omega) = 0$.
- Since Ω is two dimensional, $\beta_n(\Omega) = 0$ for $n \geq 3$.

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- We call u and v conjugate by CREs.

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- This is analogous to having the Hodge star on a surface.

Subsection 2

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- \mathcal{M} with this topology is called the *spectrum* $\text{spec}\mathcal{A}$.

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- A generic algebra is (spatially) isomorphic to its Gelfand transform.

Lemma 2

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The algebra of holomorphic functions $\mathcal{A}(\Omega)$ is generic.

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- The lemma shows that $\epsilon: \Omega \rightarrow \text{spec}\mathcal{A}(\Omega)$ is a homeomorphism, so we have determined Ω up to homeomorphism.

What's Left?

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We can only have hope access to the trace algebra $\mathcal{A}(\partial\Omega)$. So we need to determine this to reach our goal.

Subsection 3

Lemma 3

Trace Algebra

Trace Algebra

- The trace algebra $\mathcal{A}(\partial\Omega) := \iota^* \mathcal{A}(\Omega)$ is isometrically isomorphic to $\mathcal{A}(\Omega)$ since

$$\|w\|_{\mathcal{A}(\Omega)} = \|\iota^* w\|_{\mathcal{A}(\partial\Omega)}$$

and since a holomorphic function is uniquely determined by its boundary values.

Lemma 3

We have the representation

$$\mathcal{A}(\partial\Omega) = \text{clos}_{C(\partial\Omega)} \{f + ih\},$$

where h is conjugate to f by \mathcal{H} .

Subsection 4

Proof of the Main Theorem

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- Step 2: Then find $\text{spec}\mathcal{A}(\partial\Omega) = \Omega$ by Lemma 2.
- Step 3: Next, the Gelfand transform $\hat{\mathcal{A}}(\partial\Omega) = \mathcal{A}(\Omega)$ by Lemma 2.

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- Step 2: Then find $\text{spec}\mathcal{A}(\partial\Omega) = \Omega$ by Lemma 2.
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Construction of the Manifold

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- Step 5: Equip Ω with a metric g conforming to this complex structure.

Section 4

Generalizing This Method

First Issue

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- No complex structure in higher dimensions.

Resolution

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- The tools of Clifford analysis allow us to recover a notion of holomorphicity known as *monogenicity*.
- We can recover a similar algebra (Hardy space) of monogenic functions.

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- Geometric product can be extended to multivectors.

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$$x + iy \iff 1x + e_1 \wedge e_2 y,$$

where $e_1 \wedge e_2$ is the bivector (and psuedoscalar).

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- Elements in the kernel of D are monogenic.
- Monogenic objects in even subalgebra have components that are harmonic.
- There are Cauchy integral and Hilbert transform type operators for D in arbitrary dimension.

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- The spectral theory for Belishev's solution required a commutative Banach algebra.
- The spectral theory for noncommutative Banach algebras is not as developed.
- There is still work to do here to find some way around this.

Section 5

Conclusion

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- Ideal results are still not yet obtained.

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- It relies heavily on complex analysis and the spectral theory for commutative Banach algebras.
- These issues remain if we try to naively generalize this approach.

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- We can still construct the same algebra of holomorphic functions.
- The relevant algebras are noncommutative for dimensions ≥ 3 .
- There are possibly other tools at our disposal that may be able to replace the loss of commutivity.

Thank you!