## MATH 272, Worksheet 3

INTEGRATION OVER CURVES AND POTENTIAL FUNCTIONS.

**Problem 1.** Draw a picture explaining what an integral of a scalar field over a curve is computing. That is, explain the reasoning behind the definition

$$\int_{\vec{\gamma}} f(\gamma) d\vec{\gamma} = \int_{t_0}^{t_1} f(\gamma(t)) \left| \dot{\vec{\gamma}}(t) \right| dt,$$

where f is a scalar field and  $\vec{\gamma}$  is some curve starting at time  $t_0$  and ending at time  $t_1$ .

**Problem 2.** Compute the integrals of the scalar field f(x, y, z) = 2 - x + y - z over the following curves.

- (a)  $\vec{\gamma}_1$  is the boundary of the unit square in the xy-plane. (c)  $\vec{\gamma}_3$  is the curve  $\vec{\gamma}_3(t) = \begin{pmatrix} t \\ t^2 \\ t^3 \end{pmatrix}$  from time
- (b)  $\vec{\gamma}_2$  is the unit circle in the *xy*-plane. t = 0 to t = 1.

**Problem 3.** Draw a picture explaining what an integral of a vector field over a curve is computing. That is, explain the reasoning behind the definition

$$\int_{\vec{\gamma}} \vec{V}(\vec{\gamma}) \cdot d\vec{\gamma} = \int_{t_0}^{t_1} \vec{V}(\vec{\gamma}(t)) \cdot \dot{\vec{\gamma}}(t) dt,$$

where  $\vec{\boldsymbol{V}}$  is a vector field and  $\vec{\boldsymbol{\gamma}}$  is some curve starting at time  $t_0$  and ending at time  $t_1$ .

**Problem 4.** We have briefly discussed the idea of work (change in energy) before and wrote

$$W = \vec{F} \cdot \vec{r},$$

where  $\vec{F}$  was a constant force and  $\vec{r}$  was a straight line displacement.

Now, we can write the real version of this. The work done on a particle moving along a curve  $\vec{\gamma}(t)$  that is experiencing a spatially dependent force field  $\vec{F}(x,y,z)$  is

$$W = \int_{\vec{\boldsymbol{\gamma}}} \vec{\boldsymbol{F}}(\vec{\boldsymbol{\gamma}}) \cdot d\vec{\boldsymbol{\gamma}}.$$

Compute the work given the following

$$\vec{F}(x, y, z) = \begin{pmatrix} x^2 \\ y \\ \sqrt{z} \end{pmatrix}$$
 and  $\vec{\gamma}(t) = \begin{pmatrix} t \\ t^2 \\ t^3 \end{pmatrix}$ .

**Problem 5.** Note that the identity  $\vec{\nabla} \times (\vec{\nabla} f) = \vec{0}$  always holds for any smooth scalar field f.

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- Pick a few functions f(x,y) of your own and plot the graphs z=f(x,y) and plot the vector field  $\vec{\nabla} f$  as well. Can you reason why the identity must be true from these plots?
- If you plot the vector field  $\vec{V} = \begin{pmatrix} 0 \\ x \end{pmatrix}$  (which has nonzero curl), could this have come from the gradient of some function? What would the surface have to look like in order to have this as a gradient? Could it even be a valid function/surface?

**Problem 6.** Decide whether the following fields have potentials. Explain your reasoning. If they do have a potential, determine what it is. Plot the vector fields as well.

(a) 
$$\vec{U}(x, y, z) = \begin{pmatrix} 2x + 2y + 2z \\ 2x + 2y + 2z \\ 2x + 2y + 2z \end{pmatrix}$$
.

(b) 
$$\vec{\boldsymbol{V}}(x,y,z) = \begin{pmatrix} yz \\ xz \\ xy \end{pmatrix}$$
.

(c) 
$$\vec{\boldsymbol{W}}(x,y,z) = \begin{pmatrix} e^y \\ e^x \\ \sin(x)\sin(y) \end{pmatrix}$$
.

**Problem 7.** Consider the vector fields in Problem 6.

(a) Take the curves  $\vec{\gamma}_1(t) = \begin{pmatrix} t \\ t \\ t \end{pmatrix}$  and  $\vec{\gamma}_2(t) = \begin{pmatrix} t \\ t^2 \\ t^3 \end{pmatrix}$  from time t = 0 to time t = 1 and integrate  $\int_{\vec{r}_i} \vec{F} \cdot d\vec{\gamma}_i.$ 

for the given vector fields.

- (b) For which fields should this integral <u>not</u> depend on the choice of curve? In other words, which of the vector fields are conservative?
- (c) Compute

$$\int_{\vec{\boldsymbol{\gamma}}_2} (\vec{\boldsymbol{\nabla}} \times \vec{\boldsymbol{W}}) \cdot d\vec{\boldsymbol{\gamma}}_2.$$

(d) Compute

$$\int_{\vec{\gamma}_1} (\vec{\nabla} \cdot \vec{U})(\vec{\gamma}) d\vec{\gamma}_1.$$

**Problem 8.** Consider the vector field  $\vec{\boldsymbol{V}}(x,y,z) = \begin{pmatrix} yz\cos(xyz) \\ xz\cos(xyz) \\ xy\cos(xyz) \end{pmatrix}$ .

- (a) Show that  $\vec{\boldsymbol{V}}$  is conservative.
- (b) Find the potential function f for  $\vec{V}$ .
- (c) Let  $\gamma(t) = \begin{pmatrix} 0 \\ 0 \\ t \end{pmatrix}$  running from  $t_0 = 0$  to  $t_1 = 1$ . Show that

$$\int_{\vec{\gamma}} \vec{V} \cdot d\vec{\gamma} = f(\vec{\gamma}(t_1)) - f(\vec{\gamma}(t_0)).$$

(d) If you knew (c) was true, does this prove that  $\vec{\boldsymbol{V}}$  is conservative? Why or why not?

**Problem 9.** \*\*\* Given a conservative vector field  $\vec{V}$  and a curve  $\vec{\gamma}: [t_0, t_1] \to \mathbb{R}^3$ , we know that

$$\int_{\vec{\gamma}} \vec{V} \cdot d\vec{\gamma},$$

only depends on the start and end points of the curve  $\vec{\gamma}$ . That is, if we fix  $\vec{\gamma}(a)$  and  $\vec{\gamma}(b)$ , the path between those two points does <u>not</u> change the integral.

If  $\vec{V}$  is conservative, then  $\vec{V} = \vec{\nabla} f$  for some scalar field f. This yields the identity,

$$\int_{\vec{\gamma}} (\vec{\nabla} f) \cdot d\vec{\gamma} = f(\vec{\gamma}(t_1)) - f(\vec{\gamma}(t_0)). \tag{1}$$

This is, once again, some type of generalization of the Fundamental Theorem of Calculus (FTC) via the very general Stokes' theorem.

- (a) Show that the above identity in Equation (1) is nothing but FTC. Hint: take your (1-dimensional) curve  $\vec{\gamma}(x) = x$  so that  $\vec{\gamma}(t_0) = t_0$  and  $\vec{\gamma}(t_1) = t_1$ . Finally, note  $\vec{\nabla} = \frac{d}{dx}$ .
- (b) Consider now a different curve  $\vec{\eta}$ :  $[\tilde{t_0}, \tilde{t_1}] \to \mathbb{R}$ . So long as  $\vec{\eta}(\tilde{t_0}) = t_0$  and  $\vec{\eta}(\tilde{t_1}) = t_1$ , our identity states that the integral should output the same value. Realize this as the u-substitution (or change of variables) that you learned in Calc. 1.
- (c) Now, in 3-dimensions, we can discretize any curve to n small movements in the x-, y-, or z-direction, and in each direction FTC will hold. Thus, summing up the n integrals (one from each movement) will cancel off many contributions and leave you only with the beginning and end point of the whole curve as a contribution. Taking the limit that these movements are dx, dy, and dz, one can see that a choice of path for a smooth curve will not matter. Draw a picture of this argument and clarify the approach to a proof.