```
import RPi.GPIO as GPIO     # Importing RPi library to use the GPIO pins
import time
EN1 = 25          # Initializing the GPIO pin 25 for the enable 1
IN1 = 26          # Initializing the GPIO pin 26 for input 1 of the motor driver
IN2 = 27          # Initializing the GPIO pin 27 for input 2 of the motor driver

GPIO.setmode(GPIO.BCM)         # We are using the BCM pin numbering

GPIO.setup(EN1,GPIO.OUT)       ## Declaring as EN1 output pin
GPIO.setup(IN1,GPIO.OUT)       ## Declaring as IN1 output pin
GPIO.setup(IN2, GPIO.OUT)      ## Declaring as IN2 output pin



#clear GPIOs
def destroy():
   GPIO.output(25, False)
   GPIO.output(26, False)
   GPIO.output(27, False)
   GPIO.cleanup()

def Clockwise():
   GPIO.output(25, True)
   GPIO.output(26, True)
   GPIO.output(27, False)

def AntiClockwise():
   GPIO.output(25, True)
   GPIO.output(26, False)
   GPIO.output(27, True)
```

```
def Stop():
    GPIO.output(25, False)
    GPIO.output(26, False)
    GPIO.output(27, False)

if __name__ == '__main__':     # Program start from here
    try:
        while True:             # Loop will run forever
            Clockwise()
            time.sleep(2)
            Stop()
            time.sleep(1)
            AntiClockwise()
            time.sleep(2)
            Stop()
            time.sleep(1)


    # If keyboard Interrupt (CTRL-C) is pressed
    except KeyboardInterrupt:

        destroy()
```