

okapi::ControllerInput< double >



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graph BT; IntegratedEncoder[okapi::IntegratedEncoder] --> ContinuousRotarySensor[okapi::ContinuousRotarySensor]; ContinuousRotarySensor --> RotarySensor[okapi::RotarySensor]; RotarySensor --> ControllerInput[okapi::ControllerInput< double >];
```

okapi::RotarySensor

okapi::ContinuousRotarySensor

okapi::IntegratedEncoder