

okapi::ControllerInput< double >

```
graph BT; A[okapi::IntegratedEncoder] --> B[okapi::ContinuousRotarySensor]; B --> C[okapi::RotarySensor]; C --> D[okapi::ControllerInput< double >];
```

okapi::RotarySensor

okapi::ContinuousRotarySensor

okapi::IntegratedEncoder