

okapi::ControllerInput< double >

```
graph BT; ADIGyro[okapi::ADIGyro] --> ContinuousRotarySensor[okapi::ContinuousRotarySensor]; ContinuousRotarySensor --> RotarySensor[okapi::RotarySensor]; RotarySensor --> ControllerInput[okapi::ControllerInput< double >];
```

okapi::RotarySensor

okapi::ContinuousRotarySensor

okapi::ADIGyro