Mar 5, 2018 CSC263 Monday Lecture: Graphs Appendix B4 \* Graph G=(V, E), V= set of refrices, E: set of edges · directed: <u,v> + <v,v> / from a to b · undirected: (v, v) == (v, v) // petween a and b adjacency list: slot for every node, stores a linked list of the neighbours of that node (mordered) · directed: only stone is node stones pointer to other node size = n+m · undirected: store neighbours in both, size = n+2m · size O(n+m), where n=|V|, m=|E|adjacency matrix: nxm, stores 1 it edge between row/col'nodes to check if edge present, check slot either I or O checking for edge done in constant time takes up more space, more efficient OPS than list · Graph Exploration · starting nude, traverse edges, discover new nudes · can discover: cycles, length of paths, etc. · Breadth - First Search o colour[v] = W: mdiscovered nector storing state of nodes in process = G: discovered, unexplored = B: discovered, explored ) @ Panent[V] = U : "node v discovered v" · discovery path: S > U, - U = ... - U - V · D[v] = D[u] + 1: length of discovery path O first discovered, first explored: as you discover nodes, tim them over and put them on the "to explore" FIFO queue

