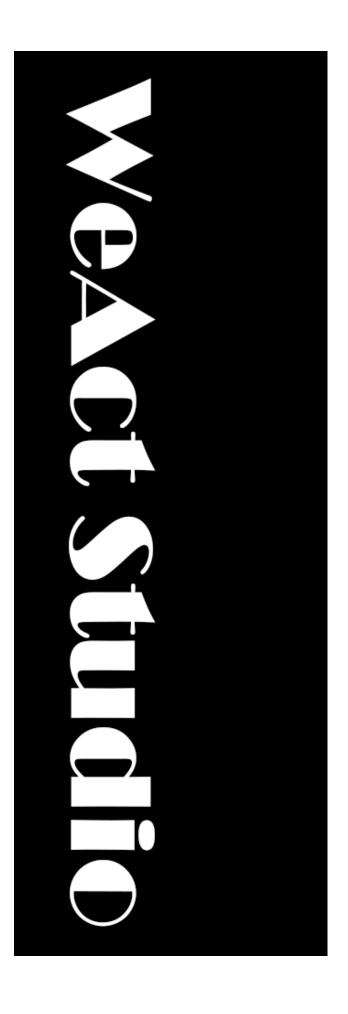


# WeAct Studio

# NANO&XAVIER TX2 NX CB

Manual



# Catalog

Rev	vision History	3
1.	Parameters	4
2.	Application scenario	6
3.	Hardware	7
4.	Hardware resource diagram	8
5.	Hardware parameters	9
6.	Electrical characteristics	10
7.	Size	11



#### **REVISION HISTORY**

Draft Date	Revision	Description	Hardware
2021.9.20	V1.0	1. Initial	A5



#### 1. PARAMETERS

- > This product is the carrier of NVIDIA Jetson nano & xaviernx & tx2nx series core board;
- > The power on sequence of the full page power supply is designed in strict accordance with NVIDIA recommendations, with discharge circuit;
- > Support DC xt30 (7-26v) [support 6S battery] and USB power supply, more power supply options;
- > The power inlet is equipped with undervoltage, overvoltage, overcurrent and anti reverse connection protection, which makes it more safe to use;
- > Support one Gigabit adaptive network port for network debugging, data communication, etc;
- > Support 2-way USB3.0 for data transmission, output by usb3.1 hub and share usb3.1 bandwidth;
- > Support 3 channels of USB2.0, of which 1 channel of OTG is used for system burning and data transmission, and the other 2 channels are host for data transmission;
- > Support 1 channel HDMI (1080p) for screen display;
- Support 1-way mircosd card for external TF card and data storage (not supported by nano SD version);
- > Support 1-channel can, 2-channel UART, 2-channel IO and other interfaces to provide more convenient data transmission;
- > Support 1-way minipcie interface, which can be connected to wireless network card or 4G network card to connect to the Internet;
- > Support 2-channel Mipi CSI camera interface, which can collect binocular camera data at the same time for binocular recognition;
- You can choose to press the button to start or power on automatically to meet more application scenarios;



- All interfaces are equipped with ESD protection to prevent damage to the carrier plate caused by static electricity;
- > The small carrier plate has compact structure, and the size is only 60mm \* 90mm;
- Regularly update the device trees of different versions to be compatible with different Tegra kernel versions;

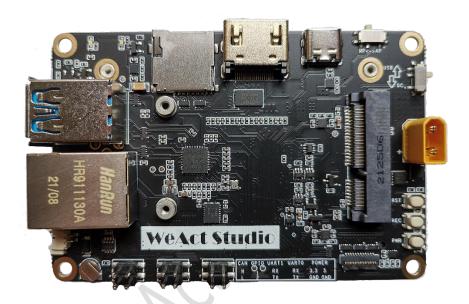


Figure 1 Carrier Board Top



Figure 2 Carrier Board Bottom

#### 2. APPLICATION SCENARIO

- √ Deep Learning
- √ Machine Vision
- √ Laboratory
- √ Robot Competition
- √ UAV
- √ Driverless
- √ AGV Navigation

#### 3. HARDWARE

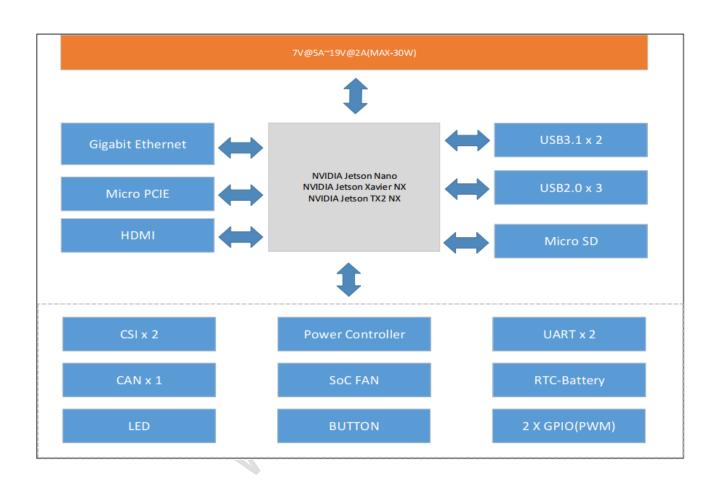


Figure 3 Carrier Board Hardware

#### 4. HARDWARE RESOURCE DIAGRAM

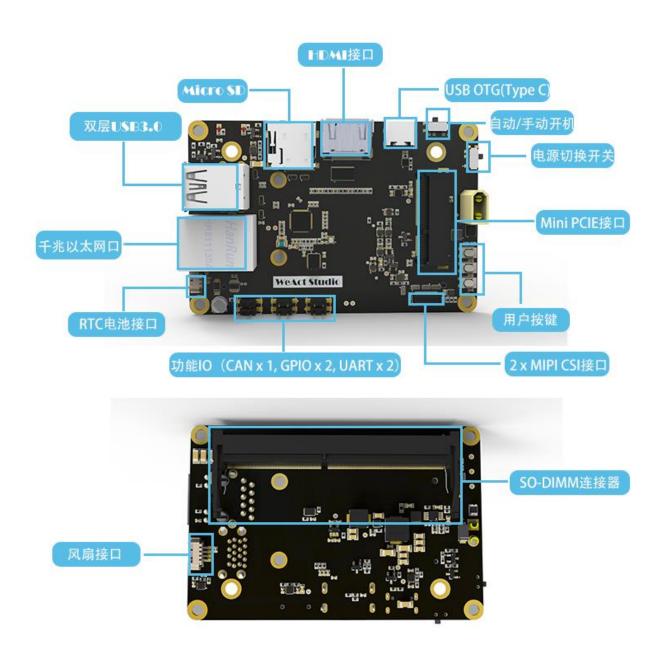


Figure 4

## 5. HARDWARE PARAMETERS

KEY	1 x power on button		
	1 x Recovery button		
	1 x Reset button		
LED	1 x power LED(Red )		
	1 x system status		
	LED(Green)		
SD	1 x Mirco SD		
USB	1 x USB3.0*2 Double		
	1 x USB2,0 OTG TypeC		
	2 x USB2.0 HOST		
CSI	2 x MIPI CSI		
PCIE	1 x Mini PCIE		
HDMI	HDMI Type-A		
Ethernet	1 x 1000M RJ45		
CAN	1, 1 x 2P HDR		
UART	2, 2 x 2P HDR		
GPIO	2, 1 x 2P HDR		
FAN	1 x TX1.25		
Auto Power On	1 x Switch		
POWER	1 x XT30		
	1 x Switch		
RTC	1 x SuperCap		
	1 x RTC		

# 6. ELECTRICAL CHARACTERISTICS

	Min	Typical	Max
Temperature	0℃	/	70°C
Voltage	7V	12V	27V

## 7. SIZE

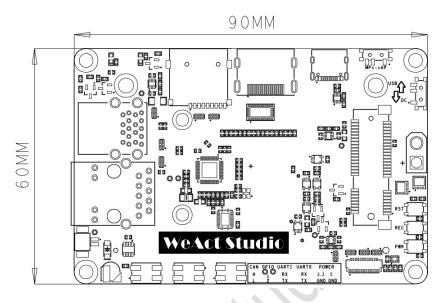


Figure 6 Top

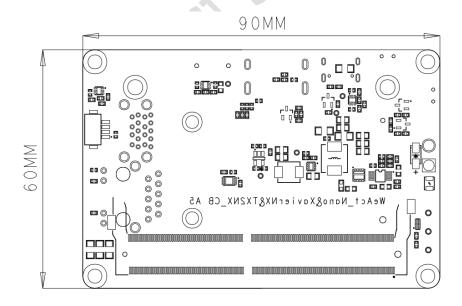


Figure 7 Bottom