Calculus Notes

Avid David

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Part I

Integral Calculus in One Variable

1 Indefinite Integrals

1.1 Integral of a function

The integral is the inverse of the derivative operator. Given a function f(x), we can find a function F(x) such that F'(x) = f(x). The integral of a function is not unique, as for each f(x), F(x) + C is also an integral of that function.

Concept

Both the derivative and the integral are linear operators, so we have:

$$\int [\alpha f(x) + \beta g(x)] dx = \alpha \int f(x) dx + \beta \int g(x) dx$$

1.2 Ways to calculate indefinite integrals

Expansion

We use the linearity rule to turn a complicated integral into the sum of many simpler ones, then calculate one by one.

Changing the differential expression (u-substitution)

If $\int f(x)dx = F(x) + C$ then $\int f(u)dx = F(u) + C$, where u = u(x) is a continuously differentiable function. Then, we can change the integrand g(x)dx into:

$$g(x) = f(u(x))u'(x)dx$$

Then the integral turns into:

$$\int g(x)dx = \int f(u(x))u'(x)dx = \int f(u(x))du = F(u) + C$$

Insight

In the simple case u = ax + b, we have du = adx. Then if $\int f(x)dx = F(x) + C$ then:

$$\int f(ax+b)dx = \frac{1}{a}F(ax+b) + C$$

Change of variables

Consider the integral $I = \int f(x)dx$, where f(x) is a continuous function. We can change f(x) such that we work with functions with known or easier antiderivatives:

1. Change of variables type 1:

Let $x = \varphi(t)$, where $\varphi(t)$ is a monotonic and continuously differentiable function. Then:

$$I = \int f(x) dx = \int f[\varphi(t)] \varphi'(t) dt$$

Denote the antiderivative of $g(t) = f[\varphi(t)]\varphi'(t)$ as G(t) and h(x) as the inverse of $x = \varphi(t)$, we then have:

$$\int g(t)dt = G(t) + C \Rightarrow I = G[h(x)] + C$$

2. Change of variables type 2:

Let $t = \psi(x)$, where $\psi(x)$ is a continuously differentiable function and we can write $f(x) = g[\psi(x)]\psi'(x)$. Then:

$$I = \int f(x) dx = \int g[\psi(x)] \psi'(x) dx$$

Denote the antiderivative of g(t) as G(t), then:

$$I = G[\psi(x)] + C$$

Important

Remember to change back to the original variable!

Integration by parts

Let u = u(x) and v = v(x) be continuously differentiable functions. We know:

$$d(uv) = udv + vdu \Rightarrow \int d(uv) = \int udv + vdu$$

Then we have the following formula:

$$\int u \mathrm{d}v = uv - \int v \mathrm{d}u$$

Consider the integral $I = \int f(x) dx$ We need to express:

$$f(x)dx = [g(x)h(x)]dx = g(x)[h(x)dx] = udv$$

then applie the integration by parts formula to u = g(x), v = h(x)dx

1.3 Integral of rational functions

A rational function is one with the form $f(x) = \frac{P(x)}{Q(x)}$, where P(x) and Q(x) are polynomials in x. If $\deg P(x) < \deg Q(x)$ then it's called a true rational function.

Using polynomial division, we can rewrite any rational function:

$$f(x) = H(x) + \frac{r(x)}{Q(x)}$$

The integral of H(x) can easily be computed. As for the true rational function $\frac{r(x)}{Q(x)}$, we will use partial fractions to decompose it into four simpler types of functions. First, using the method of Undetermined Coefficients, we can write Q(x) as the product of linear polynomials and quadratic polynomials with no real roots:

$$Q(x) = \prod_{k=1}^{n} (x - a_k)^{\alpha_k} \prod_{k=1}^{n} (x^2 + p_k x + q_k)^{\beta_k}$$

Note that this can always be achieved as per the Fundamental Theorem of Algebra. Then, we just need to compute the following four types of integrals:

Insight

1.
$$\int \frac{A}{x-a} dx$$

$$2. \int \frac{A}{(x-a)^k} \mathrm{d}x \quad (k \ge 2)$$

$$3. \int \frac{Mx + N}{x^2 + px + q} \mathrm{d}x$$

4.
$$\int \frac{Mx+N}{(x^2+px+q)^m} dx \quad (m \ge 2)$$

These integrals cover all cases because any partial fraction decomposition over \mathbb{R} involves repeated linear factors and irreducible quadratic factors, possibly raised to powers. The first two ones are simple:

1.
$$\int \frac{A}{x-a} dx = A \ln|x-a| + C$$

2.
$$\int \frac{A}{(x-a)^k} dx = A \int (x-a)^{-k} = \frac{-A}{(k-1)(x-a)^{k-1}} \quad (k \ge 2)$$

The third one is a bit more complicated: we need to use a clever substitution, inspired by completing the square, to bring it back to familiar forms:

Let
$$a = \sqrt{q - \frac{p^2}{4}}$$
 and $t = x + \frac{p}{2}$, the integral becomes:

$$\int \frac{Mx + N}{x^2 + px + q} dx = \int \frac{Mt + (N - \frac{Mp}{2})}{t^2 + a^2} dt$$
$$= M \int \frac{t}{t^2 + a^2} dt + \left(N - \frac{Mp}{2}\right) \int \frac{1}{t^2 + a^2} dt$$

For the first integral, substitute in $u=t^2$ and we have a logarithm. For the second one, divide both the numerator and the denominator by a^2 then substitute $u=\frac{t}{a}$, we yield the inverse tangent. Then the integral is simply:

$$\int \frac{Mx+N}{x^2+px+q} dx = \frac{M}{2} \ln(x^2+px+q) + \frac{2N-Mp}{\sqrt{4q-p^2}} \arctan \frac{2x+p}{\sqrt{4q-p^2}} + C$$