Calculus

Avid David

August 10, 2025

Contents

Ι	Int	tegral Calculus in One Variable	2	
1	Inde	definite Integrals		
	1.1	Integral of a function	2	
	1.2	Ways to calculate indefinite integrals	2	
	1.3	Integral of rational functions	4	
	1.4	Integral of trigonometric functions		
	1.5	Integral of irrational expressions		
2	Def	inite Integrals	8	
	2.1	Definition	8	
	2.2	Riemann Integrability	Ĝ	
	2.3	Properties of the Definite Integral	Ĝ	
	2.4	Integral Functions		
	2.5	Ways to Calculate Definite Integrals	11	
	2.6	Important Results	12	
3	Imp	proper Integrals	13	
	3.1	Improper Integrals with infinite endpoints	13	
	3.2	Improper Integrals of Unbounded functions	14	
	3.3	Convergence Criteria	14	

Part I

Integral Calculus in One Variable

1 Indefinite Integrals

1.1 Integral of a function

The integral is the inverse of the derivative operator. Given a function f(x), we can find a function F(x) such that F'(x) = f(x). The integral of a function is not unique, as for each f(x), F(x) + C is also an integral of that function.

Concept

Both the derivative and the integral are linear operators, so we have:

$$\int [\alpha f(x) + \beta g(x)] dx = \alpha \int f(x) dx + \beta \int g(x) dx$$

1.2 Ways to calculate indefinite integrals

1. Expansion

We use the linearity rule to turn a complicated integral into the sum of many simpler ones, then calculate one by one.

2. Changing the differential expression (u-substitution)

If $\int f(x)dx = F(x) + C$ then $\int f(u)dx = F(u) + C$, where u = u(x) is a continuously differentiable function. Then, we can change the integrand g(x)dx into:

$$g(x) = f(u(x))u'(x)dx$$

Then the integral turns into:

$$\int g(x)dx = \int f(u(x))u'(x)dx = \int f(u(x))du = F(u) + C$$

Insight

In the simple case u = ax + b, we have du = adx. Then if $\int f(x)dx = F(x) + C$ then:

$$\int f(ax+b)dx = \frac{1}{a}F(ax+b) + C$$

- 3. Change of variables Consider the integral $I = \int f(x) dx$, where f(x) is a continuous function. We can change f(x) such that we work with functions with known or easier antiderivatives:
 - (a) Change of variables type 1:

Let $x = \varphi(t)$, where $\varphi(t)$ is a monotonic and continuously differentiable function. Then:

$$I = \int f(x) dx = \int f[\varphi(t)] \varphi'(t) dt$$

Denote the antiderivative of $g(t) = f[\varphi(t)]\varphi'(t)$ as G(t) and h(x) as the inverse of $x = \varphi(t)$, we then have:

$$\int g(t)dt = G(t) + C \Rightarrow I = G[h(x)] + C$$

(b) Change of variables type 2:

Let $t = \psi(x)$, where $\psi(x)$ is a continuously differentiable function and we can write $f(x) = g[\psi(x)]\psi'(x)$. Then:

$$I = \int f(x) dx = \int g[\psi(x)] \psi'(x) dx$$

Denote the antiderivative of g(t) as G(t), then:

$$I = G[\psi(x)] + C$$

Important

Remember to change back to the original variable!

4. **Integration by parts** Let u = u(x) and v = v(x) be continuously differentiable functions. We know:

$$d(uv) = udv + vdu \Rightarrow \int d(uv) = \int udv + vdu$$

Then we have the following formula:

$$\int u \mathrm{d}v = uv - \int v \mathrm{d}u$$

Consider the integral $I = \int f(x) dx$ We need to express:

$$f(x)dx = [g(x)h(x)]dx = g(x)[h(x)dx] = udv$$

3

then apply the integration by parts formula to u = g(x), v = h(x)dx

1.3 Integral of rational functions

A rational function is one with the form $f(x) = \frac{P(x)}{Q(x)}$, where P(x) and Q(x) are polynomials in x. If $\deg P(x) < \deg Q(x)$ then it's called a true rational function.

Using polynomial division, we can rewrite any rational function:

$$f(x) = H(x) + \frac{r(x)}{Q(x)}$$

The integral of H(x) can easily be computed. As for the true rational function $\frac{r(x)}{Q(x)}$, we will use partial fractions to decompose it into four simpler types of functions. First, using the method of Undetermined Coefficients, we can write Q(x) as the product of linear polynomials and quadratic polynomials with no real roots:

$$Q(x) = \prod_{k=1}^{n} (x - a_k)^{\alpha_k} \prod_{k=1}^{n} (x^2 + p_k x + q_k)^{\beta_k}$$

Note that this can always be achieved as per the Fundamental Theorem of Algebra. Then, we just need to compute the following four types of integrals:

Insight

1.
$$\int \frac{A}{x-a} dx$$

$$2. \int \frac{A}{(x-a)^k} \mathrm{d}x \quad (k \ge 2)$$

$$3. \int \frac{Mx + N}{x^2 + px + q} \mathrm{d}x$$

4.
$$\int \frac{Mx+N}{(x^2+px+q)^m} dx \quad (m \ge 2)$$

These integrals cover all cases because any partial fraction decomposition over \mathbb{R} involves repeated linear factors and irreducible quadratic factors, possibly raised to powers. The first two ones are simple:

1.
$$\int \frac{A}{x-a} dx = A \ln|x-a| + C$$

2.
$$\int \frac{A}{(x-a)^k} dx = A \int (x-a)^{-k} = \frac{-A}{(k-1)(x-a)^{k-1}} \quad (k \ge 2)$$

The third one is a bit more complicated: we need to use a clever substitution, inspired by completing the square, to bring it back to familiar forms:

Let $a = \sqrt{q - \frac{p^2}{4}}$ and $t = x + \frac{p}{2}$, the integral becomes:

$$\int \frac{Mx + N}{x^2 + px + q} dx = \int \frac{Mt + (N - \frac{Mp}{2})}{t^2 + a^2} dt$$
$$= M \int \frac{t}{t^2 + a^2} dt + \left(N - \frac{Mp}{2}\right) \int \frac{1}{t^2 + a^2} dt$$

For the first integral, substitute in $u=t^2$ and we have a logarithm. For the second one, divide both the numerator and the denominator by a^2 then substitute $u=\frac{t}{a}$, we yield the inverse tangent. Then the integral is simply:

$$\int \frac{Mx+N}{x^2+px+q} dx = \frac{M}{2} \ln(x^2+px+q) + \frac{2N-Mp}{\sqrt{4q-p^2}} \arctan \frac{2x+p}{\sqrt{4q-p^2}} + C$$

Before moving on to solve the last integral, let's review a bit of complex numbers:

Concept

Some important (and beautiful) formulas::

Euler's Formula: $e^{ix} = \cos x + i \sin x$

De Moivre's Formula: $(\cos x + i \sin x)^n = \cos nx + i \sin nx$

We will prove it using ODEs. Let $f(x) = e^x$ and $g(x) = \cos x + i \sin x$. We know:

$$f'(x) = ie^{ix} = if(x)$$

$$g'(x) = -\sin x + i\cos x = ig(x)$$

And also the initial values:

$$f(0) = g(0) = 1$$

By uniqueness of solutions to first-order linear ODEs, Euler's formula is proven. By substituting f(nx) = g(nx), De Moivre's formula is proven. Then we have:

Insight

- $\cos x = \Re(e^{ix}) = \frac{e^{ix} + e^{-ix}}{2}$
- $\sin x = \Im(e^{ix}) = \frac{e^{ix} + e^{-ix}}{2i}$

From this, we can derive a general formula for powers of the sine and cosine:

$$\cos^{n} x = \left(\frac{e^{ix} + e^{-ix}}{2}\right)^{n} = \frac{1}{2^{n}} \sum_{k=0}^{n} \binom{n}{k} e^{i(n-2k)x}$$

Now if we group k and n-k in pairs to get $\cos(n-2k)$, we get:

$$\cos^n x = \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos((n-2k)x)$$

Analogously, we also have:

$$\sin^n x = \frac{1}{(2i)^n} \sum_{k=0}^n \binom{n}{k} (-1)^k \cos(\frac{\pi n}{2} - (n-2k)x)$$

Now, back to the fourth integral, we first do the same thing: change variables $a = \sqrt{q - \frac{p^2}{4}}$ and $t = x + \frac{p}{2}$. This yields:

$$\int \frac{Mx+N}{(x^2+px+q)^m} dt = \int \frac{Mt+(N-\frac{Mp}{2})}{(t^2+a^2)^m} dt$$
$$=M \int \frac{t}{(t^2+a^2)^m} dt + \left(N-\frac{Mp}{2}\right) \int \frac{1}{(t^2+a^2)^m} dt$$

Again, to compute the first integral, we use the substitution $u=t^2$. Then it is:

$$M \int \frac{t}{(t^2 + a^2)^m} dt = \frac{-M}{2(m-1)(t^2 + a^2)^{m-1}} + C$$

For the second integral however, this time we need a different substitution. Let $t = a \tan z$. Then: $t^2 + a^2 = a^2 \sec^2 z$, and $dt = a \sec^2 dz$. Then the integral turns into:

$$\int \frac{1}{(t^2 + a^2)^m} dt = a^{2m-1} \int \cos^{2m-2} z dz$$

Let $I(z) = \int \cos^{2m-2} z dz$ and now, we can take advantage of the linearity rule and the formula for powers of cosine we just derived. The integral turns into:

$$I(z) = \int \frac{1}{2^{2m-2}} \sum_{k=0}^{2m-2} {2m-2 \choose k} \cos(2(m-k-1)z) dz$$

$$= \frac{1}{2^{2m-2}} \sum_{k=0}^{2m-2} {2m-2 \choose k} \frac{1}{2m-2-2k} \sin(2(m-k-1)z) + C$$

$$= \frac{1}{2^{2m-2}} \left[{2m-2 \choose m-1} z + \sum_{k=0, k \neq m-1}^{2m-2} {2m-2 \choose k} \frac{1}{2m-2-2k} \sin(2(m-k-1)z) \right] + C$$

Then the integral, as a whole, evaluates to:

$$\int \frac{Mx+N}{(x^2+px+q)^m} dx = \frac{-M}{2(m-1)(x^2+px+q)^{m-1}} + \left(N - \frac{Mp}{2}\right) \left(\sqrt{q - \frac{p^2}{4}}\right)^{2m-1} \cdot I(z) + C$$

1.4 Integral of trigonometric functions

1. The general method

Consider the integral $\int f(\sin x, \cos x) dx$, where the integrand is a rational function in terms of $\sin x$ and $\cos x$. We can use the "universal trigonometric substitution" $x = \tan \frac{t}{2}$. Then:

$$\sin x = \frac{2t}{1+t^2}; \quad \cos x = \frac{1-t^2}{1+t^2}; \quad \tan x = \frac{2t}{1-t^2}; dt = \frac{2dt}{1+t^2}$$

The integrand turns into a rational function in terms of t.

2. Integrals of the form $\int \sin^m x \cos^n x dx$, where m, n are positive integers

- If m is odd, we let $t = \cos x$
- If n is odd, we let $t = \sin x$
- If both m and n are even, we use power-reduction formulae:

$$\sin^2 x = \frac{1 - \cos 2x}{2};$$
 $\cos^2 x = \frac{1 + \cos 2x}{2}$

Then we'll have a similar integral with the form $\int \sin^k 2x \cos^l 2x dx$

3. Special forms of $\int f(\sin x, \cos x) dx$

- Let $t = \cos x$ if $f(-\sin x, \cos x) = -f(\sin x, \cos x)$
- Let $t = \sin x$ if $f(\sin x, -\cos x) = -f(\sin x, \cos x)$
- Let $t = \tan x$ if $f(-\sin x, -\cos x) = f(\sin x, \cos x)$

1.5 Integral of irrational expressions

There are two main ways to solve these integrals: using trigonometric substitution, and using the Euler substitution. The trig-sub is very intuitive, but the Euler substitution is also very nice:

Concept

Let $t = x + \sqrt{x^2 + a}$ for the integral $\int f(x, \sqrt{x^2 + a}) dx$. Then:

$$dt = 1 + \frac{x}{\sqrt{x^2 + a}} dx = \frac{x + \sqrt{x^2 + a}}{\sqrt{x^2 + a}} dx \Rightarrow \frac{dt}{t} = \frac{dx}{\sqrt{x^2 + a}}$$

7

Important

A special integral:

$$I = \int \frac{\mathrm{d}x}{\sqrt[n]{x} - 1}$$

Let $u = \sqrt[n]{x}$. Then $dx = nu^{n-1}du$

$$I = n \int \frac{u^{n-1}}{u-1} du$$

$$= n \int \frac{u^{n-1} - 1}{u-1} + \frac{1}{u-1} du$$

$$= n \int \sum_{k=0}^{n-2} u^k + \frac{1}{u-1} du$$

$$= n \left(\sum_{k=1}^{n-1} \frac{u^k}{k} + \ln|u-1| \right) + C$$

$$= n \left(\sum_{k=1}^{n-1} \frac{\sqrt[n]{x^k}}{k} + \ln|\sqrt[n]{x} - 1| \right) + C$$

2 Definite Integrals

2.1 Definition

Say f(x) is defined and bounded on [a, b]. Partition [a, b] into n subintervals $[x_i, x_{i+1}]$ where $a = x_0 < x_1 < \ldots < x_n = b$. In each interval $[x_i, x_{i+1}]$, we choose a point $\xi \in [x_i, x_{i+1}]$ and form the expression

$$S_n = \sum_{i=0}^{n-1} f(\xi_i) \Delta x_i$$

where $\Delta x_i = x_{i+1} - x_i$. Here, S_n is the Riemann sum. Denote $\lambda = \max_{1 \le i \le n} \Delta x_i$. If there exists the limit $I = \lim_{\lambda \to 0} S_n$ that doesn't depend on how we partition [a, b] and how we choose ξ_i then I is called the definite integral of the function f(x) on [a, b], denoted $\int_a^b f(x) dx$. Then we say f(x) is integrable on [a, b].

We then have defined the definite integral for all a < b. We can then define, if b < a, $\int_a^b f(x) dx = -\int_b^a f(x) dx \text{ and when } a = b, \int_a^b f(x) dx = 0.$

2.2 Riemann Integrability

The sufficient and necessary condition for a bounded function f(x) to be integrable on [a, b] is $\lim_{\lambda \to 0} (S - s) = 0$, where:

$$S = \sum_{i=1}^{n+1} M_i \Delta x_i$$

$$S = \sum_{i=1}^{n+1} m_i \Delta x_i$$

$$M_i = \sup_{x \in [x_i, x_{i+1}]} f(x)$$

$$m_i = \inf_{x \in [x_i, x_{i+1}]} f(x)$$

From there, we have a few crucial theorems:

Concept

- If f(x) is continuous on [a, b] then it is integrable on [a, b].
- If f(x) is bounded on [a, b] and has discontinuities on [a, b] then it is integrable on [a, b]
- If f(x) is bounded and monotonic on [a, b] then it is integrable on [a, b]

2.3 Properties of the Definite Integral

1. Property 1 (Linearity:)

$$\int_{a}^{b} [\alpha f(x) + \beta g(x)] dx = \alpha \int_{a}^{b} f(x) dx + \beta \int_{a}^{b} g(x) dx$$

2. **Property 2:** Given three closed intervals [a, b], [b, c], [a, c], if f(x) is integrable on the longest interval then it is also integrable on the other two integrals, and:

$$\int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{c}^{b} f(x) dx$$

3. Property 3: Suppose a < b. Then:

(a) If
$$f(x) \ge 0 \ \forall \ x \in [a, b]$$
 then $\int_a^b f(x) dx \ge 0$

(b) If
$$f(x) \ge g(x) \ \forall \ x \in [a, b]$$
 then $\int_a^b f(x) dx \ge \int_a^b g(x) dx$

(c) If f(x) is integrable on [a, b] then |f(x)| is integrable on [a, b] and:

9

$$\left| \int_{a}^{b} f(x) dx \right| \le \int_{a}^{b} |f(x)| dx$$

(d) If $m \le f(x) \le M \ \forall \ x \in [a, b]$ then:

$$m(b-a) \le \int_a^b f(x) dx \le M(b-a)$$

4. Property 4 (First Mean Value Theorem):

Suppose f(x) is integrable on [a,b] and $m \leq f(x) \leq M \ \forall \ x \in [a,b]$, then there exists μ such that:

$$\int_{a}^{b} f(x) dx = \mu(b - a), \qquad m < \mu < M$$

If f(x) is continuous on [a, b] then there exists $c \in [a, b]$ such that:

$$\int_{a}^{b} f(x) dx = f(c)(b-a)$$

- 5. Property 5 (Second Mean Value Theorem): If we have these three conditions:
 - (a) f(x) and f(x)g(x) are integrable on [a,b]
 - (b) $m \le f(x) \le M \ \forall \ x \in [a, b]$
 - (c) g(x) does not change signs on [a, b]

Then there exists μ such that:

$$\int_{a}^{b} f(x)g(x)dx = \mu \int_{a}^{b} g(x)dx, \qquad m < \mu < M$$

If f(x) is continuous on [a, b] then there exists $c \in [a, b]$ such that:

$$\int_{a}^{b} f(x)g(x)dx = f(c) \int_{a}^{b} g(x)dx$$

2.4 Integral Functions

Suppose f(x) is an integrable function on [a,b], then for all $x \in [a,b]$, f is also integrable on [a,x]. We can then define the function $F(x) = \int_a^x f(t) dt$. We then have some very important foundational theorems:

Concept

- If f(x) is integrable on [a, b] then F(x) is continuous on [a, b]
- If f is continuous at $x_0 \in [a, b]$ then F(x) is differentiable at x_0 and

$$F'(x_0) = f(x_0)$$

• If f(x) is continuous on the closed interval [a,b] and F(x) is an integral of f(x) then:

$$\int_{a}^{b} f(x) dx = F(b) - F(a)$$

2.5 Ways to Calculate Definite Integrals

1. Integration by parts:

Suppose u(x), v(x) are continuously differentiable functions on [a, b]. Then:

$$\int_{a}^{b} u \, dv = uv \bigg|_{a}^{b} - \int_{a}^{b} v \, du$$

2. Change of variables:

(a) Substitute $x = \varphi(t)$

Consider $I = \int_a^b f(x) dx$ with f(x) being continuous on [a, b]. Substitute $x = \varphi(t)$ with the following three conditions:

- $\varphi(t)$ is has a continuous derivative on [a, b]
- $\varphi(a) = \alpha$; $\varphi(b) = \beta$
- When t changes from α to β in $[\alpha, \beta]$ then $x = \varphi(t)$ continuously changes from a to b

Then we have the following formula:

$$\int_{a}^{b} f(x) dx = \int_{\alpha}^{\beta} f[\varphi(t)] \varphi'(t) dt$$

(b) Substitute $t = \varphi(x)$

Suppose the integral we are trying to solve has the form $I = \int_a^b f[\varphi(x)]\varphi'(x)dx$, where $\varphi(x)$ is monotonic and is continuously differentiable on [a,b]. Then:

$$\int_{a}^{b} f[\varphi(x)]\varphi'(x)dx = \int_{\varphi(a)}^{\varphi(b)} f(t)dt$$

3. Recursion or Induction

We can look at an example. Calculate:

$$I_n = \int_0^{\frac{\pi}{2}} \cos^n x \cos nx dx$$

We use integration by parts: Let $u = \cos^n x$ and $dv = \cos nx dx$. Then $v = \frac{1}{n} \sin nx$. Applying the integration by parts formula, we have:

$$I_n = \frac{1}{n} \int_0^{\frac{\pi}{2}} \cos^n x \cos nx dx$$

$$= \frac{1}{n} \cos^n x \sin nx \Big|_0^{\frac{\pi}{2}} + \frac{1}{n} \int_0^{\frac{\pi}{2}} n \cos^{n-1} x \sin x \sin nx dx$$

$$= \int_0^{\frac{\pi}{2}} \cos^{n-1} x \sin x \sin nx dx$$

Then we see:

$$2I_n = \int_0^{\frac{\pi}{2}} \cos^n x \cos nx dx + \int_0^{\frac{\pi}{2}} \cos^{n-1} x \sin x \sin nx dx$$
$$= \int_0^{\frac{\pi}{2}} \cos^{n-1} x (\cos x \cos nx + \sin x \sin nx) dx$$
$$= \int_0^{\frac{\pi}{2}} \cos^{n-1} x \cos(n-1)x dx$$
$$= I_{n-1}$$

It's easy to compute $I_0 = \frac{\pi}{2}$. Then this is a geometric series, and $I_n = \frac{\pi}{2^{n+1}}$.

2.6 Important Results

1. The Fundamental Theorem of Calculus

$$\frac{\mathrm{d}y}{\mathrm{d}x} \int_{a}^{x} f(t) \mathrm{d}t = f(x)$$

And more generally:

$$\frac{\mathrm{d}y}{\mathrm{d}x} \int_{a}^{g(x)} f(t) \mathrm{d}t = f(g(x))g'(x)$$

2. Riemann Sum

Recall the formula from earlier:

$$S_n = \sum_{i=0}^{n-1} f(\xi_i) \Delta x_i \qquad \Delta x_i \in [x_i, x_{i+1}]$$

If we partition [a, b] into n subintervals with equal length using $a = x_0 < x_1 < \ldots < x_n = b$, where $x_i = a + (b - a)\frac{i}{n}$ then:

$$S_n = \frac{b-a}{n} \sum_{i=0}^{n-1} f(\xi_i) \qquad \xi_i \in [x_i, x_{i+1}]$$

If f(x) is integrable on [a, b] and choosing $\xi_i = x_i$, we have the left and right sums:

Important

Choosing $\xi_i = x_i$ yields:

$$\lim_{n \to \infty} \frac{b - a}{n} \left[\sum_{i=0}^{n-1} f\left(a + \frac{b - a}{n}i\right) \right] = \int_a^b f(x) dx$$

Choosing $\xi_i = x_{i+1}$ yields:

$$\lim_{n \to \infty} \frac{b - a}{n} \left[\sum_{i=1}^{n} f\left(a + \frac{b - a}{n}i\right) \right] = \int_{a}^{b} f(x) dx$$

3. Integral Equalities

•
$$\int_{a}^{b} f(x) dx = \int_{a}^{b} f(a+b-x) dx$$

$$\bullet \int_{-a}^{a} \frac{f(x)}{1+b^{x}} dx = \int_{0}^{a} f(x) dx$$

4. Integral Inequalities

Important

Cauchy-Schwarz Inequality:

$$\left(\int_{a}^{b} f(x)g(x)dx\right)^{2} \le \left(\int_{a}^{b} f^{2}(x)dx\right)\left(\int_{a}^{b} g^{2}(x)dx\right)$$

3 Improper Integrals

3.1 Improper Integrals with infinite endpoints

Suppose f(x) is defined on the interval $[a, +\infty)$ and integrable on every closed intervals [a, A], then:

Concept

Definition: The limit of the integral $\int_a^A f(x) dx$ as $A \to +\infty$ is called an improper integral of the function f(x) on $[a, +\infty)$ and is denoted by:

$$\int_{a}^{+\infty} f(x) dx = \lim_{A \to \infty} \int_{a}^{A} f(x) dx$$

If this limit exists then we say the improper integral *converges*. Conversely, if it does not exist or it is at infinity, we say it *diverges*. Analogously, we can define improper integrals from negative infinity to some value, and on the entire real line \mathbb{R} .

3.2 Improper Integrals of Unbounded functions

Suppose f(x) is defined on [a, b) and integrable on all intervals [a, t] such that t < b and $\lim_{x \to b} = \infty$. The point x = b is called a critical point of the function f(x).

Concept

Definition: The limit of the integral $\int_a^t f(x) dx$ as $t \to b^-$ is called an improper integral of the function f(x) on the interval [a,b) and is denoted by:

$$\int_{a}^{b} f(x) dx = \lim_{t \to b^{-}} \int_{a}^{t} f(x) dx$$

If this limit exists then we say the improper integral *converges*. Conversely, if it does not exist or it is at infinity, we say it *diverges*. Analogously, we can define improper integrals on (a, b] and on (a, b).

As for integrals with two critical points x = a and x = b, we can split:

$$\int_{a}^{b} f(x)dx = \int_{a}^{c} f(x)dx + \int_{c}^{b} f(x)dx$$

3.3 Convergence Criteria

Comparison criterium:

1. Given two functions f(x) and g(x) that are integrable on all finite intervals [a, A] and:

$$0 \le f(x) \le g(x)$$

Then:

(a) If
$$\int_a^{+\infty} g(x) dx$$
 converges then $\int_a^{+\infty} f(x) dx$ converges.

(b) If
$$\int_a^{+\infty} f(x) dx$$
 diverges then $\int_a^{+\infty} g(x) dx$ diverges.

2. Suppose f(x) and g(x) are functions integrable on every finite intervals [a,A] and $\lim_{x\to +\infty}\frac{f(x)}{g(x)}=k>0$. Then the integrals $\int_a^{+\infty}f(x)\mathrm{d}x$ and $\int_a^{+\infty}g(x)\mathrm{d}x$ either both converges or both diverges.

Corollaries:

Given f(x) and g(x) are two positive integrable functions on $[a, +\infty)$. Then:

1. If
$$\lim_{x \to +\infty} \frac{f(x)}{g(x)} = 0$$
 and $\int_a^{+\infty} g(x) dx$ converges then $\int_a^{+\infty} f(x) dx$ converges.

2. If
$$\lim_{x\to +\infty} \frac{f(x)}{g(x)} = +\infty$$
 and $\int_a^{+\infty} g(x) dx$ diverges then $\int_a^{+\infty} f(x) dx$ diverges.