

March 24, 2023

DSML: Computer Vision.

CNNs : Operations under the hood (continued)

Class starts
@ 9:05 pm.



What normal people see
when they walk on street



What Computer Vision
folks see



WHO WOULD WIN?



STATE OF THE ART
NEURAL NETWORK



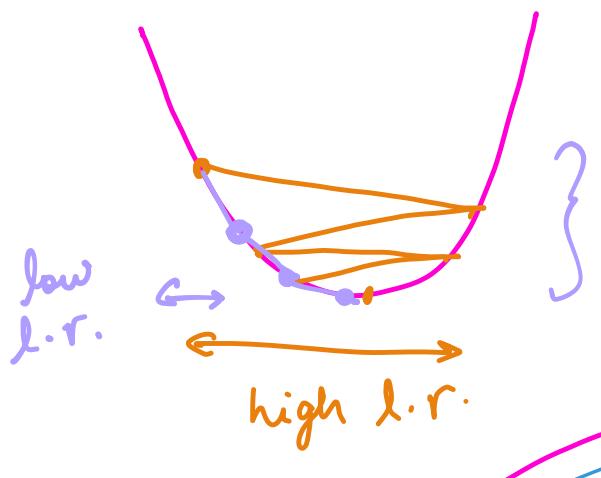
ONE NOISY BOI

Recap:

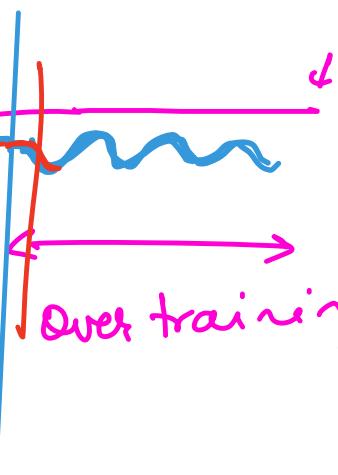
- * We trained a CNN, and observed overfitting .
- * Steps taken to deal with the problem:
 - (a) Architecture change: Reduce size of input to the Dense layers; use more blocks of conv 2D + max pooling .
 - (b) Train longer: 10 epochs were insufficient; train until validation accuracy plateaus.
 - (c) Regularization: Add batch normalization to make the model converge faster, drop-out to make it more robust .

Agenda for today:

- * Continue exploring solutions to improve accuracy:
 - (a) Learning Rate Schedule: Reduce learning rate on plateau, perform early stopping.
 - (b) L1 - L2 regularization: Prevent weights from fluctuating.
 - (c) Increase training data size through augmentation: Use crops, shifts, flips, rotate, etc.
- * Implement backpropagation for a CNN from scratch. Math + Code!!

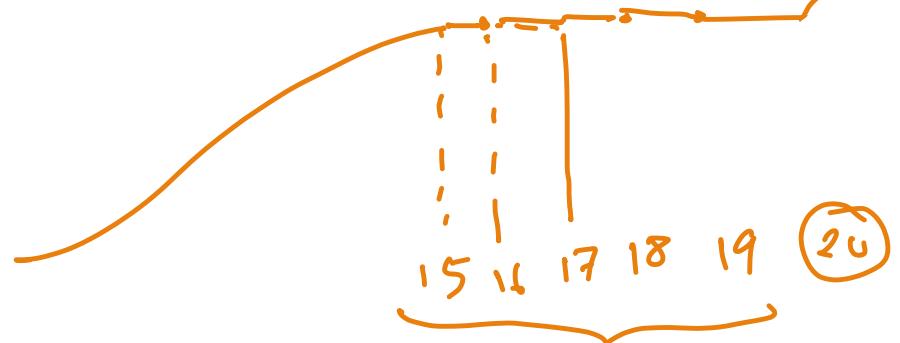


$$\frac{\text{loss}^{(t+1)}}{\text{loss}^{(t)}} \leq \delta$$

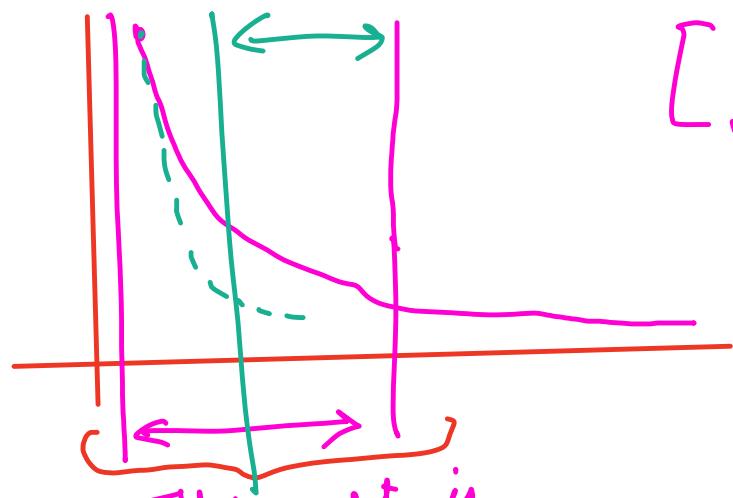


Over training / overfitting.

stop here.



if $|\text{loss}^{(t+1)} - \text{loss}^{(t)}| \leq \delta$:
 plateau + = 1
 if plateau == patience:
 → Reduce l.r.



$$[3 \cdot 2]$$

$$\frac{8 \cdot 0}{\downarrow}$$

$$[12 \cdot 1]$$

$$[2.33 e^{-3}]$$

$$\frac{1.67 e^{-4}}{12 \cdot 1 e^{-8}}$$

This part is
just to bring
the loss down.

90% of the cases,
we see that the
magnitude of our is
changing more than
the direction.

λ_1 λ_2
regularization

d	k_1	k_2	k_3
k_4	k_5	k_6	
R_7	R_8	R_9	

$\approx 10^0$

d_1

$$d' = d + \lambda \sum_{i=1}^9 |k_i|$$

≈ 98

$1 \quad 900.$

d : original loss.

d_2 :

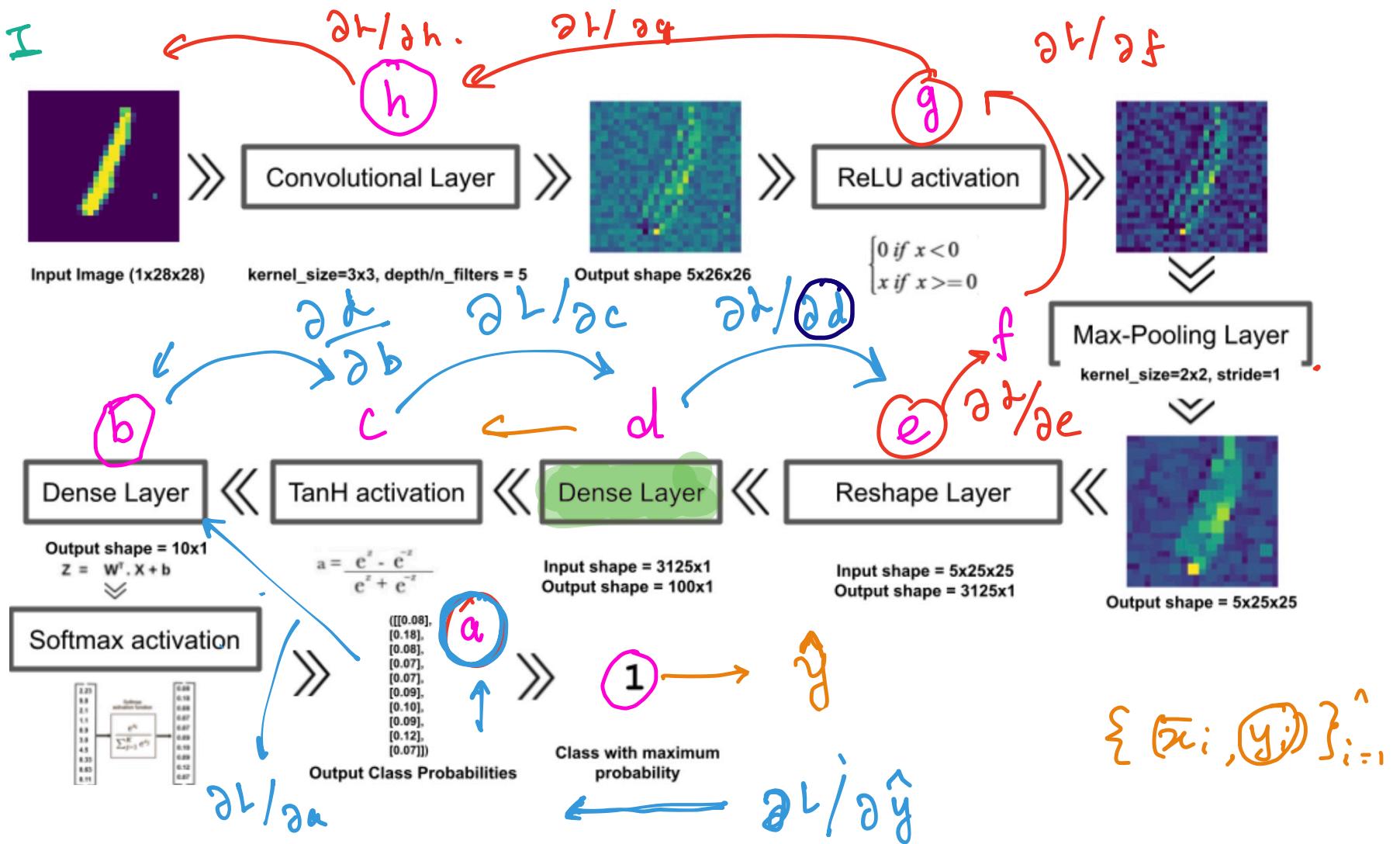
$$d' = d + \lambda \sum_{i=1}^9 k_i^2$$

≈ 98

900.00

$$1.1 \xrightarrow{w} (1.1)^2 \xrightarrow{w} (1.1)^3 \rightarrow (1.1)^{20}$$

$$0.9 \xrightarrow{w} (0.9)^2 \xrightarrow{w} (0.9)^5 \rightarrow \dots (0.9)^{20}$$

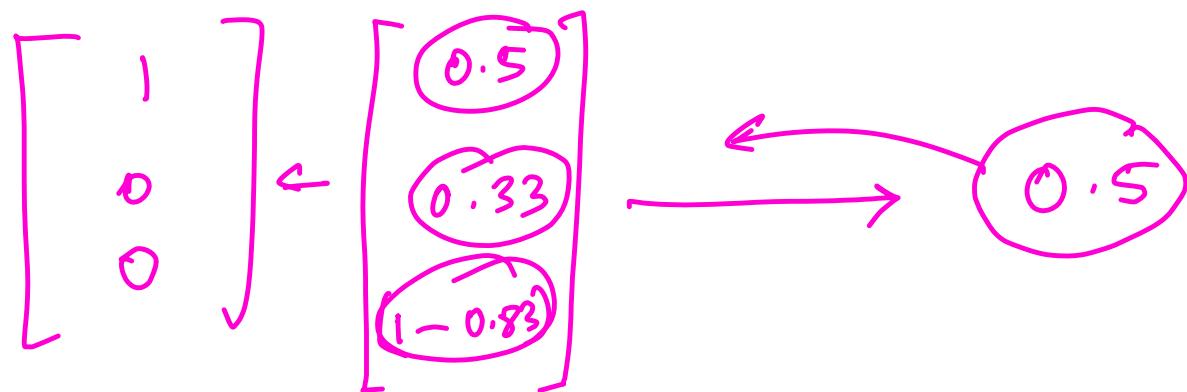


loss: Categorical Cross Entropy / Log loss.

$$L(\theta) = -\sum_{i=1}^n y_i \log(\hat{y}_i)$$

$$d = f(\hat{y})$$

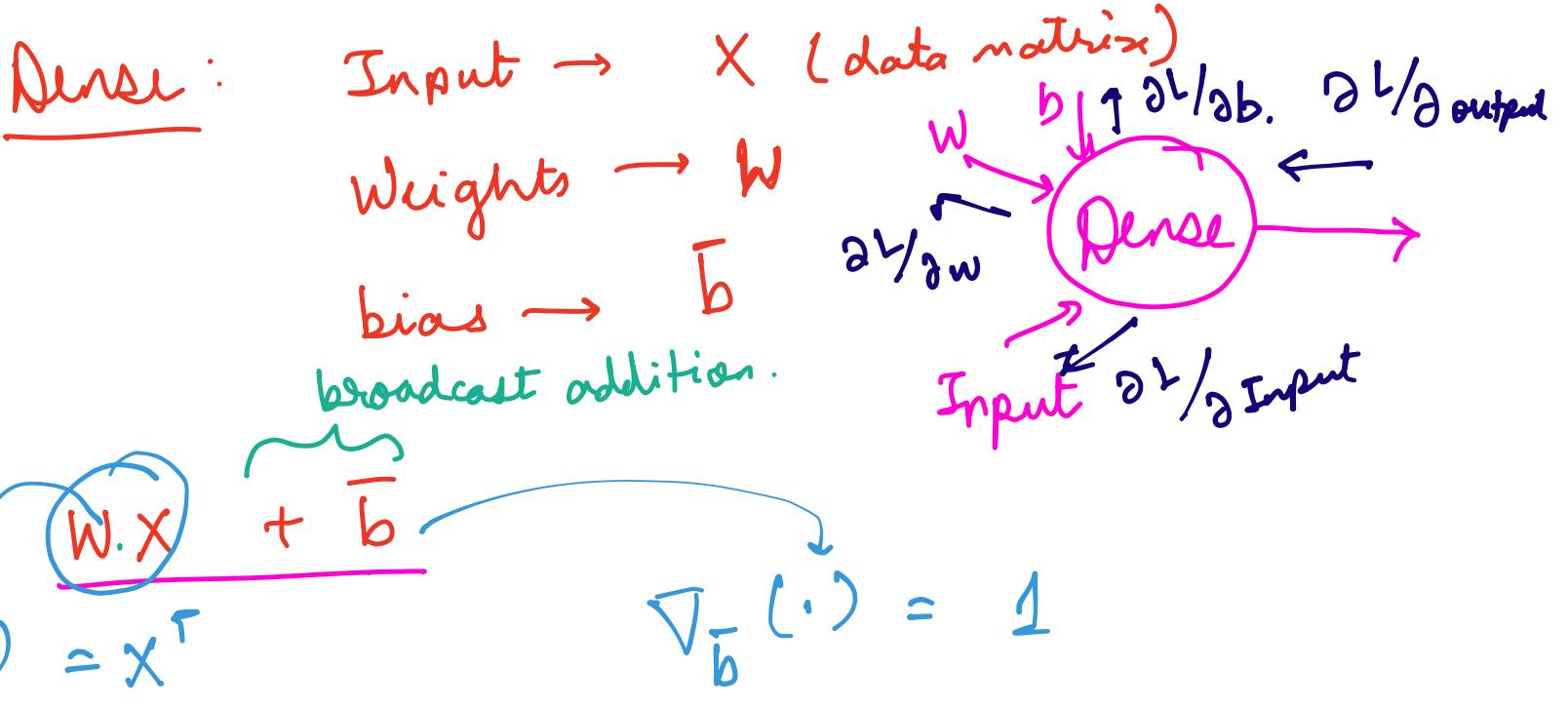
$$\hat{y} = \text{argmax}(a)$$



$$a = \text{softmax}(b)$$

$$b = \tanh(c)$$

$$c = \text{Dense}(d)$$

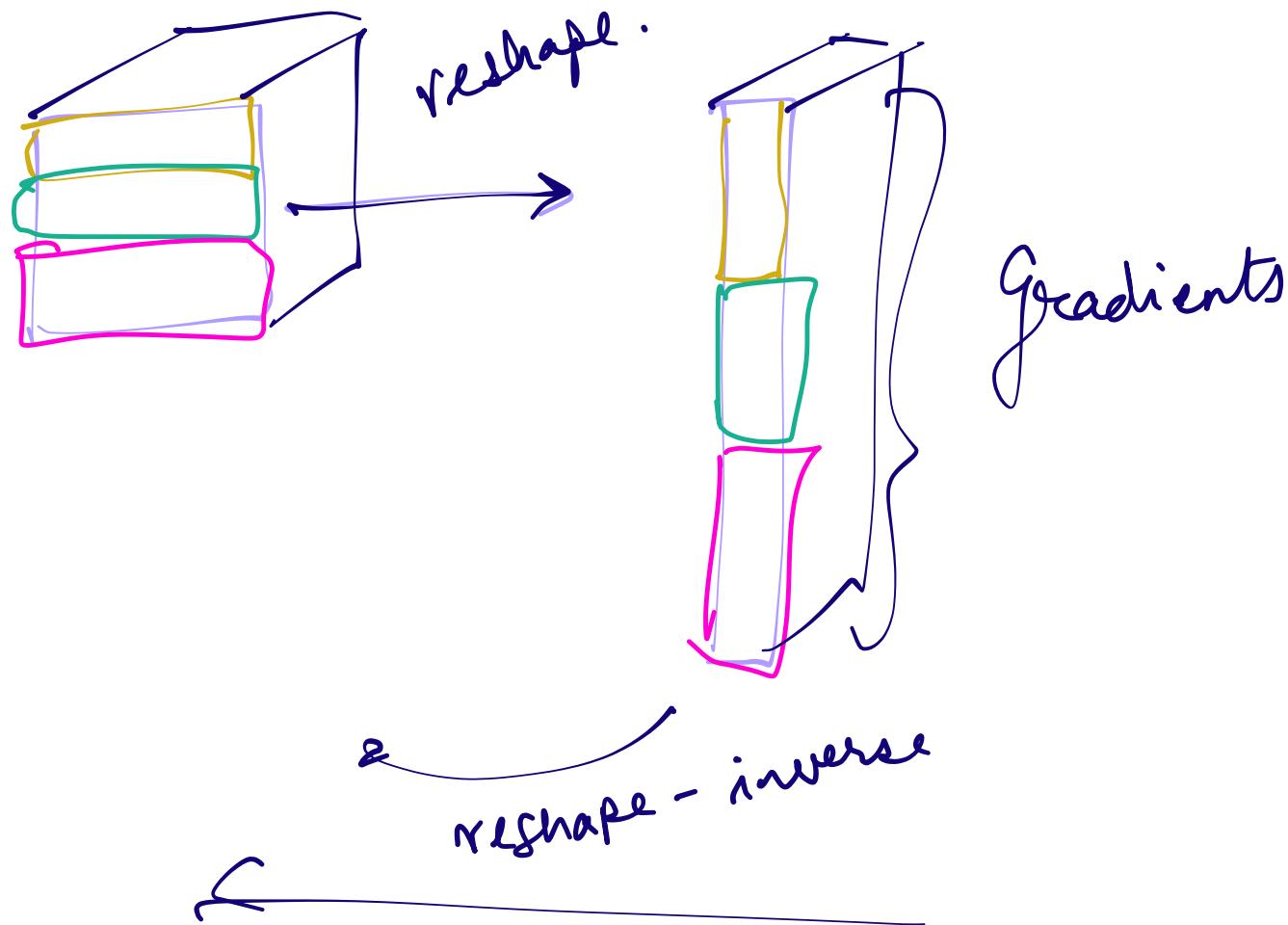


$$\nabla_{\bar{x}}(Ax) = A^T$$

$$\frac{\partial L}{\partial e} = \frac{\partial L}{\partial d} \cdot \frac{\partial d}{\partial e}$$

$$\begin{aligned}\text{Input gradient} &= \nabla_x (w x + b) \\ &= \underline{\underline{w^T}}\end{aligned}$$

forward pass



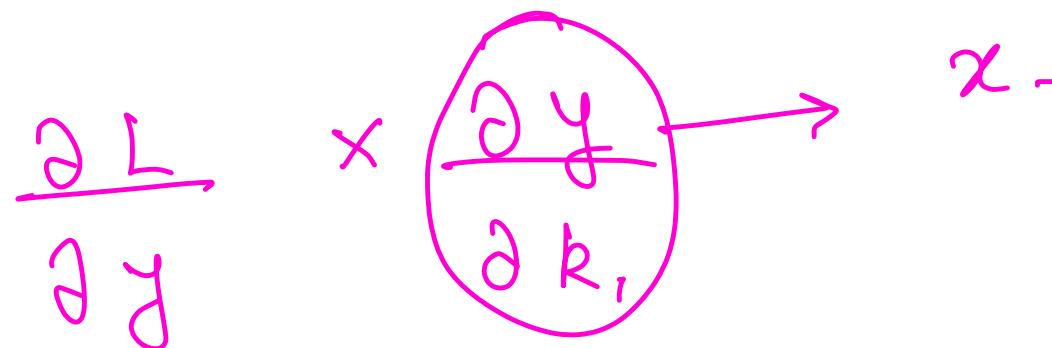
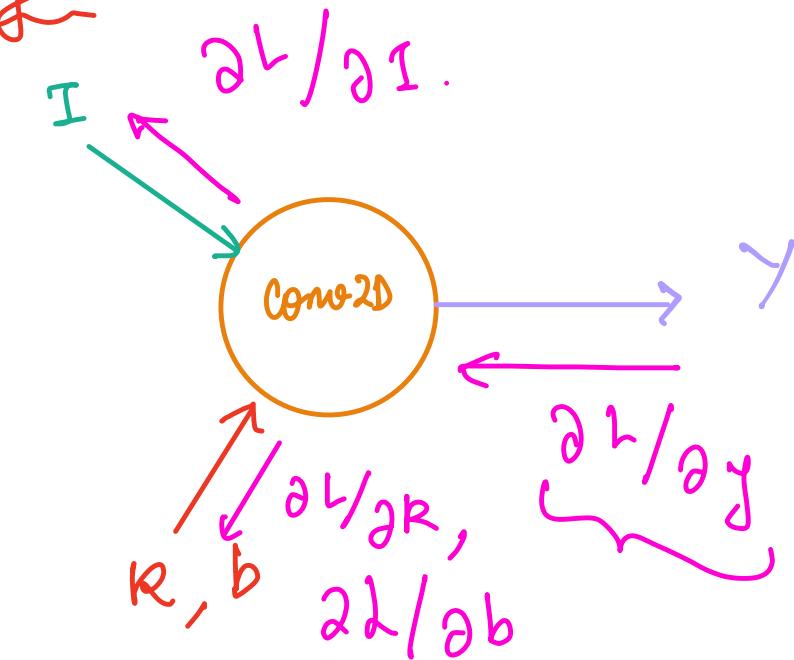
$$\max\left(\begin{array}{|c|c|}\hline 0 & 0.08 \\ \hline 0 & 0 \\ \hline\end{array}\right) = 0.08$$

A handwritten diagram illustrating the computation of the maximum value in a 2x2 matrix. The matrix is shown with four entries: 0, 0.08, 0, and 0. A pink bracket on the left side groups the top row (0 and 0.08). A pink bracket at the bottom groups the bottom row (0 and 0). A pink curved arrow points from the top bracket to the bottom bracket, indicating the comparison of the two rows. The result, 0.08, is circled in pink.

$$f(x) = \begin{cases} x & \text{if } x \geq 0 \\ 0 & \text{o/w.} \end{cases}$$

$$f'(x) = \begin{cases} 1 & \text{if } x \geq 0 \\ 0 & \text{o/w.} \end{cases}$$

Convolution Layer:



$$\frac{\partial L}{\partial k_{11}} = \frac{\partial L}{\partial y_{11}} \cdot x_{11} + \frac{\partial L}{\partial y_{12}} \cdot x_{12} + \frac{\partial L}{\partial y_{21}} \cdot x_{21} + \frac{\partial L}{\partial y_{22}} \cdot x_{22}$$

$$\frac{\partial L}{\partial k_{12}} = \frac{\partial L}{\partial y_{11}} \cdot x_{12} + \frac{\partial L}{\partial y_{12}} \cdot x_{13} + \frac{\partial L}{\partial y_{21}} \cdot x_{22} + \frac{\partial L}{\partial y_{22}} \cdot x_{23}$$

$$\frac{\partial L}{\partial k_1} = \text{Conv}\left(x, \frac{\partial L}{\partial y_i}\right)$$

$$\frac{\partial L}{\partial k_{21}} = \frac{\partial L}{\partial y_{11}} \cdot x_{21} + \frac{\partial L}{\partial y_{12}} \cdot x_{22} + \frac{\partial L}{\partial y_{21}} \cdot x_{31} + \frac{\partial L}{\partial y_{22}} \cdot x_{32}$$

↑

$$\frac{\partial L}{\partial k_{22}} = \frac{\partial L}{\partial y_{11}} \cdot x_{22} + \frac{\partial L}{\partial y_{12}} \cdot x_{23} + \frac{\partial L}{\partial y_{21}} \cdot x_{32} + \frac{\partial L}{\partial y_{22}} \cdot x_{33}$$

$$\Rightarrow \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix} \stackrel{*}{\text{Conv}}$$

$$\begin{bmatrix} \frac{\partial L}{\partial y_{11}} & \frac{\partial L}{\partial y_{12}} \\ \frac{\partial L}{\partial y_{21}} & \frac{\partial L}{\partial y_{22}} \end{bmatrix} = \begin{bmatrix} \frac{\partial L}{\partial k_{11}} & \frac{\partial L}{\partial k_{12}} \\ \frac{\partial L}{\partial k_{21}} & \frac{\partial L}{\partial k_{22}} \end{bmatrix} = \frac{\partial L}{\partial K}$$

$$\Rightarrow \frac{\partial L}{\partial K} = \text{Conv}\left(x, \frac{\partial L}{\partial y_i}\right)$$

$$\begin{bmatrix} \frac{\partial L}{\partial y_{11}} & x_{11} & \frac{\partial L}{\partial y_{12}} / x_{12} & x_{13} \\ \frac{\partial L}{\partial y_{21}} & x_{21} & \frac{\partial L}{\partial y_{22}} / x_{22} & x_{23} \\ x_{31} & y_{31} & x_{33} \end{bmatrix}$$

$$\frac{\partial L}{\partial K} = \text{Conv}\left(\underbrace{x}_{y}, \frac{\partial L}{\partial y}\right)$$

In signal processing :

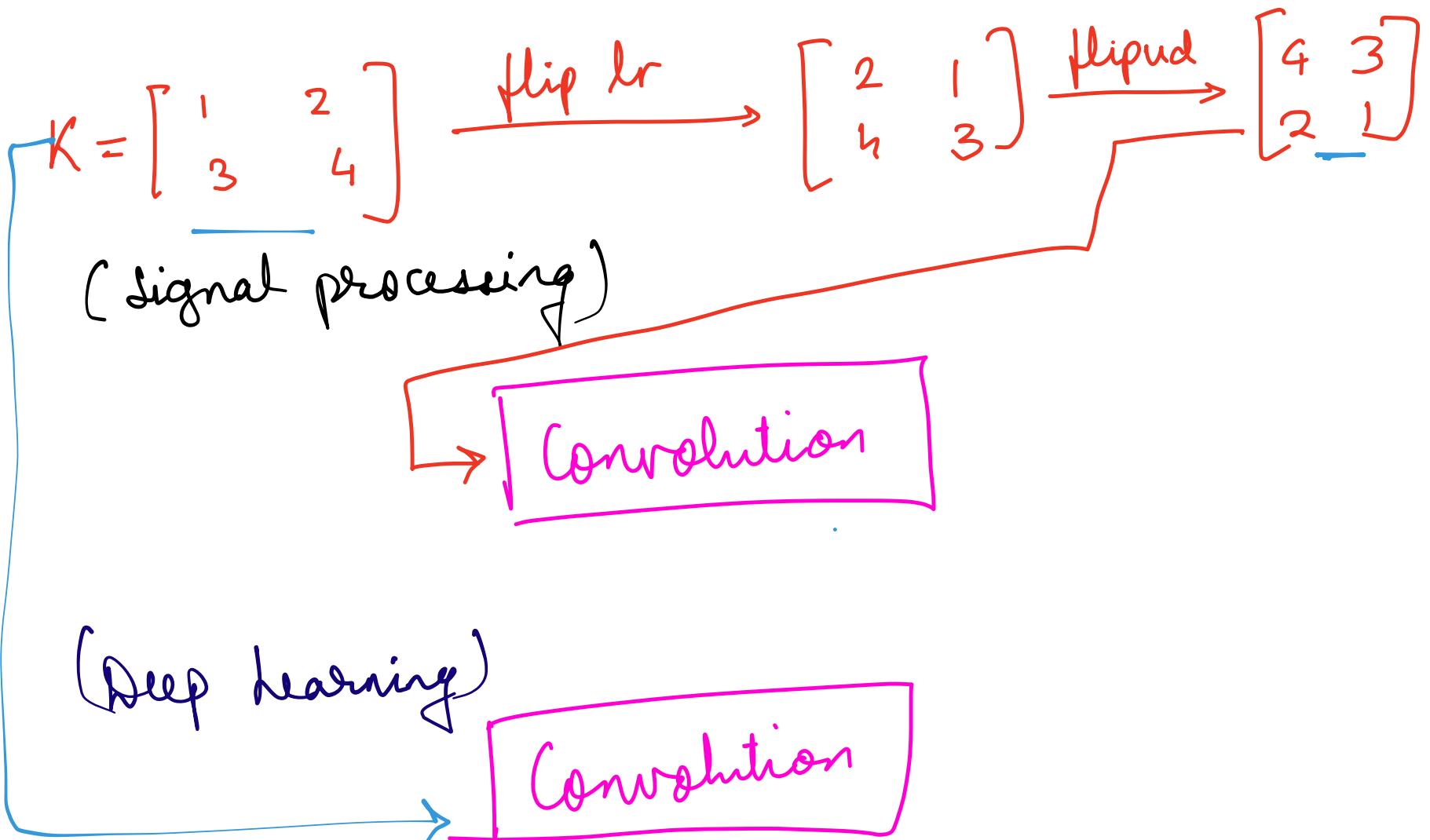
Convolution means $\underbrace{\text{flip_lr}(\text{flip_vd}(K))}$

K

And then apply correlation .

Flip left-right .

What we use in deep learning is
actually called correlation in
signal processing !!



Final test: Are we learning anything?

Accuracy of the Network on Test data is 98.67612293144208 %

Epoch 0 → 0.5383138776615902

1 → 0.16221502628227547

YES!!

2 → 0.11184481654332604

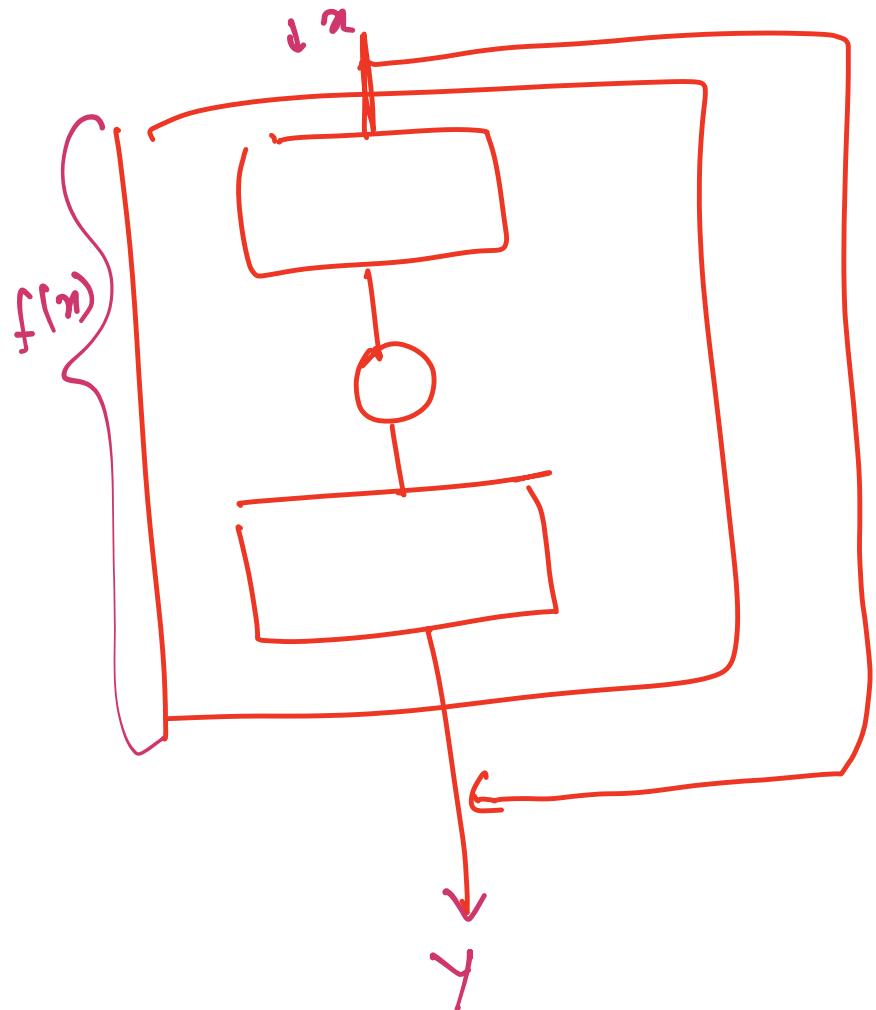
3 → 0.08838307171782168

4 → 0.07595734223282834

5 → 0.06734348866838971

6 → 0.061430346133807

7 → 0.05690578701515457



$$y = f(x) + x.$$

$$\frac{\partial y}{\partial x} = \underline{f'(x) + 1}$$

Andrew Ng → Great as a first course in CNN
(if you're from CS background)

→ Research papers → Not the best option.

go through Stanford CNN course
by Fei-Fei Li (CS 231n)