

March 31, 2023

DSML: Computer Vision.

CNNs for Medical Diagnosis

Class starts
@ 9:05 pm.



What normal people see
when they walk on street



What Computer Vision
folks see



WHO WOULD WIN?



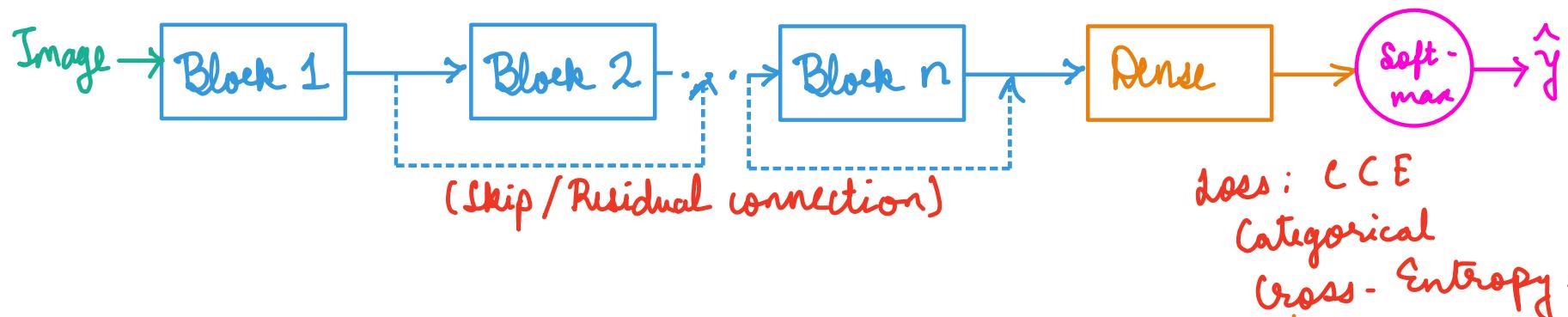
STATE OF THE ART
NEURAL NETWORK



ONE NOISY BOI

Recap:

- * Basic CNN architecture for Image Classification:



- * Popular architectures and their performance:

Model Name	Number of params	Top 1 Acc	Top 5 Acc
EfficientnetB0	5.3M	77.3	93.5
MobileNet	2.3M	71.0	90.5
ResNet50	25.6M	83.2	96.5
Inception	22.9M	79.0	94.5
VGG16	138M	74.4	91.9
AlexNet	62M	63.3	84.6

Novelty

Automated scaling strategy.
Factorizing convolutions.
Residual / skip connections.
Inception module, 1x1 conv
3x3 kernels, blocks.
First method to use GPUs,
SGD.

Recap:

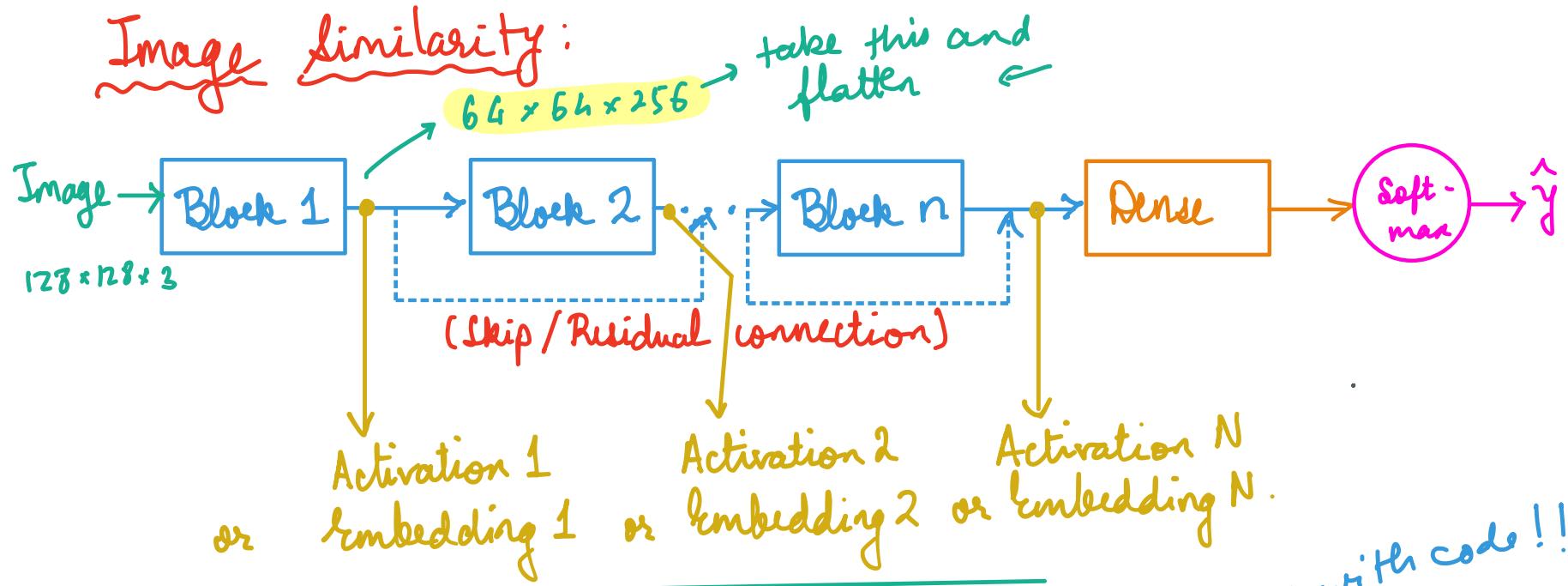
* Major CNN related concepts:

(a) Transfer learning: Reuse an already trained CNN for image classification.

- Helpful when we have a small dataset.
- As long as images are similar to Imagenet, better than training from scratch.

(b) Image similarity: Reuse of an already trained CNN for unsupervised similarity search.

- Select a convolutional representation. This is referred to as "activations" or "embeddings".
- Store these image representations in a database optimized for KNN.
- Similar images have "activations" which are close in the Euclidean sense.



* Considerations:

- Which neural network to pick?
Size, accuracy, dataset it was trained on, etc.
- Which activation / embedding to pick?
Compare all, but usually, the best is the last layer before dense.
- How to preprocess existing data?
Create a database containing all the activations & embeddings.
- How to query? Basically apply KNN (Euclidean distance)

Since we have a medical application:

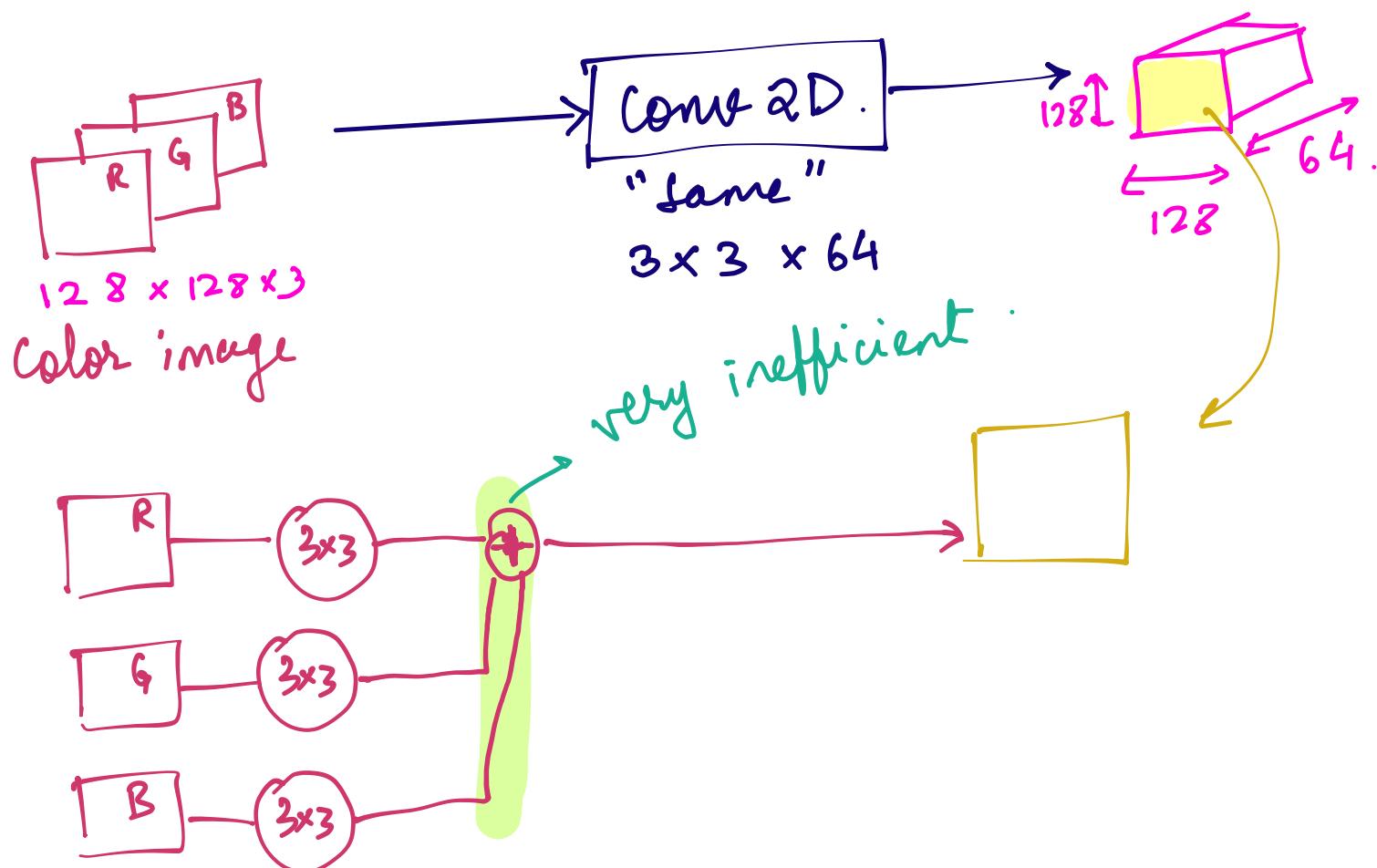
$$\text{precision} \rightarrow \frac{T.P}{T.P. + F.P.}$$

$$\text{Recall} \rightarrow \frac{T.P}{T.P. + \cancel{F.N.}}$$

This
has to
be high.

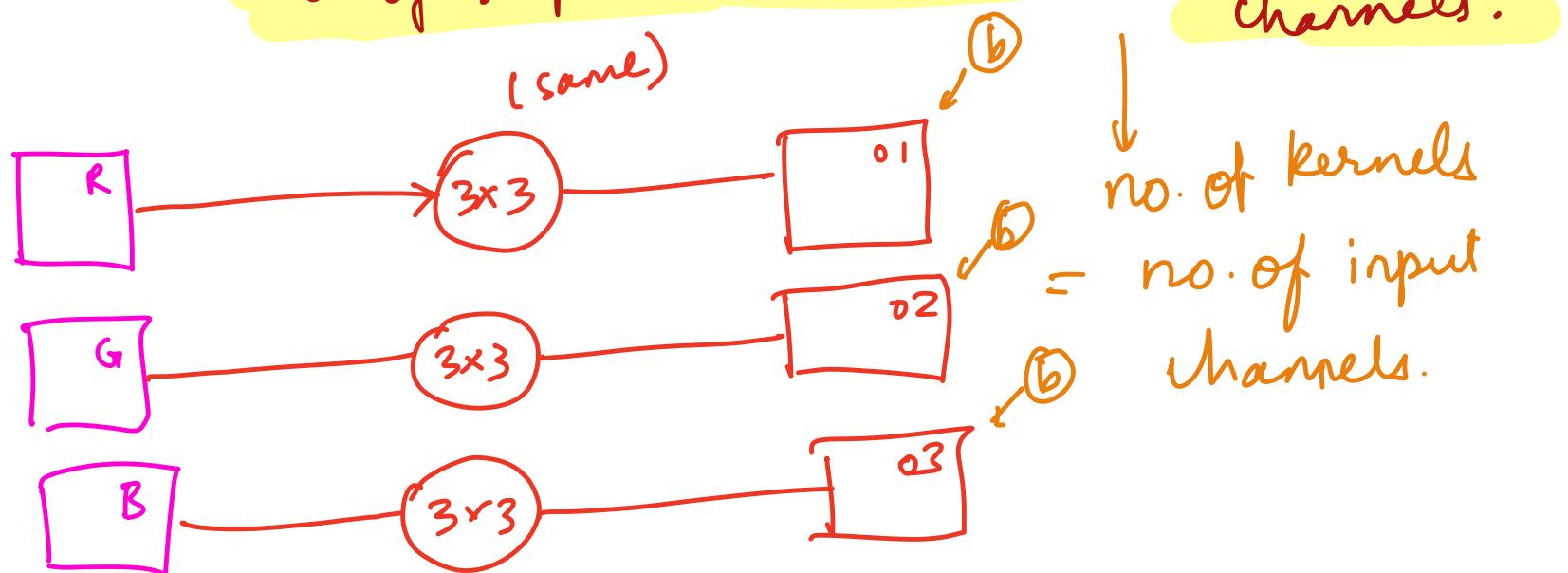
Mobile Net:

- * The basic change is the introduction of Depthwise convolutions.



Depthwise Convolution

- We no longer need multiple kernels for getting the output.
- For depthwise convolutions,
no. of input channels = = no. of output channels.



Class imbalance problem:

- In general, we have to collect more data to balance them out.
- If this cannot be done, we add weightage to the training examples. Assume more +ve examples than -ve examples.

if positive_class :

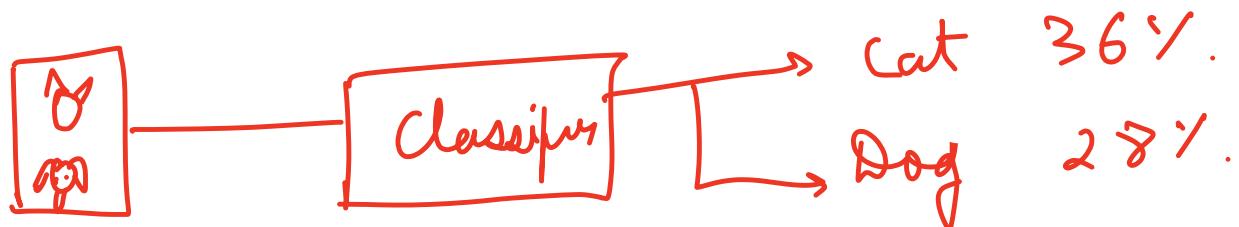
$$x^{(t+1)} = x^{(t)} - \eta \cdot \text{grad}$$

else

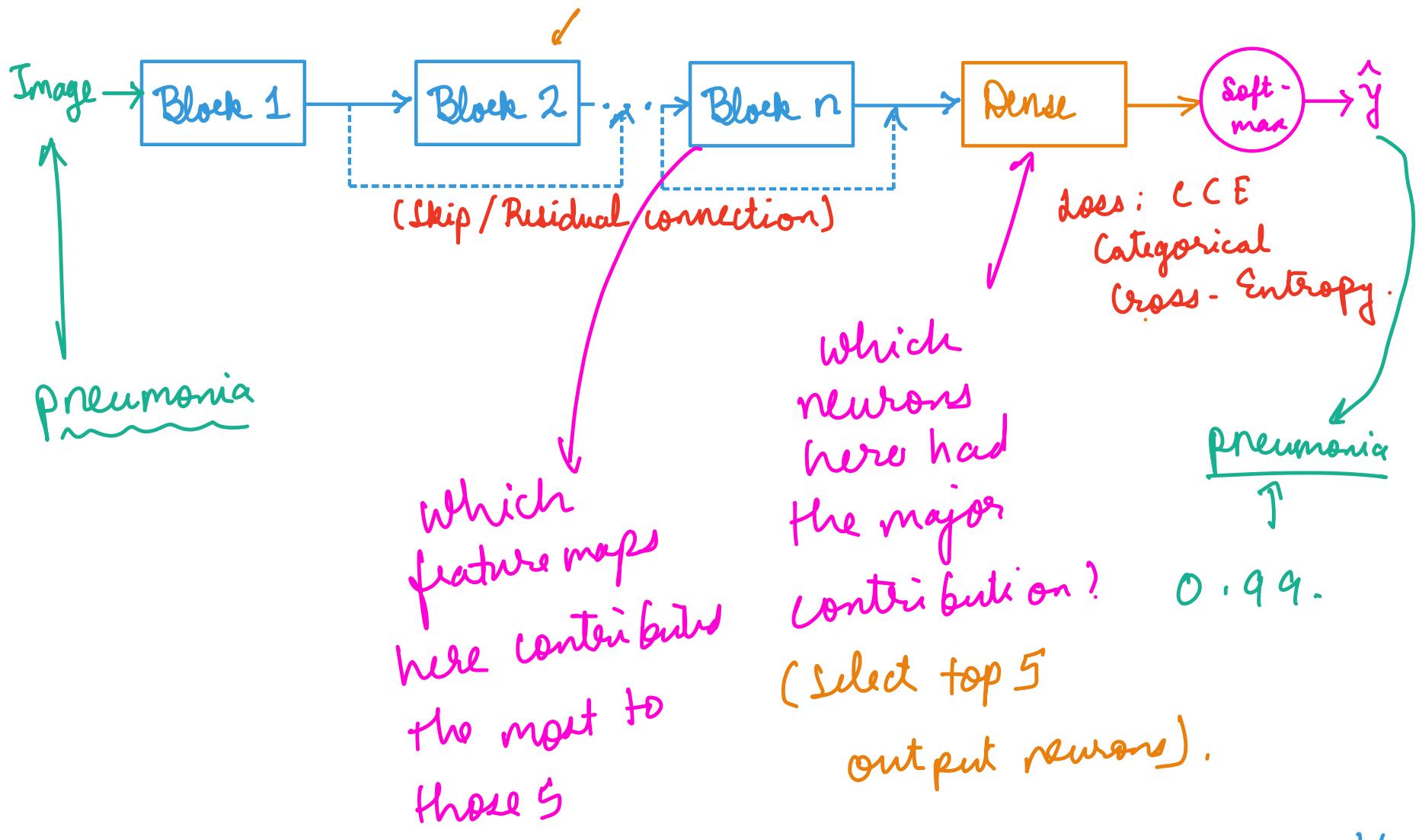
$$x^{(t+1)} = x^{(t)} - \textcircled{3} \cdot \eta \cdot \text{grad}$$

How to identify what part of the image led to the decision?

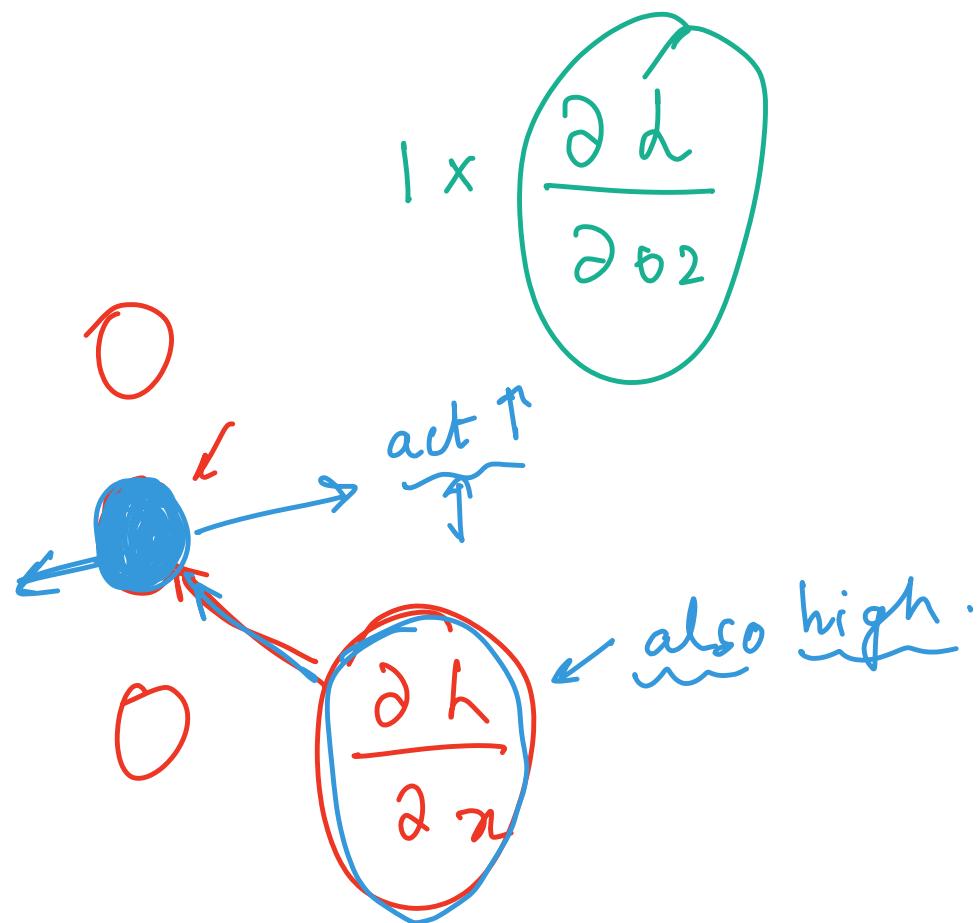
- * The biggest problem with CNNs is being able to debug it.



Can I ask why the CNN is 36% confident about cat?



Back propagation already does thi!!



$$O \times \frac{\partial L}{\partial o_1} \quad O \cdot o_1$$

$$O \times \frac{\partial L}{\partial o_2} \quad O \cdot o_2$$

$$O \times \frac{\partial L}{\partial o_3} \quad O \cdot o_3$$

$$\vdots \quad \vdots$$

$$O \cdot o_4$$

$$O \cdot o_5$$

$$O \cdot o_6$$

$$O \cdot o_7$$

$$O \cdot o_8$$

$$O \cdot o_9$$

$$O \cdot o_{10}$$

Customize VGG-16

Complete the given code snippet by filling **1), 2) and 3)**. You have a dataset containing images of shape 100x100x3. The model you are building will be used to classify those images into 7 classes. You are using a pre-trained VGG-16 model for this purpose.

```
pretrained_model = tf.keras.applications.VGG16(weights='imagenet', include_top=False , input_shape=1) 

pretrained_model.trainable=False

vgg16_model = tf.keras.Sequential([
    pretrained_model,
    2) ,
    tf.keras.layers.Dense(7, activation=3)
])
```