


Real Time Complexity and Assumed Time Complexity of Array

<i>Array Operation</i>	<i>Real Time Complexity</i>	<i>Assumed Time Complexity</i>
<i>Access i – th element</i>	$O(\sqrt{n})$	$O(1)$
<i>Traverse all elements</i>	$O(n + \sqrt{n})$	$O(n)$
<i>Override element at i – th index</i>	$O(\sqrt{n})$	$O(1)$
<i>Insert Element at E</i>	$O(n + \sqrt{n})$	$O(n)$
<i>Delete Element at E</i>	$O(n + \sqrt{n})$	$O(n)$

Why This Is NOT Used in Standard DSA Analysis

In typical computer science time complexity:

 We assume:

- data is in **main memory (RAM)**
- address arithmetic is $O(1)$
- basic operations cost constant time

So:

- access by index $\rightarrow O(1)$
- traverse $\rightarrow O(n)$
- shift for insert/delete $\rightarrow O(n)$

No \sqrt{N} terms appear in standard array time complexity.

The \sqrt{N} cost is a **hardware-level overhead**, not a complexity measure used in algorithm design.

● When \sqrt{N} Applies

The \sqrt{N} time idea is relevant when modeling:

- External memory access
- Paging and cache loads
- Disk-to-RAM block transfer

This belongs to **systems-level performance models**, not the common algorithmic time complexity used in DSA courses.

If the chip (the library) is arranged as a square grid of memory cells:

- *The width of the chip is roughly \sqrt{N} .*
 - *To reach the farthest memory cell, the signal has to travel physically across the chip.*
 - **The bigger the chip \sqrt{N} , the longer the travel time.**
 - *Time Complexity: $O(\sqrt{N})$ (Time depends on physical distance).*
-