Neural Network and Deep Learning - ICP4

AVINASH BORRA

Student ID: 700756622

Github link: https://github.com/Avinash-hub1/Assignment-4.git

Video link: https://drive.google.com/file/d/1c3CaxBTwY-9SddgzuyuPV44KWqmVd8Dd/view?usp=drive_link

In class programming:

- 1. Follow the instruction below and then report how the performance changed.(apply all at once)
- Convolutional input layer, 32 feature maps with a size of 3×3 and a rectifier activation function.
- Dropout layer at 20%.
- Convolutional layer, 32 feature maps with a size of 3×3 and a rectifier activation function.
- Max Pool layer with size 2×2 .
- Convolutional layer, 64 feature maps with a size of 3×3 and a rectifier activation function.
- Dropout layer at 20%.
- Convolutional layer, 64 feature maps with a size of 3×3 and a rectifier activation function.
- Max Pool layer with size 2×2 .
- Convolutional layer, 128 feature maps with a size of 3×3 and a rectifier activation function.
- Dropout layer at 20%.
- Convolutional layer, 128 feature maps with a size of 3×3 and a rectifier activation function.
- Max Pool layer with size 2×2 .
- Flatten layer.
- Dropout layer at 20%.
- Fully connected layer with 1024 units and a rectifier activation function.
- Dropout layer at 20%.
- Fully connected layer with 512 units and a rectifier activation function.

- Dropout layer at 20%.
- Fully connected output layer with 10 units and a Softmax activation function

Did the performance change?

2. Predict the first 4 images of the test data using the above model. Then, compare with the actual label for those 4

images to check whether or not the model has predicted correctly.

3. Visualize Loss and Accuracy using the history object

Output:

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        → C 25 colab.research.google.com/drive/1fGRCg-Cxs7Kc0GfYfaEVN3vhPUKu_TYN
            Untitled3.ipynb 
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             File Edit View Insert Runtime Tools Help All changes saved
:=
                                                                                                                                                                                                                                                       import numpy as np
from tensorflow.keras.datasets import cifar10
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, Dropout, Flatten, Conv2D, MaxPooling2D
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\{x\}
                    from tensorflow.keras.coptraints import MaxNorm from tensorflow.keras.constraints import MaxNorm from tensorflow.keras.optimizers import SGD from tensorflow.keras.utils import to_categorical from tensorflow.keras.optimizers.schedules import ExponentialDecay import matplotlib.pyplot as plt
<del>О.</del>
# Fix random seed for reproducibility
                    np.random.seed(seed)
                     (X_train, y_train), (X_test, y_test) = cifar10.load_data()
                     # Normalize inputs from 0-255 to 0.0-1.0
                     X_train = X_train.astype('float32') / 255.0
X_test = X_test.astype('float32') / 255.0
                     # One hot encode outputs
y_train = to_categorical(y_train)
y_test = to_categorical(y_test)
num_classes = y_test.shape[1]
                     # Create the model
                    # Create The model model model = model = model = Sequential() model = Sequential() model = sequential() model.add(Conv2D(32, (3, 3), input_shape=(32, 32, 3), padding='same', activation='relu', kernel_constraint=MaxNorm(3)))
                     model.add(Dropout(0.2))
model.add(Conv2D(32, (3, 3), activation='relu', padding='same', kernel_constraint=MaxNorm(3)))
model.add(MaxPooling2D(pool_size=(2, 2)))
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                     model.add(Conv2D(64, (3, 3), activation='relu', padding='same', kernel_constraint=MaxNorm(3)))
model.add(Conv2D(64, (3, 3), activation='relu', padding='same', kernel_constraint=MaxNorm(3)))
model.add(Conv2D(64, (3, 3), activation='relu', padding='same', kernel_constraint=MaxNorm(3)))
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                     model.add(MaxPooling2D(pool_size=(2, 2)))
```





