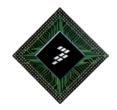




Freescale System Solutions

# **Motor Control Technologies**









### www.freescale.com/motorcontrol

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# Freescale Solutions for Motor Control Technologies

Comprehensive 8-, 16- and 32-bit systems with advanced sensor and analog/mixed signal devices

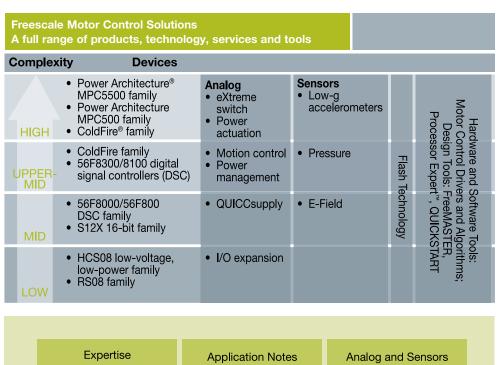
Freescale offers complete solutions for every motor control application. Our superior portfolio and breadth of devices includes:

- 8-bit microcontrollers (MCUs)
- 16-bit digital signal controllers (DSCs)
- 32-bit embedded controllers
- Acceleration and pressure sensors
- Analog and mixed signal devices

Freescale delivers solutions that have wide ranging banks of flash and RAM memories, configurable timer options, pulse width modulators (PWMs), and some even offer an enhanced Time Processing Unit (eTPU).

Freescale supports these devices with motor control-related application notes, hardware/ software tools, drivers, algorithms and helpful Web links including our motor control Web site at www.freescale.com/motorcontrol. We are dedicated to providing comprehensive system solutions that not only improve motor efficiency but also minimize system updates, development time and maintenance costs.

Freescale provides microcontrollers and development tool solutions for all of your motor control needs.



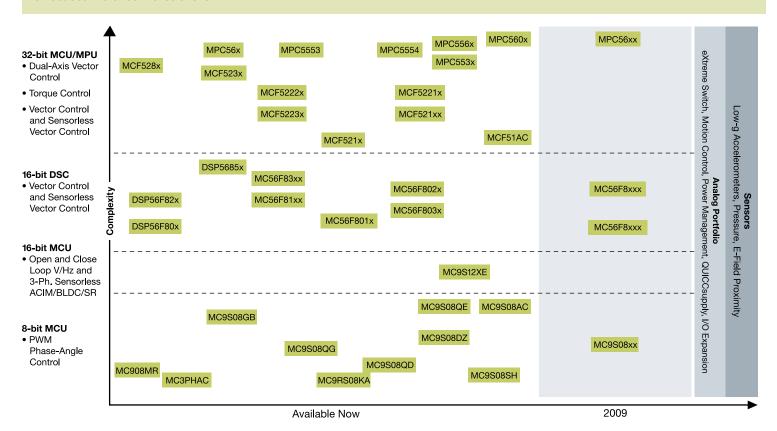
# Demos Freescale's Complete Motor Control Solution Online Training Web Site Analog and Sensors Development Tools Software and Drivers Technical Support

# A Roadmap for Your Future Design Needs

Intelligent solutions driving new generations of motor control applications

Freescale MCUs, MPUs and DSCs, when coupled with analog/mixed-signal and power integrated circuits, are designed to provide system solutions for motor control, motion control and static load control for an incredible variety of applications.

The product roadmaps demonstrate that new feature integration and software compatibility will continue to drive future generations of embedded motor control solutions.





# **Motor Control Applications**

# Motor type/control solution matrix

### **Motor Control Applications**

|                   |   | Motor Control Applications   |                  |                        |                             |  |                        |            |                                 |                                |        |
|-------------------|---|------------------------------|------------------|------------------------|-----------------------------|--|------------------------|------------|---------------------------------|--------------------------------|--------|
|                   |   | Refrigeration<br>Compressors | Washers/Dryers   | Pumps/Fans/<br>Blowers | Industrial Factory<br>Floor | CNC Tool and Dye,<br>Health Care<br>Scanners | Garage Door<br>Openers | Hand Tools | Kitchen Contertop<br>Appliances | Computers, Office<br>Equipment | Toys   |
|                   | Universal Motor                               |                              | 8-bit            |                        |                             |  | 8-bit                  | 8-bit      | 8-bit                           |                                |        |
|                   | Brush DC Motor                                |                              |                  |                        |                             |  | 8-bit                  | 8-bit      | 8-bit                           |                                | 8-bit  |
| _                 | Low-Performance<br>DC Servo                   |                              |                  |                        |                             | 8-bit  |                        |            |                                 | 8-bit                          | 8-bit  |
|                   | Switched Reluctance                           |                              | 8-bit            | 8-bit                  |                             |  |                        |            |                                 |                                |        |
| <b>Fechnology</b> | Stepper Control                               |                              |                  |                        |                             | 8-bit<br>16-bit                              |                        |            |                                 | 8-bit<br>16-bit                | 8-bit  |
| Techn             | High-Performance<br>DC Servo                  |                              |                  |                        | 16-bit                      | 16-bit                                       |                        |            |                                 | 16-bit                         | 16-bit |
|                   | AC Induction Scalar-Slip Control              | 8-bit                        | 8-bit<br>16-bit  | 8-bit<br>16-bit        | 8-bit<br>16-bit             |  | 8-bit                  |            |                                 |                                |        |
|                   | BLDC<br>Commutated Control                    | 8-bit<br>16-bit              | 8-bit<br>16-bit  | 8-bit<br>16-bit        |                             |  | 8-bit                  | 8-bit      |                                 | 8-bit                          | 8-bit  |
|                   | Permanent Magnet AC<br>Field Oriented Control | 16-bit                       | 16-bit<br>32-bit | 16-bit<br>32-bit       | 16-bit<br>32-bit            | 16-bit<br>32-bit                             |                        |            |                                 |                                |        |
|                   | AC Induction Field Oriented Control           | 16-bit                       | 16-bit<br>32-bit | 16-bit<br>32-bit       | 16-bit<br>32-bit            | 16-bit<br>32-bit                             | 16-bit                 |            |                                 |                                |        |
|                   | Technology/Application<br>Match               |                              |                  | Moderate               |                             |  | Poor                   |            |                                 |                                |        |

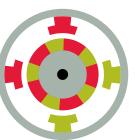
Note: There are numerous possibilities of matches between a technology and an application other than what is shown in this table. This is intended to be a high-level guide, but it is not all-inclusive.

# The Broadest Selection of Motor Control Solutions

# For multiple electric motor topologies

When designing motor control systems, instruction set efficiency and sophisticated peripherals that are specifically tuned for electric motor control environments provide the greatest performance advantages. Freescale provides comprehensive motor control solutions for virtually all electric motor topologies. In the following pages we feature recommended devices—from 8-, 16- and 32-bit embedded processors to analog/mixed signal power ICs—as well as demonstration boards and reference designs for each electric motor system listed at right.

Freescale has an extremely broad selection of embedded controller solutions for motor control applications. We give you the option to choose the system components that meet your specific electronic motor design needs.



### **Stepper Motor**

Stepper motors are used to produce incremental, noncontinuous motion, and are used primarily for precise position control. Stepper motor application examples and information can be found on pages 6, 7 and 8 of this brochure.



### **Brushed DC Motor**

Permanent magnet DC motor with rotor windings connected via "brushes" to a mechanical commutator. Brushed DC motor application examples and information can be found on page 9.



### **Brushless DC Motor (BLDC)**

BLDC motors have a classic three-phase stator and a rotor with surface-mounted permanent magnets, and are driven by electronically switching the stator winding connections with a rectangular waveform in accordance with rotor position. BLDC application examples and information can be found on pages 10, 11 and 12.



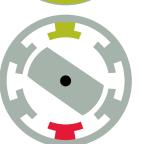
### **AC Induction Motor (ACIM)**

AC induction motors have a classic three-phase stator, and commonly have a "squirrel cage" rotor in which the conductors are shorted together at both ends. ACIM application examples and information can be found on pages 13, 14 and 15.



### Permanent Magnet Synchronous Motor (PMSM)

Similar to BLDC motors, permanent magnet synchronous motors have a classic three-phase stator and a rotor with surface-mounted permanent magnets. The construction differs from BLDC motors in they are driven by electronically switching the stator winding connections with a sinusoidal waveform in accordance with rotor position. PMSM application examples and information can be found on pages 16, 17, and 18.



### **Switched Reluctance Motor**

SR motors contain no magnets (mainly stamped metal elements), and are constructed such that both the stator and rotor have salient poles. The motor is driven by a sequence of current pulses applied at each phase, which requires control electronics for operation. SR motor application examples and information can be found on page 19.



# **Stepper Motors**

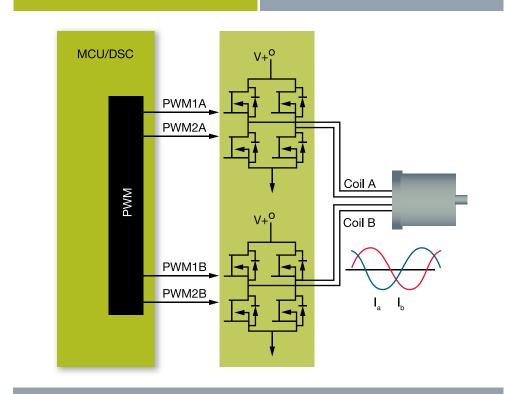
# General purpose stepper motor control

### **Advantages**

• Precise position control

### **Applications**

- Industrial machines
- Health care scanners
- Computers
- Office equipment
- Toys



### Recommended Devices

**8-bit MCU:** 908JK/JL, 908MR, 908QT/QY, 908QB, 908QC, 908GP, 908GR, 9S08AW, 9S08GB, 9S08GT, 9S08QG, 9S08QD

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**32-bit MCU:** MCF51AC, MCF521x, MCF523x, MPC56x, MPC55xx

Analog/Mixed-Signal Power ICs Power Supply: MC34702, MC34717,

Motor Driver: MC33932, MC34920, MC34921, MC34923, MPC17533, MC33887, MC33899, MC33926, MC33931, MPC17529, MPC17531, MM908E626

### **Application Notes**

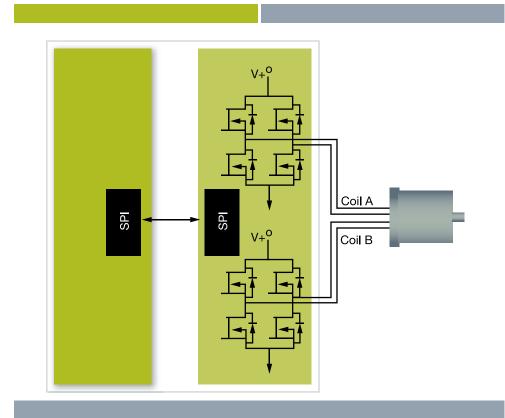
32-bit **AN23** 

**AN2353** The Essentials of the Enhanced Time Processing Unit **AN2848** Programming the eTPU

AN2869 Using the Stepper Motor (SM) eTPU Function

# **Stepper Motors**

Intelligent power



### Advantages

Precise position control

### **Applications**

- Industrial machines
- Health care scanners
- Computers
- Office equipment
- Toys

### Reference Designs

RD68HC908LHID

LIN-bus HID Lamp Leveling Stepper Motor Control Using the Freescale 908F625

### **Recommended Devices**

8-bit MCU: 9S08E6xx

Analog/Mixed Signal Power ICs Motor Driver: MM908E621, MM908E625, MM908E626

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# **Stepper Motors**

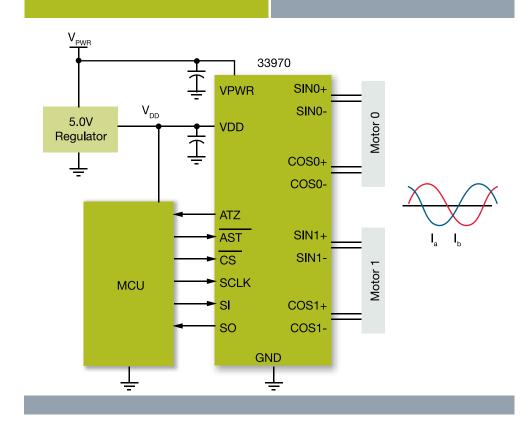
# Micro-stepped gauge drivers

### **Advantages**

• Precise position control

### **Applications**

- Industrial machines
- · Health care scanners
- Computers
- Office equipment
- Toys



### **Recommended Devices**

Analog/Mixed-Signal Power ICs: MC33970, MC33976, MC33977, MC33991

### **Application Notes**

32-bit AN2353 The Essentials of the Enhanced Time Processing Unit

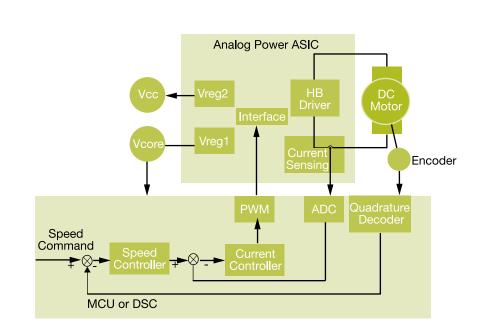
AN2848 Programming the eTPU

AN2869 Using the Stepper Motor (SM) eTPU Function

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# **Brushed DC Motor**

# Dual feedback loop control



### Advantages

- Cost-effective control topology
- High-precision speed, torque control and position loop can be added

### **Applications**

- Robots
- Traction control
- Servo systems
- Automotive
- Office equipment
- Toys
- Industrial machines

### Application Notes

32-bit A

 ${\bf AN2955}$  DC Motor with Speed and Current Closed Loops, Driven by eTPU on MCF523x AN2955SW

AN2958 Using the DC Motor Control eTPU Function Set (Set 3)

**AN3008** DC Motor with Speed and Current Closed Loops, Driven by eTPU on MPC5554 AN3008SW

### **Recommended Devices**

8-bit MCU: 908MR, 9S08GB, 9S08AC

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

16-bit MCU: S12XE

**32-bit MCU:** MCF51AC, MCF521x, MCF523x, MPC56x, MPC55xx

Analog/Mixed-Signal Power ICs Power Supply: MC34702, MC34717, MC33730, MC34923

Motor Driver: MPC17510, MPC17529, MPC17531, MPC17533, MC34920, MC34921, MC33926, MC33887, MC33899, MC33931, MC33932



# **Brushless DC Motor (BLDC)**

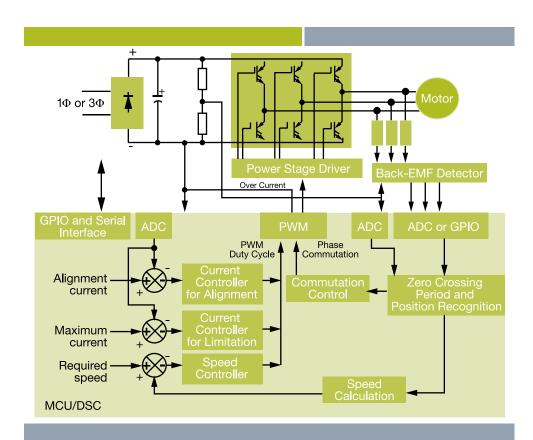
## Sensorless back EMF/Hall sensor

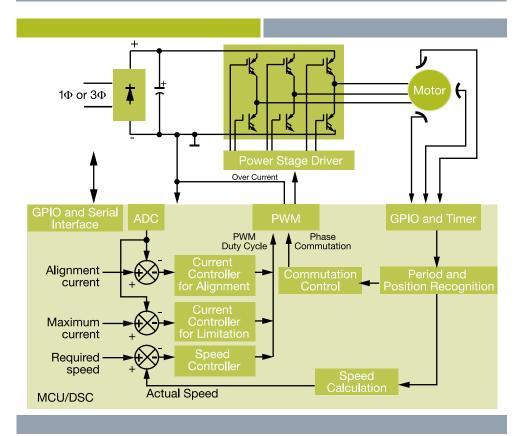
### **Advantages**

- Enables bi-directional operation with fast torque response
- Low noise, high efficiency
- · Removes the position sensor
- · Cost-effective control topology
- Speed and torque control

### **Applications**

- Industrial control
- Large appliances
- HVAC
- Compressors
- Blowers
- Toys
- Pumps
- Health care equipment





Application Notes 8-bit AN2356 Sensorless BLDC Motor Control on MC68HC908MR32 Software Porting to Customer Motor AN2355 Sensorless BLDC Motor Control on MC68HC908MR32 Software AN1858 Sensorless Brushless DC Motor Using the MC68HC908MR32 Embedded Motion Control AN1853 Embedding Microcontrollers in Domestic Refrigeration Appliances AN2396 Servo Motor Control Application on a Local Area Interconnect Network (LIN) **DRM086** Sensorless BLDC Motor Control Using MC9S08AW60 AN1913 3-Phase BLDC Motor Control with Sensorless Back-EMF ADC Zero Development System Crossing Detection Using DSP56F80x 16-bit AN1914 3-Phase BLDC Motor Control with Sensorless Back EMF Zero Crossing Detection Using DSP56F80x AN1961 3-Phase BLDC Motor Control with Quadrature Encoder Using 56F800/E **DRM078** 3-Phase BLDC Drive Using Variable DC Link Six-Step Inverter DRM070 3-Phase BLDC Motor Sensorless Control using MC56F8013/23 32-bit AN2892 3-Phase BLDC Motor with Speed Closed Loop, Driven by eTPU on MCF523x AN2892SW AN2948 Three 3-Phase BLDC Motors with Speed Closed Loop, Driven by eTPU on MCF523x AN2948SW AN2954 BLDC Motor with Speed Closed Loop and DC-Bus Break Controller, Driven by eTPU on MCF523x AN2954SW AN2957 BLDC Motor with Quadrature Encoder and Speed Closed Loop, Driven by eTPU on MCF523x AN2957SW AN3005 BLDC Motor with Quadrature Encoder and Speed Closed Loop, Driven by

eTPU on MPC5554 AN3005SW

on MPC5554 AN3006SW

| Reference Designs    |  |
|----------------------|--|
| Sensorless Back EMF  |  |
| RD68HC908BLDCZC      | Sensorless BLDC Motor Control Using the MC68HC908MR32  |
| RDDSCSENSORLESSBLDC  | 3-Phase Brushless DC Motor Sensorless Control Using 56F801X  |
| RDDSCSNSLESSBLDCAW60 | 3-Phase BLDC Motor Sensorless Control Using MC9S08AW60   |
| RDDSP56F8BLDCAZC     | 3-Phase BLDC Motor Control with Sensorless Back-EMF ADC Zero Crossing Detection Using 56F80X or 56F8300 Digital Signal Controllers |
| Hall Effect Feedback |  |
| RD56F801XBLDCHS      | 3-Phase BLDC Motor Control with Hall Sensor Using 56F801X Digital Signal Controllers   |
| RD68HC908BLDCHS      | 3-Phase BLDC Drive Control with Hall Sensors   |
| RDDSP56F8BLDCHS      | 3-Phase BLDC Motor Control with Hall Sensor Using 56F80X or 56F8300 Digital Signal Controllers                                     |
| RD68HC908BLDCFPC     | MC68HC908QT2 BLDC Fan for PCs Reference Design   |
| RD68HC908NGCD        | High-Voltage BLDC Drive for Domestic Appliances Using the MC68HC908MR8   |
| RDDSC3PHBLDCINV      | 3-Phase BLDC Drive using DC/DC Inverter on MC56F8013   |
| RDHC908BLDCF         | Low-Power BLDC Drive for Fans Using the MC68HC908QY4 MCU   |

AN3006 BLDC Motor with Hall Sensors and Speed Closed Loop, Driven by eTPU

AN3007 BLDC Motor with Speed Closed Loop and DC-Bus Break Controller, Driven by eTPU on MPC5554 AN3007SW

### **Recommended Devices**

**8-bit MCU:** 908MR, 9S08AC, 9S08GB, 9S08QD, 9RS08KA

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**16-bit MCU:** S12XE

**32-bit MCU:** MCF51AC, MCF521x, MCF523x, MPC56x. MPC55xx

Analog/Mixed-Signal Power ICs
Power Supply: MC34702, MC34717,
MC33730

Motor Driver: MC33927, MC33937, MC34923



# **Brushless DC Motor (BLDC)**

### Encoder

### **Advantages**

- Enables bi-directional operation with fast torque response, low noise and high efficiency
- High precision speed
- Torque control
- Position loop can be added

### Applications

- Robots
- Traction control
- Servo systems
- Office equipment
- Sewing machines
- Fitness machines/treadmills
- Toys
- Industrial machines

### **Recommended Devices**

8-bit MCU: 908MR. 9S08AC. 9S08GB

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

16-bit MCU: S12XE

MC33937, MC33927

**32-bit MCU:** MCF51AC, MCF521x, MCF523x, MPC56x, MPC55xx

Analog/Mixed-Signal Power ICs Power Supply: MC34702, MC34717,

Motor Driver: MPC17533, MC34923,

GPIO and Serial Interface

Speed
Reference
Speed
Controller

Actual Speed
MCU/DSC

Motor

Power Stage Driver
Over Current
Communication
Communication
Control
Speed
Calculation
Calculation
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Calculation

### **Application Notes**

8-bit

**AN2356** Sensorless BLDC Motor Control on MC68HC908MR32 Software Porting to Customer Motor

**AN2355** Sensorless BLDC Motor Control on MC68HC908MR32 Software **AN1858** Sensorless Brushless DC Motor Using the MC68HC908MR32 Embedded Motion Control

AN1853 Embedding Microcontrollers in Domestic Refrigeration Appliances
AN2396 Servo Motor Control Application on a Local Area Interconnect Network (LIN)
DRM086 Sensorless BLDC Motor Control Using MC9S08AW60

Development System 16-bit **AN1913** 3-Phase BLDC Motor Control with Sensorless Back-EMF ADC Zero Crossing Detection Using DSP56F80x

**AN1914** 3-Phase BLDC Motor Control with Sensorless Back EMF Zero Crossing Detection Using DSP56F80x

AN1961 3-Phase BLDC Motor Control with Quadrature Encoder Using 56F800/E DRM078 3-Phase BLDC Drive Using Variable DC Link Six-Step Inverter

**DRM070** 3-Phase BLDC Motor Sensorless Control Using MC56F8013/23

32-bit MCU

 $\bf AN2892$  3-Phase BLDC Motor with Speed Closed Loop, Driven by eTPU on MCF523x AN2892SW

**AN2948** Three 3-Phase BLDC Motors with Speed Closed Loop, Driven by eTPU on MCF523x AN2948SW

AN2954 BLDC Motor with Speed Closed Loop and DC-Bus Break Controller, Driven by eTPU on MCF523x AN2954SW

**AN2957** BLDC Motor with Quadrature Encoder and Speed Closed Loop, Driven by eTPU on MCF523x AN2957SW

**AN3005** BLDC Motor with Quadrature Encoder and Speed Closed Loop, Driven by eTPU on MPC5554 AN3005SW

AN3006 BLDC Motor with Hall Sensors and Speed Closed Loop, Driven by eTPU on MPC5554 AN3006SW

AN3007 BLDC Motor with Speed Closed Loop and DC-Bus Break Controller, Driven by eTPU on MPC5554 AN3007SW

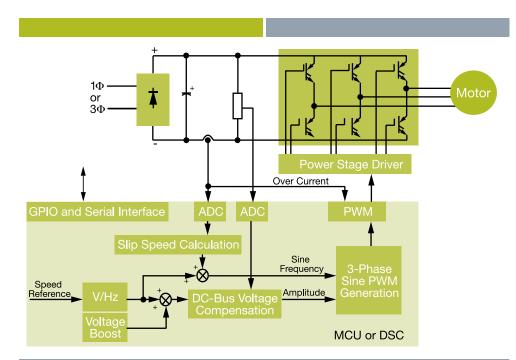
### Reference Designs

RDDSP56F8BLDCE

3-Phase BLDC Motor Control with Encoder Using 56F80X or 56F8300 Digital Signal Controllers

# **AC Induction Motors (ACIM)**

# 3-phase ACIM with V/Hz open-loop control with PFC



### **Application Notes**

it AN2154 Cost-Effective, 3-Phase, AC Motor Control System with Power Factor Correction Based on MC68HC908MR32

**AN1857** 3-Phase, AC Motor Control System with Power Factor Correction Based on MC68HC908MR32

**AN1664** Cost-Effective 3-Phase AC Motor Control System Based on MC68HC908MR32 **AN1590** High-Voltage Medium Power Board for 3-Phase Motors

**AN2149** Compressor Induction Motor Stall and Rotation Detection Using Microcontrollers **AN1853** Embedding Microcontrollers in Domestic Refrigeration Appliances

16-bit AN1918 Indirect Power Factor Correction for 3-Phase AC Motor Control with V/Hz Speed Open Loop Application

AN1930 3-Phase AC Induction Motor Vector Control

**AN1958** 3-Phase AC Motor Control with V/Hz Speed Closed Loop Using the 56F800/E **AN1942** DSP56F80x Resolver Driver and Hardware Interface

DRM092 3-Phase AC Induction Vector Control Drive with Single-Shunt Current Sensing **AN3234** Washing Machine Three-Phase AC Induction Motor Drive

### **Advantages**

- Enables bi-directional operation with fast torque response
- · Simple cost-effective control topology
- Controls both motor and PFC by single MCU
- Targeted for modest applications accepting low-precision speed control
- High efficiency
- Precise speed control
- Enables indirect torque control
- Tolerant of motor parameters fluctuation

### Applications

- Large appliances
- HVAC
- Blowers, fans
- Pumps
- Lifts, cranes, elevators
- Conveyors
- Frequency inverters
- Industrial controls
- Treadmills
- Industrial compressors
- Universal inverters

### Recommended Devices

**8-bit MCU:** 908MR, 9S08AW, 9S08GB, 9S08QD

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**32-bit MCU:** MCF51AC, MCF521x, MCF523x, MPC56x, MPC55xx



# **AC Induction Motors (ACIM)**

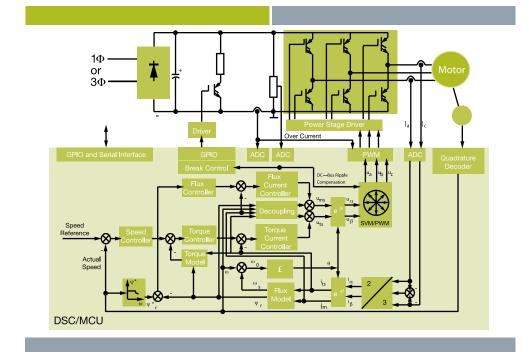
# 3-phase ACIM with field oriented control (sensored feedback)

### **Advantages**

- Very high-precision speed/torque control
- Suitable for drives with high dynamic requirements
- · Highly efficient

### **Applications**

- Large appliances
- HVAC
- Blowers
- Fan, pumps
- Industrial controlsLifts, cranes, elevators
- Universal inverters
- Conveyors



### **Recommended Devices**

**16-bit DSC:** MC56F80x, MC56F80xx,

**32-bit MCU:** MCF521x, MCF523x, MPC56x, MPC55xx

### **Application Notes**

8-bit AN2154 Cost-Effective, 3-Phase, AC Motor Control System with Power Factor Correction Based on MC68HC908MR32

**AN1857** 3-Phase, AC Motor Control System with Power Factor Correction Based on MC68HC908MR32

AN1664 Cost-Effective 3-Phase AC Motor Control System Based on MC68HC908MR32

AN1590 High-Voltage Medium Power Board for 3-Phase Motors

**AN2149** Compressor Induction Motor Stall and Rotation Detection Using Microcontrollers **AN1853** Embedding Microcontrollers in Domestic Refrigeration Appliances

6-bit AN1918 Indirect Power Factor Correction for 3-Phase AC Motor Control with V/Hz Speed Open Loop Application

AN1930 3-Phase AC Induction Motor Vector Control

**AN1958** 3-Phase AC Motor Control with V/Hz Speed Closed Loop Using the 56F800/E **AN1942** DSP56F80x Resolver Driver and Hardware Interface

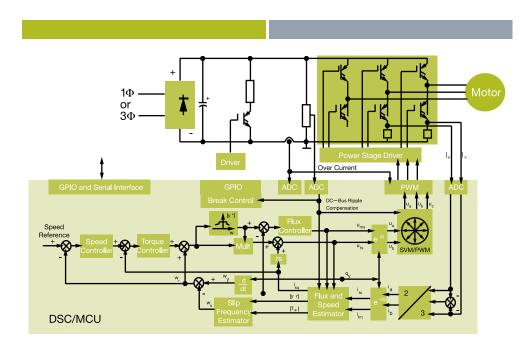
**DRM092** 3-Phase AC Induction Vector Control Drive with Single-Shunt Current Sensing **AN3234** Washing Machine Three-Phase AC Induction Motor Drive

| Reference Designs |  |
|-------------------|--|
| RDDSCACIMVC       | 3-Phase AC Induction Vector Control Drive with Single-Shunt<br>Current Sensing               |
| RDDSP56F8ACVCD    | 3-Phase AC Induction Motor Vector Control Using 56F80X or 56F8300 Digital Signal Controllers |

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# **AC Induction Motors (ACIM)**

# 3-phase ACIM with sensorless field oriented control



### Advantages

- High-precision speed/torque control
- Suitable for drives with high dynamic requirements
- Removal of speed sensor

### **Applications**

- Large appliances
- Industrial compressors
- Water pumps
- Construction machinery
- Universal inverters
- HVAC

### **Application Note**

8-bit AN2154 Cost-Effective, 3-Phase, AC Motor Control System with Power Factor Correction Based on MC68HC908MR32

AN1857 3-Phase, AC Motor Control System with Power Factor Correction Based on MC68HC908MR32

**AN1664** Cost-Effective 3-Phase AC Motor Control System Based on MC68HC908MR32 **AN1590** High-Voltage Medium Power Board for 3-Phase Motors

AN2149 Compressor Induction Motor Stall and Rotation Detection Using Microcontrollers AN1853 Embedding Microcontrollers in Domestic Refrigeration Appliances

16-bit AN1918 Indirect Power Factor Correction for 3-Phase AC Motor Control with V/Hz Speed Open Loop Application

AN1930 3-Phase AC Induction Motor Vector Control

 $\textbf{AN1958} \ 3\text{-Phase AC Motor Control with V/Hz Speed Closed Loop Using the } 56\text{F800/E}$ 

AN1942 DSP56F80x Resolver Driver and Hardware Interface

DRM092 3-Phase AC Induction Vector Control Drive with Single-Shunt Current Sensing AN3234 Washing Machine Three-Phase AC Induction Motor Drive

### **Reference Designs**

**RD56F801XACIM** Design of an ACIM Vector Control Drive Using the 56F801X

### Recommended Devices

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**32-bit MCU:** MCF521x, MCF523x, MPC56x, MPC55xx



# **Permanent Magnet Synchronous Motors (PMSM)**

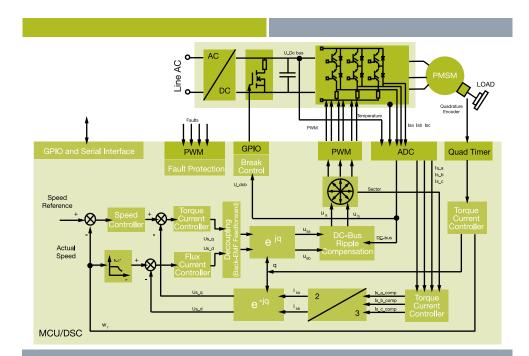
# Sensored field oriented control

### **Advantages**

- Exceptionally low noise operation
- Outstanding drive efficiency
- Precise speed/torque control

### **Applications**

- Robotics
- ElevatorsServo drivers
- Traction systems
- · Industrial motion control
- Automotive



### **Recommended Devices**

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**32-bit MCU:** MCF521x, MCF523x, MPC56x, MPC55xx

### Application Notes

AN2357 Sine Voltage Powered 3-Phase Permanent Magnet Motor with Hall Sensor
AN2149 Compressor Induction Motor Stall and Rotation Detection Using Microcontrollers
AN1853 Embedding Microcontrollers in Domestic Refrigeration Appliances
AN2396 Servo Motor Control Application on a Local Area Interconnect Network (LIN)
DRM036 Sine Voltage Powered 3-Phase Permanent Magnet Synchronous Motor with

16-bit AN1931 3-Phase PM Synchronous Motor Vector Control

AN1942 DSP56F80x Resolver Driver and Hardware Interface

**DRM102** PMSM Vector Control with Single-Shunt Current-Sensing Using MC56F8013/23 **DRM099** Sensorless PMSM Vector Control with a Sliding Mode Observer for

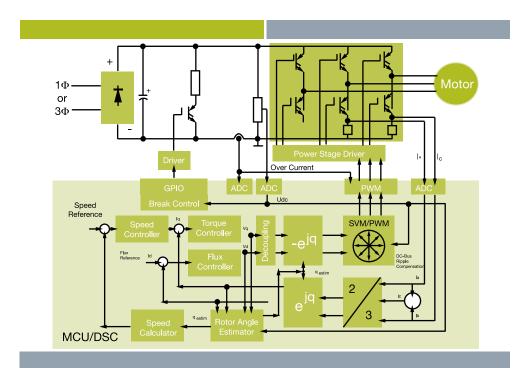
Compressors Using MC56F8013

| Reference Designs |   |
|-------------------|---|
| RD56F8300EMB      | Electro-Mechanical Braking Using 56F8300 Digital Signal Contollers                                    |
| RD56F8300EPAS     | Electronic Power Assisted Steering (EPAS) with 56F8300 Digital Signal Controllers                     |
| RD56F8300FRBBW    | FlexRay Brake-By-Wire Using 56F8300 Digital Signal Controllers  |
| RDDSP56F8PMSDE    | 3-Phase PM Synchronous Motor Control with Quadrature Encoder Using 56F80X Digital Signal Controllers  |
| RDDSP56F8SMTVC    | 3-Phase PM Synchronous Motor Torque Vector Control Using 56F80X or 56F8300 Digital Signal Controllers |

16 www.freescale.com/motorcontrol

# **Permanent Magnet Synchronous Motors (PMSM)**

Low speed sensorless sinusoidal field oriented control



### **Advantages**

- Low-noise operation
- · High drive efficiency
- High-precison speed/torque control
- Suitable for drives with high dynamic
- Removal of speed sensor

### **Applications**

requirements

- Appliances
- HVAC
- Compressors
- Blowers
- Industrial motion controls

### Application Notes

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AN2357 Sine Voltage Powered 3-Phase Permanent Magnet Motor with Hall Sensor
AN2149 Compressor Induction Motor Stall and Rotation Detection Using Microcontrollers
AN1853 Embedding Microcontrollers in Domestic Refrigeration Appliances
AN2396 Servo Motor Control Application on a Local Area Interconnect Network (LIN)
DRM036 Sine Voltage Powered 3-Phase Permanent Magnet Synchronous Motor with Hall

6-bit AN1931 3-Phase PM Synchronous Motor Vector Control
AN1942 DSP56F80x Resolver Driver and Hardware Interface

**DRM102** PMSM Vector Control with Single-Shunt Current-Sensing Using MC56F8013/23 **DRM099** Sensorless PMSM Vector Control with a Sliding Mode Observer for Compressors Using MC56F8013

### Recommended Devices

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**32-bit MCU:** MCF521x, MCF523x, MPC56x, MPC55xx



# **Permanent Magnet Synchronous Motors (PMSM)**

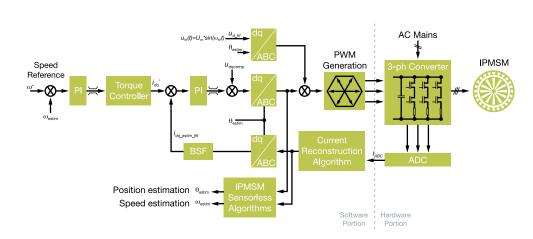
Sensorless sinusoidal field oriented control with zero speed torque capability

### **Advantages**

- Low-noise operation
- High drive efficiency
- High-precison speed/torque control
- Suitable for drives with high dynamic requirements
- · Removal of speed sensor

### **Applications**

- Appliances
- HVAC
- Compressors
- Blowers
- Industrial motion controls



### **Recommended Devices**

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

**32-bit MCU:** MCF521x, MCF523x, MPC56x, MPC55xx

Analog/Mixed Signal Power ICs Motor Driver: MC33927, MC33937

### Application Notes

AN2357 Sine Voltage Powered 3-Phase Permanent Magnet Motor with Hall Sensor
AN2149 Compressor Induction Motor Stall and Rotation Detection Using Microcontrollers
AN1853 Embedding Microcontrollers in Domestic Refrigeration Appliances
AN2396 Servo Motor Control Application on a Local Area Interconnect Network (LIN)
DRM036 Sine Voltage Powered 3-Phase Permanent Magnet Synchronous Motor with Hall Sensors

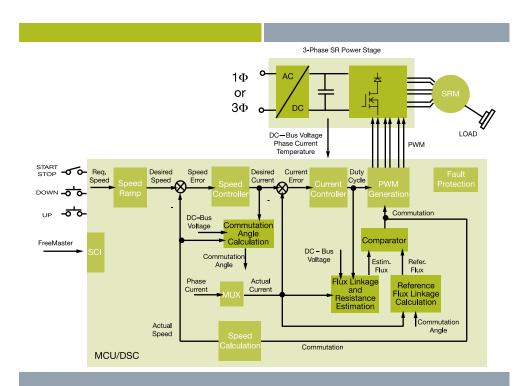
16-bit AN1931 3-Phase PM Synchronous Motor Vector Control

**AN1942** DSP56F80x Resolver Driver and Hardware Interface **DRM102** PMSM Vector Control with Single-Shunt Current-Sensing Using MC56F8013/23

**DRM099** Sensorless PMSM Vector Control with a Sliding Mode Observer for Compressors Using MC56F8013

# **Switch Reluctance Motor Drive**

# Sensorless



### **Advantages**

- Reliable electronics
- High starting torque
- Removal of position sensor

### **Applications**

- Industrial machines
- Medical scanners
- Computers, office equipment
- Toys
- Food processors
- · Vacuum cleaners
- Machine tools
- Large appliances

### Application Notes

16-bi

AN1912 3-Phase Switched Reluctance (SR) Motor Control with Hall Sensors AN1932 3-Phase Switched Reluctance (SR) Sensorless Motor Control DRM100 Sensorless High-Speed SR Motor Drive for Vacuum Cleaners Using an MC56F8013

| Reference Designs |  |
|-------------------|--|
| RDDSP56F8SRDE     | 3-Phase Switched Reluctance Motor Control with Encoder Using 56F80X Digital Signal Controllers                               |
| RDDSP56F8SRDHS    | 3-Phase Switched Reluctance Motor Control with Hall Sensor Reference Design for 56F80X or 56F8300 Digital Signal Controllers |
| RDDSP56F8SRDS     | 3-Phase Switched Reluctance Motor Sensorless Control Reference<br>Design Using 56F80X or 56F8300 Digital Signal Controllers  |

### Recommended Devices

**16-bit DSC:** MC56F80x, MC56F80xx, MC56F83xx

16-bit MCU: S12XE

Analog/Mixed Signal Power ICs Motor Driver: MC33927, MC33937



# **Power ICs for Motor Control Products**

# Analog/mixed-signal integrated circuits with SMARTMOS™ technology

Freescale's analog/mixed-signal and power integrated circuits provide comprehensive electric motor system solutions when coupled with MCUs or DSCs. Freescale's power integrated circuits (ICs) are manufactured using our advanced SMARTMOS™ technology, which enables key protection and performance functions to be monolithically integrated within the power IC silicon. When product designers rely on a printed circuit board loaded with discrete components (and the attendant poor MTBF number), Freescale delivers robust, highly integrated system solutions that provide a long life of reliable and highly functional service.

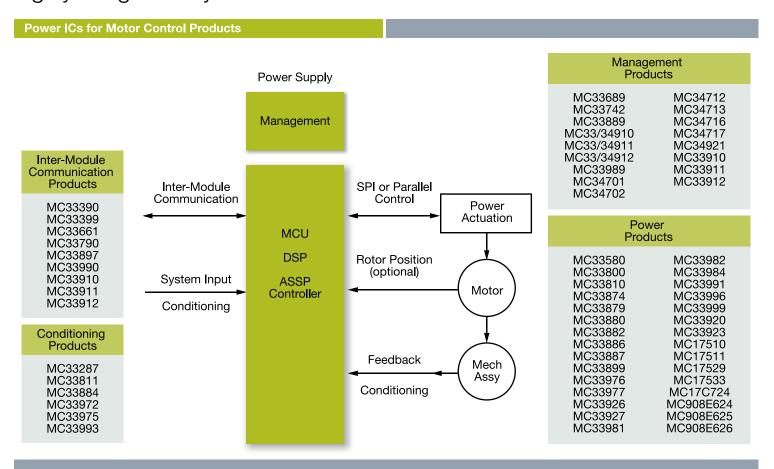
| Motor Types vs.                       | Motor Types vs. Market Power ICs and Applications   |  |   |  |  |  |  |  |  |  |
|---------------------------------------|---|--|---|--|--|--|--|--|--|--|
|                                       | Brush   | Stepper  | Hall-BLDC   | Sensorless   |  |  |  |  |  |  |
| Consumer AV and Portables             | MPC17510, 11<br>DVD Players, Tape<br>Players, Micro<br>Disks, Hobby/Toy                         | MPC17531, 33<br>Camera Lens,<br>8 Shutter Disk<br>Head, Positioner | MCxxxxx<br>Disk Spinning,<br>VCR Head Spin,<br>Heatsink Fans    | MCxxxxx<br>Disk Spinning,<br>VCR Head Spin,<br>Heatsink Fans     |  |  |  |  |  |  |
| Industrial and<br>Automation          | MC34923,<br>MC33926<br>DC Servos and<br>Actuators   | MC34920, 21<br>CNC, Robotics,<br>Pick'n'Place                      | BLDC<br>Derivatives<br>Small Servos,<br>LVDC Fans,<br>Actuators | BLDC<br>Derivatives<br>Servos,<br>LVDC Pumps                     |  |  |  |  |  |  |
| Health Care<br>(Non-Life-<br>Support) | MC33887<br>(Used as a<br>Low-Side<br>Gate Driver)<br>Hospital Beds,<br>Wheelchairs,<br>Scooters | MPC17529<br>Insulin Pumps,<br>BP Monitors                          | BLDC<br>Derivatives<br>CPAP Machines,<br>Air Purifiers          | IDC Derivatives<br>OXY Concen,<br>LVDC Blowers,<br>Air Purifiers |  |  |  |  |  |  |

| Product Selector Guide |   |   |                   |  |                              |   |  |                     |  |                                    |            |
|------------------------|---|---|-------------------|--|------------------------------|---|--|---------------------|--|------------------------------------|------------|
| Product                | Description   | Main<br>Characteristics   | No. of<br>Outputs | R <sub>DS(on)</sub> Ω<br>of Each<br>Output | Current<br>Limitation<br>(A) | Current<br>Limitation<br>Standby<br>Max | Protection<br>Features   | Control             | Status<br>Reporting                          | Packaging                          | Status     |
| MC33887                | H-bridge driver<br>with sleep mode<br>(5.2A)  | 130 mw @ 25C,<br>sleep mode,<br>current sense   | 2                 | 130<br>mΩhms                               | 6                            | 25 μΑ                                   | Short circuit, current limit, temp sense   | Parallel            | One status pin<br>(overcurrent/<br>overtemp) | 20-pin<br>HSSCP<br>54-pin<br>SOICW | Production |
| MC34920                | 0.77W max dual<br>45V H-bridge DC/<br>stepper motors<br>with charge<br>pump and dual<br>regulators, device<br>can be paralleled<br>in H-bridge<br>configuration | Dual 45V<br>H-bridge DC/<br>stepper motor<br>with charge<br>pump and dual<br>regulators | 8                 | 1400<br>mΩhms                              | 2.4 <sup>Note</sup>          | 14 mA<br>(n o m)                        | Overcurrent,<br>undervoltage,<br>overtemp,<br>undervoltage   | Serial<br>I/F       | System reset<br>on faults                    | 44-pin<br>PLCC                     | Production |
| MC34921                | Integrated motor drive IC   | Dual PWM DC<br>motor drive  | 4                 | 700<br>mΩhms                               | 2.5 Note                     | 30 mA                                   | Shoot through undervoltage detect  | Serial<br>I/F       | n/a  | 54-pin<br>SOIC<br>64-pin<br>LQFP   | Production |
| MC34923                | Full-bridge PWM<br>motor driver   | +/-2.0A @<br>45V, 0.27 Ohm<br>RDSON   | 2                 | 270<br>mΩhms                               | 2.0                          | 20 μΑ                                   | Thermal shutdown with hysteresis, cross-over current protection, undervoltage lockout, programmable PWM off-time | Serial,<br>parallel | n/a  | 24-pin<br>SOICW                    | Production |
| MPC17510               | 0.45W H-bridge  | Single 15V<br>H-bridge with<br>charge pump  | 2                 | 450<br>mΩhms                               | 3.0 Note                     | 1.0 mA                                  | Shoot through undervoltage detect  | Parallel            | Shutdown undervolage                         | 24-pin<br>TSSOP                    | Production |
| MPC17511               | 1.0A 6.8V<br>H-bridge motor<br>driver IC  | Drive DC motors<br>or bipolar step<br>motors  | 2                 | 460<br>mΩhms                               | 3.0 Note                     | 1.0 mA                                  | Undervoltage<br>shutdown, cross-<br>conduction<br>suppression  | Parallel            | n/a  | 24-pin<br>QFN, 16-<br>pin VMFP     | Production |
| MPC17529               | 0.7W dual 6.8V<br>with charge<br>pump, 3.3V logic   | Dual 6.8V with charge pump  | 2                 | 700<br>mΩhms                               | 1.4 Note                     | 1.0 mA                                  | Shoot through undervoltage detect  | Parallel            | Shutdown undervolage                         | 20-pin<br>VMFP                     | Production |
| MPC17531               | 0.7W dual 6.8V<br>with charge<br>pump and sleep<br>mode   | Dual 6.8V with charge pump  | 2                 | 700<br>mΩhms                               | 1.4 Note                     | 1.0 mA                                  | Shoot through undervoltage detect  | Parallel            | Shutdown<br>undervolage                      | 20-pin<br>VMFP                     | Production |
| MPC17533               | 0.7W dual 6.8V<br>with external<br>charge pump  | Dual 6.8V with external charge pump   | 2                 | 700<br>mΩhms                               | 1.4 Note                     | <200 mA                                 | Shoot through undervoltage detect  | Parallel            | Shutdown undervolage                         | 16-pin<br>VMFP                     | Production |

Note: peak current value

# **Power ICs for Motor Control Products**

Analog/mixed-signal integrated circuits as part of robust, highly integrated system solutions



Freescale offers the following analog evaluation boards and modules:

| Device P/N | Evaluation Boards and Modules |
|------------|-------------------------------|
| MC33399    | KIT33399DEVB                  |
| MC33661    | KIT33661DEVB                  |
| MC33689    | KIT33689DWBEVB                |
| MC33742    | KIT33742DWEVB                 |
| MC33800    | KIT33800EKEVME                |
| MC33810    | KIE33810EKEVME                |
| MC33880    | KIT33880DWBEVB                |
| MC33887    | KIT33887DWBEVB KIT33887PNBEVB |
| MC33889    | KIT33889DWEVB                 |
| MC33926    | KIT33926PNBEVBE               |
| MC33927    | KIT33927EKEVBE                |
| MC33972    | KIT33972AEWEVBE               |

| Device P/N | Evaluation Boards and Modules |
|------------|-------------------------------|
| MC33975    | KIT33975AEWEVBE               |
| MC33984    | KIT33984PNAEVB                |
| MC33989    | KIT33989DWEVB                 |
| MC33996    | KIT33996EKEVB                 |
| MC33999    | KIT33999EKEVB                 |
| MC34701    | KIT33701DWBEVB                |
| MC34702    | KIT33702DWBEVB                |
| MC34712    | KIT34712EPEVBE                |
| MC34713    | KIT34713EPEVBE                |
| MC34716    | KIT34716EPEVBE                |
| MC34717    | KIT34717EPEVBE                |
| MPC17C724  | KIT17C724EPEVBE               |

Please visit www.freescale.com/analog for more details.



# **8-bit Microcontroller Motor Control Products**

# Feature-rich portfolio that meets all of your 8-bit needs

Freescale's 8-bit portfolio includes several low-end devices that provide cost-effective solutions for motor control applications. From flash to ROM, from 1 KB to 60 KB of memory and from tiny 8-pin QFN to 64-pin quad flat packages, the HCS08 and RS08 families are designed to meet all of your 8-bit needs. They feature peripherals, such as 10-bit A/D convertors and multi-channel timers, which make them ideal candidates for low-end motor control applications.

| 8-bit Product Summary |         |         |          |      |                                       |      |                   |     |      |       |            |                                  |                           |
|-----------------------|---------|---------|----------|------|---------------------------------------|------|-------------------|-----|------|-------|------------|----------------------------------|---------------------------|
| Device                | Flash   | RAM     | ADC      | ;    |                                       | Tin  | ners              |     |      | 5V IO | Analog     | Communications                   | Packages                  |
| Device                | i idəli | T LAW   | Channels | Bits | GPT                                   | ESCI | SPI               | ľC  | ACMP | 00.10 | Comparator | Communications                   | 1 dokages                 |
| МСЗРНАС               | _       | _       | 4        | 10   | _                                     | _    | 6 Output          | N/A | _    | Y     | _          | UART                             | 1, 13, 22                 |
| MC9S08AC              | 128 KB  | 2 KB    | 16       | 10   | 2 x 2-ch. x 16-bit/<br>6-ch. x 16-bit | -    | See GPT           | N   | _    | Υ     | _          | uart, spi, i²c                   | 1, 2, 3, 4, 5             |
| MC9S08DZ              | 128 KB  | 8 KB    | 24       | 12   | 2-ch. x 16-bit/<br>8-ch. x 16-bit     | _    | See GPT           | N   | _    | Υ     | 2          | UART, CAN, SPI, I <sup>2</sup> C | 1, 4, 18, 19              |
| MC9S08GB              | 60 KB   | 4 KB    | 8        | 10   | 3-ch. x 16-bit/<br>5-ch. x 16-bit     | _    | See GPT           | N   | -    | _     | _          | uart, spi, i²c                   | 4, 5                      |
| MC9RS08KA             | 8 KB    | 0.25 KB | 12       | 10   | 2 x 8-bit/2-ch. x 8-bit               | -    | See GPT           | N   |      | Y     | 1          | I <sup>2</sup> C                 | 6, 7, 8, 9                |
| MC908MR               | 32 KB   | 0.75 KB | 10       | 10   | 4-ch. x 16-bit/<br>2-ch. x 16-bit     | _    | 6-ch. x<br>12-bit | Y   | _    | Υ     | _          | uart, spi                        | 5, 23                     |
| MC9S08QD              | 4 KB    | 0.25 KB | 4        | 10   | 2-ch. x 16-bit/<br>1-ch. x 16-bit     | -    | See GPT           | N   | _    | Υ     | _          | _                                | 16, 17                    |
| MC9S08QG              | 8 KB    | 0.5 KB  | 8        | 10   | 2-ch. x 16-bit/<br>1 x 8-bit          | _    | See GPT           | N   | _    | _     | 1          | UART, SPI, I <sup>2</sup> C      | 15, 6, 11, 20, 21         |
| MC9S08SH              | 32 KB   | 1 KB    | 16       | 10   | 2 x 2-ch. x 16-bit/<br>1 x 8-bit      |      | See GPT           | N   | _    | Υ     | 1          | uart, spi, i²c                   | 11, 12, 13,<br>14, 15, 16 |

<sup>\*\*</sup> HDI = Hardware Deadtime Insertion

| 8 Bit Development Tool Summary—HCS08/RS08 |                             |                                  |                                   |                         |   |  |  |  |
|---|-----------------------------|----------------------------------|-----------------------------------|-------------------------|---|--|--|--|
| Family                                    | Part Numbers                | Starter I                        | Kit                               | Advanced Development    |   |  |  |  |
| гаппу                                     | Part Numbers                | Demo Board                       | Software                          | Evaluation Board Kit    | Software  |  |  |  |
|   | MC9S08AC128/96              | DEMOACKIT                        |                                   |                         |   |  |  |  |
| AC  | MC9S08AC60/48/32            | DEMO9S08AC60E<br>DEMO9S08AC60KIT |                                   | DEMOACKIT +<br>DEMOACEX |   |  |  |  |
|   | MC9S08AC16/8                | DEMO9S08AC60E<br>DEMO9S08AC16KIT |                                   | DEMONDEX                |   |  |  |  |
| DZ  | MC9S08DZ128/<br>96/60/32/16 | DEMO9S08DZ60                     |                                   | EVB9S08DZ60             |   |  |  |  |
| GB  | MC9S08GB60/32               | M68DEM0908GB60E                  |                                   | M68EVB908GB60E          | Options starting<br>at \$395. More options<br>and information at<br>www.freescale.com/<br>codewarrior |  |  |  |
| KA  | MC9RS08KA2/1                | DEMO9RS08KA2<br>USBSPYDER08      | CWX-HXX-SE* Compiles up to 32k of |                         |   |  |  |  |
| NA .                                      | MC9RS08KA8/4                | DEMO9RS08KA8<br>USBSPYDER08      | object code                       | EVB9S08DZ60             |   |  |  |  |
| MR  | MC908MR32/16/8              | USBSPYDER08                      |                                   | 21500005200             |   |  |  |  |
| QD  | MC9S08QD4/2                 | DEM09S08QD4                      |                                   |                         |   |  |  |  |
| ŲD  | WIC9300QD4/2                | USBSPYDER08                      |                                   |                         |   |  |  |  |
| QG  | MC9S08QG8/4                 | DEM09S08QG8                      |                                   |                         |   |  |  |  |
| CII                                       | MC9S08SH8/4                 | DEM09S08SH8                      |                                   |                         |   |  |  |  |
| SH  | MC9S08SH32/16               | DEM09S08SH32                     |                                   | _                       |   |  |  |  |

| Package Information |            |             |            |  |  |  |
|---------------------|------------|-------------|------------|--|--|--|
| Number              | Туре       | Size (mm)   | Pitch (mm) |  |  |  |
| 1                   | 32 LQFP    | 7 x 7       | 0.8        |  |  |  |
| 2                   | 44 LQFP    | 10 x 10     | 0.8        |  |  |  |
| 3                   | 48 QFN     | 7 x 7       | 0.5        |  |  |  |
| 4                   | 64 LQFP    | 10 x 10     | 0.5        |  |  |  |
| 5                   | 64 QFP     | 14 x 14     | 0.8        |  |  |  |
| 6                   | 16 LD PDIP | 19 x 6.5    | 2.54       |  |  |  |
| 7                   | 16 LD SOIC | 10.3 x 7.5  | 1.27       |  |  |  |
| 8                   | 20 PDIP    | 24.5 x 7.25 | 2.54       |  |  |  |
| 9                   | 20 LD SOIC | 12.8 x 7.5  | 1.27       |  |  |  |
| 10                  | 80 LQFP    | 14 x 14     | 0.65       |  |  |  |
| 11                  | 16 TSSOP   | 5 x 4.4     | 0.65       |  |  |  |
| 12                  | 20 TSSOP   | 6.5 x 4.4   | 0.65       |  |  |  |
| 13                  | 28 SOIC    | 18 x 7.5    | 1.27       |  |  |  |
| 14                  | 28 TSSOP   | 9.7 x 4.4   | 0.65       |  |  |  |
| 15                  | 24 QFN     | 4 x 4       | 0.50       |  |  |  |
| 16                  | 8 NB SOIC  | 5 x 4       | 1.27       |  |  |  |
| 17                  | 8 PDIP     | 10 x 6.35   | 2.54       |  |  |  |
| 18                  | 48 LQFP    | 7 x 7       | 0.50       |  |  |  |
| 19                  | 100 LQFP   | 14 x 14     | 0.50       |  |  |  |
| 20                  | 16 QFN     | 5 x 5       | 0.80       |  |  |  |
| 21                  | 8 DFN      | 4 x 4       | 0.80       |  |  |  |
| 22                  | 28 DIP     | 37 x 14     | 2.54       |  |  |  |
| 23                  | 56 SDIP    | 52 x 14     | 1.77       |  |  |  |

<sup>\*</sup> Codewarrior Development Studio for HC(S)08 Special Edition is complimentary and is supplied with all Freescale development tools. Upgrade available to support expanded memory sizes with part number CWP-PRO-NL/FL.

# 16-bit MCU and Digital Signal Controller Motor Control Products

Specializing in automotive and DSP processing applications, the S12X and DSCs offer superior functionality in a 16-bit package

16-bit digital signal controller (DSC) products—The 56800 core-based family of DSCs combines the processing power of a DSP and the functionality of a microcontroller, with a flexible set of peripherals on a single chip. This creates an extremely cost-effective motor control solution.

MC9S12XE family will deliver 32-bit performance with all the advantages and efficiencies of a 16 bit MCU.

| 16-bit Product Summary |         |       |            |      |                       |                   |                       |       |       |        |                |                                  |            |
|------------------------|---------|-------|------------|------|-----------------------|-------------------|-----------------------|-------|-------|--------|----------------|----------------------------------|------------|
| Device Flash           | Flash   | RAM   | ADC        | ;    | Timers                |                   |                       |       | 5V IO | Analog | Communications | Packages                         |            |
| Device                 | Гіазіі  | DAIVI | Channels   | Bits | GPT                   | PIT               | PWM                   | HDI** | TPU   | 30 10  | Comparator     | Communications                   | Packages   |
| MC56F801x              | 16 KB   | 4 KB  | 2 x 4-ch.  | 12   | 4 x 16-bit            | See GPT           | 6-ch. x<br>15-bit     | Υ     | _     | Y      | _              | UART, SPI, I <sup>2</sup> C      | 5          |
| MC56F802x              | 32 KB   | 4 KB  | 2 x 8-ch.  | 12   | 2 x 4-ch. x<br>16-bit | 3 x 16-bit        | 6-ch. x<br>15-bit     | Υ     | _     | Y      | 2              | UART, SPI, CAN, I <sup>2</sup> C | 6          |
| MC56F803x              | 64 KB   | 8 KB  | 2 x 8-ch.  | 12   | 2 x 4-ch. x<br>16-bit | 3 x 16-bit        | 6-ch. x<br>15-bit     | Υ     | _     | Y      | 2              | UART, SPI, CAN, I <sup>2</sup> C | 6          |
| MC56F8123/8122         | 32 KB   | 8 KB  | 2 x 4-ch.  | 12   | 2 x 4-ch. x<br>16-bit | _                 | 6-ch. x<br>15-bit     | Υ     | _     | Υ      | _              | UART, SPI                        | 6          |
| MC56F8135              | 64 KB   | 8 KB  | 4 x 4-ch.  | 12   | 2 x 4-ch. x<br>16-bit | _                 | 6-ch. x<br>15-bit     | Υ     | _     | Υ      | _              | UART, SPI, CAN,<br>Quad Decoder  | 7          |
| MC56F8147/8146/8145    | 128 KB  | 8 KB  | 4 x 4-ch.  | 12   | 2 x 4-ch. x<br>16-bit | _                 | 6-ch. x<br>15-bit     | Υ     | _     | Υ      | _              | UART, SPI, Quad<br>Decoder       | 8          |
| MC56F8157/8156/8155    | 256 KB  | 16 KB | 4 x 4-ch.  | 12   | 2 x 4-ch. x<br>16-bit | _                 | 6-ch. x<br>15-bit     | Υ     | _     | Υ      | _              | UART, SPI, Quad<br>Decoder       | 8          |
| MC56F8167/8166/8165    | 512 KB  | 32 KB | 4 x 4-ch.  | 12   | 2 x 4-ch. x<br>16-bit | _                 | 6-ch. x<br>15-bit     | Υ     | _     | Υ      | _              | UART, SPI, Quad<br>Decoder       | 8          |
| MC56F8323/8322         | 32 KB   | 8 KB  | 2 x 4-ch.  | 12   | 2 x 4-ch. x<br>16-bit | _                 | 6-ch. x<br>15-bit     | Υ     | _     | Υ      | _              | UART, SPI, CAN,<br>Quad Decoder  | 6          |
| MC56F8335              | 64 KB   | 8 KB  | 4 x 4-ch.  | 12   | 4 x 4-ch. x<br>16-bit | _                 | 2 x 6-ch. x<br>15-bit | Υ     | _     | Υ      | _              | UART, SPI, CAN,<br>Quad Decoder  | 7          |
| MC56F8347/8346/8345    | 128 KB  | 8 KB  | 4 x 4-ch.  | 12   | 4 x 4-ch. x<br>16-bit | _                 | 2 x 6-ch. x<br>15-bit | Υ     | _     | Υ      | _              | UART, SPI, CAN,<br>Quad Decoder  | 8, 9       |
| MC56F8357/8356/8355    | 256 KB  | 16 KB | 4 x 4-ch.  | 12   | 4 x 4-ch. x<br>16-bit | _                 | 2 x 6-ch. x<br>15-bit | Υ     | _     | Υ      | _              | UART, SPI, CAN,<br>Quad Decoder  | 8, 9       |
| MC56F8367/8366/8365    | 512 KB  | 32 KB | 4 x 4-ch.  | 12   | 4 x 4-ch. x<br>16-bit | _                 | 2 x 6-ch. x<br>15-bit | Υ     | _     | Υ      | _              | UART, SPI, CAN,<br>Quad Decoder  | 8, 9       |
| MC9S12XE               | 1024 KB | 64 KB | 2 x 16-ch. | 12   | 8-ch. x 16-bit        | 8-ch. x<br>16-bit | 8/4-ch. x<br>8/16-bit | Xgate | _     | Υ      | _              | UART, CAN, SPI, I <sup>2</sup> C | 1, 2, 3, 4 |

<sup>\*\*</sup> HDI = Hardware Deadtime Insertion

| DSC De  | velopment Tool Su   | mmary          |             |                      |   |  |
|---------|---------------------|----------------|-------------|----------------------|---|--|
| Family  | Part Numbers        | Starter        | Kit         | Advanced Development |   |  |
| ганну   | Part Numbers        | Demo Board     | Software    | Evaluation Board Kit | Software                                  |  |
|         | MC56F8011           | DEM056F8014-EE |             |                      |   |  |
| 56F8000 | MC56F8013           | DEM056F8013-EE |             | _                    |   |  |
| 300000  | MC56F8014           | DEM056F8014-EE |             |                      |   |  |
|         | MC56F802x/3x        | _              |             | 56F8037EVM           |   |  |
|         | MC56F8123/8122      |                |             | MC56F8367EVME        |   |  |
|         | MC56F8135           |                | CWX-568-SE* |                      | Options starting                          |  |
| 56F8100 | MC56F8147/8146/8145 |                | Compiles up | MOCOCOOCTEVIME       | at \$395. More options and information at |  |
|         | MC56F8157/8156/8155 |                | to 32k of   | MC56F8367EVME        | www.freescale.com/                        |  |
|         | MC56F8167/8166/8165 |                | object code |                      | codewarrior                               |  |
|         | MC56F8323/8322      | _              |             | MC56F8323EVME        |   |  |
|         | MC56F8335           |                |             |                      |   |  |
| 56F8300 | MC56F8347/8346/8345 |                |             | MOCCEOOCZEVIME       |   |  |
|         | MC56F8357/8356/8355 |                |             | MC56F8367EVME        |   |  |
|         | MC56F8367/8366/8365 |                |             |                      |   |  |

|   | Package Information |            |           |            |  |  |  |  |  |  |  |
|---|---------------------|------------|-----------|------------|--|--|--|--|--|--|--|
|   | Number              | Туре       | Size (mm) | Pitch (mm) |  |  |  |  |  |  |  |
|   | 1                   | 80 LQFP    | 14 x 14   | 0.65       |  |  |  |  |  |  |  |
|   | 2                   | 112 LQFP   | 20 x 20   | 0.65       |  |  |  |  |  |  |  |
|   | 3                   | 144 LQFP   | 20 x 20   | 0.5        |  |  |  |  |  |  |  |
|   | 4                   | 208 MAPBGA | 17 x 17   | 1.0        |  |  |  |  |  |  |  |
|   | 5                   | 32 LQFP    | 7 x 7     | 0.8        |  |  |  |  |  |  |  |
|   | 6                   | 64 LQFP    | 12 x 12   | 0.5        |  |  |  |  |  |  |  |
|   | 7                   | 128 LQFP   | 20 x 14   | 0.5        |  |  |  |  |  |  |  |
|   | 8                   | 160 LQFP   | 24 x 24   | 0.5        |  |  |  |  |  |  |  |
| S | 9                   | 160 MAPBGA | 15 x 15   | 1.0        |  |  |  |  |  |  |  |
| U |                     |            |           | <u> </u>   |  |  |  |  |  |  |  |

S12X Development Tool Summary Starter Kit **Advanced Development Part Numbers** Demo Board **Evaluation Board Kit** Software Software MC9S12XEP768/100 Options starting CWX-HXX-SE\* at \$395. More options MC9S12XEQ512/384 Compiles DEM09S12XEP100 EVB9S12XEP100 MC9S12XET256 up to 32k of www.freescale.com/ MC9S12XEG128 codewarrior

<sup>\*</sup> CodeWarrior Development Studio for 56800 Special Edition is complimentary and is supplied with all Freescale 56800 development tools. Upgrade available to support expanded memory sizes with part number CWP-PRO-NL/FL.

<sup>\*</sup> CodeWarrior Development Studio for S12X Special Edition is complimentary and is supplied with all Freescale S12X development tools. Upgrade available to support expanded memory sizes with part number CWP-PRO-NL/FL.



# **32-bit Microcontroller Motor Control Products**

High performance for complex, real-time motor control applications

These 32-bit embedded microcontrollers combine higher performance with increased on-chip functionality to address complex real-time control applications that require more system throughput. Both the ColdFire® family and MPC500 and MPC5500 families built on Power Architecture® technology are capable of fulfilling the most demanding motor control requirements in a wide range of operating environments.

| 32-bit Product Summary |         |        |          |      |                 |             |                       |                |                    |       |            |  |            |
|------------------------|---------|--------|----------|------|-----------------|-------------|-----------------------|----------------|--------------------|-------|------------|--|------------|
| Device                 | Flash   | RAM    | ADC      |      | Timers          |             |                       |                |                    |       | Analog     | Communications                                     | Packages   |
| Device                 | Hasii   | ITAIVI | Channels | Bits | GPT             | PIT         | PWM                   | HDI**          | TPU                | 5V IO | Comparator | Communications                                     | 1 ackages  |
| MCF51AC                | 256 KB  | 32 KB  | 24       | 12   | 6               | _           | 2                     | Υ              | _                  | Υ     | 2          | I <sup>2</sup> C, SPI, CAN                         | 1, 8       |
| MCF521x                | 256 KB  | 32 KB  | 8        | 12   | 4-ch. x 32-bit  | 2 x 16-bit  | 8/4-ch. x<br>8/16-bit | N              | _                  | _     | _          | UART, I <sup>2</sup> C, SPI, CAN                   | 1, 2, 3, 4 |
| MCF521xx               | 128 KB  | 16 KB  | 8        | 12   | 4-ch. x 32-bit  | 2 x16-bit   | 8/4-ch. x<br>8/16-bit | N              | _                  | _     | _          | UART, I <sup>2</sup> C, SPI, CAN                   | 1, 2, 3, 4 |
| MCF5221x               | 128 KB  | 16 KB  | 8        | 12   | 4-ch. x 32-bit  | 2 x16-bit   | 8/4-ch. x<br>8/16-bit | N              | _                  | _     | _          | UART, I <sup>2</sup> C, SPI, CAN,<br>USB           | 1, 2, 3, 4 |
| MCF5222x               | 256 KB  | 32 KB  | 8        | 12   | 4-ch. x 32-bit  | 2 x16-bit   | 8/4-ch. x<br>8/16-bit | N              | _                  | _     | _          | UART, I <sup>2</sup> C, SPI, CAN,<br>USB           | 1, 2, 3, 4 |
| MCF5223x               | 256 KB  | 32 KB  | 8        | 12   | 4-ch. x 32-bit  | 2 x16-bit   | 8/4-ch. x<br>8/16-bit | N              | _                  | _     | _          | UART, I <sup>2</sup> C, SPI, CAN,<br>Ethernet      | 8, 9, 10   |
| MCF523x                | _       | 64 KB  | _        | _    | 4-ch. x 32-bit  | 4 x 16-bit  | See TPU               | eTPU           | 32-ch. eTPU        | _     | _          | UART, CAN, I <sup>2</sup> C, SPI,<br>Ethernet      | 5, 6, 7    |
| MCF5282                | 512 KB  | 64 KB  | 8        | 10   | 4-ch. x 16-bit  | 4 x 16-bit  | 1 x 16-bit            | N              | _                  | Υ     | 1          | UART, CAN, I <sup>2</sup> C, SPI,<br>Ethernet, USB | 7          |
| MPC561/2               |         | 32 KB  | 32       | 10   | 6 x 16-bit      | 1 x 16-bit  | 6 x 16-bit            | TPU            | 2 x 16-ch.         | Υ     | 1          | UART, CAN, SPI                                     | 11         |
| MPC563/4               | 512 KB  | 32 KB  | 32       | 10   | 6 x 16-bit      | 1 x 16-bit  | 6 x 16-bit            | TPU            | 2 x 16-ch.         | Υ     | _          | UART, CAN, SPI                                     | 11         |
| MPC565/6               | 1024 KB | 36 KB  | 40       | 10   | 6 x 16-bit      | 1 x 16-bit  | 6 x 16-bit            | TPU            | 3 x 16-ch.         | Υ     | _          | UART, CAN, SPI                                     | 11         |
| MPC5534                | 1024 KB | 64 KB  | 2 x 40   | 12   | 24-ch. x 24-bit | Part of GPT | _                     | eMIOS/<br>eTPU | 32-ch. eTPU        | Υ     | _          | UART, CAN, SPI                                     | 12, 13     |
| MPC5553                | 1536 KB | 64 KB  | 2 x 40   | 12   | 24-ch. x 24-bit | Part of GPT | _                     | eMIOS/<br>eTPU | 32-ch. eTPU        | Υ     | _          | UART, CAN, SPI                                     | 12, 13, 14 |
| MPC5554                | 2048 KB | 64 KB  | 2 x 40   | 12   | 24-ch. x 24-bit | Part of GPT |                       | eMIOS/<br>eTPU | 2 x 32-ch.<br>eTPU | Υ     | _          | UART, CAN, SPI,<br>Ethernet                        | 12, 13, 14 |
| MPC5565                | 2048 KB | 80 KB  | 2 x 40   | 12   | 24-ch. x 24-bit | Part of GPT | _                     | eMIOS/<br>eTPU | 32-ch. eTPU        | Υ     | _          | UART, CAN, SPI                                     | 13         |
| MPC5566                | 3072 KB | 128 KB | 2 x 40   | 12   | 24-ch. x 24-bit | Part of GPT | _                     | eMIOS/<br>eTPU | 2 x 32-ch.<br>eTPU | Υ     | _          | UART, CAN, SPI,<br>Ethernet                        | 14         |

<sup>\*</sup> Specifications listed are for the superset device in each family. Memory sizes, peripherals and communication options vary by device. Please see appropriate data sheet for further information.

<sup>\*\*</sup> HDI = Hardware Deadtime Insertion

| ColdFire Development Tool Summary |                  |              |             |                             |  |  |  |  |  |  |
|-----------------------------------|------------------|--------------|-------------|-----------------------------|--|--|--|--|--|--|
| Family                            | Part Numbers     | Starter      | Kit         | Advanced Development        |  |  |  |  |  |  |
| ганну                             | Part Numbers     | Demo Board   | Software    | <b>Evaluation Board Kit</b> | Software                                   |  |  |  |  |  |
| MCF51ACxxx                        | MCF51AC256/128   | DEMOACKIT    | CWX-HXX-SE* | DEMOACKIT / DEMOACEX        |  |  |  |  |  |  |
| MCF521x                           | MCF5213/2/1      | M5211DEM0    |             | M5213EVBE                   |  |  |  |  |  |  |
| MICLOSIX                          | MCF5216/4        | M5282LITEKIT |             | M5282EVBE                   | 0 11 1 11                                  |  |  |  |  |  |
| MCF521xx                          | MCF52110/52100   | M52210DEM0   |             | M52211EVB                   | Options starting<br>at \$395. More options |  |  |  |  |  |
| MCF522xx                          | MCF52211/52210   | M52210DEM0   | CWX-MCF-SE* | M52211EVB                   | and information at                         |  |  |  |  |  |
| IVIUFOZZXX                        | MCF52223/1       | _            |             | M52223EVB                   | www.freescale.com/<br>codewarrior          |  |  |  |  |  |
| MCF5223x                          | MCF52235/4/3/1/0 | M52233DEM0   |             | M52235EVB                   | Coucwailloi                                |  |  |  |  |  |
| MCF523x                           | MCF5235/4/3/2    | M5235BCCKIT  |             | M523XEVBE                   |  |  |  |  |  |  |
| MCF528x                           | MCF5282/1/0      | M5282LITEKIT |             | M5282EVBE                   |  |  |  |  |  |  |

| Package Information |            |           |            |  |  |  |  |  |  |
|---------------------|------------|-----------|------------|--|--|--|--|--|--|
| Number              | Туре       | Size (mm) | Pitch (mm) |  |  |  |  |  |  |
| 1                   | 64 LQFP    | 10 x 10   | 0.5        |  |  |  |  |  |  |
| 2                   | 64 QFN     | 9 x 9     | 0.5        |  |  |  |  |  |  |
| 3                   | 81 MAPBGA  | 10 x 10   | 1.0        |  |  |  |  |  |  |
| 4                   | 100 LQFP   | 14 x 14   | 0.5        |  |  |  |  |  |  |
| 5                   | 160 QFP    | 28 x 28   | 0.65       |  |  |  |  |  |  |
| 6                   | 196 MAPBGA | 15 x 15   | 1.0        |  |  |  |  |  |  |
| 7                   | 256 MAPBGA | 17 x 17   | 1.0        |  |  |  |  |  |  |
| 8                   | 80 LQFP    | 12 x 12   | 0.5        |  |  |  |  |  |  |
| 9                   | 112 LQFP   | 20 x 20   | 0.65       |  |  |  |  |  |  |
| 10                  | 121 MAPBGA | 12 x 12   | 1.0        |  |  |  |  |  |  |
| 11                  | 388 MAPBGA | 27 x 27   | 1.0        |  |  |  |  |  |  |
| 12                  | 208 MAPBGA | 17 x 17   | 1.0        |  |  |  |  |  |  |
| 13                  | 324 PBGA   | 23 x 23   | 1.0        |  |  |  |  |  |  |
| 14                  | 416 PGBA   | 27 x 27   | 1.0        |  |  |  |  |  |  |

| MPC Development Tool Summary |              |                     |  |                             |   |  |  |  |  |  |
|------------------------------|--------------|---------------------|--|-----------------------------|---|--|--|--|--|--|
| Family                       | Part Numbers | Starter             | Kit                                      | Advanced Development        |   |  |  |  |  |  |
| Family                       | Part Numbers | Demo Board Software |  | <b>Evaluation Board Kit</b> | Software  |  |  |  |  |  |
| MDCEEvy                      | MPC5553      |                     | CWS-MPC-<br>5500-SE*                     | MPC5553EVBE                 | Options starting at \$395. More options                 |  |  |  |  |  |
| MPC55xx                      | MPC5554      |                     | Compiles up<br>to 128k of<br>object code | MPC5554EVBE                 | and information at<br>www.freescale.com/<br>codewarrior |  |  |  |  |  |
|                              |              |                     |  |                             |   |  |  |  |  |  |

CodeWarrior Development Studio Special Edition for all MPC devices is complimentary, and is supplied with all MPC55xx evaluation Boards. This version of CodeWarrior supports object code sizes up to 128 KB. Upgrade available to support expanded memory sizes. For information on these upgrade options, visit www.freescale.com/codewarrior.

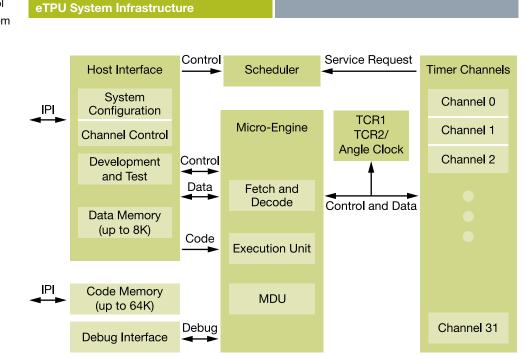
# **32-bit Microcontroller Motor Control Products**

Enhanced time processing unit (eTPU) on the MCF523x and MPC55xx families

The eTPU is a programmable I/O and control module with its own core and memory system dedicated to performing complex timing, control and I/O management functions independently of the main processor.

The eTPU is essentially a microcontroller itself, used in a variety of applications, including general timing functions, serial communications, motor control, custom logic replacement and engine control.

With some applications requiring more than 70 percent of the CPU bandwidth, the eTPU on the MCF523x and MPC55xx is an ideal solution.



| eTPU Functions Library                            |                                       |                                    |  |                                      |  |   |   |  |                               |   |
|---|---------------------------------------|------------------------------------|--|--------------------------------------|--|---|---|--|-------------------------------|---|
| General<br>Timing and<br>Measurement              | General<br>Input-<br>Output<br>(GPIO) | Pulse Width<br>Modulation          | Input<br>Capture                                   | Output<br>Compare                    | Frequency<br>and Period<br>Measurement | Queued<br>Output<br>Match                 | Synchronized<br>Pulse Width<br>Modulation |  |                               |   |
| Communications                                    | Serial Periperal<br>Interface (SPI)   | UART                               | UART with Flow Control                             |                                      |  |   |   |  |                               |   |
| DC Motors   | Motor Speed                           | DC Bus Break<br>Control            | Quadrature<br>Decode                               | Hall Sensor<br>Decode                | Analog Sensing                         | Motor Control<br>PWM                      | Current Control                           | Quadrature<br>Decoder                        | Hall Sensor<br>Decoder        |   |
| AC Motors   | Motor Speed                           | DC Bus Break<br>Control            | Quadrature<br>Decode                               | Hall Sensor<br>Decode                | Analolg Sensing                        | Motor Control<br>PWM                      | ACIM Vector                               | ACIM V/Hz<br>Control                         | PMSM Vector<br>Control        |   |
| Electronic<br>Motors and<br>Controls<br>Supported | CD Open<br>Loop                       | DC Speed<br>Loop with QD           | DC Speed<br>Loop with HD                           | DC Speed<br>Loop and<br>Current Loop | BLDC with HD<br>Open Loop              | BLDC with<br>HD Speed<br>Loop             | BLDC with HD<br>Speed and<br>Current Loop | BLDC with<br>QD Open<br>Loop                 | BLDC with<br>QD Speed<br>Loop | BLDC<br>with QD<br>Speed and<br>Current<br>Loop |
|   | ACIM V/Hz<br>Open Loop<br>with Sine   | ACIM V/Hz<br>Open Loop<br>with SVM | ACIM V/Hz<br>Speed Loop<br>with Sine<br>Wave Drive | ACIM V/Hz<br>Speed Loop<br>with SVM  | ACIM Torque<br>Vector Control          | ACIM Vector<br>Control with<br>Speed Loop | PMSM Torque<br>Vector Control             | PMSM<br>Vector<br>Control with<br>Speed Loop |                               |   |

Freescale provides a free library of eTPU function including C source code, Host C API and detailed application notes. See it all at www.freescale.com/eTPU.

Users may customize library functions and/or develop custom functions using the Byte Craft C Compiler and ASH WARE Simulator.



# **Motor Control Products**

# Algorithms and drivers provided by Processor Expert™

| Microcontroller Di                  | rivers and Algorithms—Available      | in Processor Expert                            |                                     |  |
|-------------------------------------|--------------------------------------|--|-------------------------------------|--|
| Motor Type                          | Available Drivers and Algorithms     |  |                                     |  |
|                                     | Timer                                | PWM  | I/O ports                           |  |
| Standard Drivers                    | Flash                                | SCI  | CAN (DSP only)                      |  |
|                                     | ADC                                  | SPI  | Position Sensing Encoder (DSP only) |  |
|                                     | Power factor                         | Brake control                                  | Board identification                |  |
|                                     | 3-phase waveform generation          | V/Hz and PFC                                   | SCI communication routine           |  |
| AC Induction                        | Space vector modulation              | PI/PID controllers                             | Lookup table                        |  |
|                                     | Ramp                                 | Velocity calculation and estimation            |                                     |  |
|                                     | Switch/push button                   | Position calculation and estimation            |                                     |  |
|                                     | BLDC commutation handler with sensor | BLDC with sensors                              | Switch control                      |  |
|                                     | BLDC commutation handler, sensorless | Ramp board identification                      | SCI communication routine           |  |
| Brushless DC                        | PI/PID controllers                   | Switch/push button                             |                                     |  |
|                                     | Position calculation and estimation  | Velocity calculation and estimation            |                                     |  |
|                                     | BLDC with zero crossing              | Brake control                                  |                                     |  |
|                                     | SR commutation handler               | Switch/push button                             | Brake control                       |  |
|                                     | SR commutation angle calculation     | PI/PID controllers                             | Switch control                      |  |
| Switched Reluctance                 | SR with sensors                      | Velocity calculation and estimation            | Board identification                |  |
|                                     | SCI communication routine            | Position calculation and estimation            |                                     |  |
|                                     | Ramp                                 | Look-up table                                  |                                     |  |
| 16-bit Digital Sign                 | al Controller Drivers and Algorit    | hms—Available in Processor Expert              |                                     |  |
|                                     | ADC                                  | DAC  | Quadrature Decoder                  |  |
|                                     | MSCAN                                | Analog Comparator                              | PIT                                 |  |
|                                     | Flash                                | GPIO GPIO                                      | Interrupt Controller                |  |
| Standard Drivers                    | PLL                                  | PWM  | Quad Timer                          |  |
|                                     | Serial/SCI (also with LIN)           | SPI  | Posix Timer                         |  |
|                                     | SIM                                  | SSI  | TOD                                 |  |
|                                     | FlexCAN                              |  |                                     |  |
|                                     | I <sup>2</sup> C                     | Terminal                                       | Button                              |  |
| Drivers for off-Chip<br>Peripherals | BLDC                                 | LED  | Brake                               |  |
| Топрпогаю                           | Codec                                | EEPROM/Flash (SPI Bus Serial)                  | Switch                              |  |
| Toolo                               | PC Master                            | File I/O                                       | JTAG Flash Loader                   |  |
| Tools                               | FreeMaster                           | RTOS Support                                   | MicroC/OS-II                        |  |
| NA:I                                | Serial Boot Loader                   | Data Structures (FIFO)                         | Cycle Count                         |  |
| Miscelaneous                        | Stack Check                          | Test   |                                     |  |
|                                     | 3-Phase Sine Wave Generation         | Clarke/Park Transformation                     | Space Vector Modulation             |  |
|                                     | Ramp                                 | D-Q System (2-Phase)                           | FOC Decoupling                      |  |
|                                     | BLDC Commutation Handler w/Sensors   | BLDC Commutation Handler Sensorless-Zero Cross | SR Commutation Handler              |  |
| Markara O 1 Al                      | PI/PID Controllers                   | Velocity Calculation and Estimation            | Look-up Table                       |  |
| Motor Control Algorithms            | Brake Control                        | Switch Control                                 | Flux Model                          |  |
|                                     | Brushless DC w/Encoder               | AC Induction Motors V/Hz Closed Loop           | Digital Power Factor Correction     |  |
|                                     | Wave Generate                        | Phase Flux Estimation                          |                                     |  |
|                                     |                                      |  |                                     |  |

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# **Additional Motor Control Application Notes** and Reference Designs

| <b>Applicati</b> | on Notes                               |   |  |  |  |  |  |
|------------------|--|---|--|--|--|--|--|
| AN1976           | Migrating from SDK to Processor Expert |   |  |  |  |  |  |
| AN1920           | DSP56800 Hardware Interface Techniques |   |  |  |  |  |  |
| AN1926           | Production F                           | Flash Programming 56F80x, 56F826 and 56F827   |  |  |  |  |  |
| AN1933           | Synchroniza                            | tion of On-Chip Analog to Digital Converter   |  |  |  |  |  |
| AN1935           | Programming JTAG/OnCE                  | g On-Chip Flash Memories of DSP56F80x DSPs Using the Interface                                |  |  |  |  |  |
| AN1947           | DSP56800 A                             | DSP56800 ADC  |  |  |  |  |  |
| AN1948           | Real-Time D                            | evelopment of MC Applications PC Master Software Visualization Tool                           |  |  |  |  |  |
| AN1952           | Using Progra                           | am Memory as Data Memory  |  |  |  |  |  |
| AN1965           | Design of Inc                          | direct Power Factor Correction  |  |  |  |  |  |
| AN1973           | Production F                           | Flash Programming   |  |  |  |  |  |
| AN1974           | 56F8300 and                            | 56F8100 ADC   |  |  |  |  |  |
| AN1975           | Multiple Targ                          | et Features Using Processor Expert and CodeWarrior  |  |  |  |  |  |
| AN3118           | Production F                           | lash Programming for the 56F8000 Family   |  |  |  |  |  |
| AN3103           | 56F8000 Clo                            | ock Generation Guidelines to Ensure Correct Functionality                                     |  |  |  |  |  |
| AN3102           | Unique Feat                            | ures of the 56F801x Family of Devices   |  |  |  |  |  |
| AN2395           | PC Master S                            | oftware Usage   |  |  |  |  |  |
| AN2263           | PC Master S                            | oftware: Creation of Advanced Control Pages   |  |  |  |  |  |
| AN2095           | Porting and                            | Optimizing DSP56800 Applications to DSP56800E   |  |  |  |  |  |
| AN1999           | 56F8300 Hyl                            | orid Controller Used in Control of Electro-Mechanical Brake                                   |  |  |  |  |  |
| AN1994           | Start-Up Co                            | nsiderations for 56F8300 and 56F8100 Family Devices   |  |  |  |  |  |
| AN1991           | Controlling F                          | Power Consumption in 56F8300 and 56F8100 Family Devices                                       |  |  |  |  |  |
| AN1983           | Software Co                            | mpatibility Considerations for HCS12, HC16 and 56800/E Devices                                |  |  |  |  |  |
| AN1980           | Using the 56                           | F83xx Temperature Sensor  |  |  |  |  |  |
| AN1734           | Pulse Width                            | Modulation Using the 16-bit Timer   |  |  |  |  |  |
| Referenc         | e Designs                              |   |  |  |  |  |  |
| RDHC08A          | CIM                                    | PWM Control of the Single-Phase AC Induction Motor Using the MC68HC908QT4 MCU                 |  |  |  |  |  |
| RDDSC56          | F8xxxPFC                               | Direct PFC Using the MC56F8013  |  |  |  |  |  |
| RD68HC908ACIMDTC |  | 3-Phase AC Induction Motor Drive with Dead Time Distortion Correction Using the MC68HC908MR32 |  |  |  |  |  |
| RD68HC908ACIMVHD |  | 3-Phase AC Induction Motor Drive with Tachogenerator Using MC68HC908MR32                      |  |  |  |  |  |
| RDDSP56          | F8ACIMVHD                              | 3-Phase ACIM Volt Per Hertz Motor Control Using 56F80X or 56F8300 Digital Signal Controllers  |  |  |  |  |  |
| RDMC3PHAC        |  | General-Purpose 3-Phase AC Industrial Motor Controller Reference Design                       |  |  |  |  |  |
| RD68HC9          | 08SVPMD                                | Sine Voltage Powered 3-Phase Permanent Magnet Synchronous Motor with Hall Sensors             |  |  |  |  |  |
|                  |  |   |  |  |  |  |  |



# **Motor Control Product Development Tools**

Hardware and software tools and reference designs that work for you

# Start with your idea

Then use Freescale's Interactive Development Tool Ecosystem to design a development process that fulfills your specific needs.

Begin by selecting software and hardware tools you need to complete your design.

Get your product to market, on time and on budget.



# **Development Hardware**

**Demonstration boards (DEMOs)** give designers a cost-effective platform to program and debug project application code, with basic I/O functions and I/O headers for easy expandability. It may be all you need for product evaluation before moving to prototyping.

**Evaluation boards (EVBs)** provide more functionality than demo boards with expanded capabilities. Programmers have the option to either step up to an EVB after initial evaluation on a demo board, or they can start with an EVB and move directly to prototyping.

**BDM debug cables** like the USB multilink and the open source BDM (OSBDM) are the link between the IDE running on your PC and the target hardware. These interfaces allow full, non-intrusive in-circuit emulation, are and are provided by Freescale and our partners and are integrated in every Freescale Evaluation board. Acquiring one of these standalone cables is essential when designing a custom board.





# Development Software

**Software development tools,** including CodeWarrior Development Studio and other third-party tools, provide a comprehensive set of integrated development environment (IDE) options, as well as other development tools such as debuggers, emulators, RTOSes, stacks and drivers.

**Drivers and Stacks** provide everything needed to begin using a complex module without spending any time writing module-specific code. Freescale and our Tools Alliance Program partners offer many drivers and stacks for all of our devices.

Freescale offers a comprehensive ecosystem of product development tools that can help you successfully complete your product design. Our extensive library of hardware, software tools and reference designs are designed to enable fast and inexpensive product development. This leads to fast time to market and cost-effective solutions.

- CodeWarrior—The backbone of
  Freescale's software development tools is
  the CodeWarrior Integrated Development
  Environment (IDE). With compiler, debugger,
  linker, editor, assembler and other features,
  the CodeWarrior IDE, makes C/C++ sourcelevel debugging and embedded application
  development as worry-free as possible. The
  CodeWarrior tool suite is consistent across
  all supported platforms, without host-to
  host incompatibilities.
- Processor Expert—CodeWarrior
   Development Studios can also come
   with UNIS Processor Expert, a Rapid
   Application Design (RAD) component-based
   application builder and system integration
   tool. This tool enables component-oriented
   programming, provides tested, ready-to use code and delivers instant functionality
   of generated code. (See table on the next
   page for a list of algorithms and software
   examples provided by Processor Expert)
- Freescale software tools include GNU support plus additional development tools from a large network of third-party vendor partners.
- Comprehensive evaluation kits include demo boards, serial cables, quick start guides and CodeWarrior software development tools with Processor Expert. The kits give developers a comprehensive package to develop and evaluate applications using Freescale solutions.
- FreeMASTER is a free and intuitive application development tool for all motor control devices from 8- to 32-bit. This powerful diagnostic and demonstration tool allows real-time debugging and remote control of an application from a user friendly graphical environment running on a PC.
   FreeMASTER supports: HC(S)08, S12X, DSP66F800, MC56F8300, MC56F8100, MC56F8000, MPC5XXX and ColdFire® families of devices.

In addition to all of the above, you can test drive our development tools and products through virtual labs and benefit from our motor control tutorials found at Freescale's Embedded Learning Center.



# **Specialized Motor Control Development Tools**

# Accelerate application development and speed time to market

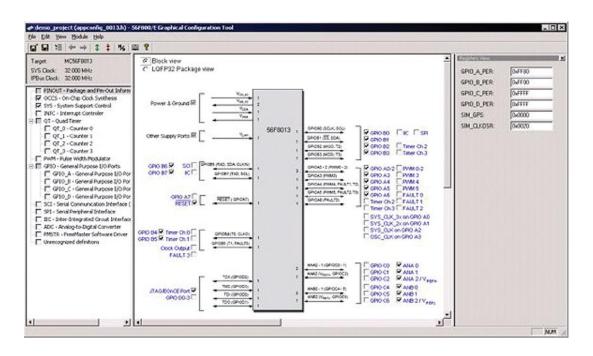
Freescale provides complimentary start-up and diagnostic development tools that are unique to the industry. These are the DSP56800E Quick Start Initialization and Development Tool and the FreeMASTER Real-Time Control and Debugging Tool.

The DSP56800E Quick Start Initialization and Development Tool is a software environment for embedded applications development. It is based on the graphical configuration tool (GCT) and a unified application programming

interface (API)-style of accessing the peripheral modules. The Quick Start toolset helps users to accelerate the application development, to become quickly familiar with the target device and to create real-time applications rapidly and efficiently while retaining complete control over each portion of the underlying hardware.

The DSP56800E Quick Start toolset was specially designed for the real-time applications written in C or mixed

Assembler/C languages where a deterministic behavior and transparent software structure are required. It provides a software infrastructure that allows development of efficient applications that are portable and reusable between devices within the architecture family or even between different architectures. The Quick Start tool complements the other development and initialization tools for Freescale processors like Processor Expert or RAppID.

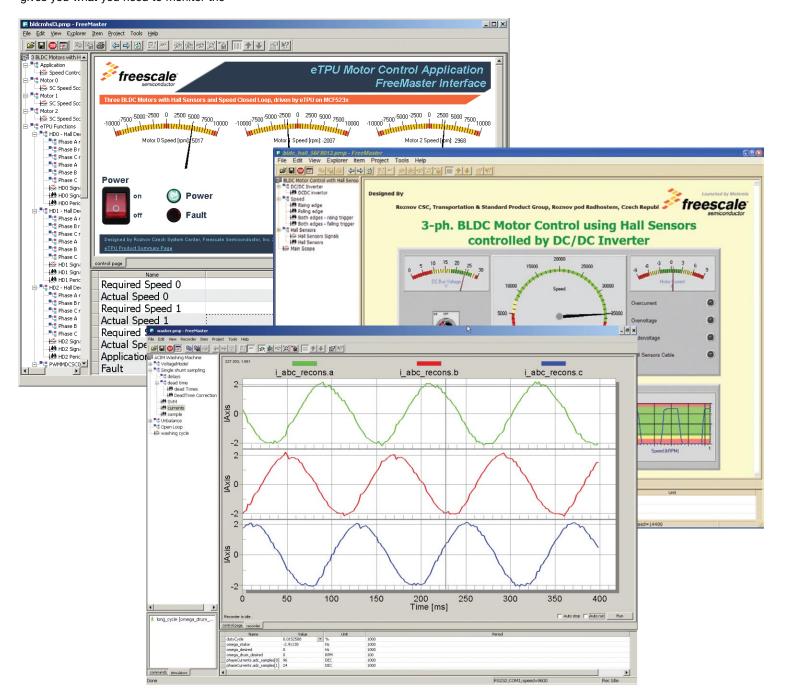


FreeMASTER software (formerly known as PC Master) represents a sophisticated tool with intuitive navigation that can be used in any application development. This tool allows control of an application remotely from a user-friendly graphical environment running on a PC. It also provides the ability to view real-time application variables in both textual and graphical form. FreeMASTER gives you what you need to monitor the

system in real-time, control the embedded application form a PC and demonstrate advanced capabilities of Freescale driven solutions. Designers may take advantage of the versatility and use FreeMASTER for multipurpose algorithms and applications. It may be used for real-time debugging, diagnostics as well as for demonstration, sales and educational purposes.

Below are some examples of interfaces created in FreeMaster for different motor control applications.

For additional information on these tools, as well as others like Processor Expert and Rappid, please go to **www.freescale.com**.



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# Software Library Set for MC56F80XX and MCF51AC Families

# Software libraries GFLIB, MCLIB, GDFLIB used to build digital control systems

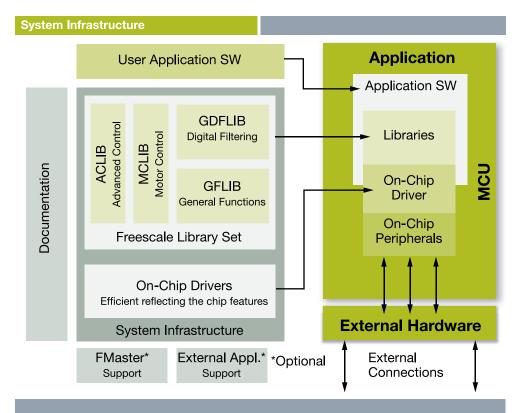
The software libraries for MC56F80XX and MCF51AC families are designed to construct digital control systems for different motor types. The libraries contain software modules implemented in optimized assembly form and having C-callable function interface.

General Function Library (GFLIB) contains math, trigonometric, look-up table and control functions. These software modules are basic building blocks.

Motor Control Library (MCLIB) contains vector modulation, transformation and specific motor related functions to build digitally controlled motor drives.

General Digital Filter Library (GDFLIB) contains filter functions for signal conditioning. Upcoming Advanced Control Library (ACLIB) will contain functions to enable building the variable speed AC motor drive systems with field oriented control techniques without a position or speed transducer.

Individual libraries are delivered in library modules and are intended for use in small data memory model projects. The interfaces to the algorithms included in these libraries have been combined into a single public interface file. This is done to simplify the number of files required for inclusion by application programs. Refer to the specific algorithm sections of user document for details on the software Application Programming Interface (API).



# Motor Control Libraries General Function Library (GFLIB)

- Sine, cosine, tangent
- Inverse sine, cosine, tangent\*
- · Two-argument inverse tangent\*
- Signum\*
- . 1D look-up table\*
- Hysteresis\*
- Square root
- Ramp, dynamic ramp
- Limitation on input signalProportional-integral (PI)
- Proportional-integral (PI) controller of parallel form\*
- Proportional-integral (PI) controller of recurrent form

# Motor Control Library (MCLIB)

- Clark, inverse clark
- Dork inverse perk
- Park, inverse park
- Vector limitation
- DC bus voltage ripple elimination

**Digital Filter Library** 

· 1st order IIR filter

2nd order IIR filter

· Moving average filter

Simplified MA filter\*

- Space vector modulation techniques
- PM motor decoupling
- ACIM flux model
- Annie treating about
- Angle tracking observer
- Back EMF observer for PM motor
   Callian authorisis and a great and a g
- · Saliency tracking observer

For more information on these libraries, please contact your Freescale sales represenative.

# **Design Resources—Quick Start**

Freescale offers easily accessible products, tools and services to help you speed your product to market

### **Freescale Fast Track**

The companies that win the race to market with new product designs often become market leaders in their industries. Freescale Fast Track helps you win that race, accelerating the development cycle by providing immediate services at every step of the design process. Fast Track opens the door to assistance programs that not only will help you be the first to market but also be the best in market. Below are just a few of our Fast Track services.

Embedded Learning Center provides a wealth of online technical training courses and Webcasts—24 hours a day, 7 days a week—that can bring you up to speed on our latest products, tools and technologies.

**DevToolDirect** is an easy way to order Freescale development tools, software and third-party design tools directly online for shipment anywhere in the world.

**Online Samples Program** is simple and straightforward, starting with an "Order Sample" button next to a selected product that begins an easy three-step request process.

Technical Support is available online by our worldwide team of specialists. Your personal data is protected by an e-mail-ID/password combination, and each service request is assigned a number to enable easy follow-up communication.

To access Freescale's Fast Track services, visit freescale.com/fasttrack.



### Web Links

Freescale Motor Control Solutions Homepage freescale.com/motorcontrol

Freescale 8-bit Microcontrollers Homepage freescale.com/8bit

Freescale 16-bit DSC Homepage freescale.com/dsc

Freescale 16-bit Microcontrollers Homepage freescale.com/16bit

Freescale 32-bit ColdFire Microcontrollers

Homepage freescale.com/coldfire

Freescale Power Architecture Homepage

Homepage freescale.com/powerarchitecture

Freescale eTPU Homepage freescale.com/etpu

Freescale Analog Products Homepage freescale.com/analog

Freescale Sensor Products Homepage freescale.com/sensors

Freescale Design Tools Search freescale.com/tools

Freescale CodeWarrior Software Development Tools freescale.com/codewarrior

<sup>\*</sup> Indicates library is available only for MC56F80xx devices.



Learn More: For more information about Freescale products, please visit www.freescale.com/motorcontrol.

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