

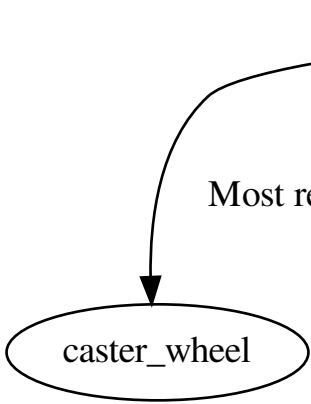
view_frames Result

Recorded at time: 1591795410.851

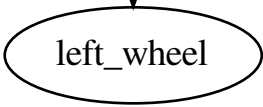
base_footprint

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Most recent transform: 0.000 (1591795410.851 sec old)
Buffer length: 0.000 sec

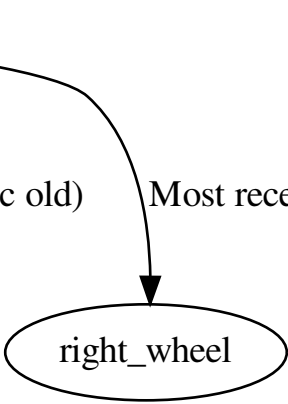
base_link



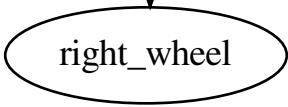
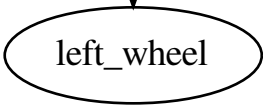
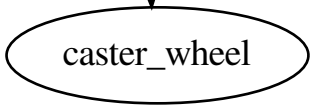
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Most recent transform: 1591795410.801 (0.049 sec old)
Buffer length: 4.900 sec



Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1591795410.801 (0.049 sec old)
Buffer length: 4.900 sec



Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1591795410.801 (0.049 sec old)
Buffer length: 4.900 sec



caster_wheel

left_wheel

right_wheel