```
view_frames Result

Recorded at time: 1591797029.274
```

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1591797029.274 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1591797029.221 (0.054 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1591797029.221 (0.054 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1591797029.221 (0.054 sec old)
Buffer length: 4.800 sec

caster_wheel

left_wheel

right_wheel