

# Lecture #07 - Multi-file programs and Make

AMath 483/583

# Announcements

- Quick tutorial: using Jupyter to create PDFs
- Homework #2 - online after lecture
- Today:
  - multi-file C programs
  - Python  $\longleftrightarrow$  C interfaces
  - Primary References on syllabus

# Function Prototypes

```
#include <stdio.h>
```

```
int main() {  
    int a = 2;  
    int b = square(a);    // equals 4  
}
```

```
int square(int x) {  
    return x*x;  
}
```

# Function Prototypes

```
#include <stdio.h>

int main() {
    int a = 2;
    int b = square(a);
}

int square(int x) {
    return x*x;
}
```

Compile Error!

- Compile-time checking for function existence **from top down**
- square(int) is undefined at time of call in main()
- Solution: use function prototype

# Function Prototypes

```
#include <stdio.h>
```

```
int square(int x); // “prototype”
```

```
int main() {  
    int a = 2;  
    int b = square(a); // equals 4  
}
```

```
int square(int x) {  
    return x*x;  
}
```

# Function Prototypes

```
#include <stdio.h>
```

```
int square(int x); //
```

```
int main() {  
    int a = 2;  
    int b = square(a);  
}
```

```
int square(int x) {  
    return x*x;  
}
```

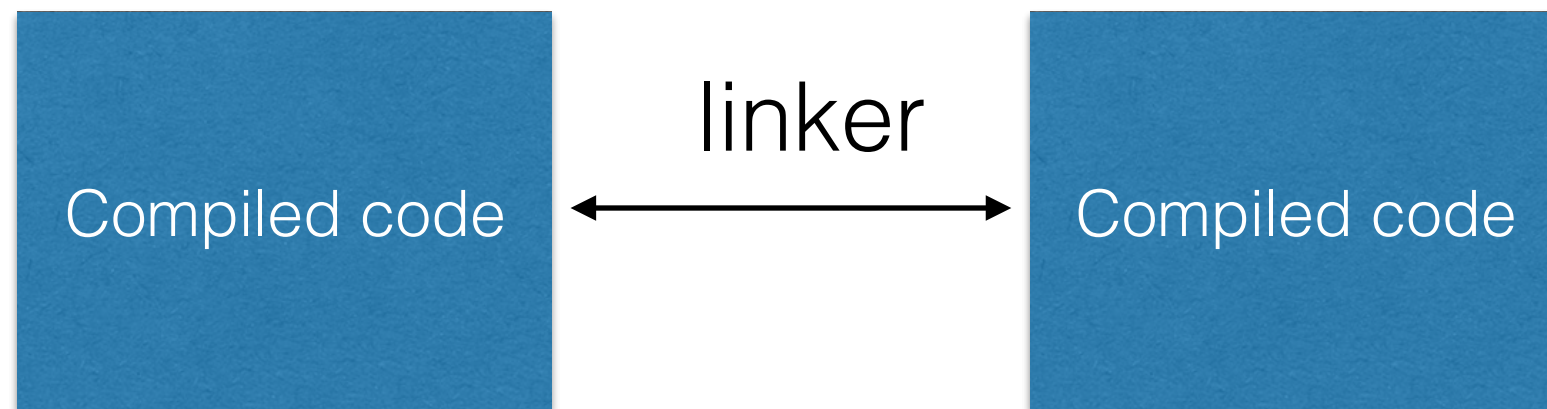
Also declares the “signature” of square -  
return type and arg type

“Header files” (e.g. “stdio.h”) contain  
function prototypes

# Compiling and Linking

- 1) compile C code into machine code
- 2) “link” to other compiled code to find missing function definitions
  - “headers” define prototypes
  - “compiled code” contains function definitions

- 



# Two Types of Compiled Code

- **Executables**

- entry point for a program
- something with `int main()` defined

- **Libraries**

- stand-alone, non-executable
- grouping of functionality
- distributable



# Multi-file Code

```
// main.c
void sub1();
void sub2();
int main() {
    printf("In main\n");
    sub1();
    sub2();
    return 0;
}
```

```
// sub1.c
void sub1() {
    printf("In sub1\n");
}
```

```
// sub2.c
void sub2() {
    printf("In sub2\n");
}
```

# Multi-File Code

- Method 1: compile all three together and link to single executable

```
$ gcc main.c sub1.c sub2.c -o main.exe
```

- Run:

```
$ ./main.exe
```

```
In main
```

```
In sub1
```

```
In sub2
```

# Multi-File Code

- Method 2: split into separate “binaries”...

```
$ gcc -c main.c sub1.c sub2.c
```

```
$ ls ./*.o
```

```
main.o  sub1.o  sub2.o
```

- ...explicitly link files:

```
$ gcc ./*.o -o ./main2.exe
```

```
$ ./main2.exe
```

```
...
```

# Multi-File Code

- **Advantage:** if we change `sub2.c` we only need to recompile it (and re-link everything)

```
$ gcc -c sub2.c
```

```
$ gcc ./*.o -o main3.exe
```

```
$ ./main3.exe
```

```
...
```

- Large codes have long compile times

# Header Files

- Recall at top of main.c:

```
sub1(); // function prototypes  
sub2();
```

- How do you know the signature from a different source file? What if you only have a binary?
- **Header files:** *prototypes for corresponding definitions in a binary*

# Header Files

```
// main.c
```

```
#include "sub1.h"  
#include "sub2.h"
```

```
int main() {  
    printf("In main\n");  
    sub1();  
    sub2();  
    return 0;  
}
```

```
// sub1.h  
void sub1();
```

```
// sub1.c  
void sub1() {  
    printf("In sub1\n");  
}
```

```
// sub2.h  
void sub2();
```

```
// sub2.c  
void sub2() {  
    printf("In sub2\n");  
}
```

# Header Files

```
// main.c
```

```
#include "sub1.h"  
#include "sub2.h"
```

```
int main() {  
    printf("In main\n");  
    sub1();  
    sub2();  
    return 0;  
}
```

```
// sub1.h  
void sub1();
```

#include copies the text in  
sub1.h verbatim before compiling

"C preprocessor"

```
// sub2.c  
void sub2() {  
    printf("In sub2\n");  
}
```

# Header Files

```
// main.c
```

```
#include "sub1.h"  
#include "sub2.h"
```

```
int main() {  
    printf("In main\n");  
    sub1();  
    sub2();  
    return 0;  
}
```

At compile-time main.c is identical to:

```
// main.c
```

```
void sub1();  
void sub2();
```

```
int main() {  
    printf("In main\n");  
    sub1();  
    sub2();  
    return 0;  
}
```

```
);
```

```
);
```



# Header Files

- Need to tell compiler where to look for headers:  
happens at compile-time

```
$ gcc -I. -c main.c sub1.c sub2.c
```

```
$ gcc ./*.o -o main4.exe
```

```
$ ./main4.exe
```

```
...
```

# Libraries

- `sub1.c` and `sub2.c` contain useful code — distribute as a “library”

*“implementation of behavior with well-defined interface”*

- **Examples:**
  - blas / lapack — linear algebra libraries
  - openmp / mpi — parallel code libraries

# Libraries

- The “don’t do this way”:
  - distribute each `sub.o` file and corresponding header `sub.h`
  - messy
- **Instead:** group object files into one library.

# Static Libraries

- Use the “archiver tool”:

```
$ gcc -c sub1.c sub2.c
```

```
$ ar rcs sub1.o sub2.o -o libsubs.a
```

- Linking:

```
$ gcc -L. -lsubs main.c -o main5.exe
```

# Static Libraries

- Use the

```
$ gcc
```

```
$ ar
```

`-Ldir`

add `dir` to the list of directories to check for a  
compiled libraries

- Linking

```
$ gcc -L. -lsubs main.c -o main5.exe
```

# Static Libraries

- Use the

```
$ gcc  
$ ar
```

`-lname`

look for libraries matching the name

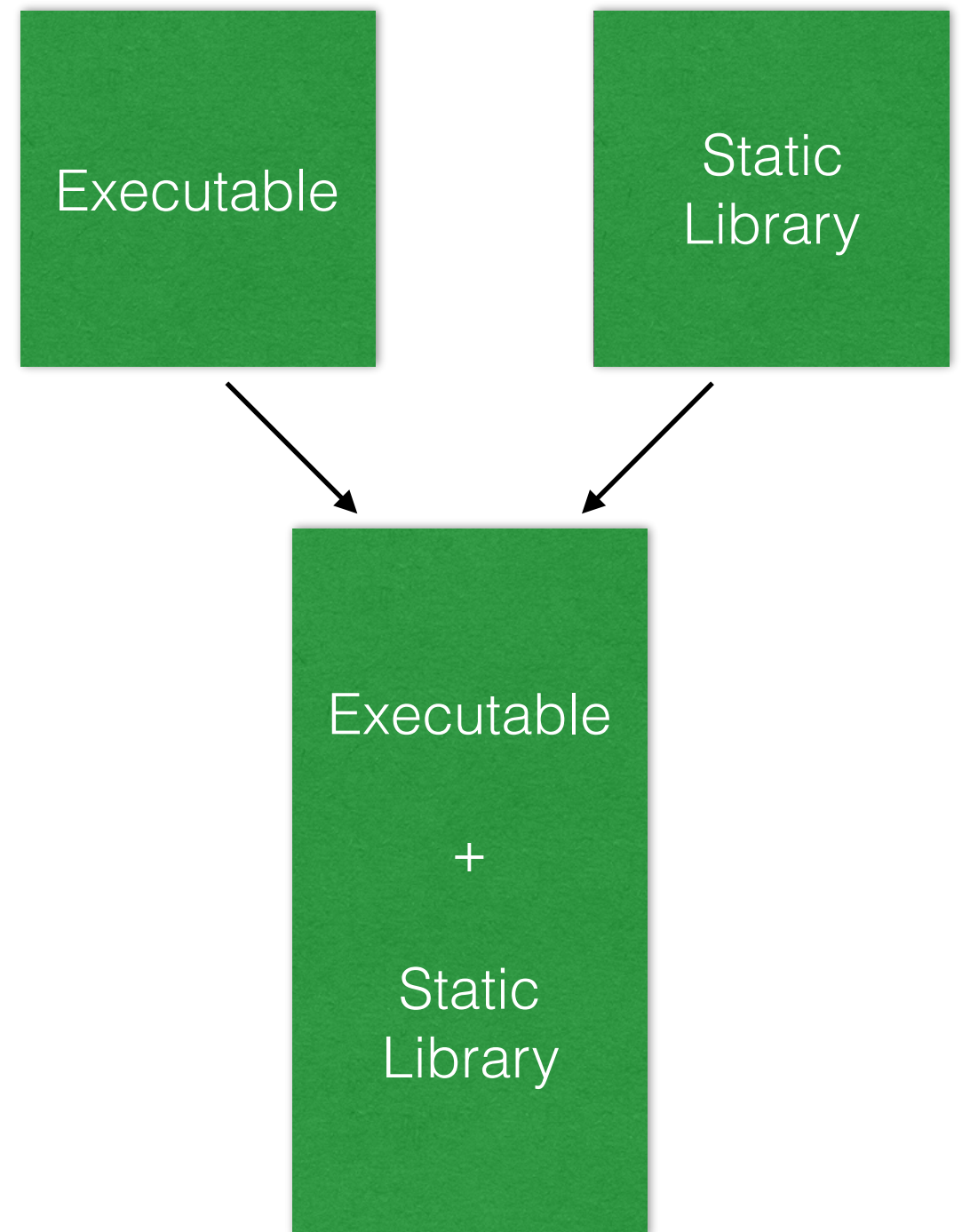
`lname.{a,so}`

- Linking

```
$ gcc -L. -lsubs main.c -o main5.exe
```

# Static Libraries

- Disadvantages:
  - library is loaded at compile time
  - creates a “fat binary” with all library data
- Why make two copies of the library?



# Dynamic Libraries

- Use the `-fPIC` and `-shared` flags:

```
$ gcc -c -fPIC sub1.c sub2.c
```

```
$ gcc -shared -o libsubs.so ./subs*.o
```

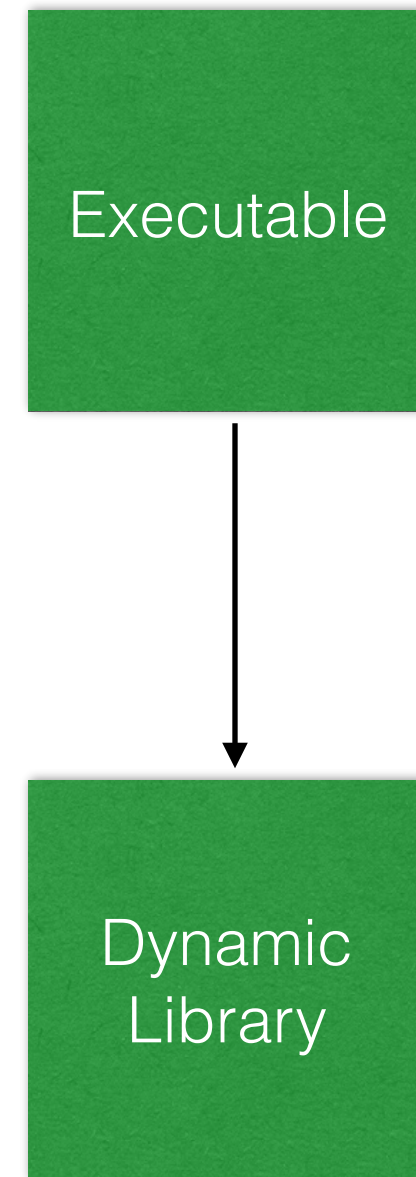
- Linking:

```
$ gcc -L. -lsubs main.c -o main5.exe
```



# Dynamic Libraries

- Advantages:
  - library is loaded at run time (linking establishes connection)
  - no copies of contents



# Makefiles

- Tedious having to:
  - type compile and linking commands
  - keep track of changed files (no need to recompile unchanged files)
- *Makefiles* are a “compile script”:
  - make, cmake, scons, ...

# Makefiles

```
main.exe: libsubs.so
```

```
    gcc -L. -lsubs main.c -o main.exe
```

```
libsubs.so: sub1.o sub2.o
```

```
    gcc -shared -o libsubs.so sub1.o sub2.o
```

```
main.o: main.c
```

```
    gcc -c main.c
```

```
sub1.o: sub1.c
```

```
    gcc -c -fPIC sub1.c
```

```
sub2.o: sub2.c
```

```
    gcc -c -fPIC sub2.c
```

# Makefiles

```
main.exe: libsubs.so
```

```
gcc -L. -lsubs main.c -o main.exe
```

```
libsubs.so: sub1.o sub2.o
```

```
gcc -shared -o libsubs.so sub1.o sub2.o
```

command(s)

target

dependencies

```
main.c
```

```
main.c
```

```
sub1.c
```

```
gcc -c -fPIC sub1.c
```

```
sub2.o: sub2.c
```

```
gcc -c -fPIC sub2.c
```

# Makefiles

- See primary references for details
- You won't need to write them for this class but it is important to understand (used everywhere)

# Interfacing Python with C

- C Code can be called by Python
- Often, Python “wrappers” are created:
  - `C code`: `int is_prime(int n)`
  - `Python`:  

```
def is_prime(n): # calls C's is_prime
```
- Software design: easy to use **and** fast

# Interfacing Python with C

- Two common tools:
  - **ctypes** — included with Python, simple
  - **cython** — almost different language but very powerful, highly recommended (but beyond scope of class)

# Demo

Interfacing with C Code using ctypes