DETAILS
ESCON 70/10, 4-Q Servocontroller for DC/EC motors, 10/30 A, 10 - 70 VDC
Part number 422969



PRICE SCALES	Quantity	Price per unit
Prices excluding VAT and shipping costs	1-4	€351.37
	5-19	€330.37
	20-49	€307.28
	from 50	On request

Start combination

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1

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Specifications	Description	Downloads	Videos
Specifications			
PRODUCT			
Weight	259 g		
MOTOR			
DC motors up to	700 W		
EC motors up to	700 W		
SENSOR Without sensor (DC motors)	Yes		
DC tacho	Yes		
Digital incremental encoder (2-channel, single-ended)	Yes		
Digital incremental encoder (2-channel, differential)	Yes		
Digital incremental encoder (3-channel, differential)	Yes		
al Hall sensors (EC Motors)	Yes		
OPERATING MODES			

:54 PM	
Current controller	Yes
Speed controller (open loop)	Yes
Speed controller (closed loop)	Yes
ELECTRICAL DATA	
Operating voltage V _{cc} (min.)	10 V
Operating voltage V _{cc} (max.)	70 V
Max. output voltage (factor * V _{cc})	0.95
Max. output current I _{max}	30 A
Max. time of peak output current I_{max}	20 s
Continuous output current Icont	10 A
PWM clock frequency of power stage	53.6 kHz
Sampling rate PI current controller	53.6 kHz
Sampling rate PI speed controller	5.36 kHz
Max. efficiency	98 %
Max. speed (DC)	150000 rpm
	150000 ***
Max. speed (EC; 1 pole pair) block commutation	150000 rpm
	15 µH
Built-in motor choke per phase	15 µH
Built-in motor choke per phase INPUTS Hall sensor signals	15 μH H1, H2, H3
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals	15 μH H1, H2, H3 A, A, B, B\
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency	15 μH H1, H2, H3 A, A, B, B\ 1 MHz
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs	15 μH H1, H2, H3 A, A, B, B\ 1 MHz 2
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency	15 μH H1, H2, H3 A, A, B, B\ 1 MHz
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CW+CCW, enable + direction of rotation, stop,
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs Resolution, range, circuit	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2 12-bit, -10+10V, differential
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs Resolution, range, circuit Functionality of analog inputs	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2 12-bit, -10+10V, differential Set value, current limit, offset, speed ramp
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs Resolution, range, circuit Functionality of analog inputs Potentiometers Functionality of the	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2 12-bit, -10+10V, differential Set value, current limit, offset, speed ramp 2
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs Resolution, range, circuit Functionality of analog inputs Potentiometers Functionality of the potentiometers	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2 12-bit, -10+10V, differential Set value, current limit, offset, speed ramp 2
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs Resolution, range, circuit Functionality of analog inputs Potentiometers Functionality of the potentiometers OUTPUTS	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2 12-bit, -10+10V, differential Set value, current limit, offset, speed ramp 2 set value, current limit, offset, speed ramp, gain, IxR factor
Built-in motor choke per phase INPUTS Hall sensor signals Encoder signals Max. encoder input frequency Digital inputs Functionality of digital inputs Analog inputs Resolution, range, circuit Functionality of analog inputs Potentiometers Functionality of the potentiometers OUTPUTS Digital outputs	H1, H2, H3 A, A, B, B\ 1 MHz 2 Enable, enable CW, enable CCW, enable CW+CCW, enable + direction of rotation, stop, PWM set value, RC Servo set value, fixed set value 2 12-bit, -10+10V, differential Set value, current limit, offset, speed ramp 2 set value, current limit, offset, speed ramp, gain, IxR factor
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GE OUTPUTS

Hall sensor supply voltage	+5 VDC, max.	30 mA
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Encoder supply voltage	+5 VDC, max. 70 mA
Auxiliary output voltage	+5 VDC, max. 10 mA
INTERFACE	
USB 2.0 (full speed)	Yes
DISPLAY	
Status indicator "Ready"	green LED
Status indicator "Error"	red LED
PROTECTIVE FUNCTIONS	
Protective functions	current limit, overcurrent, excess temperature, undervoltage, overvoltage, voltage transients, short-circuits in the motor cable
AMBIENT CONDITIONS	
Temperature – Operation (min.)	-30 °C
Temperature – Operation (max.)	45 °C
Temperature – Extended Range	+45+82°C, Derating: -0.27 A/°C
Temperature – Storage (min.)	-40 °C
Temperature – Storage (max.)	85 °C
Humidity (non-condensing) (min.)	5 %
Humidity (non-condensing) (max.)	90 %
MECHANICAL DATA	
Weight	259 g
Dimension (length)	125 mm
Dimension (width)	78.5 mm
Dimension (height)	27 mm
Mounting	Flange for M4 screws
SOFTWARE	
	ESCON Satura
Installation program	ESCON Studio
Graphical User Interface	ESCON Studio Windows 10. 9. 7. Windows VD SD2
Operating system	Windows 10, 8, 7, Windows XP SP3

Description

The **ESCON 70/10** is a small-sized, powerful 4-quadrant PWM servo controller for the highly efficient control of permanent magnet-activated brushed DC motors or brushless EC motors up to approximately 700 Watts.

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- IWARE/FIRMWARE

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Diagnostics Tool 03:01 min



Data Recorder Tool 03:55 min



Help at your fingertips 05:59 min



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Startup Wizard (EC motor) 05:35 min



ESCON Studio – Startup Wizard (DC Motor) 04:37 min



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