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Moving Robot

Design Document

Table of Contents

[Revision History 2](#_Toc44712761)

[Introduction 3](#_Toc44712762)

[Problem Description 4](#_Toc44712763)

[TASK-1 5](#_Toc44712764)

[Solution 5](#_Toc44712765)

# Revision History

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| --- | --- | --- | --- |
| Version | Date | Name | Comment |
| 0.1 | 04-Jul-2020 | Awad A. Bekhet | Initial document |
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# Introduction

Design document for Tasks for Embedded SW Design course.

# Problem Description

A Moving Robot has 4-DC motors and can move in four directions; forward, backward, right and left.

The robot has a character LCD to display the moving direction.

At power-up:

* The robot moves forward with increasing speed from 0% to 100% speed for 5 seconds.
* The robot enters a running state.

At Running State:

* The robot decreases its speed gradually to 50% in 5 seconds.
* Robot rotates right 90 degrees clockwise.
* The robot decreases its speed gradually to 0% in 5 seconds.

# TASK-1

1. Extract the modules from moving robot requirements.
2. Design modules’ APIs.

## Proposed Solution

1. Modules:
   * Port
   * Dio
   * Robot
   * MotorDc: 4-Instances per DC Motor
   * Pwm
   * Print
   * LcdChar
   * System
   * Timer



1. Modules’ APIs

|  |  |
| --- | --- |
| Module | APIs |
| PORT | Port\_Init |
| DIO | Dio\_Init Dio\_ReadPin Dio\_WritePin Dio\_ReadPort Dio\_WritePort |
| LcdChar | LcdChar\_Init LcdChar\_SetLcdState(ON|OFF) LcdChar\_SetPosition(X, Y) LcdChar\_Write LcdChar\_SetBacklight(0%-100%) LcdChar\_SendCommand |
| Print | Print\_Init Print\_WriteString Print\_WriteValue |
| PWM | Pwm\_Init Pwm\_DeInit Pwm\_SetDuty Pwm\_SetPeriodAndDuty |
| Timer | Timer\_Init Timer\_Start Timer\_Stop Timer\_EnableNotification Timer\_DisableNotification |
| MotorDc | MotorDc\_Init MotorDc\_DeInit MotorDc\_Start(Forward|Backward) MotorDc\_Stop  MotorDc\_SetSpeed |
| Robot | Robot\_Init  Robot\_SetDirectionAngle  Robot\_SetSpeed |
| System | System\_Init |

Q.:

* HW behavior and Proposed Controllers to check how to achieve that on the controller? Right!
* Reqs. are not clear enough.