

SIMILARITY OF MATRICES:

An $n \times n$ matrix B is called similar to an $n \times n$ matrix A

if
$$B = P^{-1}AP$$

for some non-singular matrix P .

Th: If B is similar to A then B has the same eigenvalues as A .

If x is an eigenvector of A then $y = P^{-1}x$ is an eigenvector of B corresponding to the same eigenvalue.

Proof:

$$Ax = \lambda x$$

$$\Rightarrow \lambda P^{-1}x = P^{-1}Ax$$

$$\Rightarrow \lambda P^{-1}x = P^{-1}A(P P^{-1})x = B(P^{-1}x)$$

$\Rightarrow \lambda$ is an eigenvalue of B and $P^{-1}x$ a corresponding eigenvector.

Note: Similar matrices have the same determinant.

DIAGONALIZATION OF A MATRIX

A matrix A is diagonalizable if there exists a non-singular matrix P and a diagonal matrix D such that

$$P^{-1}AP = D.$$

THEOREM: An $n \times n$ matrix A is diagonalizable iff it has n linearly independent vectors.

THEOREM: An $n \times n$ matrix A is diagonalizable if its all the eigenvalues are real and distinct.

Remark: The matrix P which diagonalizes A is called modal matrix of A whose columns are the eigenvectors corresponding to different eigenvalues.

Ex: 1: $A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$ eigenvalues 1 6
eigenvectors $\begin{bmatrix} -1 \\ 1 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix}$

$$P = \begin{bmatrix} -1 & 4 \\ 1 & 1 \end{bmatrix} \quad P^{-1} = -\frac{1}{5} \begin{bmatrix} 1 & -4 \\ -1 & -1 \end{bmatrix}$$

$$P^{-1}AP = \begin{bmatrix} 1 & 0 \\ 0 & 6 \end{bmatrix}.$$

Ex: 2: $A = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$ eigenvalues 2 2 8
eigenvectors: $\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$

$$P = \begin{bmatrix} 1 & -1 & 2 \\ 2 & 0 & -1 \\ 0 & 2 & 1 \end{bmatrix}$$

$$P^{-1}AP = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{bmatrix}.$$

Ex: 3: $A = \begin{bmatrix} 2 & 0 & 0 \\ 4 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ Eigenvalues 2 2 3
eigenvectors $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

The given matrix is not diagonalizable.

Application of Diagonalization:

a) Power of matrices:

$$\bar{P}^{-1} A P = D$$

$$\Rightarrow A = P D \bar{P}^{-1}$$

$$\begin{aligned} A^2 &= (P D \bar{P}^{-1})(P D \bar{P}^{-1}) \\ &= P D (\bar{P}^{-1} P) D \bar{P}^{-1} \end{aligned}$$

$$A^2 = P D^2 \bar{P}^{-1}$$

$$A^3 = (P D^2 \bar{P}^{-1})(P D \bar{P}^{-1})$$

$$A^3 = P D^3 \bar{P}^{-1} \quad \dots \quad \boxed{A^n = P D^n \bar{P}^{-1}}$$

Ex: Find A^5 for $A = \begin{bmatrix} 1 & 4 \\ 4 & 0 \end{bmatrix}$

Eigenvalues $-1 \quad 2$

Eigenvectors $\begin{bmatrix} 2 \\ -1 \end{bmatrix} \quad \begin{bmatrix} 4 \\ 1 \end{bmatrix}$

$$P = \begin{bmatrix} 2 & 4 \\ -1 & 1 \end{bmatrix} \quad \bar{P}^{-1} = \frac{1}{6} \begin{bmatrix} 1 & -4 \\ 1 & 2 \end{bmatrix}$$

$$A^5 = \frac{1}{6} \begin{bmatrix} 2 & 4 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} (-1)^5 & 0 \\ 0 & 2^5 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 2 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 2 & 4 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 32 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 21 & 44 \\ 5.5 & 10 \end{bmatrix}$$

b)

system of linear differential equation

$$\dot{x}(t) = Ax(t)$$

$$D = P^{-1}AP \Rightarrow A = PD P^{-1}$$

$$\Rightarrow \dot{x}(t) = PD P^{-1} x(t)$$

$$\Rightarrow [P^{-1}x(t)]' = D[P^{-1}x(t)]$$

Substitute: $P^{-1}x(t) =: y(t)$

then: $\dot{y}(t) = Dy(t)$

$$\Rightarrow \begin{bmatrix} \dot{y}_1(t) \\ \vdots \\ \dot{y}_n(t) \end{bmatrix} = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} y_1(t) \\ \vdots \\ y_n(t) \end{bmatrix}$$

$$\Rightarrow \dot{y}_i(t) = \lambda_i y_i(t) \Rightarrow y_i(t) = C_i e^{\lambda_i t} \quad \neq i$$

$$\Rightarrow x(t) = P y(t)$$

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Quadratic forms:

A function $q(x_1, x_2, \dots, x_n)$ from \mathbb{R}^n to \mathbb{R} of the form

$$q(x_1, x_2, \dots, x_n) = \sum_{i \leq j} a_{ij} x_i x_j$$

is called a quadratic form.

A quadratic form can be written as

$$q(x_1, x_2, \dots, x_n) = q(x) = x^T A x$$

for a symmetric matrix A .

Ex: Consider the quadratic form:

$$q(x_1, x_2) = 3x_1^2 + 10x_1x_2 + 2x_2^2.$$

Find a symmetric matrix A such that $q(x_1, x_2) = x^T A x$.

Sol:

$$A = \begin{bmatrix} 3 & 5 \\ 5 & 2 \end{bmatrix}.$$

$$\text{Check: } x^T A x = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 3x_1 + 5x_2 \\ 5x_1 + 2x_2 \end{bmatrix}$$

$$= 3x_1^2 + 5x_1x_2 + 5x_2x_1 + 2x_2^2$$

$$= 3x_1^2 + 10x_1x_2 + 2x_2^2$$

- Note that making A symmetric is important for a unique representation of A .

Ex: Consider the quadratic form $q(x_1, x_2, x_3) = 9x_1^2 + 7x_2^2 + 3x_3^2 - 2x_1x_2 + 4x_1x_3 - 6x_2x_3$.

Find the corresponding matrix A .

Sol:

$$A = \begin{bmatrix} 9 & -1 & 2 \\ -1 & 7 & -3 \\ 2 & -3 & 3 \end{bmatrix}$$

The general 3 dimensional quadratic form:

$$a_{11}x_1^2 + a_{22}x_2^2 + a_{33}x_3^2 + a_{12}x_1x_2 + a_{13}x_1x_3 + a_{23}x_2x_3$$

Can be written as

$$[x_1 \ x_2 \ x_3] \begin{bmatrix} a_{11} & \frac{1}{2}a_{12} & \frac{1}{2}a_{13} \\ \frac{1}{2}a_{12} & a_{22} & \frac{1}{2}a_{23} \\ \frac{1}{2}a_{13} & \frac{1}{2}a_{23} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Def: Let A be an $n \times n$ symmetric matrix, then A is: (valid for non-symmetric matrices)

- a) Positive definite if $x^T A x > 0$ for all $x \neq 0$ in \mathbb{R}^n
- b) Positive semidefinite if $x^T A x \geq 0$ for all $x \neq 0$ in \mathbb{R}^n
- c) negative definite if $x^T A x < 0$ for all $x \neq 0$ in \mathbb{R}^n
- d) negative semidefinite if $x^T A x \leq 0$ for all $x \neq 0$ in \mathbb{R}^n and
- e) indefinite if $x^T A x \leq 0$ for some x in \mathbb{R}^n and $x^T A x > 0$ for some other x in \mathbb{R}^n .

The Principal Axes Theorem: Let A be an $n \times n$ symmetric matrix.

Then there is an (orthogonal) change of variable,
 $x = Py$ that transforms the quadratic form $x^T A x$ into
 a quadratic form $y^T D y$ with no cross product term.

Ex: Find out what type of curve the equation $8x_1^2 - 4x_1x_2 + 5x_2^2 = 1$ represents:

By the transformation $x = Py$ we can transform the given equation to:
 $9y_1^2 + 4y_2^2 = 1$ where 9 & 4 are the eigenvalues of
 This represents the ellipse.

$$A = \begin{bmatrix} 8 & -2 \\ -2 & 5 \end{bmatrix}.$$