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In [1]: # HSV Color
import cv2
import numpy as np

for i in range(1,12):
    frame = cv2.imread("./images/{i}.jpg".format(i))
    new_width = 640
    new_height = 480

    # Resize the frame
    frame = cv2.resize(frame, (new_width, new_height))
    blurred_frame = cv2.GaussianBlur(frame, (5, 5), 0)
    hsv = cv2.cvtColor(frame, cv2.COLOR_BGR2HSV)

    blue = 142
    lower = np.array([0,0,40])
    upper = np.array([225,225,blue])
    mask = cv2.inRange(hsv, lower, upper)
    contours, _ = cv2.findContours(mask, cv2.RETR_TREE, cv2.CHAIN_APPROX_NONE)
    # print(type(contours))

    c = 0
    for contour in contours:
        area = cv2.contourArea(contour)

        if area > 2000:
            temp_blue = blue
            rect = cv2.boundingRect(contour)
            x, y, w, h = rect
            roi = frame[y:y+h, x:x+w]
            h_roi = hsv[y:y+h, x:x+w]

            # If the area is tooooooooo large. The contour contains more than one ob
            if area > 60000:
                segment = []
                while len(segment) < 1:
                    temp_blue -= 3
                    lower = np.array([0,0,40])
                    upper = np.array([225,225,temp_blue])
                    mask = cv2.inRange(h_roi, lower, upper)
                    new_contours, _ = cv2.findContours(mask, cv2.RETR_TREE, cv2.CHAIN_APPROX_NONE)
                    filtered_contours = []
                    for cont in new_contours:
                        narea = cv2.contourArea(cont)
                        if narea > 2000:
                            filtered_contours.append(cont)
                    if len(filtered_contours) > 1:
                        segment += filtered_contours

                for cont in segment:
                    rect = cv2.boundingRect(cont)
                    x, y, w, h = rect
                    new_roi = roi[y:y+h, x:x+w]
                    cv2.imwrite('./res/{i}-object{c}.jpg'.format(i,c), new_roi)
                    c += 1
                # cv2.rectangle(frame, (x, y), (x + w, y + h), (0, 255, 0), 2)

            continue

    cv2.imwrite('./res/{i}-object{c}.jpg'.format(i,c), roi)
    c += 1

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#         cv2.rectangle(frame, (x, y), (x + w, y + h), (0, 255, 0), 2)

#     cv2.imwrite('./res/segment{}.jpg'.format(i), frame)
cv2.destroyAllWindows()
```

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In [2]: from sentence_transformers import SentenceTransformer, util
import matplotlib.pyplot as plt
from PIL import Image
import glob
import os
import numpy as np

def calculate_histogram(image_path, width, height):
    image = Image.open(image_path)
    image = image.resize((width, height), Image.ANTIALIAS)
    array = np.array(image)

    # Calculate histogram for each color channel
    hist_r, _ = np.histogram(array[:, :, 0], bins=256, range=[0, 256])
    hist_g, _ = np.histogram(array[:, :, 1], bins=256, range=[0, 256])
    hist_b, _ = np.histogram(array[:, :, 2], bins=256, range=[0, 256])

    # Concatenate the histograms for all color channels
    hist = np.concatenate((hist_r, hist_g, hist_b))

    # Normalize the histogram
    hist = hist.astype(float) / np.sum(hist)

    return hist

def compare_color_similarity(image_path1, image_path2, width, height):
    hist1 = calculate_histogram(image_path1, width, height)
    hist2 = calculate_histogram(image_path2, width, height)

    # Calculate Bhattacharyya coefficient
    similarity = np.sum(np.sqrt(hist1 * hist2))

    return similarity

def getMostSim(contains, objectpath, processed_images):

    most_sim = processed_images[0]
    max_score = 0
    # find images that has the largest image[0]
    for image in processed_images:
        if (image[1] <= 4 and image[2]<=4):
            continue
        image_path1 = objectpath[image[1]]
        image_path2 = objectpath[image[2]]
        similarity_score = compare_color_similarity(image_path1, image_path2, 500, 500)
        # print(most_sim)

        n_img = image_path2.replace('./res\\', '')
        img_num = n_img.split('-')[0]
        exist = contains[img_num]

        obj_name = image_path1.replace('./object\\', '')
        obj_name = obj_name.replace('@.jpg', '')

        score = (image[0]+2*similarity_score)/3
        # print("cur most_sim: ", most_sim, similarity_score)
        if ((most_sim[1] <= 4 and most_sim[2]<=4) or (score > max_score))and obj_n
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        most_sim = image
        max_score = score
    return max_score, most_sim

# Load the OpenAI CLIP Model
print('Loading CLIP Model...')
model = SentenceTransformer('clip-ViT-B-32')

# Next we compute the embeddings
# To encode an image, you can use the following code:
# from PIL import Image
# encoded_image = model.encode(Image.open(filepath))
image_names = list(glob.glob('./res/*.jpg'))
print("Images:", len(image_names))
objectpath = list(glob.glob('./object/*.jpg'))

correct_list = {"Box": [],
                "Airpods": [],
                "Cup": [],
                "Book": [],
                "Controler": []}
contains = {'1': [], '2': [], '3': [], '4': [], '5': [], '6': [], '7': [], '8': [], '9': [],

for imagepath in image_names:
    objectpath.append(imagepath)

    encoded_image = model.encode([Image.open(filepath) for filepath in objectpath],
    processed_images = util.paraphrase_mining_embeddings(encoded_image)

    score, most_sim = getMostSim(contains, objectpath, processed_images)

    _, image_id1, image_id2 = most_sim

    if image_id1 <= 4 and image_id2 <= 4:
        objectpath.pop()
        continue

    object_img = objectpath[image_id1]
    n_img = objectpath[image_id2].replace('./res\\', '')
    print("n_img: ", n_img)

    obj_name = object_img.replace('./object\\', '')
    obj_name = obj_name.replace('@.jpg', '')

    img_num = n_img.split('-')[0]

    if score > 0.65 and obj_name not in contains[img_num]:
        contains[img_num].append(obj_name)
        correct_list[obj_name].append(n_img)

    objectpath.pop()

delimiter = ', '
for key, value in contains.items():
    image_path = f"./images/{key}.jpg"
    image = plt.imread(image_path)
    plt.imshow(image)
    result = delimiter.join(value)
    plt.title(result)
    plt.show()

print(correct_list)

```

Loading CLIP Model...

ftfy or spacy is not installed using BERT BasicTokenizer instead of ftfy.

Images: 46

C:\Users\Anna Feng\AppData\Local\Temp\ipykernel_16256\926398296.py:10: DeprecationWarning: ANTIALIAS is deprecated and will be removed in Pillow 10 (2023-07-01). Use LANCZOS or Resampling.LANCZOS instead.

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image = image.resize((width, height), Image.ANTIALIAS)
```

n_img: 1-object0.jpg

n_img: 1-object1.jpg

n_img: 1-object2.jpg

n_img: 1-object3.jpg

n_img: 10-object0.jpg

n_img: 10-object1.jpg

n_img: 10-object2.jpg

n_img: 10-object3.jpg

n_img: 10-object4.jpg

n_img: 11-object0.jpg

n_img: 11-object1.jpg

n_img: 11-object2.jpg

n_img: 11-object3.jpg

n_img: 2-object0.jpg

n_img: 2-object1.jpg

n_img: 2-object2.jpg

n_img: 2-object3.jpg

n_img: 3-object0.jpg

n_img: 3-object1.jpg

n_img: 3-object2.jpg

n_img: 3-object3.jpg

n_img: 4-object0.jpg

n_img: 4-object1.jpg

n_img: 4-object2.jpg

n_img: 4-object3.jpg

n_img: 5-object0.jpg

n_img: 5-object1.jpg

n_img: 5-object2.jpg

n_img: 6-object0.jpg

n_img: 6-object1.jpg

n_img: 6-object2.jpg

n_img: 6-object3.jpg

n_img: 7-object0.jpg

n_img: 7-object1.jpg

n_img: 7-object2.jpg

n_img: 8-object0.jpg

n_img: 8-object1.jpg

n_img: 8-object2.jpg

n_img: 8-object3.jpg

n_img: 8-object4.jpg

n_img: 8-object5.jpg

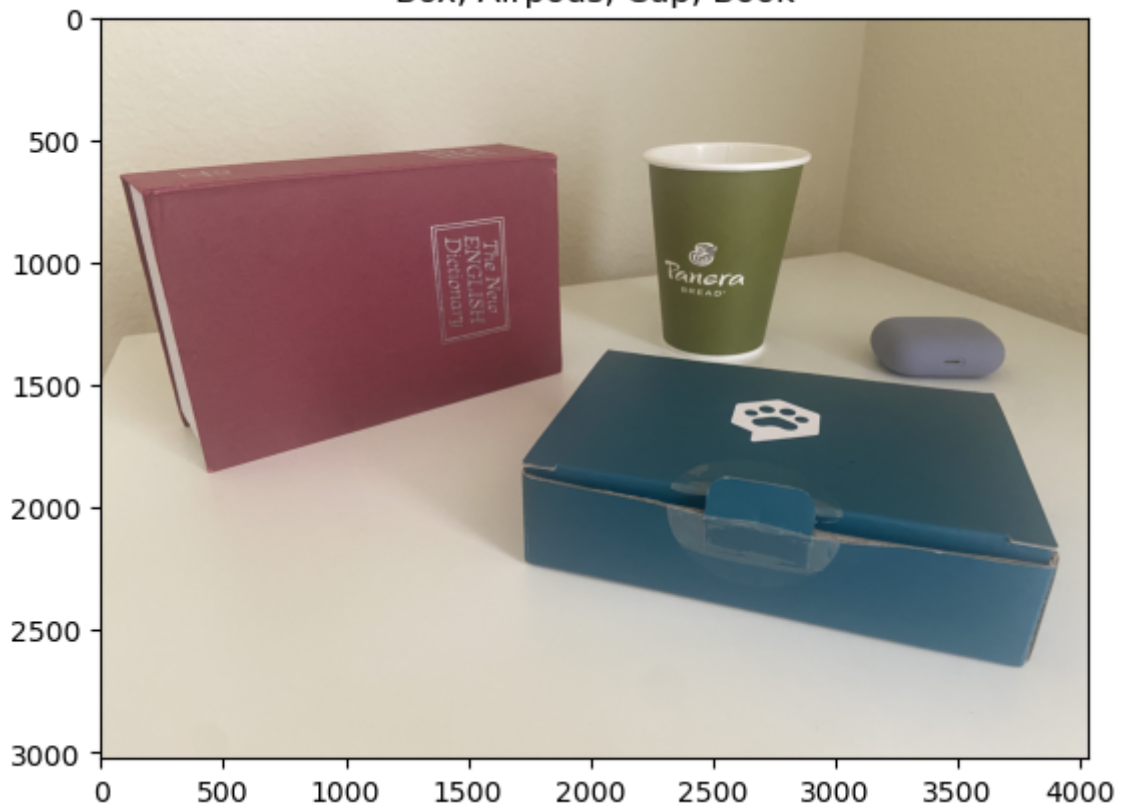
n_img: 9-object0.jpg

n_img: 9-object1.jpg

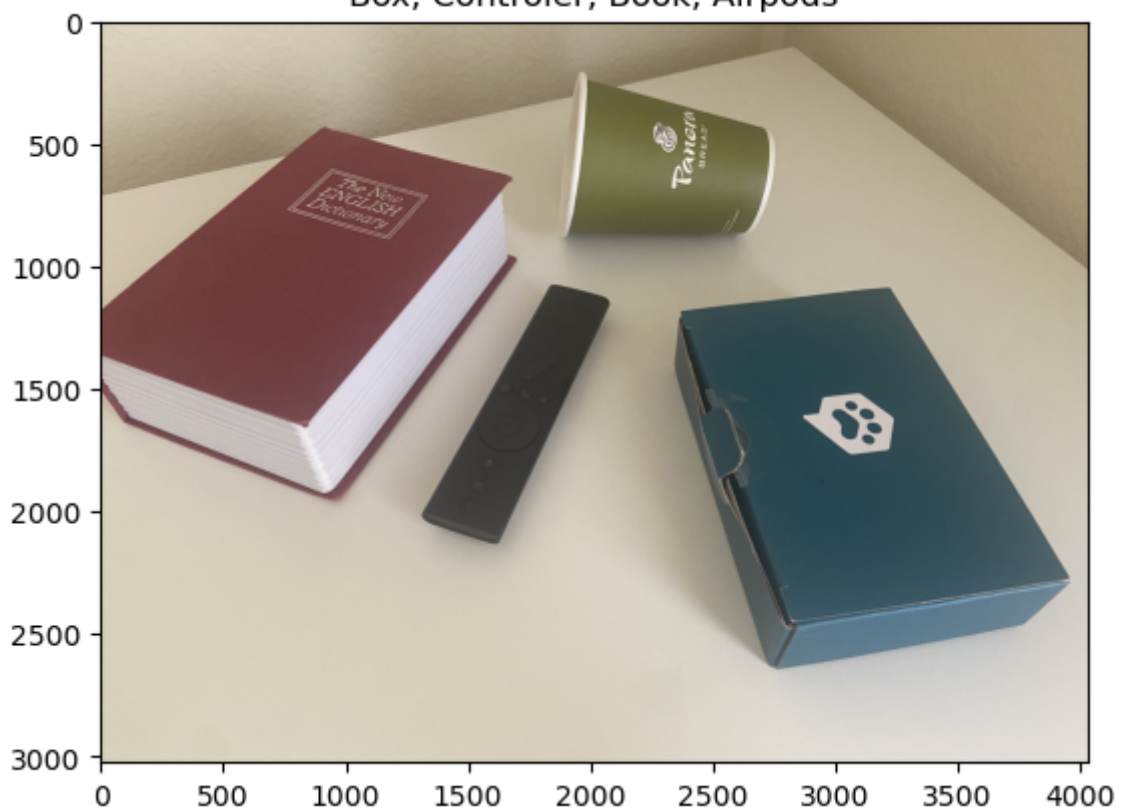
n_img: 9-object2.jpg

n_img: 9-object3.jpg

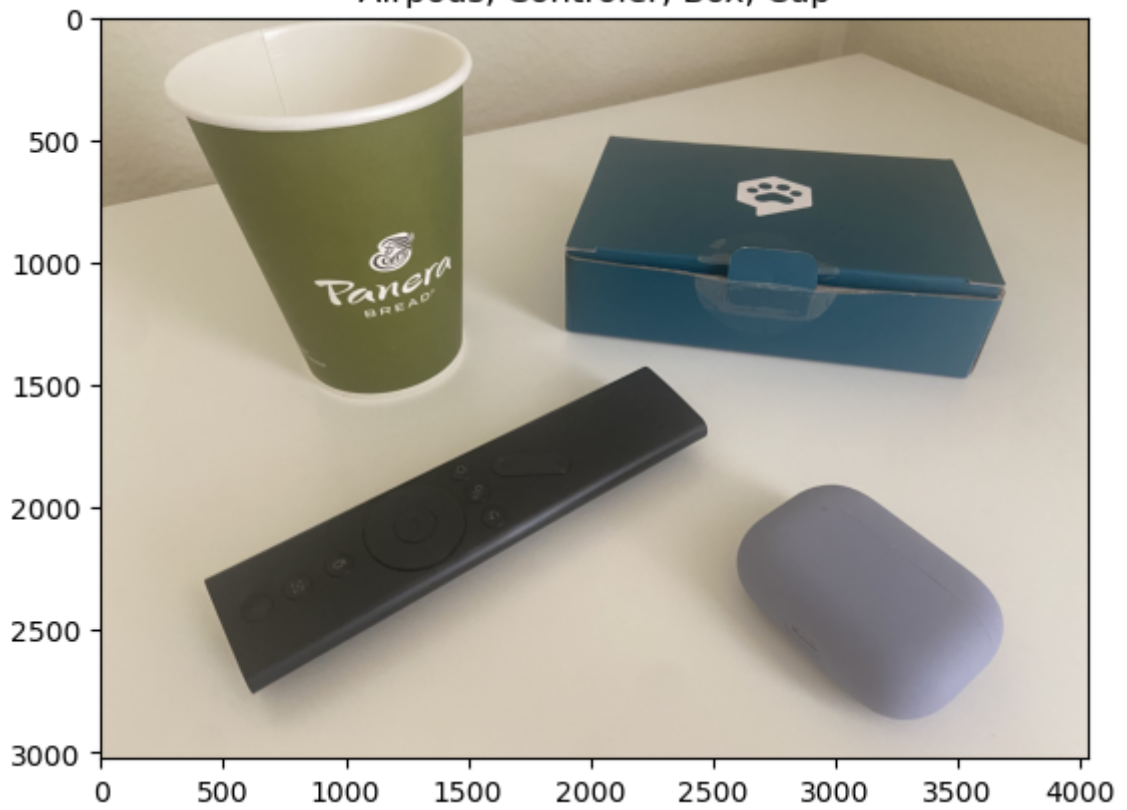
Box, Airpods, Cup, Book



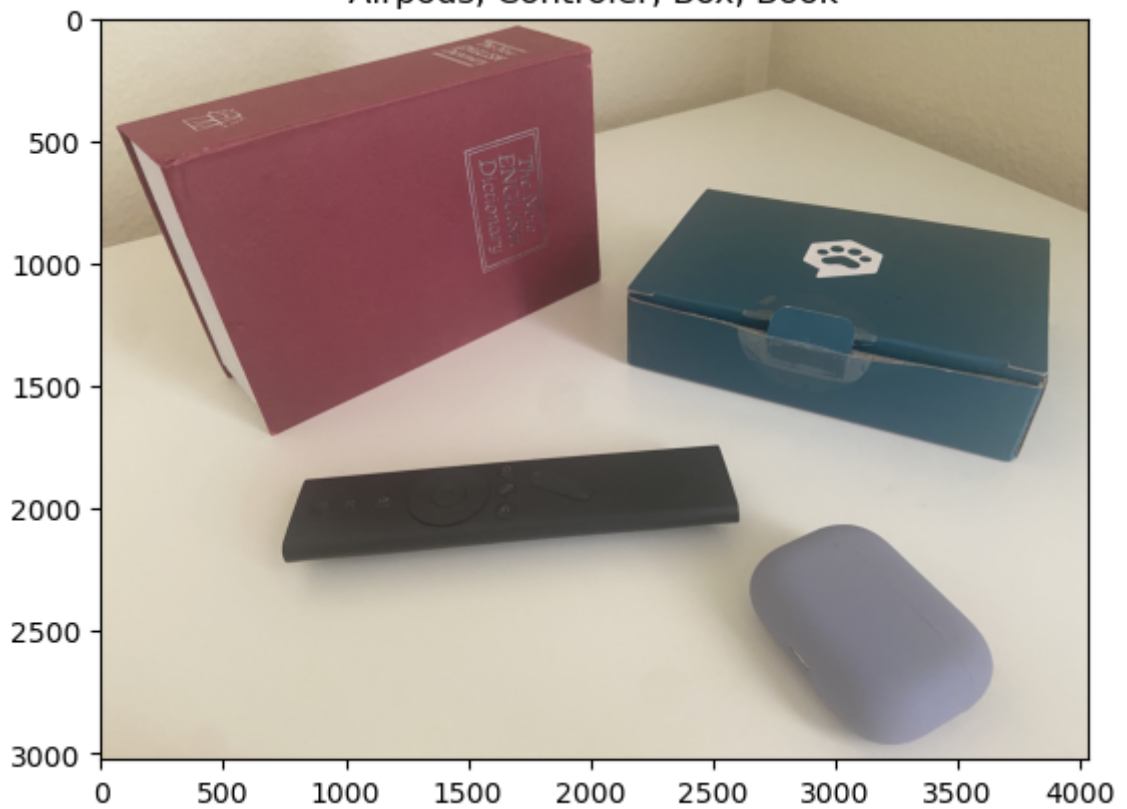
Box, Controller, Book, Airpods



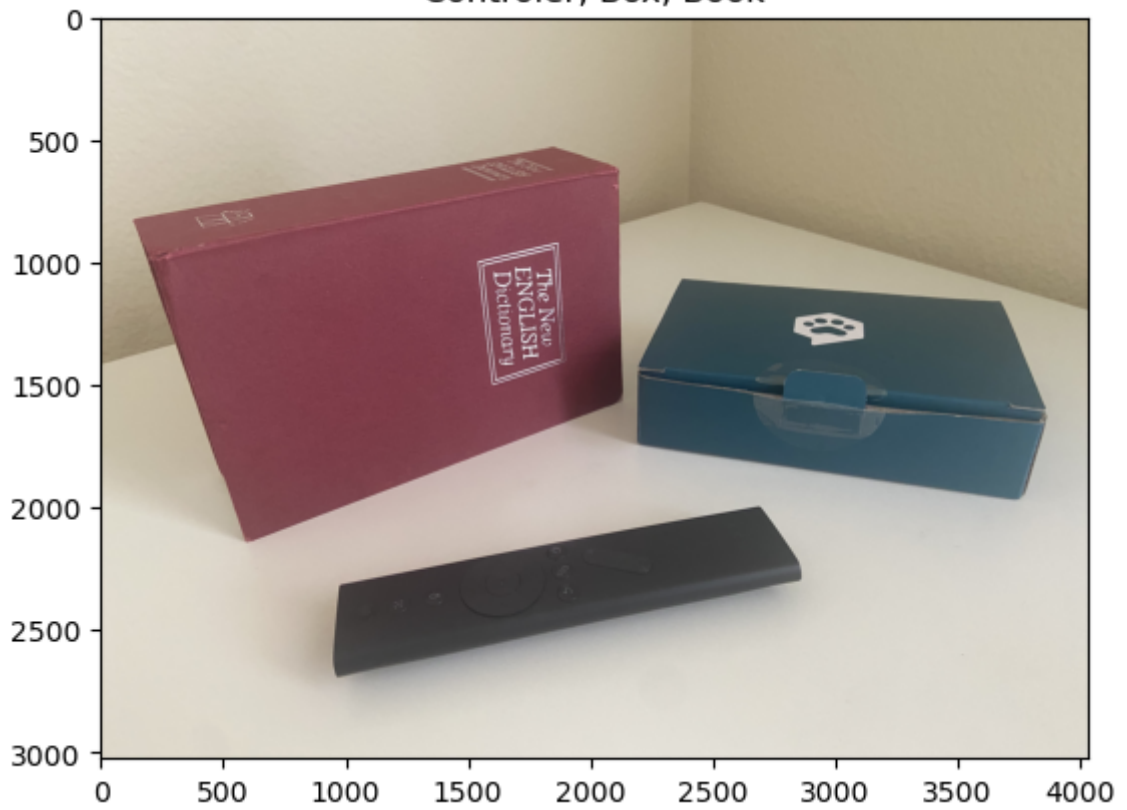
Airpods, Controller, Box, Cup



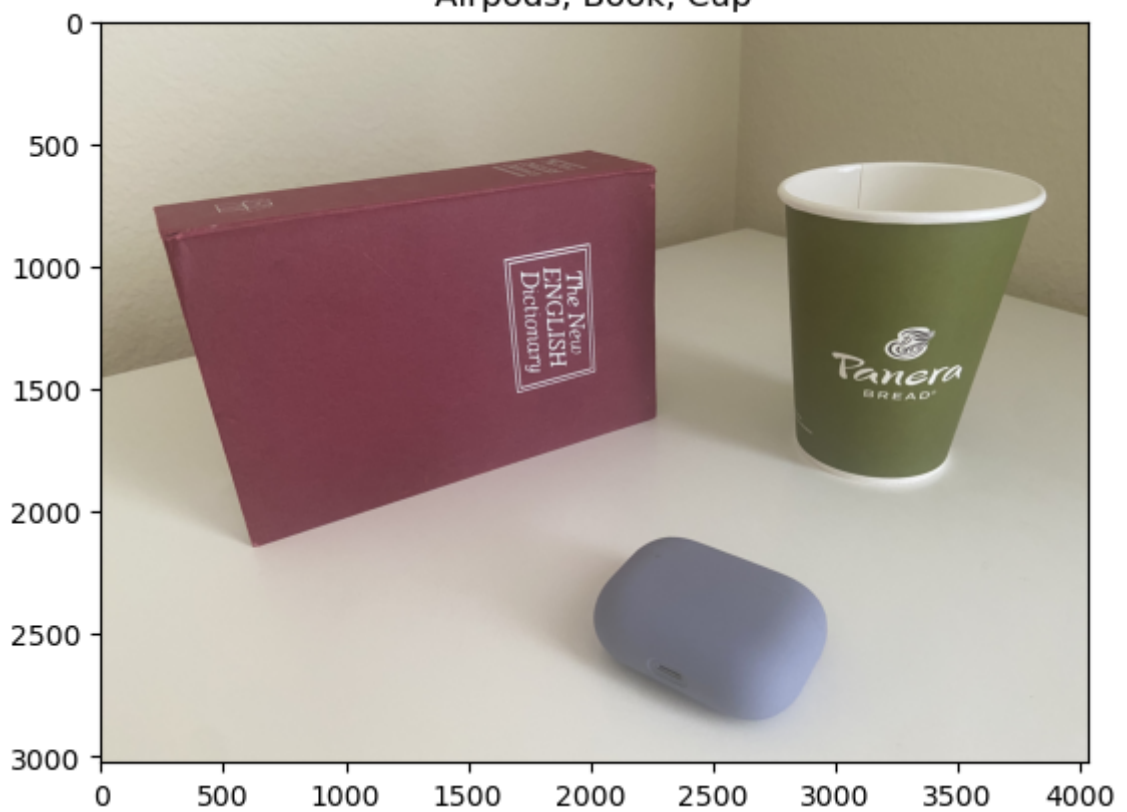
Airpods, Controller, Box, Book



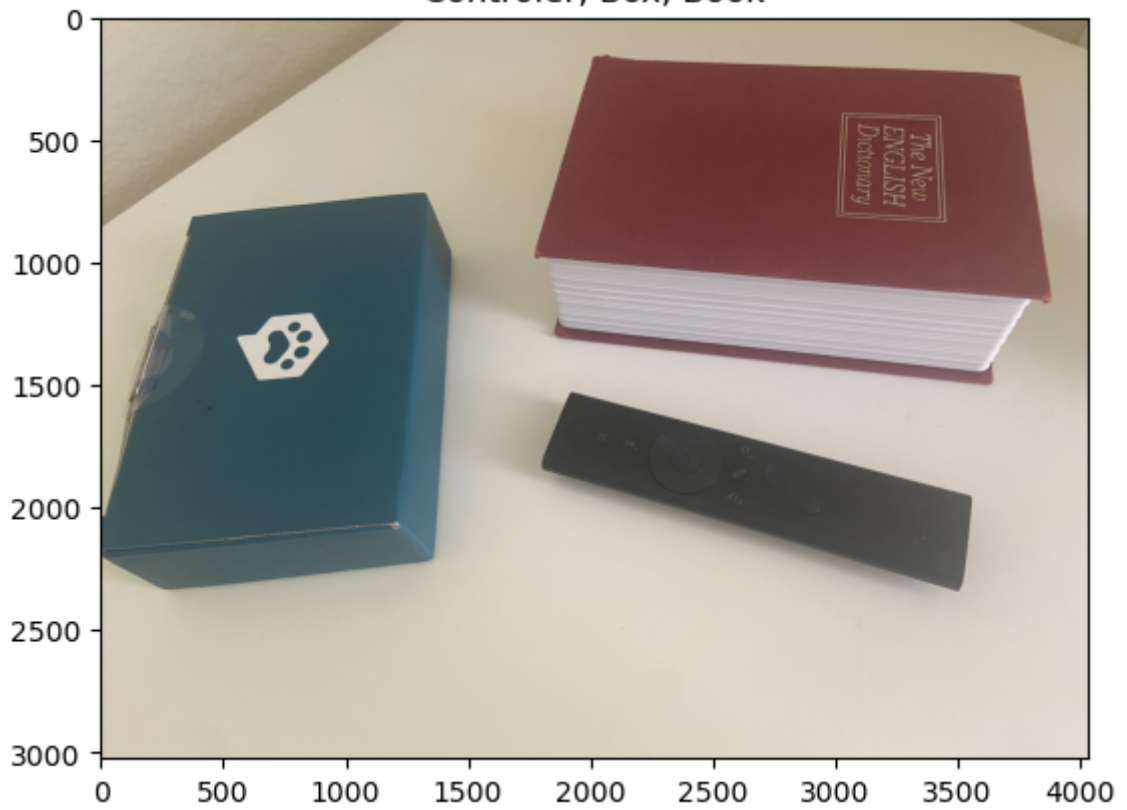
Controler, Box, Book



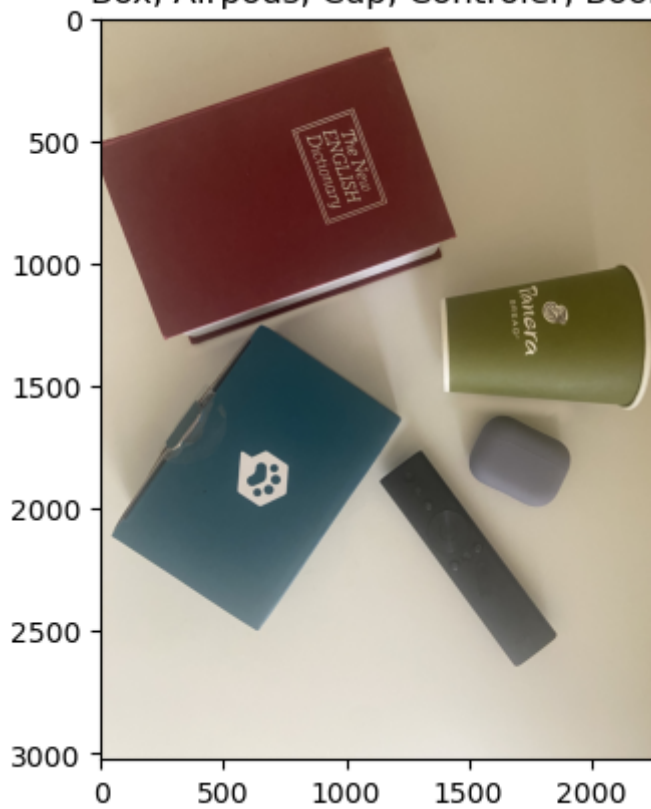
Airpods, Book, Cup



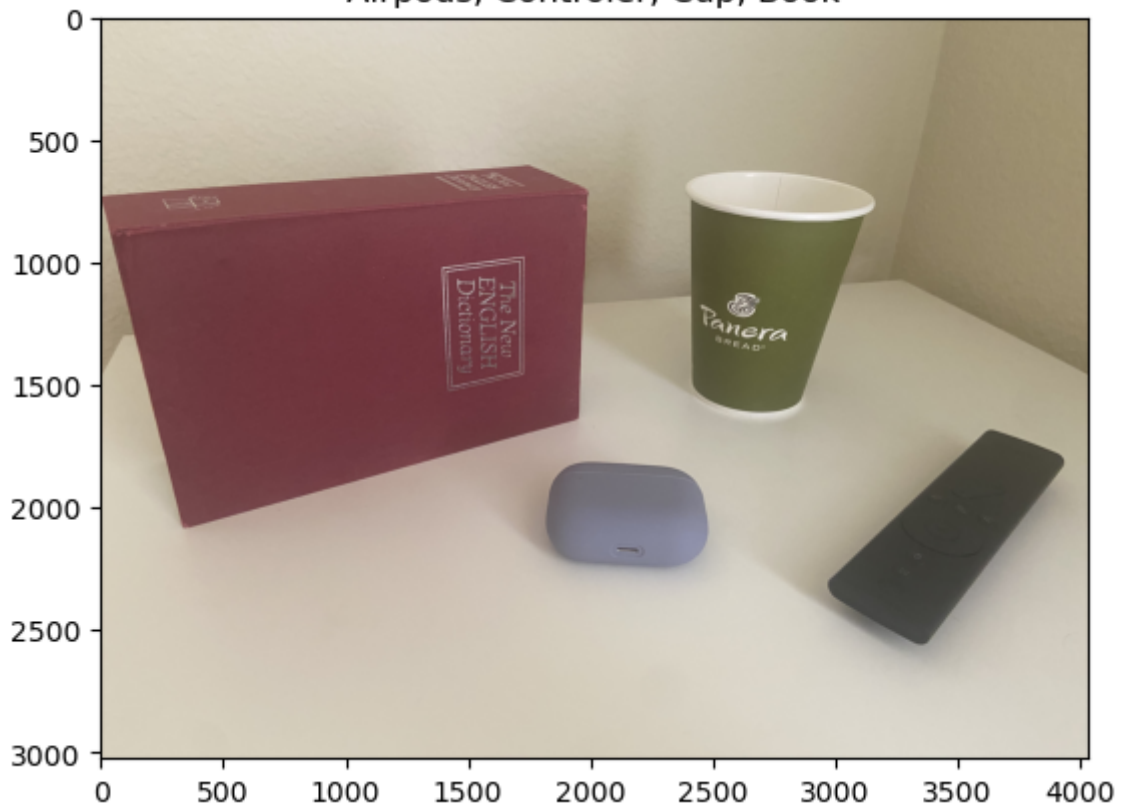
Controler, Box, Book



Box, Airpods, Cup, Controler, Book



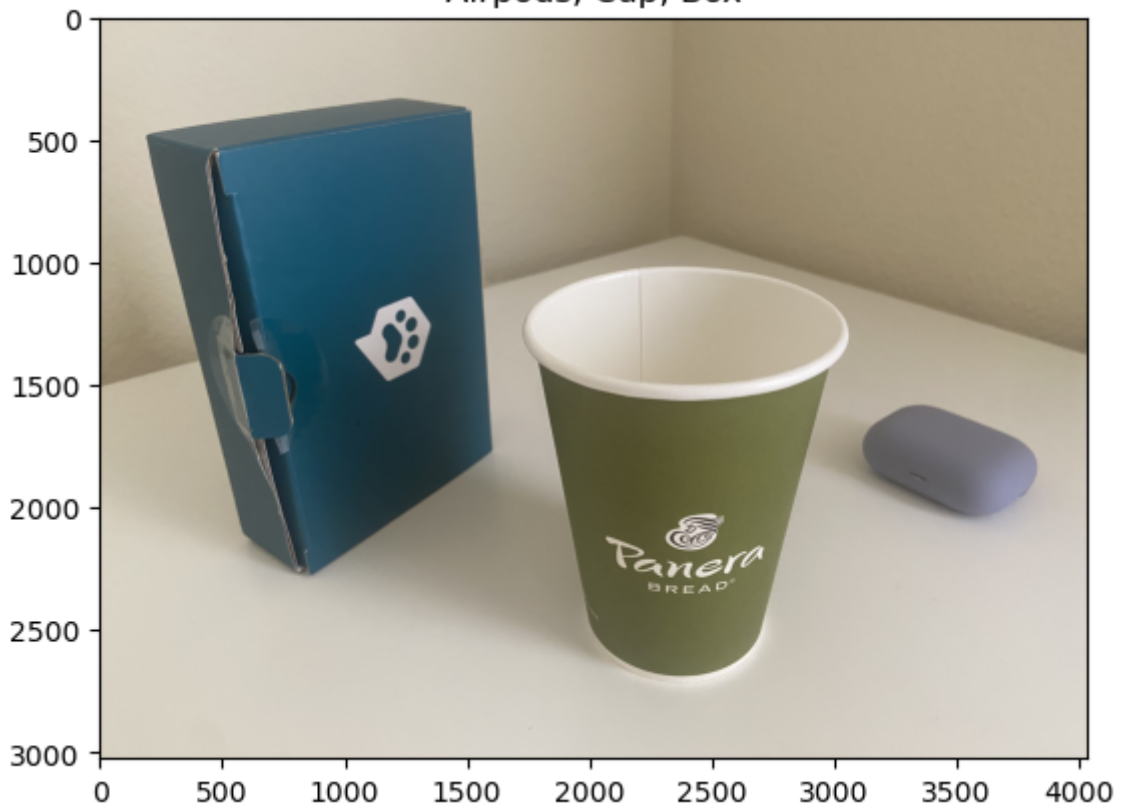
Airpods, Controler, Cup, Book



Airpods, Book, Box, Cup, Controler



Airpods, Cup, Box



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{ 'Box': ['1-object0.jpg', '10-object2.jpg', '11-object2.jpg', '11-object3.jpg', '2-object0.jpg', '3-object2.jpg', '4-object2.jpg', '5-object1.jpg', '6-object3.jpg', '7-object1.jpg', '8-object0.jpg'], 'Airpods': ['1-object1.jpg', '10-object0.jpg', '11-object0.jpg', '2-object3.jpg', '3-object0.jpg', '4-object0.jpg', '6-object0.jpg', '8-object1.jpg', '9-object0.jpg'], 'Cup': ['1-object2.jpg', '10-object3.jpg', '11-object1.jpg', '3-object3.jpg', '6-object2.jpg', '8-object2.jpg', '9-object2.jpg'], 'Book': ['1-object3.jpg', '10-object1.jpg', '2-object2.jpg', '4-object3.jpg', '5-object2.jpg', '6-object1.jpg', '7-object2.jpg', '8-object4.jpg', '8-object5.jpg', '9-object3.jpg'], 'Controler': ['10-object4.jpg', '2-object1.jpg', '3-object1.jpg', '4-object1.jpg', '5-object0.jpg', '7-object0.jpg', '8-object3.jpg', '9-object1.jpg']}
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In []: