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This acknowledges that

Changhong Fu, Fuling Lin, Fan Li, and Yujie He

"Sample Purification-Aware Correlation Filters for  ${\it UAV}$  Tracking with Cooperative Deep Features"

has been awarded

## BEST POSTER AWARD

at the IROS workshop on

Fast Neural Perception and Learning for Intelligent Vehicles and Robotics

Nov. 4<sup>th</sup>

Tie Gao Harter zhu

Signed by Workshop Organizers

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