Alexey Konstantinov





Send me Profile Download CV PDF

Education

- Peter the Great St.Petersburg Polytechnic University
 (Saint-Petersburg) Mechatronics and Robotics, Autonomous robots
- Sirius University of Science and Technology
 (Sochi) Mathematical Robotics and Artificial Intelligence

% Skills

- Python, C++, C
 Main programming languages
- Computer vision, OpenCV, YOLO
 Object detection, Stereo vision, Structure-from-motion, etc.
- TensorFlow, Deep Learning, Machine Learning

 CV applications, Natural language processing, etc.
- Robot Operating System (ROS)

CV, Autonomous navigation, etc.

- Servers, Git, VPN, Linux, Docker, MongoDB

 Launch, support, API-development, Every-day-use
- Embedded systems developing
 STM32, NRF24, ESP8266, NVIDIA Jetson, Arduino
- CAD & CNC, Electrionics, PCB developing
 3D-modeling and 3D-printing, Laser cutting, Milling, Practical skills

O Location: Sirius, Russia



• Tutor of C++ & Python programming languages

Freelance

Teaching the students (high-school students, university students and graduates) a programming languages from zero to hero, project assistance and support.

• Embedded systems developer

Freelance

Developing a firmware for such devices as radio transceivers, special equipment, control systems etc.

• Team-Lead in FabLab

Youth Project Activity Center "FabLab Polytech" (St.-Petersburg)

Tutor of programming STM32 microcontrollers, 3D-Modeling and 3D-printing, Theoretical mechanics for BioMechanic applications for university students, participating competitions (such as WorldSkills), etc.

• Python Developer

Freelance

Developing a Python-based projects, such as CV projects, chat-bots, etc.



• Closed-Source projects (can be discussed on the interview)

- Surveillance system WorldSkills winning project, based on YOLOv4 and SORT tracking
- Skincare Telegram Bot A bot for the telegram which can analyze your skin conditions and advice you skincare products which you need, based on TensorFlow for a dialog processing
- Autonomous navigation algorithm for the following robot University graduating project, based on ROS, allow a robot to follow the particular person with using object detection & tracking, gestures recongition, path planning algorithms, etc.

• EMG Sensors - Electo-MyoGraphy sensors for the prostheses and overall control systems application

• Open-Source projects

 E-Board Receiver - The firmware for the receiver in the DIY electric longboard based on STM32 and NRF24L01+