## **Network Simulator 2: Introduction**

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# **NS-2 Overview**

#### NS-2

- Developed by UC Berkeley
- Maintained by USC
- Popular simulator in scientific environment
- Other popular network simulators
  - Glomosim: UCLA, CMU; ParseC, Mobile Simulation mostly
  - OPNET: commercial software, graphical interface, not free;
  - Others: commercial ones, not free, e.g. IBM TPNS

#### **NS2 Goals**

- To support networking research and education
  - Protocol design, traffic studies, etc.
  - Protocol comparison;
  - New architecture designs are also supported.
- To provide *collaborative* environment
  - Freely distributed, open source;
  - *Increase confidence* in result

## Two Languages: C++, OTcl

OTcl: short for MIT Object Tcl, an extension to Tcl/Tk for object-oriented programming.

- Used to build the network structure and topology which is just the surface of your simulatoion;
- Easily to configure your network parameters;
- Not enough for research schemes and protocol architecture adaption.

#### Two Languages (Con't)

C++: Most important and kernel part of the NS2

- To implement the kernel of the architecture of the protocol designs;
- From the packet flow view, the processes run on a single node;
- To change or "comment out" the existing protocols running in NS2;
- Details of your research scheme.

#### Why 2 Languages?

- 2 requirements of the simulator
  - Detailed simulation of Protocol: Run-time speed;
  - Varying parameters or configuration: easy to use.
- C++ is fast to run but slower to code and change;
- OTcl is easy to code but runs slowly.

### Protocols/Models supported by NS2

- Wired Networking
  - Routing: Unicast, Multicast, and Hierarchical Routing, etc.
  - Transportation: TCP, UDP, others;
  - Traffic sources: web, ftp, telnet, cbr, etc.
  - Queuing disciplines: drop-tail, RED, etc.
  - QoS: IntServ and Diffserv Wireless Networking
- Ad hoc routing and mobile IP
- Sensor Networks(hmmm)
  - SensorSim: built up on NS2, additional features, for TinyOS

#### **NS2** Models

- Traffic models and applications:
   Web, FTP, telnet, constant-bit rate(CBR)
- Transport protocols:
   Unicast: TCP (Reno, Vegas), UDP Multicast
- Routing and queuing:
   Wired routing, Ad Hoc routing.
- Queuing protocols:
   RED(Random Early Drop), drop-tail
- Physical media:
   Wired (point-to-point, LANs), wireless, satellite

#### Researches based on NS2

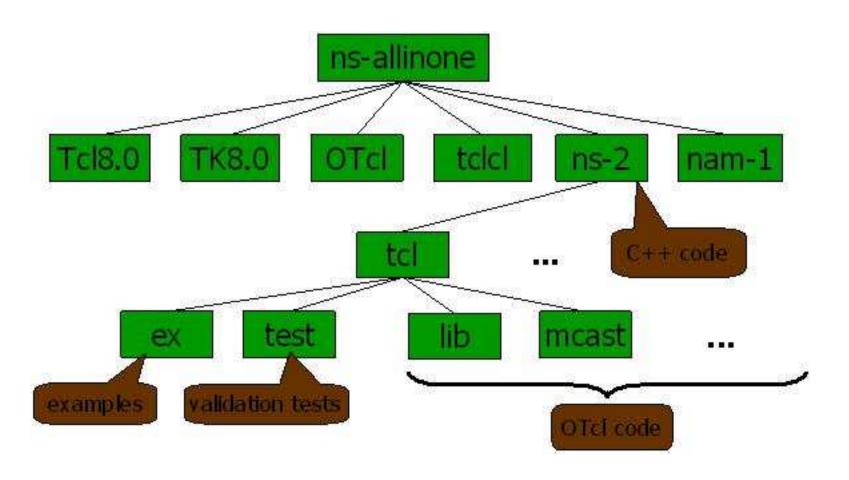
- Intserv/Diffserv (QoS)
- Multicast: Routing, Reliable multicast
- Transport: TCP Congestion control
- Application: Web caching Multimedia
- Sensor Networks: LEACH, Directed Diffusion, etc. Most are routing protocols.
- etc.

### **NS2** Components

- NS2: the simulator itself, now version: ns-2.26
   We will work with the part mostly.
- NAM: Network animator. Visualized trace tool(not really).
   Nam editor: GUI interface to generate ns scripts
   Just for presentation now, not useful for research tracing.
- Pre-processing:
   Traffic and topology generators
- Post-processing:
   Simple trace analysis, often in Awk, Perl(mostly), or Tcl

# Living under NS2

## The NS2 Directory Structure



### A Simple Example in OTcl

```
#Create a simulator object
set ns [new Simulator]
#Define different colors for data flows (for NAM)
$ns color 1 Blue
$ns color 2 Red
#Open the NAM trace file
set nf [open out.nam w]
$ns namtrace-all $nf
#Define a 'finish' procedure proc finish {} {
        global ns nf
        $ns flush-trace
        #Close the NAM trace file
        close $nf
        #Execute NAM on the trace file
        exec nam out.nam &
        exit 0
```

```
set n0 [$ns node]
set n1 [$ns node]
set n2 [$ns node]
set n3 [$ns node]
#Create links between the nodes
$ns duplex-link $n0 $n2 2Mb 10ms DropTail
$ns duplex-link $n1 $n2 2Mb 10ms DropTail
$ns duplex-link $n2 $n3 1.7Mb 20ms DropTail
#Set Queue Size of link (n2-n3) to 10
$ns queue-limit $n2 $n3 10
#Give node position (for NAM)
$ns duplex-link-op $n0 $n2 orient right-down
$ns duplex-link-op $n1 $n2 orient right-up
$ns duplex-link-op $n2 $n3 orient right
#Monitor the queue for link (n2-n3). (for NAM)
$ns duplex-link-op $n2 $n3 queuePos 0.5
```

#Create four nodes

```
set tcp [new Agent/TCP]
$tcp set class_ 2
$ns attach-agent $n0 $tcp
set sink [new Agent/TCPSink]
$ns attach-agent $n3 $sink
$ns connect $tcp $sink
$tcp set fid_ 1
#Setup a FTP over TCP connection
set ftp [new Application/FTP]
$ftp attach-agent $tcp
$ftp set type_ FTP
#Setup a UDP connection
set udp [new Agent/UDP]
$ns attach-agent $n1 $udp
set null [new Agent/Null]
$ns attach-agent $n3 $null
$ns connect $udp $null
$udp set fid_ 2
```

#Setup a TCP connection

```
#Setup a CBR over UDP connection
set cbr [new Application/Traffic/CBR]
$cbr attach-agent $udp $cbr
set type_ CBR $cbr
set packet_size_ 1000 $cbr
set rate_ 1mb $cbr
set random false
#Schedule events for the CBR and FTP agents
$ns at 0.1 "$cbr start"
$ns at 1.0 "$ftp start"
$ns at 4.0 "$ftp stop"
$ns at 4.5 "$cbr stop"
#Detach tcp and sink agents (not really necessary)
$ns at 4.5 "$ns detach-agent $n0 $tcp ;
$ns detach-agent $n3 $sink"
#Call the finish procedure after 5 seconds of simulation time
$ns at 5.0 "finish"
```

```
#Print CBR packet size and interval
puts "CBR packet size = [$cbr set packet_size_]"
puts "CBR interval = [$cbr set interval_]"

#Run the simulation
$ns run
```

## Steps in writing a simulating script

- Create the event scheduler
- Turn on tracing
- Create network
- Setup routing
- Insert errors
- Create transport connection
- Create traffic
- Transmit application-level data

#### The trace file

Turn on tracing on specific links

```
$ns_ trace-queue $n0 $n1
```

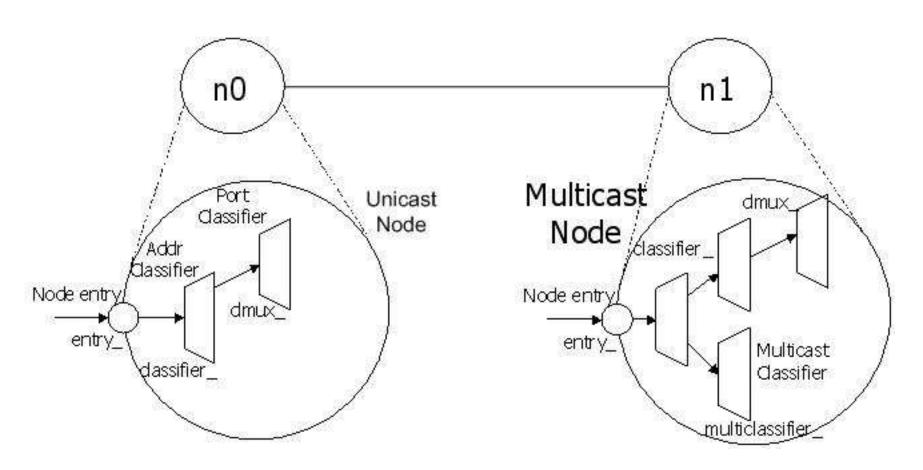
Each line in the trace file is in the format:

```
< event > < time > < from > < to >
< pkt - type > < pkt - size > < flags >
< fid > < src > < dst > < seq > < uid >
```

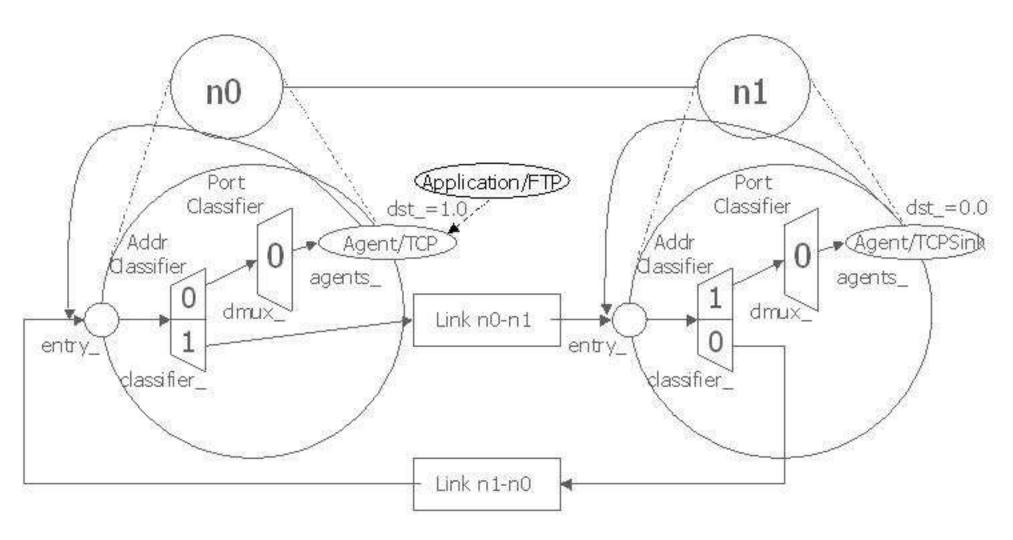
• Trace example:

```
+ 1 0 2 cbr 210 ----- 0 0.0 3.1 0 0
- 1 0 2 cbr 210 ----- 0 0.0 3.1 0 0
r 1.00234 0 2 cbr 210 ----- 0 0.0 3.1 0 0
```

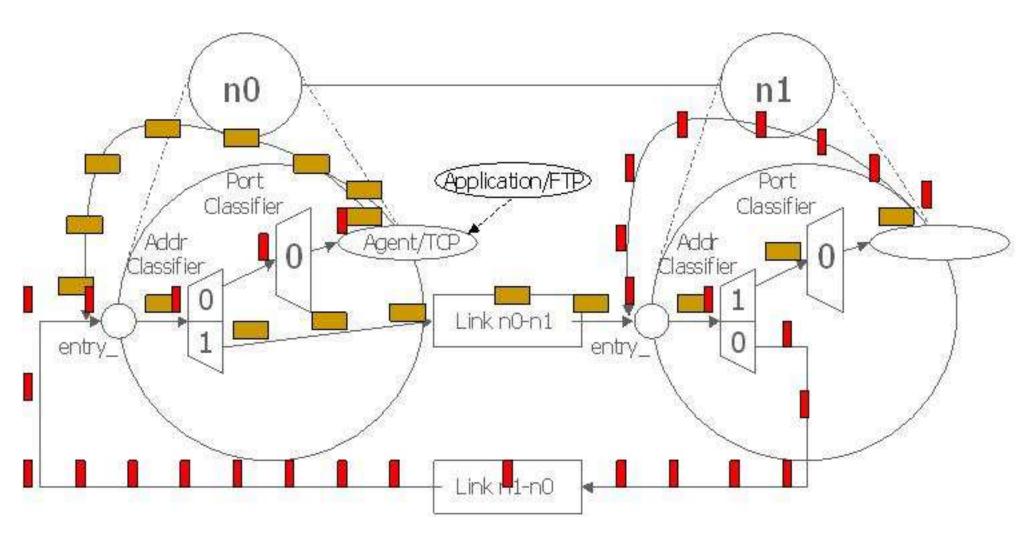
## The network Topology



#### The Node Architecture

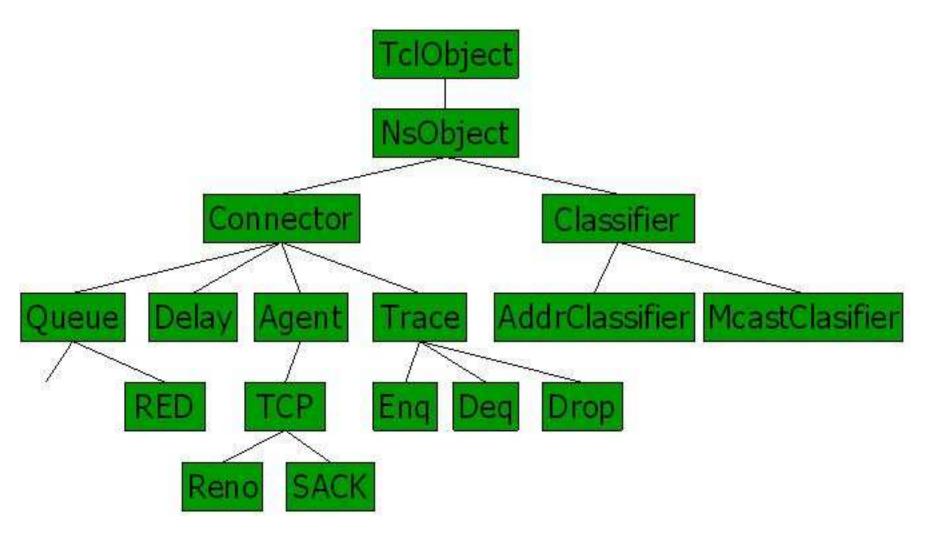


#### The Packet Flow



# Extending to NS2

### Class Hierarchy in NS2(Partial, C++ code)

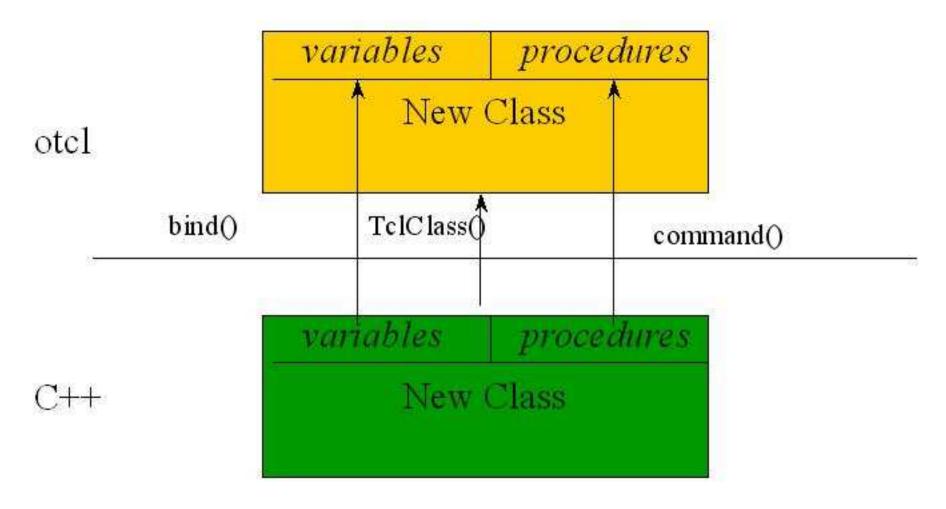


### Create New Component for NS2

Your research needs you to do so, no escaping(crying!!!).

- Extending ns in Otcl source your changes in your simulation scripts
- Extending ns in C++
  - Change Makefile (if created new files)
  - make depend
  - recompile
  - Makefile is in the "ns-2.26" directory

## **Adding New Class**



## A piece of my code

#### Applications based on Sensor Networks

• .h file:

```
class TmprSensorApp : public DiffApp {
    public:
        TmprSensorApp();
        int command(int argc, const char*const* argv);
        void run();
    ...
}
```

### A piece of my code (Con't)

#### • .cc file:

```
static class TmprSensorAppClass : public TclClass {
    public:
        TmprSensorAppClass() : TclClass("Application/DiffApp/TmprSensor"){}
        TclObject* create(int, const char*const*){
            return (new TmprSensorApp());
        }
} class_tmpr_sensor;

int TmprSensorApp :: command(int argc, const char*const* argv){
    if(argc == 2){
        if(strcmp(argv[1], "publish") ==0){
            run();
            return TCL_OK;
        }
    }
}
```

#### Binding New C++Object to TclObject

Link C++ member variables to OTcl object variables

• C++:

```
NewClass() : TclClass("class hierarchy");
```

#### • OTcl:

```
set "object belongs to NewClass" [new "class hierarchy"]
set src_(0) [new Application/DiffApp/TmprSensor]
$ns_ attach-diffapp $node_(0) $src_(0)
$ns at 1.23456 "$src (0) publish"
```

## Thank You!

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