

# Software engineering with exponential decay models

Hans Petter Langtangen<sup>1,2</sup>

<sup>1</sup>Center for Biomedical Computing, Simula Research Laboratory

<sup>2</sup>Department of Informatics, University of Oslo

Feb 12, 2016

## Contents

<b>1</b>	<b>Implementations with functions and modules</b>	<b>4</b>
1.1	Mathematical problem and solution technique . . . . .	4
1.2	A first, quick implementation . . . . .	5
1.3	A more decent program . . . . .	6
1.4	Prefixing imported functions by the module name . . . . .	7
1.5	Implementing the numerical algorithm in a function . . . . .	10
1.6	Do not have several versions of a code . . . . .	10
1.7	Making a module . . . . .	11
1.8	Example on extending the module code . . . . .	13
1.9	Documenting functions and modules . . . . .	15
1.10	Logging intermediate results . . . . .	16
<b>2</b>	<b>User interfaces</b>	<b>24</b>
2.1	Command-line arguments . . . . .	25
2.2	Positional command-line arguments . . . . .	27
2.3	Option-value pairs on the command line . . . . .	28
2.4	Creating a graphical web user interface . . . . .	30
<b>3</b>	<b>Tests for verifying implementations</b>	<b>33</b>
3.1	Doctests . . . . .	34
3.2	Unit tests and test functions . . . . .	35
3.3	Test function for the solver . . . . .	39
3.4	Test function for reading positional command-line arguments . . . . .	40
3.5	Test function for reading option-value pairs . . . . .	41
3.6	Classical class-based unit testing . . . . .	42

<b>4</b>	<b>Sharing the software with other users</b>	<b>44</b>
4.1	Organizing the software directory tree . . . . .	44
4.2	Publishing the software at GitHub . . . . .	46
4.3	Downloading and installing the software . . . . .	47
<b>5</b>	<b>Classes for problem and solution method</b>	<b>49</b>
5.1	The problem class . . . . .	49
5.2	The solver class . . . . .	51
5.3	Improving the problem and solver classes . . . . .	52
<b>6</b>	<b>Automating scientific experiments</b>	<b>54</b>
6.1	Available software . . . . .	55
6.2	The results we want to produce . . . . .	56
6.3	Combining plot files . . . . .	57
6.4	Running a program from Python . . . . .	58
6.5	The automating script . . . . .	59
6.6	Making a report . . . . .	62
6.7	Publishing a complete project . . . . .	65
<b>7</b>	<b>Exercises</b>	<b>66</b>
	<b>References</b>	<b>70</b>
	<b>Index</b>	<b>71</b>

## List of Exercises and Problems

Problem	1	Make a tool for differentiating curves	p. 66
Problem	2	Make solid software for the Trapezoidal rule	p. 67
Problem	3	Implement classes for the Trapezoidal rule	p. 69
Problem	4	Write a doctest and a test function	p. 69
Problem	5	Investigate the size of tolerances in comparisons ...	p. 69
Exercise	6	Make use of a class implementation	p. 70
Problem	7	Make solid software for a difference equation	p. 70

Teaching material on scientific computing has traditionally been very focused on the mathematics and the applications, while details on how the computer is programmed to solve the problems have received little attention. Many end up writing as simple programs as possible, without being aware of much useful computer science technology that would increase the fun, efficiency, and reliability of their scientific computing activities.

This chapter demonstrates a series of good practices and tools from modern computer science, using the simple mathematical problem  $u' = -au$ ,  $u(0) = I$ , such that we minimize the mathematical details and can go more in depth with implementations. The goal is to increase the technological quality of computer programming and make it match the more well-established quality of the mathematics of scientific computing.

The conventions and techniques outlined here will save you a lot of time when you incrementally extend software over time from simpler to more complicated problems. In particular, you will benefit from many good habits:

- new code is added in a modular fashion to a library (modules),
- programs are run through convenient user interfaces,
- it takes one quick command to let all your code undergo heavy testing,
- tedious manual work with running programs is automated,
- your scientific investigations are reproducible,
- scientific reports with top quality typesetting are produced both for paper and electronic devices.

## 1 Implementations with functions and modules

All previous examples in this book have implemented numerical algorithms as Python functions. This is a good style that readers are expected to adopt. However, this author has experienced that many students and engineers are inclined to make “flat” programs, i.e., a sequence of statements without any use of functions, just to get the problem solved as quickly as possible. Since this programming style is so widespread, especially among people with MATLAB experience, we shall look at the weaknesses of flat programs and show how they can be *refactored* into more reusable programs based on functions.

### 1.1 Mathematical problem and solution technique

We address the differential equation problem

$$u'(t) = -au(t), \quad t \in (0, T], \quad (1)$$

$$u(0) = I, \quad (2)$$

where  $a$ ,  $I$ , and  $T$  are prescribed parameters, and  $u(t)$  is the unknown function to be estimated. This mathematical model is relevant for physical phenomena featuring exponential decay in time, e.g., vertical pressure variation in the atmosphere, cooling of an object, and radioactive decay.

The time domain is discretized with points  $0 = t_0 < t_1 \cdots < t_{N_t} = T$ , here with a constant spacing  $\Delta t$  between the mesh points:  $\Delta t = t_n - t_{n-1}$ ,  $n = 1, \dots, N_t$ . Let  $u^n$  be the numerical approximation to the exact solution at  $t_n$ . A family of popular numerical methods are provided by the  $\theta$  scheme,

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} u^n, \quad (3)$$

for  $n = 0, 1, \dots, N_t - 1$ . This formula produces the Forward Euler scheme when  $\theta = 0$ , the Backward Euler scheme when  $\theta = 1$ , and the Crank-Nicolson scheme when  $\theta = 1/2$ .

## 1.2 A first, quick implementation

Solving (3) in a program is very straightforward: just make a loop over  $n$  and evaluate the formula. The  $u(t_n)$  values for discrete  $n$  can be stored in an array. This makes it easy to also plot the solution. It would be natural to also add the exact solution curve  $u(t) = Ie^{-at}$  to the plot.

Many have programming habits that would lead them to write a simple program like this:

```
from numpy import *
from matplotlib.pyplot import *

A = 1
a = 2
T = 4
dt = 0.2
N = int(round(T/dt))
y = zeros(N+1)
t = linspace(0, T, N+1)
theta = 1
y[0] = A
for n in range(0, N):
    y[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*y[n]

y_e = A*exp(-a*t) - y
error = y_e - y
E = sqrt(dt*sum(error**2))
print 'Norm of the error: %.3E' % E
plot(t, y, 'r--o')
t_e = linspace(0, T, 1001)
y_e = A*exp(-a*t_e)
plot(t_e, y_e, 'b-')
legend(['numerical, theta=%g' % theta, 'exact'])
xlabel('t')
ylabel('y')
show()
```

This program is easy to read, and as long as it is correct, many will claim that it has sufficient quality. Nevertheless, the program suffers from two serious flaws:

1. The notation in the program does not correspond *exactly* to the notation in the mathematical problem: the solution is called  $y$  and corresponds to  $u$  in the mathematical description, the variable  $A$  corresponds to the mathematical parameter  $I$ ,  $N$  in the program is called  $N_t$  in the mathematics.
2. There are no comments in the program.

These kind of flaws quickly become crucial if present in code for complicated mathematical problems and code that is meant to be extended to other problems.

We also note that the program is *flat* in the sense that it does not contain functions. Usually, this is a bad habit, but let us first correct the two mentioned flaws.

### 1.3 A more decent program

A code of better quality arises from fixing the notation and adding comments:

```
from numpy import *
from matplotlib.pyplot import *

I = 1
a = 2
T = 4
dt = 0.2
Nt = int(round(T/dt))      # no of time intervals
u = zeros(Nt+1)           # array of u[n] values
t = linspace(0, T, Nt+1)  # time mesh
theta = 1                  # Backward Euler method

u[0] = I                  # assign initial condition
for n in range(0, Nt):    # n=0,1,...,Nt-1
    u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]

# Compute norm of the error
u_e = I*exp(-a*t) - u     # exact u at the mesh points
error = u_e - u
E = sqrt(dt*sum(error**2))
print 'Norm of the error: %.3E' % E

# Compare numerical (u) and exact solution (u_e) in a plot
plot(t, u, 'r--o')
t_e = linspace(0, T, 1001) # very fine mesh for u_e
u_e = I*exp(-a*t_e)
plot(t_e, u_e, 'b-')
legend(['numerical, theta=%g' % theta, 'exact'])
xlabel('t')
ylabel('u')
show()
```

**Comments in a program.** There is obviously not just one way to comment a program, and opinions may differ as to what code should be commented. The guiding principle is, however, that comments should make the program easy to understand for the human eye. Do not comment obvious constructions, but focus on ideas and (“what happens in the next statements?”) and on explaining code that can be found complicated.

**Refactoring into functions.** At first sight, our updated program seems like a good starting point for playing around with the mathematical problem: we can just change parameters and rerun. Although such edit-and-rerun sessions are good for initial exploration, one will soon extend the experiments and start developing the code further. Say we want to compare  $\theta = 0, 1, 0.5$  in the same plot. This extension requires changes all over the code and quickly leads to errors. To do something serious with this program, we have to break it into smaller pieces and make sure each piece is well tested, and ensure that the program is sufficiently general and can be reused in new contexts without changes. The next natural step is therefore to isolate the numerical computations and the visualization in separate Python functions. Such a rewrite of a code, without essentially changing the functionality, but just improve the quality of the code, is known as *refactoring*. After quickly putting together and testing a program, the next step is to refactor it so it becomes better prepared for extensions.

**Program file vs IDE vs notebook.** There are basically three different ways of working with Python code:

1. One writes the code in a file, using a text editor (such as Emacs or Vim) and runs it in a terminal window.
2. One applies an *Integrated Development Environment* (the simplest is IDLE, which comes with standard Python) containing a graphical user interface with an editor and an element where Python code can be run.
3. One applies the Jupyter Notebook (previously known as IPython Notebook), which offers an interactive environment for Python code where plots are automatically inserted after the code, see Figure 1.

It appears that method 1 and 2 are quite equivalent, but the notebook encourages more experimental code and therefore also flat programs. Consequently, notebook users will normally need to think more about refactoring code and increase the use of functions after initial experimentation.

## 1.4 Prefixing imported functions by the module name

Import statements of the form `from module import *` import *all* functions and variables in `module.py` into the current file. This is often referred to as “import star”, and many find this convenient, but it is not considered as a good programming style in Python. For example, when doing

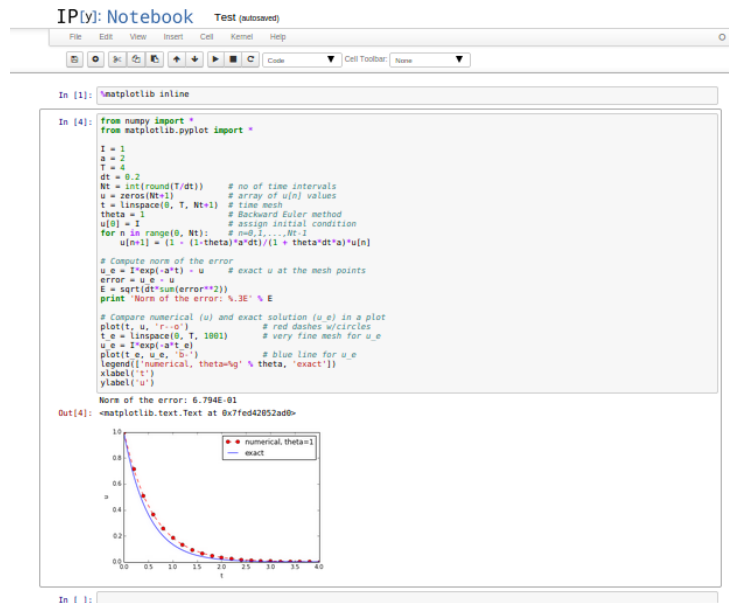


Figure 1: Experimental code in a notebook.

```
from numpy import *
from matplotlib.pyplot import *
```

we get mathematical functions like `sin` and `exp` as well as MATLAB-style functions like `linspace` and `plot`, which can be called by these well-known names. Unfortunately, it sometimes becomes confusing to know where a particular function comes from, i.e., what modules you need to import. Is a desired function from `numpy` or `matplotlib.pyplot`? Or is it our own function? These questions are easy to answer if functions in modules are prefixed by the module name. Doing an additional `from math import *` is really crucial: now `sin`, `cos`, and other mathematical functions are imported and their names hide those previously imported from `numpy`. That is, `sin` is now a sine function that accepts a `float` argument, not an array.

Doing the import such that module functions must have a prefix is generally recommended:

```
import numpy
import matplotlib.pyplot

t = numpy.linspace(0, T, Nt+1)
u_e = I*numpy.exp(-a*t)
matplotlib.pyplot.plot(t, u_e)
```



The modules `numpy` and `matplotlib.pyplot` are frequently used, and since their full names are quite tedious to write, two standard abbreviations have evolved in the Python scientific computing community:

```
import numpy as np
import matplotlib.pyplot as plt

t = np.linspace(0, T, Nt+1)
u_e = I*np.exp(-a*t)
plt.plot(t, u_e)
```

The downside of prefixing functions by the module name is that mathematical expressions like  $e^{-at} \sin(2\pi t)$  get cluttered with module names,

```
numpy.exp(-a*t)*numpy.sin(2*numpy.pi*t)
# or
np.exp(-a*t)*np.sin(2*np.pi*t)
```

Such an expression looks like `exp(-a*t)*sin(2*pi*t)` in most other programming languages. Similarly, `np.linspace` and `plt.plot` look less familiar to people who are used to MATLAB and who have not adopted Python's prefix style. Whether to do `from module import *` or `import module` depends on personal taste and the problem at hand. In these writings we use `from module import *` in more basic, shorter programs where similarity with MATLAB could be an advantage. However, in reusable modules we prefix calls to module functions by their function name, *or* do explicit import of the needed functions:

```
from numpy import exp, sum, sqrt

def u_exact(t, I, a):
    return I*exp(-a*t)

error = u_exact(t, I, a) - u
E = sqrt(dt*sum(error**2))
```

### Prefixing module functions or not?

It can be advantageous to do a combination: mathematical functions in formulas are imported without prefix, while module functions in general are called with a prefix. For the `numpy` package we can do

```
import numpy as np
from numpy import exp, sum, sqrt
```

such that mathematical expression can apply `exp`, `sum`, and `sqrt` and hence look as close to the mathematical formulas as possible (without a disturbing prefix). Other calls to `numpy` function are done with the prefix, as in `np.linspace`.

## 1.5 Implementing the numerical algorithm in a function

The solution formula (3) is completely general and should be available as a Python function `solver` with all input data as function arguments and all output data returned to the calling code. With this `solver` function we can solve all types of problems (1)-(2) by an easy-to-read one-line statement:

```
u, t = solver(I=1, a=2, T=4, dt=0.2, theta=0.5)
```

Refactoring the numerical method in the previous flat program in terms of a `solver` function and prefixing calls to module functions by the module name leads to this code:

```
def solver(I, a, T, dt, theta):
    """Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt."""
    dt = float(dt)          # avoid integer division
    Nt = int(round(T/dt))     # no of time intervals
    T = Nt*dt               # adjust T to fit time step dt
    u = np.zeros(Nt+1)      # array of u[n] values
    t = np.linspace(0, T, Nt+1) # time mesh

    u[0] = I                # assign initial condition
    for n in range(0, Nt):  # n=0,1,...,Nt-1
        u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]
    return u, t
```

### Tip: Always use a doc string to document a function!

Python has a convention for documenting the purpose and usage of a function in a *doc string*: simply place the documentation in a one- or multi-line triple-quoted string right after the function header.

### Be careful with unintended integer division!

Note that we in the `solver` function explicitly covert `dt` to a `float` object. If not, the updating formula for `u[n+1]` may evaluate to zero because of integer division when `theta`, `a`, and `dt` are integers!

## 1.6 Do not have several versions of a code

One of the most serious flaws in computational work is to have several slightly different implementations of the same computational algorithms lying around in various program files. This is very likely to happen, because busy scientists often want to test a slight variation of a code to see what happens. A quick copy-and-edit does the task, but such quick hacks tend to survive. When a real correction is needed in the implementation, it is difficult to ensure that

the correction is done in all relevant files. In fact, this is a general problem in programming, which has led to an important principle.

#### The DRY principle: Don't repeat yourself!

When implementing a particular functionality in a computer program, make sure this functionality and its variations are implemented in just one piece of code. That is, if you need to revise the implementation, there should be *one and only one* place to edit. It follows that you should never duplicate code (don't repeat yourself!), and code snippets that are similar should be factored into one piece (function) and parameterized (by function arguments).

The DRY principle means that our `solver` function should not be copied to a new file if we need some modifications. Instead, we should try to extend `solver` such that the new and old needs are met by a single function. Sometimes this process requires a new refactoring, but having a numerical method in one and only one place is a great advantage.

## 1.7 Making a module

As soon as you start making Python functions in a program, you should make sure the program file fulfills the requirement of a module. This means that you can import and reuse your functions in other programs too. For example, if our `solver` function resides in a module file `decay.py`, another program may reuse of the function either by

```
from decay import solver
u, t = solver(I=1, a=2, T=4, dt=0.2, theta=0.5)
```

or by a slightly different import statement, combined with a subsequent prefix of the function name by the name of the module:

```
import decay
u, t = decay.solver(I=1, a=2, T=4, dt=0.2, theta=0.5)
```

The requirements for a program file to also qualify for a module are simple:

1. The filename without `.py` must be a valid Python variable name.
2. The main program must be executed (through statements or a function call) in the *test block*.

The *test block* is normally placed at the end of a module file:

```
if __name__ == '__main__':  
    # Statements
```

When the module file is executed as a stand-alone program, the if test is true and the indented statements are run. If the module file is imported, however, `__name__` equals the module name and the test block is not executed.

To demonstrate the difference, consider the trivial module file `hello.py` with one function and a call to this function as main program:

```
def hello(arg='World!'):  
    print 'Hello, ' + arg  
  
if __name__ == '__main__':  
    hello()
```

Without the test block, the code reads

```
def hello(arg='World!'):  
    print 'Hello, ' + arg  
  
hello()
```

With this latter version of the file, any attempt to import `hello` will, at the same time, execute the call `hello()` and hence write “Hello, World!” to the screen. Such output is not desired when importing a module! To make import and execution of code independent for another program that wants to use the function `hello`, the module `hello` must be written with a test block. Furthermore, running the file itself as `python hello.py` will make the block active and lead to the desired printing.

### All coming functions are placed in a module!

The many functions to be explained in the following text are put in one module file `decay.py`.

What more than the `solver` function is needed in our `decay` module to do everything we did in the previous, flat program? We need import statements for `numpy` and `matplotlib` as well as another function for producing the plot. It can also be convenient to put the exact solution in a Python function. Our module `decay.py` then looks like this:

```
import numpy as np  
import matplotlib.pyplot as plt  
  
def solver(I, a, T, dt, theta):  
    ...  
  
def u_exact(t, I, a):  
    return I*np.exp(-a*t)  
  
def experiment_compare_numerical_and_exact():
```

```

I = 1; a = 2; T = 4; dt = 0.4; theta = 1
u, t = solver(I, a, T, dt, theta)

t_e = np.linspace(0, T, 1001)      # very fine mesh for u_e
u_e = u_exact(t_e, I, a)

plt.plot(t, u, 'r--o')              # dashed red line with circles
plt.plot(t_e, u_e, 'b-')            # blue line for u_e
plt.legend(['numerical, theta=%g' % theta, 'exact'])
plt.xlabel('t')
plt.ylabel('u')
plotfile = 'tmp'
plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')

error = u_exact(t, I, a) - u
E = np.sqrt(dt*np.sum(error**2))
print 'Error norm:', E

if __name__ == '__main__':
    experiment_compare_numerical_and_exact()

```

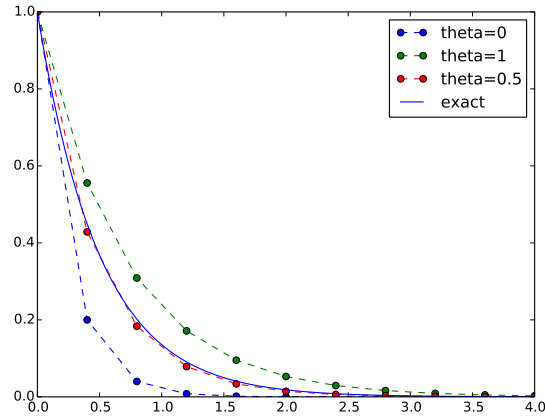
We could consider doing `from numpy import exp, sqrt, sum` to make the mathematical expressions with these functions closer to the mathematical formulas, but here we employed the prefix since the formulas are so simple and easy to read.

This module file does exactly the same as the previous, `flat` program, but now it becomes much easier to extend the code with more functions that produce other plots, other experiments, etc. Even more important, though, is that the numerical algorithm is coded and tested once and for all in the `solver` function, and any need to solve the mathematical problem is a matter of one function call.

## 1.8 Example on extending the module code

Let us specifically demonstrate one extension of the `flat` program in Section 1.2 that would require substantial editing of the `flat` code (Section 1.3), while in a structured module (Section 1.7), we can simply add a new function without affecting the existing code.

Our example that illustrates the extension is to make a comparison between the numerical solutions for various schemes ( $\theta$  values) and the exact solution:



### Wait a minute!

Look at the flat program in Section 1.2, and try to imagine which edits that are required to solve this new problem.

With the `solver` function at hand, we can simply create a function with a loop over `theta` values and add the necessary plot statements:

```
def experiment_compare_schemes():
    """Compare theta=0,1,0.5 in the same plot."""
    I = 1; a = 2; T = 4; dt = 0.4
    legends = []
    for theta in [0, 1, 0.5]:
        u, t = solver(I, a, T, dt, theta)
        plt.plot(t, u, '--o')
        legends.append('theta=%g' % theta)
    t_e = np.linspace(0, T, 1001) # very fine mesh for u_e
    u_e = u_exact(t_e, I, a)
    plt.plot(t_e, u_e, 'b-')
    legends.append('exact')
    plt.legend(legends, loc='upper right')
    plotfile = 'tmp'
    plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')
```

A call to this `experiment_compare_schemes` function must be placed in the test block, or you can run the program from IPython instead:

```
In[1]: from decay import *
In[2]: experiment_compare_schemes()
```

We do not present how the flat program from Section 1.3 must be refactored to produce the desired plots, but simply state that the danger of introducing bugs is significantly larger than when just writing an additional function in the `decay` module.

## 1.9 Documenting functions and modules

We have already emphasized the importance of documenting functions with a doc string (see Section 1.5). Now it is time to show how doc strings should be structured in order to take advantage of the documentation utilities in the `numpy` module. The idea is to follow a convention that in itself makes a good pure text doc string in the terminal window and at the same time can be translated to beautiful HTML manuals for the web.

The conventions for `numpy` style doc strings are well [documented](#), so here we just present a basic example that the reader can adopt. Input arguments to a function are listed under the heading **Parameters**, while returned values are listed under **Returns**. It is a good idea to also add an **Examples** section on the usage of the function. More complicated software may have additional sections, see `pydoc numpy.load` for an example. The markup language available for doc strings is Sphinx-extended reStructuredText. The example below shows typical constructs: 1) how inline mathematics is written with the `:math:` directive, 2) how arguments to the functions are referred to using single backticks (inline monospace font for code applies double backticks), and 3) how arguments and return values are listed with types and explanation.

```
def solver(I, a, T, dt, theta):
    """
    Solve :math:'u'=-au' with :math:'u(0)=I' for :math:'t \in (0,T]'
    with steps of 'dt' and the method implied by 'theta'.

    Parameters
    -----
    I: float
        Initial condition.
    a: float
        Parameter in the differential equation.
    T: float
        Total simulation time.
    theta: float, int
        Parameter in the numerical scheme. 0 gives
        Forward Euler, 1 Backward Euler, and 0.5
        the centered Crank-Nicolson scheme.

    Returns
    -----
    'u': array
        Solution array.
    't': array
        Array with time points corresponding to 'u'.

    Examples
    -----
    Solve :math:'u' = -\frac{1}{2}u, u(0)=1.5'
    with the Crank-Nicolson method:

    >>> u, t = solver(I=1.5, a=0.5, T=9, theta=0.5)
    >>> import matplotlib.pyplot as plt
    >>> plt.plot(t, u)
    >>> plt.show()
    """
```

If you follow such doc string conventions in your software, you can easily produce nice manuals that meet the standard expected within the Python scientific computing community.

[Sphinx](#) requires quite a number of manual steps to prepare a manual, so it is recommended to use a [premade script](#) to automate the steps. (By default, the script generates documentation for all `*.py` files in the current directory. You need to do a `pip install` of `sphinx` and `numpydoc` to make the script work.) Figure 2 provides an example of what the above doc strings look like when Sphinx has transformed them to HTML.

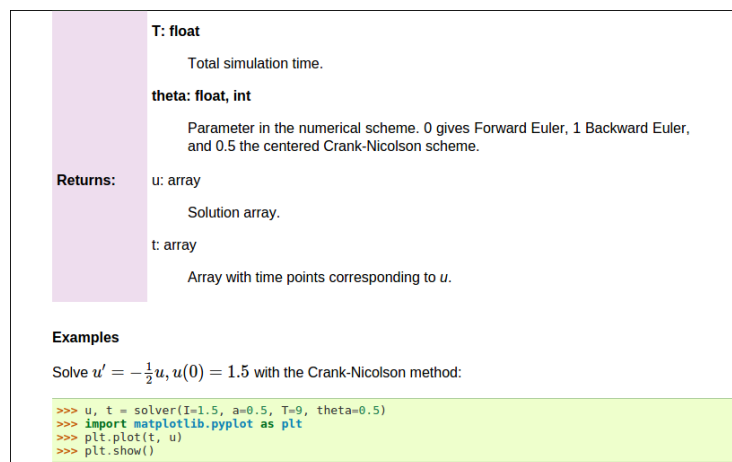


Figure 2: Example on Sphinx API manual in HTML.

## 1.10 Logging intermediate results

Sometimes one may wish that a simulation program could write out intermediate results for inspection. This could be accomplished by a (global) `verbose` variable and code like

```
if verbose >= 2:
    print 'u[%d]=%g' % (i, u[i])
```

The professional way to do report intermediate results and problems is, however, to use a *logger*. This is an object that writes messages to a log file. The messages are classified as debug, info, and warning.

**Introductory example.** Here is a simple example using defining a logger, using Python's `logging` module:



```

import logging
# Configure logger
logging.basicConfig(
    filename='myprog.log', filemode='w', level=logging.WARNING,
    format='%(asctime)s - %(levelname)s - %(message)s',
    datefmt='%m/%d/%Y %I:%M:%S %p')
# Perform logging
logging.info('Here is some general info.')
logging.warning('Here is a warning.')
logging.debug('Here is some debugging info.')
logging.critical('Dividing by zero!')
logging.error('Encountered an error.')

```

Running this program gives the following output in the log file `myprog.log`:

```

09/26/2015 09:25:10 AM - INFO - Here is some general info.
09/26/2015 09:25:10 AM - WARNING - Here is a warning.
09/26/2015 09:25:10 AM - CRITICAL - Dividing by zero!
09/26/2015 09:25:10 AM - ERROR - Encountered an error.

```

The logger has different *levels* of messages, ordered as *critical*, *error*, *warning*, *info*, and *debug*. The `level` argument to `logging.basicConfig` sets the level and thereby determines what the logger will print to the file: all messages at the specified *and lower* levels are printed. For example, in the above example we set the level to be *info*, and therefore the critical, error, warning, and info messages were printed, but not the debug message. Setting level to debug (`logging.DEBUG`) prints all messages, while level *critical* prints only the critical messages.

The `filemode` argument is set to `w` such that any existing log file is overwritten (the default is `a`, which means append new messages to an existing log file, but this is seldom what you want in mathematical computations).

The messages are preceded by the date and time and the level of the message. This output is governed by the `format` argument: `asctime` is the date and time, `levelname` is the name of the message level, and `message` is the message itself. Setting `format='%(message)s'` ensures that just the message and nothing more is printed on each line. The `datefmt` string specifies the formatting of the date and time, using the rules of the `time.strftime` function.

**Using a logger in our solver function.** Let us let a logger write out intermediate results and some debugging results in the `solver` function. Such messages are useful for monitoring the simulation and for debugging it, respectively.

```

def solver_with_logging(I, a, T, dt, theta):
    """Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt."""
    dt = float(dt)                # avoid integer division
    Nt = int(round(T/dt))          # no of time intervals
    T = Nt*dt                     # adjust T to fit time step dt
    u = np.zeros(Nt+1)            # array of u[n] values
    t = np.linspace(0, T, Nt+1)   # time mesh
    logging.debug('solver: dt=%g, Nt=%g, T=%g' % (dt, Nt, T))

    u[0] = I                      # assign initial condition
    for n in range(0, Nt):        # n=0,1,...,Nt-1

```

```

        u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]

        logging.info('u[%d]=%g' % (n, u[n]))
        logging.debug('1 - (1-theta)*a*dt: %g, %s' %
                      (1-(1-theta)*a*dt,
                       str(type(1-(1-theta)*a*dt))[7:-2]))
        logging.debug('1 + theta*dt*a: %g, %s' %
                      (1 + theta*dt*a,
                       str(type(1 + theta*dt*a))[7:-2]))

    return u, t

def configure_basic_logger():
    logging.basicConfig(
        filename='decay.log', filemode='w', level=logging.DEBUG,
        format='%(asctime)s - %(levelname)s - %(message)s',
        datefmt='%Y.%m.%d %I:%M:%S %p')

import sys

def read_command_line_positional():
    if len(sys.argv) < 6:
        print 'Usage: %s I a T on/off BE/FE/CN dt1 dt2 dt3 ...' % \
              sys.argv[0]; sys.exit(1) # abort

    I = float(sys.argv[1])
    a = float(sys.argv[2])
    T = float(sys.argv[3])

    # Name of schemes: BE (Backward Euler), FE (Forward Euler),
    # CN (Crank-Nicolson)
    scheme = sys.argv[4]
    scheme2theta = {'BE': 1, 'CN': 0.5, 'FE': 0}
    if scheme in scheme2theta:
        theta = scheme2theta[scheme]
    else:
        print 'Invalid scheme name:', scheme; sys.exit(1)

    dt_values = [float(arg) for arg in sys.argv[5:]]

    return I, a, T, theta, dt_values

def define_command_line_options():
    import argparse
    parser = argparse.ArgumentParser()
    parser.add_argument(
        '--I', '--initial_condition', type=float,
        default=1.0, help='initial condition, u(0)',
        metavar='I')
    parser.add_argument(
        '--a', type=float, default=1.0,
        help='coefficient in ODE', metavar='a')
    parser.add_argument(
        '--T', '--stop_time', type=float,
        default=1.0, help='end time of simulation',
        metavar='T')
    parser.add_argument(
        '--scheme', type=str, default='CN',
        help='FE, BE, or CN')
    parser.add_argument(
        '--dt', '--time_step_values', type=float,
        default=[1.0], help='time step values',
        metavar='dt', nargs='+', dest='dt_values')
    return parser

```

```

def read_command_line_argparse():
    parser = define_command_line_options()
    args = parser.parse_args()
    scheme2theta = {'BE': 1, 'CN': 0.5, 'FE': 0}
    data = (args.I, args.a, args.T, scheme2theta[args.scheme],
            args.dt_values)
    return data

def experiment_compare_dt(option_value_pairs=False):
    I, a, T, theta, dt_values = \
        read_command_line_argparse() if option_value_pairs else \
        read_command_line_positional()

    legends = []
    for dt in dt_values:
        u, t = solver(I, a, T, dt, theta)
        plt.plot(t, u)
        legends.append('dt=%g' % dt)
    t_e = np.linspace(0, T, 1001)      # very fine mesh for u_e
    u_e = u_exact(t_e, I, a)
    plt.plot(t_e, u_e, '--')
    legends.append('exact')
    plt.legend(legends, loc='upper right')
    plt.title('theta=%g' % theta)
    plotfile = 'tmp'
    plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')

def compute4web(I, a, T, dt, theta=0.5):
    """
    Run a case with the solver, compute error measure,
    and plot the numerical and exact solutions in a PNG
    plot whose data are embedded in an HTML image tag.
    """
    u, t = solver(I, a, T, dt, theta)
    u_e = u_exact(t, I, a)
    e = u_e - u
    E = np.sqrt(dt*np.sum(e**2))

    plt.figure()
    t_e = np.linspace(0, T, 1001)      # fine mesh for u_e
    u_e = u_exact(t_e, I, a)
    plt.plot(t, u, 'r--o')
    plt.plot(t_e, u_e, 'b-')
    plt.legend(['numerical', 'exact'])
    plt.xlabel('t')
    plt.ylabel('u')
    plt.title('theta=%g, dt=%g' % (theta, dt))
    # Save plot to HTML img tag with PNG code as embedded data
    from parampool.utils import save_png_to_str
    html_text = save_png_to_str(plt, plotwidth=400)

    return E, html_text

def main_GUI(I=1.0, a=.2, T=4.0,
             dt_values=[1.25, 0.75, 0.5, 0.1],
             theta_values=[0, 0.5, 1]):
    # Build HTML code for web page. Arrange plots in columns
    # corresponding to the theta values, with dt down the rows
    theta2name = {0: 'FE', 1: 'BE', 0.5: 'CN'}
    html_text = '<table>\n'
    for dt in dt_values:
        html_text += '<tr>\n'
        for theta in theta_values:
            E, html = compute4web(I, a, T, dt, theta)

```

```

        html_text += """
<td>
<center><b>%s, dt=%g, error: %.3E</b></center><br>
%s
</td>
""" % (theta2name[theta], dt, E, html)
        html_text += '</tr>\n'
        html_text += '</table>\n'
        return html_text

def solver_with_doctest(I, a, T, dt, theta):
    """
    Solve  $u' = -a*u$ ,  $u(0)=I$ , for  $t$  in  $(0, T]$  with steps of  $dt$ .

    >>> u, t = solver(I=0.8, a=1.2, T=1.5, dt=0.5, theta=0.5)
    >>> for n in range(len(t)):
    ...     print 't=%.1f, u=%.14f' % (t[n], u[n])
    t=0.0, u=0.8000000000000000
    t=0.5, u=0.43076923076923
    t=1.0, u=0.23195266272189
    t=1.5, u=0.12489758761948
    """
    dt = float(dt) # avoid integer division
    Nt = int(round(T/dt)) # no of time intervals
    T = Nt*dt # adjust T to fit time step dt
    u = np.zeros(Nt+1) # array of u[n] values
    t = np.linspace(0, T, Nt+1) # time mesh

    u[0] = I # assign initial condition
    for n in range(0, Nt): # n=0,1,...,Nt-1
        u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]
    return u, t

def third(x):
    return x/3.

def test_third():
    x = 0.15
    expected = (1/3.)*x
    computed = third(x)
    tol = 1E-15
    success = abs(expected - computed) < tol
    assert success

def u_discrete_exact(n, I, a, theta, dt):
    """Return exact discrete solution of the numerical schemes."""
    dt = float(dt) # avoid integer division
    A = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)
    return I*A**n

def test_u_discrete_exact():
    """Check that solver reproduces the exact discr. sol."""
    theta = 0.8; a = 2; I = 0.1; dt = 0.8
    Nt = int(8/dt) # no of steps
    u, t = solver(I=I, a=a, T=Nt*dt, dt=dt, theta=theta)

    # Evaluate exact discrete solution on the mesh
    u_de = np.array([u_discrete_exact(n, I, a, theta, dt)
                     for n in range(Nt+1)])

    # Find largest deviation
    diff = np.abs(u_de - u).max()
    tol = 1E-14

```

```

success = diff < tol
assert success

def test_potential_integer_division():
    """Choose variables that can trigger integer division."""
    theta = 1; a = 1; I = 1; dt = 2
    Nt = 4
    u, t = solver(I=I, a=a, T=Nt*dt, dt=dt, theta=theta)
    u_de = np.array([u_discrete_exact(n, I, a, theta, dt)
                     for n in range(Nt+1)])
    diff = np.abs(u_de - u).max()
    assert diff < 1E-14

def test_read_command_line_positional():
    # Decide on a data set of input parameters
    I = 1.6; a = 1.8; T = 2.2; theta = 0.5
    dt_values = [0.1, 0.2, 0.05]
    # Expected return from read_command_line_positional
    expected = [I, a, T, theta, dt_values]
    # Construct corresponding sys.argv array
    sys.argv = [sys.argv[0], str(I), str(a), str(T), 'CN'] + \
               [str(dt) for dt in dt_values]
    computed = read_command_line_positional()
    for expected_arg, computed_arg in zip(expected, computed):
        assert expected_arg == computed_arg

def test_read_command_line_argparse():
    I = 1.6; a = 1.8; T = 2.2; theta = 0.5
    dt_values = [0.1, 0.2, 0.05]
    # Expected return from read_command_line_argparse
    expected = [I, a, T, theta, dt_values]
    # Construct corresponding sys.argv array
    command_line = '%s --a %s --I %s --T %s --scheme CN --dt % ' % \
                   (sys.argv[0], a, I, T)
    command_line += ' '.join([str(dt) for dt in dt_values])
    sys.argv = command_line.split()
    computed = read_command_line_argparse()
    for expected_arg, computed_arg in zip(expected, computed):
        assert expected_arg == computed_arg

# Classes

class Problem(object):
    def __init__(self, I=1, a=1, T=10):
        self.T, self.I, self.a = I, float(a), T

    def define_command_line_options(self, parser=None):
        """Return updated (parser) or new ArgumentParser object."""
        if parser is None:
            import argparse
            parser = argparse.ArgumentParser()

        parser.add_argument(
            '--I', '--initial_condition', type=float,
            default=1.0, help='initial condition, u(0)',
            metavar='I')
        parser.add_argument(
            '--a', type=float, default=1.0,
            help='coefficient in ODE', metavar='a')
        parser.add_argument(
            '--T', '--stop_time', type=float,
            default=1.0, help='end time of simulation',
            metavar='T')
        return parser

```

```

def init_from_command_line(self, args):
    """Load attributes from ArgumentParser into instance."""
    self.I, self.a, self.T = args.I, args.a, args.T

def u_exact(self, t):
    """Return the exact solution  $u(t)=I\exp(-a*t)$ ."""
    I, a = self.I, self.a
    return I*exp(-a*t)

class Solver(object):
    def __init__(self, problem, dt=0.1, theta=0.5):
        self.problem = problem
        self.dt, self.theta = float(dt), theta

    def define_command_line_options(self, parser):
        """Return updated (parser) or new ArgumentParser object."""
        parser.add_argument(
            '--scheme', type=str, default='CN',
            help='FE, BE, or CN')
        parser.add_argument(
            '--dt', '--time_step_values', type=float,
            default=[1.0], help='time step values',
            metavar='dt', nargs='+', dest='dt_values')
        return parser

    def init_from_command_line(self, args):
        """Load attributes from ArgumentParser into instance."""
        self.dt, self.theta = args.dt, args.theta

    def solve(self):
        self.u, self.t = solver(
            self.problem.I, self.problem.a, self.problem.T,
            self.dt, self.theta)

    def error(self):
        """Return norm of error at the mesh points."""
        u_e = self.problem.u_exact(self.t)
        e = u_e - self.u
        E = np.sqrt(self.dt*np.sum(e**2))
        return E

def experiment_classes():
    problem = Problem()
    solver = Solver(problem)

    # Read input from the command line
    parser = problem.define_command_line_options()
    parser = solver.define_command_line_options(parser)
    args = parser.parse_args()
    problem.init_from_command_line(args)
    solver.init_from_command_line(args)

    # Solve and plot
    solver.solve()
    import matplotlib.pyplot as plt
    t_e = np.linspace(0, T, 1001) # very fine mesh for u_e
    u_e = problem.u_exact(t_e)
    print 'Error:', solver.error()

    plt.plot(t, u, 'r--o')
    plt.plot(t_e, u_e, 'b-')
    plt.legend(['numerical, theta=%g' % theta, 'exact'])

```

```

plt.xlabel('t')
plt.ylabel('u')
plotfile = 'tmp'
plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')
plt.show()

if __name__ == '__main__':
    configure_logger()
    experiment_compare_dt(True)
    plt.show()

```

The application code that calls `solver_with_logging` needs to configure the logger. The `decay` module offers a default configure function:

```

import logging

def configure_basic_logger():
    logging.basicConfig(
        filename='decay.log', filemode='w', level=logging.DEBUG,
        format='%(asctime)s - %(levelname)s - %(message)s',
        datefmt='%Y.%m.%d %I:%M:%S %p')

```

If the user of a library does not configure a logger or call this configure function, the library should prevent error messages by declaring a default logger that does nothing:

```

import logging
logging.getLogger('decay').addHandler(logging.NullHandler())

```

We can run the new solver function with logging in a shell:

```

>>> import decay
>>> decay.configure_basic_logger()
>>> u, t = decay.solver_with_logging(I=1, a=0.5, T=10, \
    dt=0.5, theta=0.5)

```

During this execution, each logging message is appended to the log file. Suppose we add some pause (`time.sleep(2)`) at each time level such that the execution takes some time. In another terminal window we can then monitor the evolution of `decay.log` and the simulation by the `tail -f` Unix command:

```

Terminal> tail -f decay.log
2015.09.26 05:37:41 AM - INFO - u[0]=1
2015.09.26 05:37:41 AM - INFO - u[1]=0.777778
2015.09.26 05:37:41 AM - INFO - u[2]=0.604938
2015.09.26 05:37:41 AM - INFO - u[3]=0.470508
2015.09.26 05:37:41 AM - INFO - u[4]=0.36595
2015.09.26 05:37:41 AM - INFO - u[5]=0.284628

```

Especially in simulation where each time step demands considerable CPU time (minutes, hours), it can be handy to monitor such a log file to see the evolution of the simulation.

If we want to look more closely into the numerator and denominator of the formula for  $u^{n+1}$ , we can change the logging level to `level=logging.DEBUG` and get output in `decay.log` like

```

2015.09.26 05:40:01 AM - DEBUG - solver: dt=0.5, Nt=20, T=10
2015.09.26 05:40:01 AM - INFO - u[0]=1
2015.09.26 05:40:01 AM - DEBUG - 1 - (1-theta)*a*dt: 0.875, float
2015.09.26 05:40:01 AM - DEBUG - 1 + theta*dt*a: 1.125, float
2015.09.26 05:40:01 AM - INFO - u[1]=0.777778
2015.09.26 05:40:01 AM - DEBUG - 1 - (1-theta)*a*dt: 0.875, float
2015.09.26 05:40:01 AM - DEBUG - 1 + theta*dt*a: 1.125, float
2015.09.26 05:40:01 AM - INFO - u[2]=0.604938
2015.09.26 05:40:01 AM - DEBUG - 1 - (1-theta)*a*dt: 0.875, float
2015.09.26 05:40:01 AM - DEBUG - 1 + theta*dt*a: 1.125, float
2015.09.26 05:40:01 AM - INFO - u[3]=0.470508
2015.09.26 05:40:01 AM - DEBUG - 1 - (1-theta)*a*dt: 0.875, float
2015.09.26 05:40:01 AM - DEBUG - 1 + theta*dt*a: 1.125, float
2015.09.26 05:40:01 AM - INFO - u[4]=0.36595
2015.09.26 05:40:01 AM - DEBUG - 1 - (1-theta)*a*dt: 0.875, float
2015.09.26 05:40:01 AM - DEBUG - 1 + theta*dt*a: 1.125, float

```

Logging can be much more sophisticated than shown above. One can, e.g., output critical messages to the screen and all messages to a file. This requires more code as demonstrated in the [Logging Cookbook](#).

## 2 User interfaces

It is good programming practice to let programs read input from some *user interface*, rather than requiring users to *edit* parameter values in the source code. With effective user interfaces it becomes easier and safer to apply the code for scientific investigations and in particular to automate large-scale investigations by other programs (see Section 6).

Reading input data can be done in many ways. We have to decide on the functionality of the user interface, i.e., how we want to operate the program when providing input. Thereafter, we use appropriate tools to implement the particular user interface. There are four basic types of user interface, listed here according to implementational complexity, from lowest to highest:

1. Questions and answers in the terminal window
2. Command-line arguments
3. Reading data from files
4. Graphical user interfaces (GUIs)

Personal preferences of user interfaces differ substantially, and it is difficult to present recommendations or pros and cons. Alternatives 2 and 4 are most popular and will be addressed next. The goal is to make it easy for the user to set physical and numerical parameters in our `decay.py` program. However, we use a little toy program, called `prog.py`, as introductory example:

```

delta = 0.5
p = 2
from math import exp
result = delta*exp(-p)
print result

```



The essential content is that `prog.py` has two input parameters: `delta` and `p`. A user interface will replace the first two assignments to `delta` and `p`.

## 2.1 Command-line arguments

The command-line arguments are all the words that appear on the command line after the program name. Running a program `prog.py` as `python prog.py arg1 arg2` means that there are two command-line arguments (separated by white space): `arg1` and `arg2`. Python stores all command-line arguments in a special list `sys.argv`. (The name `argv` stems from the C language and stands for “argument values”. In C there is also an integer variable called `argc` reflecting the number of arguments, or “argument counter”. A lot of programming languages have adopted the variable name `argv` for the command-line arguments.) Here is an example on a program `what_is_sys_argv.py` that can show us what the command-line arguments are

```
import sys
print sys.argv
```

A sample run goes like

---

Terminal

---

```
Terminal> python what_is_sys_argv.py 5.0 'two words' -1E+4
['what_is_sys_argv.py', '5.0', 'two words', '-1E+4']
```

---

We make two observations:

- `sys.argv[0]` is the name of the program, and the sublist `sys.argv[1:]` contains all the command-line arguments.
- Each command-line argument is available as a string. A conversion to `float` is necessary if we want to compute with the numbers 5.0 and  $10^4$ .

There are, in principle, two ways of programming with command-line arguments in Python:

- **Positional arguments:** Decide upon a sequence of parameters on the command line and read their values directly from the `sys.argv[1:]` list.
- **Option-value pairs:** Use `-option value` on the command line to replace the default value of an input parameter `option` by `value` (and utilize the `argparse.ArgumentParser` tool for implementation).

Suppose we want to run some program `prog.py` with specification of two parameters `p` and `delta` on the command line. With positional command-line arguments we write

---

Terminal

---

```
Terminal> python prog.py 2 0.5
```

---

and must know that the first argument 2 represents `p` and the next 0.5 is the value of `delta`. With option-value pairs we can run

---

Terminal

---

```
Terminal> python prog.py --delta 0.5 --p 2
```

---

Now, both `p` and `delta` are supposed to have default values in the program, so we need to specify only the parameter that is to be changed from its default value, e.g.,

---

Terminal

---

```
Terminal> python prog.py --p 2           # p=2, default delta
Terminal> python prog.py --delta 0.7     # delta=0.7, default a
Terminal> python prog.py                 # default a and delta
```

---

How do we extend the `prog.py` code for positional arguments and option-value pairs? Positional arguments require very simple code:

```
import sys
p = float(sys.argv[1])
delta = float(sys.argv[2])

from math import exp
result = delta*exp(-p)
print result
```

If the user forgets to supply two command-line arguments, Python will raise an `IndexError` exception and produce a long error message. To avoid that, we should use a `try-except` construction:

```
import sys
try:
    p = float(sys.argv[1])
    delta = float(sys.argv[2])
except IndexError:
    print 'Usage: %s p delta' % sys.argv[0]
    sys.exit(1)

from math import exp
result = delta*exp(-p)
print result
```

Using `sys.exit(1)` aborts the program. The value 1 (actually any value different from 0) notifies the operating system that the program failed.

### Command-line arguments are strings!

Note that all elements in `sys.argv` are string objects. If the values are used in mathematical computations, we need to explicitly convert the strings to numbers.

Option-value pairs requires more programming and is actually better explained in a more comprehensive example below. Minimal code for our `prog.py` program reads

```
import argparse
parser = argparse.ArgumentParser()
parser.add_argument('--p', default=1.0)
parser.add_argument('--delta', default=0.1)

args = parser.parse_args()
p = args.p
delta = args.delta

from math import exp
result = delta*exp(-p)
print result
```

Because the default values of `delta` and `p` are float numbers, the `args.delta` and `args.p` variables are automatically of type `float`.

Our next task is to use these basic code constructs to equip our `decay.py` module with command-line interfaces.

## 2.2 Positional command-line arguments

For our `decay.py` module file, we want to include functionality such that we can read  $I$ ,  $a$ ,  $T$ ,  $\theta$ , and a range of  $\Delta t$  values from the command line. A plot is then to be made, comparing the different numerical solutions for different  $\Delta t$  values against the exact solution. The technical details of getting the command-line information into the program is covered in the next two sections.

The simplest way of reading the input parameters is to decide on their sequence on the command line and just index the `sys.argv` list accordingly. Say the sequence of input data for some functionality in `decay.py` is  $I$ ,  $a$ ,  $T$ ,  $\theta$  followed by an arbitrary number of  $\Delta t$  values. This code extracts these *positional* command-line arguments:

```
def read_command_line_positional():
    if len(sys.argv) < 6:
        print 'Usage: %s I a T on/off BE/FE/CN dt1 dt2 dt3 ...' % \
            sys.argv[0]; sys.exit(1) # abort

    I = float(sys.argv[1])
    a = float(sys.argv[2])
    T = float(sys.argv[3])
    theta = float(sys.argv[4])
    dt_values = [float(arg) for arg in sys.argv[5:]]

    return I, a, T, theta, dt_values
```

Note that we may use a `try-except` construction instead of the if test.

A run like

---

Terminal

---

```
Terminal> python decay.py 1 0.5 4 0.5 1.5 0.75 0.1
```

---

results in

```
sys.argv = ['decay.py', '1', '0.5', '4', '0.5', '1.5', '0.75', '0.1']
```

and consequently the assignments `I=1.0`, `a=0.5`, `T=4.0`, `thet=0.5`, and `dt_values = [1.5, 0.75, 0.1]`.

Instead of specifying the  $\theta$  value, we could be a bit more sophisticated and let the user write the name of the scheme: **BE** for Backward Euler, **FE** for Forward Euler, and **CN** for Crank-Nicolson. Then we must map this string to the proper  $\theta$  value, an operation elegantly done by a dictionary:

```
scheme = sys.argv[4]
scheme2theta = {'BE': 1, 'CN': 0.5, 'FE': 0}
if scheme in scheme2theta:
    theta = scheme2theta[scheme]
else:
    print 'Invalid scheme name:', scheme; sys.exit(1)
```

Now we can do

---

Terminal

---

```
Terminal> python decay.py 1 0.5 4 CN 1.5 0.75 0.1
```

---

and get `'theta=0.5'` in the code.

## 2.3 Option-value pairs on the command line

Now we want to specify option-value pairs on the command line, using `-I` for `I` ( $I$ ), `-a` for `a` ( $a$ ), `-T` for `T` ( $T$ ), `-scheme` for the scheme name (**BE**, **FE**, **CN**), and `-dt` for the sequence of `dt` ( $\Delta t$ ) values. Each parameter must have a sensible default value so that we specify the option on the command line only when the default value is not suitable. Here is a typical run:

---

Terminal

---

```
Terminal> python decay.py --I 2.5 --dt 0.1 0.2 0.01 --a 0.4
```

---

Observe the major advantage over positional command-line arguments: the input is much easier to read and much easier to write. With positional arguments it is easy to mess up the sequence of the input parameters and quite challenging to detect errors too, unless there are just a couple of arguments.

Python's `ArgumentParser` tool in the `argparse` module makes it easy to create a professional command-line interface to any program. The documentation of `ArgumentParser` demonstrates its versatile applications, so we shall here just list an example containing the most basic features. It always pays off to use `ArgumentParser` rather than trying to manually inspect and interpret option-value pairs in `sys.argv`!

The use of `ArgumentParser` typically involves three steps:

```
import argparse
parser = argparse.ArgumentParser()

# Step 1: add arguments
parser.add_argument('--option_name', ...)

# Step 2: interpret the command line
args = parser.parse_args()

# Step 3: extract values
value = args.option_name
```

A function for setting up all the options is handy:

```
def define_command_line_options():
    import argparse
    parser = argparse.ArgumentParser()
    parser.add_argument(
        '--I', '--initial_condition', type=float,
        default=1.0, help='initial condition, u(0)',
        metavar='I')
    parser.add_argument(
        '--a', type=float, default=1.0,
        help='coefficient in ODE', metavar='a')
    parser.add_argument(
        '--T', '--stop_time', type=float,
        default=1.0, help='end time of simulation',
        metavar='T')
    parser.add_argument(
        '--scheme', type=str, default='CN',
        help='FE, BE, or CN')
    parser.add_argument(
        '--dt', '--time_step_values', type=float,
        default=[1.0], help='time step values',
        metavar='dt', nargs='+', dest='dt_values')
    return parser
```

Each command-line option is defined through the `parser.add_argument` method<sup>1</sup>. Alternative options, like the short `-I` and the more explaining version `--initial_condition` can be defined. Other arguments are `type` for the Python object type, a default value, and a help string, which gets printed if the command-line argument `-h` or `-help` is included. The `metavar` argument specifies the value associated with the option when the help string is printed. For example, the option for `I` has this help output:

---

Terminal

---

```
Terminal> python decay.py -h
...
--I I, --initial_condition I
                        initial condition, u(0)
...
```

---

The structure of this output is

---

<sup>1</sup>We use the expression *method* here, because `parser` is a class variable and functions in classes are known as methods in Python and many other languages. Readers not familiar with class programming can just substitute this use of *method* by *function*.

```
--I metavar, --initial_condition metavar
                        help-string
```

Finally, the `-dt` option demonstrates how to allow for more than one value (separated by blanks) through the `nargs='+'` keyword argument. After the command line is parsed, we get an object where the values of the options are stored as attributes. The attribute name is specified by the `dest` keyword argument, which for the `-dt` option is `dt_values`. Without the `dest` argument, the value of an option `-opt` is stored as the attribute `opt`.

The code below demonstrates how to read the command line and extract the values for each option:

```
def read_command_line_argparse():
    parser = define_command_line_options()
    args = parser.parse_args()
    scheme2theta = {'BE': 1, 'CN': 0.5, 'FE': 0}
    data = (args.I, args.a, args.T, scheme2theta[args.scheme],
            args.dt_values)
    return data
```

As seen, the values of the command-line options are available as attributes in `args`: `args.opt` holds the value of option `-opt`, unless we used the `dest` argument (as for `--dt_values`) for specifying the attribute name. The `args.opt` attribute has the object type specified by `type` (`str` by default).

The making of the plot is not dependent on whether we read data from the command line as positional arguments or option-value pairs:

```
def experiment_compare_dt(option_value_pairs=False):
    I, a, T, theta, dt_values = \
        read_command_line_argparse() if option_value_pairs else \
        read_command_line_positional()

    legends = []
    for dt in dt_values:
        u, t = solver(I, a, T, dt, theta)
        plt.plot(t, u)
        legends.append('dt=%g' % dt)
    t_e = np.linspace(0, T, 1001)      # very fine mesh for u_e
    u_e = u_exact(t_e, I, a)
    plt.plot(t_e, u_e, '--')
    legends.append('exact')
    plt.legend(legends, loc='upper right')
    plt.title('theta=%g' % theta)
    plotfile = 'tmp'
    plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')
```

## 2.4 Creating a graphical web user interface

The Python package [Parampool](#) can be used to automatically generate a web-based *graphical user interface* (GUI) for our simulation program. Although the programming technique dramatically simplifies the efforts to create a GUI, the forthcoming material on equipping our decay module with a GUI is quite

technical and of significantly less importance than knowing how to make a command-line interface.

**Making a compute function.** The first step is to identify a function that performs the computations and that takes the necessary input variables as arguments. This is called the *compute function* in Parampool terminology. The purpose of this function is to take values of  $I$ ,  $a$ ,  $T$  together with a sequence of  $\Delta t$  values and a sequence of  $\theta$  and plot the numerical against the exact solution for each pair of  $(\theta, \Delta t)$ . The plots can be arranged as a table with the columns being scheme type ( $\theta$  value) and the rows reflecting the discretization parameter ( $\Delta t$  value). Figure 3 displays what the graphical web interface may look like after results are computed (there are  $3 \times 3$  plots in the GUI, but only  $2 \times 2$  are visible in the figure).

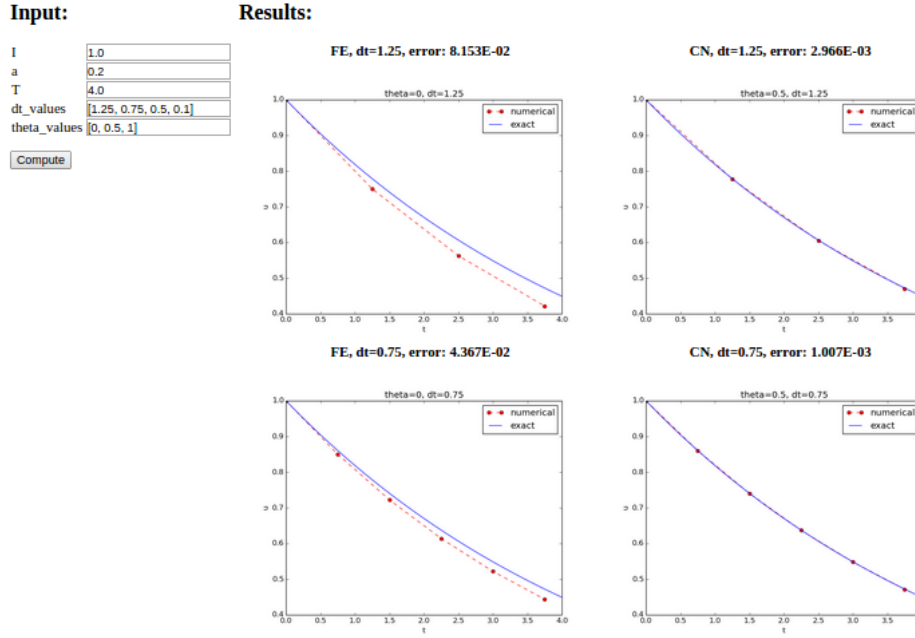


Figure 3: Automatically generated graphical web interface.

To tell Parampool what type of input data we have, we assign default values of the right type to all arguments in the compute function, here called `main_GUI`:

```
def main_GUI(I=1.0, a=.2, T=4.0,
             dt_values=[1.25, 0.75, 0.5, 0.1],
             theta_values=[0, 0.5, 1]):
```

The compute function must return the HTML code we want for displaying the result in a web page. Here we want to show a table of plots. Assume for now

that the HTML code for one plot and the value of the norm of the error can be computed by some other function `compute4web`. The `main_GUI` function can then loop over  $\Delta t$  and  $\theta$  values and put each plot in an HTML table. Appropriate code goes like

```
def main_GUI(I=1.0, a=.2, T=4.0,
            dt_values=[1.25, 0.75, 0.5, 0.1],
            theta_values=[0, 0.5, 1]):
    # Build HTML code for web page. Arrange plots in columns
    # corresponding to the theta values, with dt down the rows
    theta2name = {0: 'FE', 1: 'BE', 0.5: 'CN'}
    html_text = '<table>\n'
    for dt in dt_values:
        html_text += '<tr>\n'
        for theta in theta_values:
            E, html = compute4web(I, a, T, dt, theta)
            html_text += """
<td>
<center><b>%s, dt=%g, error: %.3E</b></center><br>
%s
</td>
""" % (theta2name[theta], dt, E, html)
        html_text += '</tr>\n'
    html_text += '</table>\n'
    return html_text
```

Making one plot is done in `compute4web`. The statements should be straightforward from earlier examples, but there is one new feature: we use a tool in Parampool to embed the PNG code for a plot file directly in an HTML image tag. The details are hidden from the programmer, who can just rely on relevant HTML code in the string `html_text`. The function looks like

```
def compute4web(I, a, T, dt, theta=0.5):
    """
    Run a case with the solver, compute error measure,
    and plot the numerical and exact solutions in a PNG
    plot whose data are embedded in an HTML image tag.
    """
    u, t = solver(I, a, T, dt, theta)
    u_e = u_exact(t, I, a)
    e = u_e - u
    E = np.sqrt(dt*np.sum(e**2))

    plt.figure()
    t_e = np.linspace(0, T, 1001)    # fine mesh for u_e
    u_e = u_exact(t_e, I, a)
    plt.plot(t, u, 'r--o')
    plt.plot(t_e, u_e, 'b-')
    plt.legend(['numerical', 'exact'])
    plt.xlabel('t')
    plt.ylabel('u')
    plt.title('theta=%g, dt=%g' % (theta, dt))
    # Save plot to HTML img tag with PNG code as embedded data
    from parampool.utils import save_png_to_str
    html_text = save_png_to_str(plt, plotwidth=400)

    return E, html_text
```



**Generating the user interface.** The web GUI is automatically generated by the following code, placed in the file `decay_GUI_generate.py`.

```
from parampool.generator.flask import generate
from decay import main_GUI
generate(main_GUI,
         filename_controller='decay_GUI_controller.py',
         filename_template='decay_GUI_view.py',
         filename_model='decay_GUI_model.py')
```

Running the `decay_GUI_generate.py` program results in three new files whose names are specified in the call to `generate`:

1. `decay_GUI_model.py` defines HTML widgets to be used to set input data in the web interface,
2. `templates/decay_GUI_views.py` defines the layout of the web page,
3. `decay_GUI_controller.py` runs the web application.

We only need to run the last program, and there is no need to look into these files.

**Running the web application.** The web GUI is started by

---

Terminal

---

```
Terminal> python decay_GUI_controller.py
```

---

Open a web browser at the location `127.0.0.1:5000`. Input fields for `I`, `a`, `T`, `dt_values`, and `theta_values` are presented. Figure 3 shows a part of the resulting page if we run with the default values for the input parameters. With the techniques demonstrated here, one can easily create a tailored web GUI for a particular type of application and use it to interactively explore physical and numerical effects.

### 3 Tests for verifying implementations

Any module with functions should have a set of tests that can check the correctness of the implementations. There exists well-established procedures and corresponding tools for automating the execution of such tests. These tools allow large test sets to be run with a one-line command, making it easy to check that the software still works (as far as the tests can tell!). Here we shall illustrate two important software testing techniques: *doctest* and *unit testing*. The first one is Python specific, while unit testing is the dominating test technique in the software industry today.

### 3.1 Doctests

A doc string, the first string after the function header, is used to document the purpose of functions and their arguments (see Section 1.5). Very often it is instructive to include an example in the doc string on how to use the function. Interactive examples in the Python shell are most illustrative as we can see the output resulting from the statements and expressions. For example, in the `solver` function, we can include an example on calling this function and printing the computed `u` and `t` arrays:

```
def solver(I, a, T, dt, theta):
    """
    Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt.

    >>> u, t = solver(I=0.8, a=1.2, T=1.5, dt=0.5, theta=0.5)
    >>> for n in range(len(t)):
    ...     print 't=%.1f, u=%.14f' % (t[n], u[n])
    t=0.0, u=0.8000000000000000
    t=0.5, u=0.43076923076923
    t=1.0, u=0.23195266272189
    t=1.5, u=0.12489758761948
    """
    ...
```

When such interactive demonstrations are inserted in doc strings, Python's `doctest` module can be used to automate running all commands in interactive sessions and compare new output with the output appearing in the doc string. All we have to do in the current example is to run the module file `decay.py` with

```
Terminal> python -m doctest decay.py
```

This command imports the `doctest` module, which runs all doctests found in the file and reports discrepancies between expected and computed output. Alternatively, the test block in a module may run all doctests by

```
if __name__ == '__main__':
    import doctest
    doctest.testmod()
```

Doctests can also be embedded in nose/pytest unit tests as explained in the next section.

#### Doctests prevent command-line arguments!

No additional command-line argument is allowed when running doctests. If your program relies on command-line input, make sure the doctests can be run *without* such input on the command line.

However, you can simulate command-line input by filling `sys.argv` with values, e.g.,

```
import sys; sys.argv = '--I 1.0 --a 5'.split()
```

The execution command above will report any problem if a test fails. As an illustration, let us alter the  $u$  value at  $t=1.5$  in the output of the doctest by replacing the last digit 8 by 7. This edit triggers a report:

```
Terminal> python -m doctest decay.py
*****
File "decay.py", line ...
Failed example:
    for n in range(len(t)):
        print 't=%.1f, u=%.14f' % (t[n], u[n])
Expected:
    t=0.0, u=0.8000000000000000
    t=0.5, u=0.43076923076923
    t=1.0, u=0.23195266272189
    t=1.5, u=0.12489758761948
Got:
    t=0.0, u=0.8000000000000000
    t=0.5, u=0.43076923076923
    t=1.0, u=0.23195266272189
    t=1.5, u=0.12489758761947
```

### Pay attention to the number of digits in doctest results!

Note that in the output of  $t$  and  $u$  we write  $u$  with 14 digits. Writing all 16 digits is not a good idea: if the tests are run on different hardware, round-off errors might be different, and the `doctest` module detects that the numbers are not precisely the same and reports failures. In the present application, where  $0 < u(t) \leq 0.8$ , we expect round-off errors to be of size  $10^{-16}$ , so comparing 15 digits would probably be reliable, but we compare 14 to be on the safe side. On the other hand, comparing a small number of digits may hide software errors.

Doctests are highly encouraged as they do two things: 1) demonstrate how a function is used and 2) test that the function works.

## 3.2 Unit tests and test functions

The unit testing technique consists of identifying smaller units of code and writing one or more tests for each unit. One unit can typically be a function. Each test should, ideally, not depend on the outcome of other tests. The recommended practice is actually to design and write the unit tests first and *then* implement the functions!

In scientific computing it is not always obvious how to best perform unit testing. The units are naturally larger than in non-scientific software. Very often the solution procedure of a mathematical problem identifies a unit, such as our `solver` function.

**Two Python test frameworks: nose and pytest.** Python offers two very easy-to-use software frameworks for implementing unit tests: nose and pytest. These work (almost) in the same way, but our recommendation is to go for pytest.

**Test function requirements.** For a test to qualify as a *test function* in nose or pytest, three rules must be followed:

1. The function name must start with `test_`.
2. Function arguments are not allowed.
3. An `AssertionError` exception must be raised if the test fails.

A specific example might be illustrative before proceeding. We have the following function that we want to test:

```
def double(n):  
    return 2*n
```

The corresponding test function could, in principle, have been written as

```
def test_double():  
    """Test that double(n) works for one specific n."""  
    n = 4  
    expected = 2*4  
    computed = double(4)  
    if expected != computed:  
        raise AssertionError
```

The last two lines, however, are never written like this in test functions. Instead, Python's `assert` statement is used: `assert success, msg`, where `success` is a boolean variable, which is `False` if the test fails, and `msg` is *an optional* message string that is printed when the test fails. A better version of the test function is therefore

```
def test_double():  
    """Test that double(n) works for one specific n."""  
    n = 4  
    expected = 2*4  
    computed = double(4)  
    msg = 'expected %g, computed %g' % (expected, computed)  
    success = expected == computed  
    assert success, msg
```

**Comparison of real numbers.** Because of the finite precision arithmetics on a computer, which gives rise to round-off errors, the `==` operator is not suitable for checking whether two real numbers are equal. Obviously, this principle also applies to tests in test functions. We must therefore replace `a == b` by a comparison based on a tolerance `tol`: `abs(a-b) < tol`. The next example illustrates the problem and its solution.

Here is a slightly different function that we want to test:

```
def third(x):
    return x/3.
```

We write a test function where the expected result is computed as  $\frac{1}{3}x$  rather than  $x/3$ :

```
def test_third():
    """Check that third(x) works for many x values."""
    for x in np.linspace(0, 1, 21):
        expected = (1/3.0)*x
        computed = third(x)
        success = expected == computed
    assert success
```

This `test_third` function executes silently, i.e., no failure, until `x` becomes 0.15. Then round-off errors make the `==` comparison `False`. In fact, seven of the `x` values above face this problem. The solution is to compare `expected` and `computed` with a small tolerance:

```
def test_third():
    """Check that third(x) works for many x values."""
    for x in np.linspace(0, 1, 21):
        expected = (1/3.)*x
        computed = third(x)
        tol = 1E-15
        success = abs(expected - computed) < tol
    assert success
```

#### Always compare real numbers with a tolerance!

Real numbers should never be compared with the `==` operator, but always with the absolute value of the difference and a tolerance. So, replace `a == b`, if `a` and/or `b` is float, by

```
tol = 1E-14
abs(a - b) < tol
```

The suitable size of `tol` depends on the size of `a` and `b` (see Problem 5). Unless `a` and `b` are around unity in size, one should use a *relative difference*:

```
tol = 1E-14
abs((a - b)/a) < tol
```

**Special assert functions from nose.** Test frameworks often contain more tailored *assert functions* that can be called instead of using the `assert` statement. For example, comparing two objects within a tolerance, as in the present case, can be done by the `assert_almost_equal` from the nose framework:

```
import nose.tools as nt

def test_third():
    x = 0.15
    expected = (1/3.)*x
    computed = third(x)
    nt.assert_almost_equal(
        expected, computed, delta=1E-15,
        msg='diff=%.17E' % (expected - computed))
```

Whether to use the plain `assert` statement with a comparison based on a tolerance or to use the ready-made function `assert_almost_equal` depends on the programmer's preference. The examples used in the documentation of the pytest framework stick to the plain `assert` statement.

**Locating test functions.** Test functions can reside in a module together with the functions they are supposed to verify, or the test functions can be collected in separate files having names starting with `test`. Actually, nose and pytest can recursively run all test functions in all `test*.py` files in the current directory, as well as in all subdirectories!

The `decay.py` module file features test functions in the module, but we could equally well have made a subdirectory `tests` and put the test functions in `tests/test_decay.py`.

**Running tests.** To run all test functions in the file `decay.py` do

---

Terminal

---

```
Terminal> nosetests -s -v decay.py
Terminal> py.test -s -v decay.py
```

---

The `-s` option ensures that output from the test functions is printed in the terminal window, while `-v` prints the outcome of each individual test function.

Alternatively, if the test functions are located in some separate `test*.py` files, we can just write

---

Terminal

---

```
Terminal> py.test -s -v
```

---

to *recursively* run *all* test functions in the current directory tree. The corresponding

---

```
Terminal> nosetests -s -v
```

---

command does the same, but requires subdirectory names to start with `test` or end with `_test` or `_tests` (which is a good habit anyway). An example of a `tests` directory with a `test*.py` file is found in [src/softeng/tests](#).

**Embedding doctests in a test function.** Doctests can also be executed from nose/pytest unit tests. Here is an example of a file `test_decay_doctest.py` where we in the test block run all the doctests in the imported module `decay`, but we also include a local test function that does the same:

```
import sys, os
sys.path.insert(0, os.pardir)
import decay
import doctest

def test_decay_module_with_doctest():
    """Doctest embedded in a nose/pytest unit test."""
    # Test all functions with doctest in module decay
    failure_count, test_count = doctest.testmod(m=decay)
    assert failure_count == 0

if __name__ == '__main__':
    # Run all functions with doctests in this module
    failure_count, test_count = doctest.testmod(m=decay)
```

Running this file as a program from the command line triggers the `doctest.testmod` call in the test block, while applying `py.test` or `nosetests` to the file triggers an import of the file and execution of the test function `test_decay_module_with_doctest`.

**Installing nose and pytest.** With `pip` available, it is trivial to install nose and/or pytest: `sudo pip install nose` and `sudo pip install pytest`.

### 3.3 Test function for the solver

Finding good test problems for verifying the implementation of numerical methods is a topic on its own. The challenge is that we very seldom know what the numerical errors are. For the present model problem (1)-(2) solved by (3) one can, fortunately, derive a formula for the numerical approximation:

$$u^n = I \left( \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} \right)^n.$$

Then we know that the implementation should produce numbers that agree with this formula to machine precision. The formula for  $u^n$  is known as an *exact discrete solution* of the problem and can be coded as

```
def u_discrete_exact(n, I, a, theta, dt):
    """Return exact discrete solution of the numerical schemes."""
    dt = float(dt) # avoid integer division
    A = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)
    return I*A**n
```

A test function can evaluate this solution on a time mesh and check that the `u` values produced by the `solver` function do not deviate with more than a small tolerance:

```
def test_u_discrete_exact():
    """Check that solver reproduces the exact discr. sol."""
    theta = 0.8; a = 2; I = 0.1; dt = 0.8
    Nt = int(8/dt) # no of steps
    u, t = solver(I=I, a=a, T=Nt*dt, dt=dt, theta=theta)

    # Evaluate exact discrete solution on the mesh
    u_de = np.array([u_discrete_exact(n, I, a, theta, dt)
                     for n in range(Nt+1)])

    # Find largest deviation
    diff = np.abs(u_de - u).max()
    tol = 1E-14
    success = diff < tol
    assert success
```

Among important things to consider when constructing test functions is testing the effect of wrong input to the function being tested. In our `solver` function, for example, integer values of  $a$ ,  $\Delta t$ , and  $\theta$  may cause unintended integer division. We should therefore add a test to make sure our `solver` function does not fall into this potential trap:

```
def test_potential_integer_division():
    """Choose variables that can trigger integer division."""
    theta = 1; a = 1; I = 1; dt = 2
    Nt = 4
    u, t = solver(I=I, a=a, T=Nt*dt, dt=dt, theta=theta)
    u_de = np.array([u_discrete_exact(n, I, a, theta, dt)
                     for n in range(Nt+1)])
    diff = np.abs(u_de - u).max()
    assert diff < 1E-14
```

In more complicated problems where there is no exact solution of the numerical problem solved by the software, one must use the method of manufactured solutions, compute convergence rates for a series of  $\Delta t$  values, and check that the rates converges to the expected ones (from theory).

### 3.4 Test function for reading positional command-line arguments

The function `read_command_line_positional` extracts numbers from the command line. To test it, we must decide on a set of values for the input data, fill `sys.argv` accordingly, and check that we get the expected values:



```

def test_read_command_line_positional():
    # Decide on a data set of input parameters
    I = 1.6; a = 1.8; T = 2.2; theta = 0.5
    dt_values = [0.1, 0.2, 0.05]
    # Expected return from read_command_line_positional
    expected = [I, a, T, theta, dt_values]
    # Construct corresponding sys.argv array
    sys.argv = [sys.argv[0], str(I), str(a), str(T), 'CN'] + \
        [str(dt) for dt in dt_values]
    computed = read_command_line_positional()
    for expected_arg, computed_arg in zip(expected, computed):
        assert expected_arg == computed_arg

```

Note that `sys.argv[0]` is always the program name and that we have to copy that string from the original `sys.argv` array to the new one we construct in the test function. (Actually, this test function destroys the original `sys.argv` that Python fetched from the command line.)

Any numerical code writer should always be skeptical to the use of the exact equality operator `==` in test functions, since round-off errors often come into play. Here, however, we set some real values, convert them to strings and convert back again to real numbers (of the same precision). This string-number conversion does not involve any finite precision arithmetics effects so we can safely use `==` in tests. Note also that the last element in `expected` and `computed` is the list `dt_values`, and `==` works for comparing two lists as well.

### 3.5 Test function for reading option-value pairs

The function `read_command_line_argparse` can be verified with a test function that has the same setup as `test_read_command_line_positional` above. However, the construction of the command line is a bit more complicated. We find it convenient to construct the line as a string and then split the line into words to get the desired list `sys.argv`:

```

def test_read_command_line_argparse():
    I = 1.6; a = 1.8; T = 2.2; theta = 0.5
    dt_values = [0.1, 0.2, 0.05]
    # Expected return from read_command_line_argparse
    expected = [I, a, T, theta, dt_values]
    # Construct corresponding sys.argv array
    command_line = '%s --a %s --I %s --T %s --scheme CN --dt ' % \
        (sys.argv[0], a, I, T)
    command_line += ''.join([str(dt) for dt in dt_values])
    sys.argv = command_line.split()
    computed = read_command_line_argparse()
    for expected_arg, computed_arg in zip(expected, computed):
        assert expected_arg == computed_arg

```

Recall that the Python function `zip` enables iteration over several lists, tuples, or arrays at the same time.

### Let silent test functions speak up during development!

When you develop test functions in a module, it is common to use IPython for interactive experimentation:

```
In[1]: import decay
In[2]: decay.test_read_command_line_argparse()
```

Note that a working test function is completely silent! Many find it psychologically annoying to convince themselves that a completely silent function is doing the right things. It can therefore, during development of a test function, be convenient to insert print statements in the function to monitor that the function body is indeed executed. For example, one can print the expected and computed values in the terminal window:

```
def test_read_command_line_argparse():
    ...
    for expected_arg, computed_arg in zip(expected, computed):
        print expected_arg, computed_arg
        assert expected_arg == computed_arg
```

After performing this edit, we want to run the test again, but in IPython the module must first be reloaded (reimported):

```
In[3]: reload(decay) # force new import
In[2]: decay.test_read_command_line_argparse()
1.6 1.6
1.8 1.8
2.2 2.2
0.5 0.5
[0.1, 0.2, 0.05] [0.1, 0.2, 0.05]
```

Now we clearly see the objects that are compared.

## 3.6 Classical class-based unit testing

The test functions written for the nose and pytest frameworks are very straightforward and to the point, with no framework-required boilerplate code. We just write the statements we need to get the computations and comparisons done, before applying the required `assert`.

The classical way of implementing unit tests (which derives from the JUnit object-oriented tool in Java) leads to much more comprehensive implementations with a lot of boilerplate code. Python comes with a built-in module `unittest` for doing this type of classical unit tests. Although nose or pytest are much more convenient to use than `unittest`, class-based unit testing in the style of `unittest` has a very strong position in computer science and is so widespread

in the software industry that even computational scientists should have an idea how such unit test code is written. A short demo of `unittest` is therefore included next. (Readers who are not familiar with object-oriented programming in Python may find the text hard to understand, but one can safely jump to the next section.)

Suppose we have a function `double(x)` in a module file `mymod.py`:

```
def double(x):
    return 2*x
```

Unit testing with the aid of the `unittest` module consists of writing a file `test_mymod.py` for testing the functions in `mymod.py`. The individual tests must be methods with names starting with `test_` in a class derived from class `TestCase` in `unittest`. With one test method for the function `double`, the `test_mymod.py` file becomes

```
import unittest
import mymod

class TestMyCode(unittest.TestCase):
    def test_double(self):
        x = 4
        expected = 2*x
        computed = mymod.double(x)
        self.assertEqual(expected, computed)

if __name__ == '__main__':
    unittest.main()
```

The test is run by executing the test file `test_mymod.py` as a standard Python program. There is no support in `unittest` for automatically locating and running all tests in all test files in a directory tree.

We could use the basic `assert` statement as we did with `nose` and `pytest` functions, but those who write code based on `unittest` almost exclusively use the wide range of built-in assert functions such as `assertEqual`, `assertNotEqual`, `assertAlmostEqual`, to mention some of them.

Translation of the test functions from the previous sections to `unittest` means making a new file `test_decay.py` file with a test class `TestDecay` where the stand-alone functions for `nose`/`pytest` now become methods in this class.

```
import unittest
import decay
import numpy as np

def u_discrete_exact(n, I, a, theta, dt):
    ...

class TestDecay(unittest.TestCase):

    def test_exact_discrete_solution(self):
        theta = 0.8; a = 2; I = 0.1; dt = 0.8
        Nt = int(8/dt) # no of steps
        u, t = decay.solver(I=I, a=a, T=Nt*dt, dt=dt, theta=theta)
        # Evaluate exact discrete solution on the mesh
```

```

        u_de = np.array([u_discrete_exact(n, I, a, theta, dt)
                          for n in range(Nt+1)])
        diff = np.abs(u_de - u).max() # largest deviation
        self.assertAlmostEqual(diff, 0, delta=1E-14)

    def test_potential_integer_division(self):
        ...
        self.assertAlmostEqual(diff, 0, delta=1E-14)

    def test_read_command_line_positional(self):
        ...
        for expected_arg, computed_arg in zip(expected, computed):
            self.assertEqual(expected_arg, computed_arg)

    def test_read_command_line_argparse(self):
        ...

if __name__ == '__main__':
    unittest.main()

```

## 4 Sharing the software with other users

As soon as you have some working software that you intend to share with others, you should package your software in a standard way such that users can easily download your software, install it, improve it, and ask you to approve their improvements in new versions of the software. During recent years, the software development community has established quite firm tools and rules for how all this is done. The following subsections cover three steps in sharing software:

1. Organizing the software for public distribution.
2. Uploading the software to a cloud service (here GitHub).
3. Downloading and installing the software.

### 4.1 Organizing the software directory tree

We start with organizing our software as a directory tree. Our software consists of one module file, `decay.py`, and possibly some unit tests in a separate file located in a directory `tests`.

The `decay.py` can be used as a module or as a program. For distribution to other users who install the program `decay.py` in system directories, we need to insert the following line at the top of the file:

```
#!/usr/bin/env python
```

This line makes it possible to write just the filename and get the file executed by the `python` program (or more precisely, the first `python` program found in the directories in the `PATH` environment variable).

**Distributing just a module file.** Let us start out with the minimum solution alternative: distributing just the `decay.py` file. Then the software is just one file and all we need is a directory with this file. This directory will also contain an installation script `setup.py` and a `README` file telling what the software is about, the author's email address, a URL for downloading the software, and other useful information.

The `setup.py` file can be as short as

```
from distutils.core import setup
setup(name='decay',
      version='0.1',
      py_modules=['decay'],
      scripts=['decay.py'],
      )
```

The `py_modules` argument specifies a list of modules to be installed, while `scripts` specifies stand-alone programs. Our `decay.py` can be used either as a module or as an executable program, so we want users to have both possibilities.

**Distributing a package.** If the software consists of more files than one or two modules, one should make a Python *package* out of it. In our case we make a package `decay` containing one module, also called `decay`.

To make a package `decay`, create a directory `decay` and an empty file in it with name `__init__.py`. A `setup.py` script must now specify the directory name of the package and also an executable program (`scripts=`) in case we want to run `decay.py` as a stand-alone application:

```
from distutils.core import setup
import os

setup(name='decay',
      version='0.1',
      author='Hans Petter Langtangen',
      author_email='hpl@simula.no',
      url='https://github.com/hplgit/decay-package/',
      packages=['decay'],
      scripts=[os.path.join('decay', 'decay.py')]
      )
```

We have also added some author and download information. The reader is referred to the [Distutils documentation](#) for more information on how to write `setup.py` scripts.

#### Remark about the executable file.

The executable program, `decay.py`, is in the above installation script taken to be the complete module file `decay.py`. It would normally be preferred to instead write a very short script essentially importing `decay` and running the test block in `decay.py`. In this way, we distribute a module and a very short file, say `decay-main.py`, as an executable program:

```
#!/usr/bin/env python
import decay
decay.decay.experiment_compare_dt(True)
decay.decay.plt.show()
```

In this package example, we move the unit tests out of the `decay.py` module to a separate file, `test_decay.py`, and place this file in a directory `tests`. Then the `nosetests` and `py.test` programs will automatically find and execute the tests.

The complete directory structure reads

---

Terminal

---

```
Terminal> /bin/ls -R
.:
decay README setup.py

./decay:
decay.py __init__.py tests

./decay/tests:
test_decay.py
```

---

## 4.2 Publishing the software at GitHub

The leading site today for publishing open source software projects is GitHub at <http://github.com>, provided you want your software to be open to the world. With a paid GitHub account, you can have private projects too.

Sign up for a GitHub account if you do not already have one. Go to your account settings and provide an SSH key (typically the file `~/.ssh/id_rsa.pub`) such that you can communicate with GitHub without being prompted for your password. All communication between your computer and GitHub goes via the version control system Git. This may at first sight look tedious, but this is the way professionals work with software today. With Git you have full control of the history of your files, i.e., “who did what when”. The technology makes Git superior to simpler alternatives like Dropbox and Google Drive, especially when you collaborate with others. There is a reason why Git has gained the position it has, and there is no reason why you should not adopt this tool.

To create a new project, click on *New repository* on the main page and fill out a project name. Click on the check button *Initialize this repository with a README*, and click on *Create repository*. The next step is to clone (copy) the GitHub repo (short for repository) to your own computer(s) and fill it with files. The typical clone command is

---

Terminal

---

```
Terminal> git clone git://github.com:username/projname.git
```

---

where `username` is your GitHub username and `projname` is the name of the repo (project). The result of `git clone` is a directory `projname`. Go to this directory and add files. As soon as the repo directory is populated with files, run

---

Terminal

---

```
Terminal> git add .
Terminal> git commit -am 'First registration of project files'
Terminal> git push origin master
```

---

The above `git` commands look cryptic, but these commands plus 2-3 more are the essence of what you need in your daily work with files in small or big software projects. I strongly encourage you to learn more about [version control systems and project hosting sites](#) [1].

Your project files are now stored in the cloud at <https://github.com/username/projname>. Anyone can get the software by the listed `git clone` command you used above, or by clicking on the links for zip and tar files.

Every time you update the project files, you need to register the update at GitHub by

---

Terminal

---

```
Terminal> git commit -am 'Description of the changes you made...'
Terminal> git push origin master
```

---

The files at GitHub are now synchronized with your local ones. Similarly, every time you start working on files in this project, make sure you have the latest version: `git pull origin master`.

You are recommended to read [a quick intro](#) that makes you up and going with this style of professional work. And you should put all your writings and programming projects in repositories in the cloud!

### 4.3 Downloading and installing the software

Users of your software go to the Git repo at `github.com` and clone the repository. One can use either SSH or HTTP for communication. Most users will use the latter, typically

---

Terminal

---

```
Terminal> git clone https://github.com/username/projname.git
```

---

The result is a directory `projname` with the files in the repo.

**Installing just a module file.** The software package is in the case above a directory `decay` with three files

---

Terminal

---

```
Terminal> ls decay
README  decay.py  setup.py
```

---

To install the `decay.py` file, a user just runs `setup.py`:

---

Terminal

---

```
Terminal> sudo python setup.py install
```

---

This command will install the software in system directories, so the user needs to run the command as `root` on Unix systems (therefore the command starts with `sudo`). The user can now import the module by `import decay` and run the program by

---

Terminal

---

```
Terminal> decay.py
```

---

A user can easily install the software on her personal account if a system-wide installation is not desirable. We refer to the [installation documentation](#) for the many arguments that can be given to `setup.py`. Note that if the software is installed on a personal account, the `PATH` and `PYTHONPATH` environment variables must contain the relevant directories.

Our `setup.py` file specifies a module `decay` to be installed as well as a program `decay.py`. Modules are typically installed in some `lib` directory on the computer system, e.g., `/usr/local/lib/python2.7/dist-packages`, while executable programs go to `/usr/local/bin`.

**Installing a package.** When the software is organized as a Python package, the installation is done by running `setup.py` exactly as explained above, but the use of a module `decay` in a package `decay` requires the following syntax:

```
import decay
u, t = decay.decay.solver(...)
```

That is, the call goes like `packagename.modulename.functionname`.

#### Package import in `__init__.py`

One can ease the use of packages by providing a somewhat simpler import like

```
import decay
u, t = decay.solver(...)

# or
from decay import solver
u, t = solver(...)
```

This is accomplished by putting an import statement in the `__init__.py` file, which is always run when doing the package import `import decay` or `from decay import`. The `__init__.py` file must now contain



```
from decay import *
```

Obviously, it is the package developer who decides on such an `__init__.py` file or if it should just be empty.

## 5 Classes for problem and solution method

The numerical solution procedure was compactly and conveniently implemented in a Python function `solver` in Section 1.1. In more complicated problems it might be beneficial to use classes instead of functions only. Here we shall describe a class-based software design well suited for scientific problems where there is a mathematical model of some physical phenomenon, and some numerical methods to solve the equations involved in the model.

We introduce a class `Problem` to hold the definition of the physical problem, and a class `Solver` to hold the data and methods needed to numerically solve the problem. The forthcoming text will explain the inner workings of these classes and how they represent an alternative to the `solver` and `experiment_*` functions in the `decay` module.

Explaining the details of class programming in Python is considered far beyond the scope of this text. Readers who are unfamiliar with Python class programming should first consult one of the many electronic Python tutorials or textbooks to come up to speed with concepts and syntax of Python classes before reading on. The author has a gentle introduction to class programming for scientific applications in [2], see Chapter 7 and 9 and Appendix E. Other useful resources are

- The Python Tutorial: <http://docs.python.org/2/tutorial/classes.html>
- Wiki book on Python Programming: [http://en.wikibooks.org/wiki/Python\\_Programming/Classes](http://en.wikibooks.org/wiki/Python_Programming/Classes)
- tutorialspoint.com: [http://www.tutorialspoint.com/python/python\\_classes\\_objects.htm](http://www.tutorialspoint.com/python/python_classes_objects.htm)

### 5.1 The problem class

The purpose of the problem class is to store all information about the mathematical model. This usually means the physical parameters and formulas in the problem. Looking at our model problem (1)-(2), the physical data cover  $I$ ,  $a$ , and  $T$ . Since we have an analytical solution of the ODE problem, we may add this solution in terms of a Python function (or method) to the problem class as well. A possible problem class is therefore

```

from numpy import exp

class Problem(object):
    def __init__(self, I=1, a=1, T=10):
        self.T, self.I, self.a = I, float(a), T

    def u_exact(self, t):
        I, a = self.I, self.a
        return I*exp(-a*t)

```

We could in the `u_exact` method have written `self.I*exp(-self.a*t)`, but using local variables `I` and `a` allows the nicer formula `I*exp(-a*t)`, which looks much closer to the mathematical expression  $Ie^{-at}$ . This is not an important issue with the current compact formula, but is beneficial in more complicated problems with longer formulas to obtain the closest possible relationship between code and mathematics. The coding style in this standalone is to strip off the `self` prefix when the code expresses mathematical formulas.

The class data can be set either as arguments in the constructor or at any time later, e.g.,

```

problem = Problem(T=5)
problem.T = 8
problem.dt = 1.5

```

(Some programmers prefer `set` and `get` functions for setting and getting data in classes, often implemented via *properties* in Python, but this author considers that overkill when there are just a few data items in a class.)

It would be convenient if class `Problem` could also initialize the data from the command line. To this end, we add a method for defining a set of command-line options and a method that sets the local attributes equal to what was found on the command line. The default values associated with the command-line options are taken as the values provided to the constructor. Class `Problem` now becomes

```

class Problem(object):
    def __init__(self, I=1, a=1, T=10):
        self.T, self.I, self.a = I, float(a), T

    def define_command_line_options(self, parser=None):
        """Return updated (parser) or new ArgumentParser object."""
        if parser is None:
            import argparse
            parser = argparse.ArgumentParser()

        parser.add_argument(
            '--I', '--initial_condition', type=float,
            default=1.0, help='initial condition, u(0)',
            metavar='I')
        parser.add_argument(
            '--a', type=float, default=1.0,
            help='coefficient in ODE', metavar='a')
        parser.add_argument(
            '--T', '--stop_time', type=float,
            default=1.0, help='end time of simulation',
            metavar='T')
        return parser

```

```

def init_from_command_line(self, args):
    """Load attributes from ArgumentParser into instance."""
    self.I, self.a, self.T = args.I, args.a, args.T

def u_exact(self, t):
    """Return the exact solution u(t)=I*exp(-a*t)."""
    I, a = self.I, self.a
    return I*exp(-a*t)

```

Observe that if the user already has an `ArgumentParser` object it can be supplied, but if she does not have any, class `Problem` makes one. Python's `None` object is used to indicate that a variable is not initialized with a proper value.

## 5.2 The solver class

The solver class stores parameters related to the numerical solution method and provides a function `solve` for solving the problem. For convenience, a problem object is given to the constructor in a solver object such that the object gets access to the physical data. In the present example, the numerical solution method involves the parameters  $\Delta t$  and  $\theta$ , which then constitute the data part of the solver class. We include, as in the problem class, functionality for reading  $\Delta t$  and  $\theta$  from the command line:

```

class Solver(object):
    def __init__(self, problem, dt=0.1, theta=0.5):
        self.problem = problem
        self.dt, self.theta = float(dt), theta

    def define_command_line_options(self, parser):
        """Return updated (parser) or new ArgumentParser object."""
        parser.add_argument(
            '--scheme', type=str, default='CN',
            help='FE, BE, or CN')
        parser.add_argument(
            '--dt', '--time_step_values', type=float,
            default=[1.0], help='time step values',
            metavar='dt', nargs='+', dest='dt_values')
        return parser

    def init_from_command_line(self, args):
        """Load attributes from ArgumentParser into instance."""
        self.dt, self.theta = args.dt, args.theta

    def solve(self):
        self.u, self.t = solver(
            self.problem.I, self.problem.a, self.problem.T,
            self.dt, self.theta)

    def error(self):
        """Return norm of error at the mesh points."""
        u_e = self.problem.u_exact(self.t)
        e = u_e - self.u
        E = np.sqrt(self.dt*np.sum(e**2))
        return E

```

Note that we see no need to repeat the body of the previously developed and tested `solver` function. We just call that function from the `solve` method.

In this way, class `Solver` is merely a class wrapper of the stand-alone `solver` function. With a single object of class `Solver` we have all the physical and numerical data bundled together with the numerical solution method.

**Combining the objects.** Eventually we need to show how the classes `Problem` and `Solver` play together. We read parameters from the command line and make a plot with the numerical and exact solution:

```
def experiment_classes():
    problem = Problem()
    solver = Solver(problem)

    # Read input from the command line
    parser = problem.define_command_line_options()
    parser = solver.define_command_line_options(parser)
    args = parser.parse_args()
    problem.init_from_command_line(args)
    solver.init_from_command_line(args)

    # Solve and plot
    solver.solve()
    import matplotlib.pyplot as plt
    t_e = np.linspace(0, T, 1001) # very fine mesh for u_e
    u_e = problem.u_exact(t_e)
    print 'Error:', solver.error()

    plt.plot(t, u, 'r--o')
    plt.plot(t_e, u_e, 'b-')
    plt.legend(['numerical, theta=%g' % theta, 'exact'])
    plt.xlabel('t')
    plt.ylabel('u')
    plotfile = 'tmp'
    plt.savefig(plotfile + '.png'); plt.savefig(plotfile + '.pdf')
    plt.show()
```

### 5.3 Improving the problem and solver classes

The previous `Problem` and `Solver` classes containing parameters soon get much repetitive code when the number of parameters increases. Much of this code can be parameterized and be made more compact. For this purpose, we decide to collect all parameters in a dictionary, `self.prm`, with two associated dictionaries `self.type` and `self.help` for holding associated object types and help strings. The reason is that processing dictionaries is easier than processing a set of individual attributes. For the specific ODE example we deal with, the three dictionaries in the problem class are typically

```
self.prm = dict(I=1, a=1, T=10)
self.type = dict(I=float, a=float, T=float)
self.help = dict(I='initial condition, u(0)',
                  a='coefficient in ODE',
                  T='end time of simulation')
```

Provided a problem or solver class defines these three dictionaries in the constructor, we can create a super class `Parameters` with general code for defining

command-line options and reading them as well as methods for setting and getting each parameter. A `Problem` or `Solver` for a particular mathematical problem can then inherit most of the needed functionality and code from the `Parameters` class. For example,

```
class Problem(Parameters):
    def __init__(self):
        self.prm = dict(I=1, a=1, T=10)
        self.type = dict(I=float, a=float, T=float)
        self.help = dict(I='initial condition, u(0)',
                        a='coefficient in ODE',
                        T='end time of simulation')

    def u_exact(self, t):
        I, a = self['I a'].split()
        return I*np.exp(-a*t)

class Solver(Parameters):
    def __init__(self, problem):
        self.problem = problem # class Problem object
        self.prm = dict(dt=0.5, theta=0.5)
        self.type = dict(dt=float, theta=float)
        self.help = dict(dt='time step value',
                        theta='time discretization parameter')

    def solve(self):
        from decay import solver
        I, a, T = self.problem['I a T'].split()
        dt, theta = self['dt theta'].split()
        self.u, self.t = solver(I, a, T, dt, theta)
```

By inheritance, these classes can automatically do a lot more when it comes to reading and assigning parameter values:

```
problem = Problem()
solver = Solver(problem)

# Read input from the command line
parser = problem.define_command_line_options()
parser = solver.define_command_line_options(parser)
args = parser.parse_args()
problem.init_from_command_line(args)
solver.init_from_command_line(args)

# Other syntax for setting/getting parameter values
problem['T'] = 6
print 'Time step:', solver['dt']

solver.solve()
u, t = solver.u, solver.t
```

**A generic class for parameters.** A simplified version of the parameter class looks as follows:

```
class Parameters(object):
    def __getitem__(self, name):
        """obj[name] syntax for getting parameters."""
```

```

        if isinstance(name, (list,tuple)):           # get many?
            return [self.prm[n] for n in name]
        else:
            return self.prm[name]

    def __setitem__(self, name, value):
        """obj[name] = value syntax for setting a parameter."""
        self.prm[name] = value

    def define_command_line_options(self, parser=None):
        """Automatic registering of options."""
        if parser is None:
            import argparse
            parser = argparse.ArgumentParser()

        for name in self.prm:
            tp = self.type[name] if name in self.type else str
            help = self.help[name] if name in self.help else None
            parser.add_argument(
                '--' + name, default=self.get(name), metavar=name,
                type=tp, help=help)

        return parser

    def init_from_command_line(self, args):
        for name in self.prm:
            self.prm[name] = getattr(args, name)

```

The file `decay_oo.py` contains a slightly more advanced version of class `Parameters` where the functions for getting and setting parameters contain tests for valid parameter names, and raise exceptions with informative messages if any name is not registered.

We have already sketched the `Problem` and `Solver` classes that build on inheritance from `Parameters`. We have also shown how they are used. The only remaining code is to make the plot, but this code is identical to previous versions when the numerical solution is available in an object `u` and the exact one in `u_e`.

The advantage with the `Parameters` class is that it scales to problems with a large number of physical and numerical parameters: as long as the parameters are defined once via a dictionary, the compact code in class `Parameters` can handle any collection of parameters of any size.

## 6 Automating scientific experiments

Empirical scientific investigations based on running computer programs require careful design of the experiments and accurate reporting of results. Although there is a strong tradition to do such investigations manually, the extreme requirements to scientific accuracy make a program much better suited to conduct the experiments. We shall in this section outline how we can write such programs, often called *scripts*, for running other programs and archiving the results.

### Scientific investigation.

The purpose of the investigations is to explore the quality of numerical solutions to an ordinary differential equation. More specifically, we solve the initial-value problem

$$u'(t) = -au(t), \quad u(0) = I, \quad t \in (0, T], \quad (4)$$

by the  $\theta$ -rule:

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} u^n, \quad u^0 = I. \quad (5)$$

This scheme corresponds to well-known methods:  $\theta = 0$  gives the Forward Euler (FE) scheme,  $\theta = 1$  gives the Backward Euler (BE) scheme, and  $\theta = \frac{1}{2}$  gives the Crank-Nicolson (CN) or midpoint/centered scheme.

For chosen constants  $I$ ,  $a$ , and  $T$ , we run the three schemes for various values of  $\Delta t$ , and present the following results in a report:

1. visual comparison of the numerical and exact solution in a plot for each  $\Delta t$  and  $\theta = 0, 1, \frac{1}{2}$ ,
2. a table and a plot of the norm of the numerical error versus  $\Delta t$  for  $\theta = 0, 1, \frac{1}{2}$ .

The report will also document the mathematical details of the problem under investigation.

## 6.1 Available software

Appropriate software for implementing (5) is available in a program `model.py`, which is run as

```
Terminal> python model.py --I 1.5 --a 0.25 --T 6 --dt 1.25 0.75 0.5
```

The command-line input corresponds to setting  $I = 1.5$ ,  $a = 0.25$ ,  $T = 6$ , and run three values of  $\Delta t$ : 1.25, 0.75, and 0.5.

The results of running this `model.py` command are text in the terminal window and a set of plot files. The plot files have names `M_D.E`, where `M` denotes the method (FE, BE, CN for  $\theta = 0, 1, \frac{1}{2}$ , respectively), `D` the time step length (here 1.25, 0.75, or 0.5), and `E` is the plot file extension `png` or `pdf`. The text output in the terminal window looks like

```
0.0  1.25:  5.998E-01
0.0  0.75:  1.926E-01
0.0  0.50:  1.123E-01
```

0.0	0.10:	1.558E-02
0.5	1.25:	6.231E-02
0.5	0.75:	1.543E-02
0.5	0.50:	7.237E-03
0.5	0.10:	2.469E-04
1.0	1.25:	1.766E-01
1.0	0.75:	8.579E-02
1.0	0.50:	6.884E-02
1.0	0.10:	1.411E-02

The first column is the  $\theta$  value, the next the  $\Delta t$  value, and the final column represents the numerical error  $E$  (the norm of discrete error function on the mesh).

## 6.2 The results we want to produce

The results we need for our investigations are slightly different than what is directly produced by `model.py`:

1. We need to collect all the plots for one numerical method (FE, BE, CN) in a single plot. For example, if 4  $\Delta t$  values are run, the summarizing figure for the BE method has  $2 \times 2$  subplots, with the subplot corresponding to the largest  $\Delta t$  in the upper left corner and the smallest in the bottom right corner.
2. We need to create a table containing  $\Delta t$  values in the first column and the numerical error  $E$  for  $\theta = 0, 0.5, 1$  in the next three columns. This table should be available as a standard CSV file.
3. We need to plot the numerical error  $E$  versus  $\Delta t$  in a log-log plot.

Consequently, we must write a script that can run `model.py` as described and produce the results 1-3 above. This requires combining multiple plot files into one file and interpreting the output from `model.py` as data for plotting and file storage.

If the script's name is `exper1.py`, we run it with the desired  $\Delta t$  values as positional command-line arguments:

---

Terminal

---

```
Terminal> python exper1.py 0.5 0.25 0.1 0.05
```

---

This run will then generate eight plot files: `FE.png` and `FE.pdf` summarizing the plots with the FE method, `BE.png` and `BE.pdf` with the BE method, `CN.png` and `CN.pdf` with the CN method, and `error.png` and `error.pdf` with the log-log plot of the numerical error versus  $\Delta t$ . In addition, the table with numerical errors is written to a file `error.csv`.



### Reproducible and replicable science.

A script that automates running our computer experiments will ensure that the experiments can easily be rerun by anyone in the future, either to confirm the same results or redo the experiments with other input data. Also, whatever we did to produce the results is documented in every detail in the script.

A project where anyone can easily repeat the experiments with the same data is referred to as being *replicable*, and replicability should be a fundamental requirement in scientific computing work. Of more scientific interest is *reproducibility*, which means that we can also run alternative experiments to arrive at the same conclusions. This requires more than an automating script.

## 6.3 Combining plot files

The script for running experiments needs to combine multiple image files into one. The `montage` and `convert` programs in the ImageMagick software suite can be used to combine image files. However, these programs are best suited for PNG files. For vector plots in PDF format one needs other tools to preserve the quality: `pdftk`, `pdfnup`, and `pdfcrop`.

Suppose you have four files `f1.png`, `f2.png`, `f3.png`, and `f4.png` and want to combine them into a  $2 \times 2$  table of subplots in a new file `f.png`, see Figure 4 for an example.

The appropriate ImageMagick commands are

```
Terminal
Terminal> montage -background white -geometry 100% -tile 2x \
             f1.png f2.png f3.png f4.png f.png
Terminal> convert -trim f.png f.png
Terminal> convert f.png -transparent white f.png
```

The first command mounts the four files in one, the next `convert` command removes unnecessary surrounding white space, and the final `convert` command makes the white background transparent.

High-quality montage of PDF files `f1.pdf`, `f2.pdf`, `f3.pdf`, and `f4.pdf` into `f.pdf` goes like

```
Terminal
Terminal> pdftk f1.pdf f2.pdf f3.pdf f4.pdf output tmp.pdf
Terminal> pdfnup --nup 2x2 --outfile tmp.pdf tmp.pdf
Terminal> pdfcrop tmp.pdf f.pdf
Terminal> rm -f tmp.pdf
```

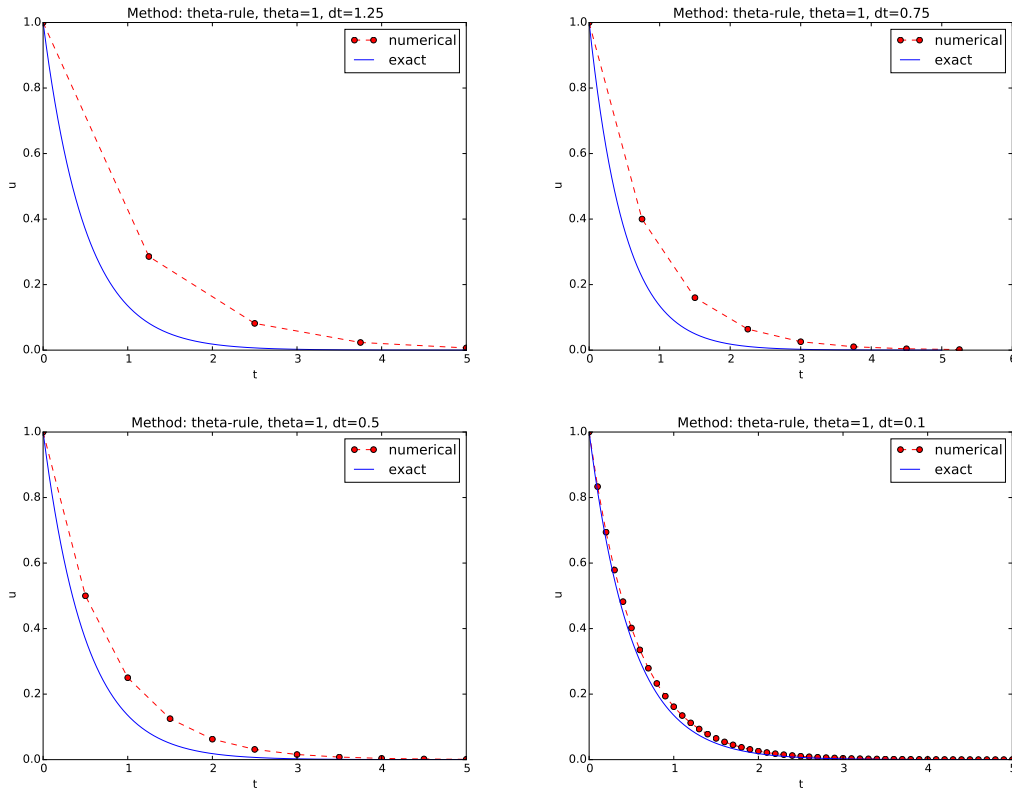


Figure 4: Illustration of the Backward Euler method for four time step values.

## 6.4 Running a program from Python

The script for automating experiments needs to run the `model.py` program with appropriate command-line options. Python has several tools for executing an arbitrary command in the operating systems. Let `cmd` be a string containing the desired command. In the present case study, `cmd` could be `'python model.py -I 1 -dt 0.5 0.2'`. The following code executes `cmd` and loads the text output into a string `output`:

```
from subprocess import Popen, PIPE, STDOUT
p = Popen(cmd, shell=True, stdout=PIPE, stderr=STDOUT)
output, _ = p.communicate()

# Check if the execution was successful
failure = p.returncode
if failure:
    print 'Command failed:', cmd; sys.exit(1)
```

Unsuccessful execution usually makes it meaningless to continue the program, and therefore we abort the program with `sys.exit(1)`. Any argument different

from 0 signifies to the computer's operating system that our program stopped with a failure.

#### Programming tip: use `_` for dummy variable.

Sometimes we need to unpack tuples or lists in separate variables, but we are not interested in all the variables. One example is

```
output, error = p.communicate()
```

but `error` is of no interest in the example above. One can then use underscore `_` as variable name for the dummy (uninteresting) variable(s):

```
output, _ = p.communicate()
```

Here is another example where we iterate over a list of three-tuples, but the interest is limited to the second element in each three-tuple:

```
for _, value, _ in list_of_three_tuples:
    # work with value
```

We need to interpret the contents of the string `output` and store the data in an appropriate data structure for further processing. Since the content is basically a table and will be transformed to a spread sheet format, we let the columns in the table be represented by lists in the program, and we collect these columns in a dictionary whose keys are natural column names: `dt` and the three values of  $\theta$ . The following code translates the output of `cmd (output)` to such a dictionary of lists (`errors`):

```
errors = {'dt': dt_values, 1: [], 0: [], 0.5: []}
for line in output.splitlines():
    words = line.split()
    if words[0] in ('0.0', '0.5', '1.0'): # line with E?
        # typical line: 0.0 1.25: 7.463E+00
        theta = float(words[0])
        E = float(words[2])
        errors[theta].append(E)
```

## 6.5 The automating script

We have now all the core elements in place to write the complete script where we run `model.py` for a set of  $\Delta t$  values (given as positional command-line arguments), make the error plot, write the CSV file, and combine plot files as described above. The complete code is listed below, followed by some explaining comments.

```

import os, sys, glob
import matplotlib.pyplot as plt

def run_experiments(I=1, a=2, T=5):
    # The command line must contain dt values
    if len(sys.argv) > 1:
        dt_values = [float(arg) for arg in sys.argv[1:]]
    else:
        print 'Usage: %s dt1 dt2 dt3 ...' % sys.argv[0]
        sys.exit(1) # abort

    # Run module file and grab output
    cmd = 'python model.py --I %g --a %g --T %g' % (I, a, T)
    dt_values_str = ' '.join([str(v) for v in dt_values])
    cmd += ' --dt %s' % dt_values_str
    print cmd
    from subprocess import Popen, PIPE, STDOUT
    p = Popen(cmd, shell=True, stdout=PIPE, stderr=STDOUT)
    output, _ = p.communicate()
    failure = p.returncode
    if failure:
        print 'Command failed:', cmd; sys.exit(1)

    errors = {'dt': dt_values, 1: [], 0: [], 0.5: []}
    for line in output.splitlines():
        words = line.split()
        if words[0] in ('0.0', '0.5', '1.0'): # line with E?
            # typical line: 0.0 1.25: 7.463E+00
            theta = float(words[0])
            E = float(words[2])
            errors[theta].append(E)

    # Find min/max for the axis
    E_min = 1E+20; E_max = -E_min
    for theta in 0, 0.5, 1:
        E_min = min(E_min, min(errors[theta]))
        E_max = max(E_max, max(errors[theta]))

    plt.loglog(errors['dt'], errors[0], 'ro-')
    plt.loglog(errors['dt'], errors[0.5], 'b+-')
    plt.loglog(errors['dt'], errors[1], 'gx-')
    plt.legend(['FE', 'CN', 'BE'], loc='upper left')
    plt.xlabel('log(time step)')
    plt.ylabel('log(error)')
    plt.axis([min(dt_values), max(dt_values), E_min, E_max])
    plt.title('Error vs time step')
    plt.savefig('error.png'); plt.savefig('error.pdf')

    # Write out a table in CSV format
    f = open('error.csv', 'w')
    f.write(r'$\Delta t$, $\theta=0$, $\theta=0.5$, $\theta=1$' + '\n')
    for _dt, _fe, _cn, _be in zip(
        errors['dt'], errors[0], errors[0.5], errors[1]):
        f.write('%0.2f, %0.4f, %0.4f, %0.4f\n' % (_dt, _fe, _cn, _be))
    f.close()

    # Combine images into rows with 2 plots in each row
    image_commands = []
    for method in 'BE', 'CN', 'FE':
        pdf_files = ' '.join(['%s_%g.pdf' % (method, dt)
                               for dt in dt_values])
        png_files = ' '.join(['%s_%g.png' % (method, dt)
                               for dt in dt_values])

```

```

        image_commands.append(
            'montage -background white -geometry 100%' +
            ' -tile 2x %s %s.png' % (png_files, method))
        image_commands.append(
            'convert -trim %s.png %s.png' % (method, method))
        image_commands.append(
            'convert %s.png -transparent white %s.png' %
            (method, method))
        image_commands.append(
            'pdftk %s output tmp.pdf' % pdf_files)
        num_rows = int(round(len(dt_values)/2.0))
        image_commands.append(
            'pdfnup --nup 2x%d --outfile tmp.pdf tmp.pdf' % num_rows)
        image_commands.append(
            'pdfcrop tmp.pdf %s.pdf' % method)

    for cmd in image_commands:
        print cmd
        failure = os.system(cmd)
        if failure:
            print 'Command failed:', cmd; sys.exit(1)

    # Remove the files generated above and by model.py
    from glob import glob
    filenames = glob('*.*.png') + glob('*.*.pdf') + glob('tmp*.pdf')
    for filename in filenames:
        os.remove(filename)

if __name__ == '__main__':
    run_experiments(I=1, a=2, T=5)
    plt.show()

```

We may comment upon many useful constructs in this script:

- `[float(arg) for arg in sys.argv[1:]]` builds a list of real numbers from all the command-line arguments.
- `['%s_%s.png' % (method, dt) for dt in dt_values]` builds a list of filenames from a list of numbers (`dt_values`).
- All `montage`, `convert`, `pdftk`, `pdfnup`, and `pdfcrop` commands for creating composite figures are stored in a list and later executed in a loop.
- `glob('*.*.png')` returns a list of the names of all files in the current directory where the filename matches the [Unix wildcard notation](#) `*.*.png` (meaning any text, underscore, any text, and then `.png`).
- `os.remove(filename)` removes the file with name `filename`.
- `failure = os.system(cmd)` runs an operating system command with simpler syntax than what is required by `subprocess` (but the output of `cmd` cannot be captured).

## 6.6 Making a report

The results of running computer experiments are best documented in a little report containing the problem to be solved, key code segments, and the plots from a series of experiments. At least the part of the report containing the plots should be automatically generated by the script that performs the set of experiments, because in the script we know exactly which input data that were used to generate a specific plot, thereby ensuring that each figure is connected to the right data. Take a look at [a sample report](#) to see what we have in mind.

**Word, OpenOffice, GoogleDocs.** Microsoft Word, its open source counterparts OpenOffice and LibreOffice, along with GoogleDocs and similar online services are the dominating tools for writing reports today. Nevertheless, scientific reports often need mathematical equations and nicely typeset computer code in monospace font. The support for mathematics and computer code in the mentioned tools is in this author’s view not on par with the technologies based on *markup languages* and which are addressed below. Also, with markup languages one has a readable, pure text file as source for the report, and changes in this text can easily be tracked by version control systems like Git. The result is a very strong tool for monitoring “who did what when” with the files, resulting in increased reliability of the writing process. For collaborative writing, the merge functionality in Git leads to safer simultaneously editing than what is offered even by collaborative tools like GoogleDocs.

**HTML with MathJax.** HTML is the markup language used for web pages. Nicely typeset computer code is straightforward in HTML, and high-quality mathematical typesetting is available using an extension to HTML called [MathJax](#), which allows formulas and equations to be typeset with  $\text{\LaTeX}$  syntax and nicely rendered in web browsers, see Figure 5. A relatively small subset of  $\text{\LaTeX}$  environments for mathematics is supported, but the syntax for formulas is quite rich. Inline formulas look like `\( u'=-au \)` while equations are surrounded by `$$` signs. Inside such signs, one can use `\[ u'=-au \]` for unnumbered equations, or `\begin{equation}` and `\end{equation}` for numbered equations, or `\begin{align}` and `\end{align}` for multiple numbered aligned equations. You need to be familiar with [mathematical typesetting in LaTeX](#) to write MathJax code.

The file `exper1_mathjax.py` calls a script `exper1.py` to perform the numerical experiments and then runs Python statements for creating an [HTML file](#) with the source code for [the scientific report](#).

**$\text{\LaTeX}$ .** The *de facto* language for mathematical typesetting and scientific report writing is [LaTeX](#). A number of very sophisticated packages have been added to the language over a period of three decades, allowing very fine-tuned layout and typesetting. For output in the [PDF format](#), see Figure 6 for an example,  $\text{\LaTeX}$  is the definite choice when it comes to *typesetting quality*. The  $\text{\LaTeX}$  language used to write the reports has typically a lot of commands involving [backslashes](#)

We address the initial-value problem

$$u'(t) = -au(t), \quad t \in (0, T], \quad (1)$$

$$u(0) = I, \quad (2)$$

where  $a$ ,  $I$ , and  $T$  are prescribed parameters, and  $u(t)$  is the unknown function to be estimated. This mathematical model is relevant for physical phenomena featuring exponential decay in time.

### Numerical solution method

We introduce a mesh in time with points  $0 = t_0 < t_1 < \dots < t_N = T$ . For simplicity, we assume constant spacing  $\Delta t$  between the mesh points:  $\Delta t = t_n - t_{n-1}$ ,  $n = 1, \dots, N$ . Let  $u^n$  be the numerical approximation to the exact solution at  $t_n$ . The  $\theta$ -rule is used to solve (1) numerically:

$$u^{n+1} = \frac{1 - (1 - \theta)a\Delta t}{1 + \theta a\Delta t} u^n,$$

for  $n = 0, 1, \dots, N - 1$ . This scheme corresponds to

- The Forward Euler scheme when  $\theta = 0$
- The Backward Euler scheme when  $\theta = 1$
- The Crank-Nicolson scheme when  $\theta = 1/2$

### Implementation

The numerical method is implemented in a Python function:

```
def theta_rule(I, a, T, dt, theta):
    """Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt."""
    N = int(round(T/float(dt))) # no of intervals
    u = zeros(N+1)
    t = linspace(0, T, N+1)
```

Figure 5: Report in HTML format with MathJax.

and braces, and many claim that L<sup>A</sup>T<sub>E</sub>X syntax is not particularly readable. For output on the web via HTML code (i.e., not only showing the PDF in the browser window), L<sup>A</sup>T<sub>E</sub>X struggles with delivering high quality typesetting. Other tools, especially Sphinx, give better results and can also produce nice-looking PDFs. The file `exper1_latex.py` shows how to generate the L<sup>A</sup>T<sub>E</sub>X source from a program.

## 3 Implementation

The numerical method is implemented in a Python function:

```
def theta_rule(I, a, T, dt, theta):
    """Solve u'=-a*u, u(0)=I, for t in (0,T] with steps of dt."""
    N = int(round(T/float(dt))) # no of intervals
    u = zeros(N+1)
    t = linspace(0, T, N+1)

    u[0] = I
    for n in range(0, N):
        u[n+1] = (1 - (1-theta)*a*dt)/(1 + theta*dt*a)*u[n]
    return u, t
```

## 4 Numerical experiments

We define a set of numerical experiments where  $I$ ,  $a$ , and  $T$  are fixed, while  $\Delta t$  and  $\theta$  are varied. In particular,  $I = 1$ ,  $a = 2$ ,  $\Delta t = 1.25, 0.75, 0.5, 0.1$ .

Figure 6: Report in PDF format generated from L<sup>A</sup>T<sub>E</sub>X source.

**Sphinx.** [Sphinx](#) is a typesetting language with similarities to HTML and  $\text{\LaTeX}$ , but with much less tagging. It has recently become very popular for software documentation and mathematical reports. Sphinx can utilize  $\text{\LaTeX}$  for mathematical formulas and equations. Unfortunately, the subset of  $\text{\LaTeX}$  mathematics supported is less than in full MathJax (in particular, numbering of multiple equations in an `align` type environment is not supported). The [Sphinx syntax](#) is an extension of the reStructuredText language. An attractive feature of Sphinx is its rich support for [fancy layout of web pages](#). In particular, Sphinx can easily be combined with various layout *themes* that give a certain look and feel to the web site and that offers table of contents, navigation, and search facilities, see Figure 7.

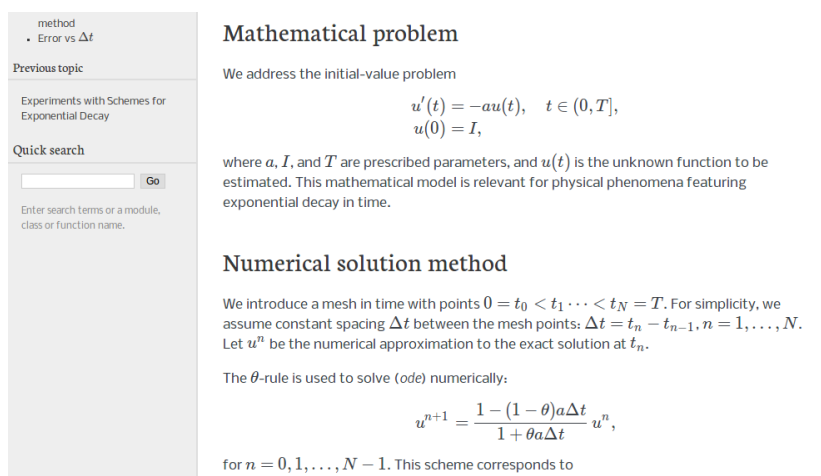


Figure 7: Report in HTML format generated from Sphinx source.

**Markdown.** A recent, very popular format for easy writing of web pages is [Markdown](#). Text is written very much like one would do in email, using spacing and special characters to naturally format the code instead of heavily tagging the text as in  $\text{\LaTeX}$  and HTML. With the tool [Pandoc](#) one can go from Markdown to a variety of formats. HTML is a common output format, but  $\text{\LaTeX}$ , epub, XML, OpenOffice/LibreOffice, MediaWiki, and Microsoft Word are some other possibilities. A Markdown version of our scientific report demo is available as an IPython/Jupyter notebook (described next).

**IPython/Jupyter notebooks.** The [IPython Notebook](#) is a web-based tool where one can write scientific reports with live computer code and graphics. Or the other way around: software can be equipped with documentation in the style of scientific reports. A slightly extended version of Markdown is used for writing text and mathematics, and the [source code of a notebook](#) is in json format. The interest in the notebook has grown amazingly fast over just a few years, and



further development now takes place in the [Jupyter project](#), which supports a lot of programming languages for interactive notebook computing. Jupyter notebooks are primarily live electronic documents, but they can be printed out as PDF reports too. A notebook version of our scientific report can be [downloaded](#) and experimented with or [just statically viewed](#) in a browser.

**Wiki formats.** A range of wiki formats are popular for creating notes on the web, especially documents which allow groups of people to edit and add content. Apart from [MediaWiki](#) (the wiki format used for Wikipedia), wiki formats have no support for mathematical typesetting and also limited tools for displaying computer code in nice ways. Wiki formats are therefore less suitable for scientific reports compared to the other formats mentioned here.

**DocOnce.** Since it is difficult to choose the right tool or format for writing a scientific report, it is advantageous to write the content in a format that easily translates to  $\text{\LaTeX}$ , HTML, Sphinx, Markdown, IPython/Jupyter notebooks, and various wikis. [DocOnce](#) is such a tool. It is similar to Pandoc, but offers some special convenient features for writing about mathematics and programming. The [tagging is modest](#), somewhere between  $\text{\LaTeX}$  and Markdown. The program [exper1\\_do.py](#) demonstrates how to generate DocOnce code for a scientific report. There is also a corresponding rich demo of the [resulting reports](#) that can be made from this DocOnce code.

## 6.7 Publishing a complete project

To assist the important principle of *replicable* science, a report documenting scientific investigations should be accompanied by all the software and data used for the investigations so that others have a possibility to redo the work and assess the quality of the results.

One way of documenting a complete project is to make a directory tree with all relevant files. Preferably, the tree is published at some project hosting site like [Bitbucket](#) or [GitHub](#) so that others can download it as a tarfile, zipfile, or clone the files directly using the Git version control system. For the investigations outlined in Section 6.6, we can create a directory tree with files

```
setup.py
./src:
  model.py
./doc:
  ./src:
    exper1_mathjax.py
    make_report.sh
    run.sh
  ./pub:
    report.html
```

The `src` directory holds source code (modules) to be reused in other projects, the `setup.py` script builds and installs such software, the `doc` directory contains the

documentation, with `src` for the source of the documentation (usually written in a markup language) and `pub` for published (compiled) documentation. The `run.sh` file is a simple Bash script listing the `python` commands we used to run `exper1_mathjax.py` to generate the experiments and the `report.html` file.

## 7 Exercises

### Problem 1: Make a tool for differentiating curves

Suppose we have a curve specified through a set of discrete coordinates  $(x_i, y_i)$ ,  $i = 0, \dots, n$ , where the  $x_i$  values are uniformly distributed with spacing  $\Delta x$ :  $x_i = \Delta x$ . The derivative of this curve, defined as a new curve with points  $(x_i, d_i)$ , can be computed via finite differences:

$$d_0 = \frac{y_1 - y_0}{\Delta x}, \quad (6)$$

$$d_i = \frac{y_{i+1} - y_{i-1}}{2\Delta x}, \quad i = 1, \dots, n-1, \quad (7)$$

$$d_n = \frac{y_n - y_{n-1}}{\Delta x}. \quad (8)$$

a) Write a function `differentiate(x, y)` for differentiating a curve with coordinates in the arrays `x` and `y`, using the formulas above. The function should return the coordinate arrays of the resulting differentiated curve.

b) Since the formulas for differentiation used here are only approximate, with unknown approximation errors, it is challenging to construct test cases. Here are three approaches, which should be implemented in three separate test functions.

1. Consider a curve with three points and compute  $d_i$ ,  $i = 0, 1, 2$ , by hand. Make a test that compares the hand-calculated results with those from the function in a).
2. The formulas for  $d_i$  are exact for points on a straight line, as all the  $d_i$  values are then the same, equal to the slope of the line. A test can check this property.
3. For points lying on a parabola, the values for  $d_i$ ,  $i = 1, \dots, n-1$ , should equal the exact derivative of the parabola. Make a test based on this property.

c) Start with a curve corresponding to  $y = \sin(\pi x)$  and  $n+1$  points in  $[0, 1]$ . Apply `differentiate` four times and plot the resulting curve and the exact  $y = \sin \pi x$  for  $n = 6, 11, 21, 41$ .  
Filename: `curvediff`.

## Problem 2: Make solid software for the Trapezoidal rule

An integral

$$\int_a^b f(x)dx$$

can be numerically approximated by the Trapezoidal rule,

$$\int_a^b f(x)dx \approx \frac{h}{2}(f(a) + f(b)) + h \sum_{i=1}^{n-1} f(x_i),$$

where  $x_i$  is a set of uniformly spaced points in  $[a, b]$ :

$$h = \frac{b-a}{n}, \quad x_i = a + ih, \quad i = 1, \dots, n-1.$$

Somebody has used this rule to compute the integral  $\int_0^\pi \sin^2 x \, dx$ :

```
from math import pi, sin
np = 20
h = pi/np
I = 0
for k in range(1, np):
    I += sin(k*h)**2
print I
```

a) The “flat” implementation above suffers from serious flaws:

1. A general numerical algorithm (the Trapezoidal rule) is implemented in a specialized form where the formula for  $f$  is inserted directly into the code for the general integration formula.
2. A general numerical algorithm is not encapsulated as a general function, with appropriate parameters, which can be reused across a wide range of applications.
3. The lazy programmer dropped the first terms in the general formula since  $\sin(0) = \sin(\pi) = 0$ .
4. The sloppy programmer used `np` (number of points?) as variable for `n` in the formula and a counter `k` instead of `i`. Such small deviations from the mathematical notation are completely unnecessary. The closer the code and the mathematics can get, the easier it is to spot errors in formulas.

Write a function `trapezoidal` that fixes these flaws. Place the function in a module `trapezoidal`.

b) Write a test function `test_trapezoidal`. Call the test function explicitly to check that it works. Remove the call and run `pytest` on the module:

---

Terminal

---

```
Terminal> py.test -s -v trapezoidal
```

---

**Hint.** Note that even if you know the value of the integral, you do not know the error in the approximation produced by the Trapezoidal rule. However, the Trapezoidal rule will integrate linear functions exactly (i.e., to machine precision). Base a test function on a linear  $f(x)$ .

c) Add functionality such that we can compute  $\int_a^b f(x)dx$  by providing  $f$ ,  $a$ ,  $b$ , and  $n$  as positional command-line arguments to the module file:

---

Terminal

---

```
Terminal> python trapezoidal.py 'sin(x)**2' 0 pi 20
```

---

Here,  $a = 0$ ,  $b = \pi$ , and  $n = 20$ .

Note that the `trapezoidal.py` file must still be a valid module file, so the interpretation of command-line data and computation of the integral must be performed from calls in a test block.

**Hint.** To translate a string formula on the command line, like `sin(x)**2`, into a Python function, you can wrap a function declaration around the formula and run `exec` on the string to turn it into live Python code:

```
import math, sys
formula = sys.argv[1]
f_code = """
def f(x):
    return %s
""" % formula
exec(code, math.__dict__)
```

The result is the same as if we had hardcoded

```
from math import *
def f(x):
    return sin(x)**2
```

in the program. Note that `exec` needs the namespace `math.__dict__`, i.e., all names in the `math` module, such that it understands `sin` and other mathematical functions. Similarly, to allow  $a$  and  $b$  to be `math` expressions like `pi/4` and `exp(4)`, do

---

Terminal

---

```
a = eval(sys.argv[2], math.__dict__)
b = eval(sys.argv[2], math.__dict__)
```

---

d) Write a test function for verifying the implementation of data reading from the command line.

Filename: `trapezoidal`.

### Problem 3: Implement classes for the Trapezoidal rule

We consider the same problem setting as in Problem 2. Make a module with a class `Problem` representing the mathematical problem to be solved and a class `Solver` representing the solution method. The rest of the functionality of the module, including test functions and reading data from the command line, should be as in Problem 2. Filename: `trapezoidal_class`.

### Problem 4: Write a doctest and a test function

Type in the following program:

```
import sys
# This sqrt(x) returns real if x>0 and complex if x<0
from numpy.lib.scimath import sqrt

def roots(a, b, c):
    """
    Return the roots of the quadratic polynomial
    p(x) = a*x**2 + b*x + c.

    The roots are real or complex objects.
    """
    q = b**2 - 4*a*c
    r1 = (-b + sqrt(q))/(2*a)
    r2 = (-b - sqrt(q))/(2*a)
    return r1, r2

a, b, c = [float(arg) for arg in sys.argv[1:]]
print roots(a, b, c)
```

a) Equip the `roots` function with a doctest. Make sure to test both real and complex roots. Write out numbers in the doctest with 14 digits or less.

b) Make a test function for the `roots` function. Perform the same mathematical tests as in a), but with different programming technology.

Filename: `test_roots`.

### Problem 5: Investigate the size of tolerances in comparisons

When we replace a comparison `a == b`, where `a` and/or `b` are `float` objects, by a comparison with tolerance, `abs(a-b) < tol`, the appropriate size of `tol` depends on the size of `a` and `b`. Investigate how the size of `abs(a-b)` varies when `b` takes on values  $10^k$ ,  $k = -5, -9, \dots, 20$  and `a=1.0/49*b*49`. Thereafter, compute the *relative* difference `abs((a-b)/a)` for the same `b` values.

Filename: `tolerance`.

**Remarks.** You will experience that if `a` and `b` are large, as they can be in, e.g., geophysical applications where lengths measured in meters can be of size  $10^6$  m, `tol` must be about  $10^{-9}$ , while `a` and `b` around unity can have `tol` of size  $10^{-15}$ . The way out of the problem with choosing a tolerance is to use relative differences.

## Exercise 6: Make use of a class implementation

Implement the `experiment_compare_dt` function from `decay.py` using class `Problem` and class `Solver` from Section 5. The parameters `I`, `a`, `T`, the scheme name, and a series of `dt` values should be read from the command line. Filename: `experiment_compare_dt_class`.

## Problem 7: Make solid software for a difference equation

We have the following evolutionary difference equation for the number of individuals  $u^n$  of a certain specie at time  $n\Delta t$ :

$$u^{n+1} = u^n + \Delta t r u^n \left(1 - \frac{u^n}{M^n}\right), \quad u^0 = U_0. \quad (9)$$

Here,  $n$  is a counter in time,  $\Delta t$  is time between time levels  $n$  and  $n+1$  (assumed constant),  $r$  is a net reproduction rate for the specie, and  $M^n$  is the upper limit of the population that the environment can sustain at time level  $n$ . Filename: `logistic`.

## References

- [1] H. P. Langtangen. Quick intro to version control systems and project hosting sites. <http://hplgit.github.io/teamods/bitgit/html/>.
- [2] H. P. Langtangen. *A Primer on Scientific Programming with Python*. Texts in Computational Science and Engineering. Springer, fourth edition, 2014.

## Index

`argparse` (Python module), 28  
`ArgumentParser` (Python class), 28  
command-line arguments, 27, 28  
debugging, 16  
`Distutils`, 45  
`DocOnce`, 65  
doctest in test function, 39  
doctests, 34  
GitHub, 46  
Google Docs, 62  
HTML, 62  
importing modules, 7, 48  
IPython notebooks, 64  
Jupyter notebooks, 64  
LaTeX, 62  
LibreOffice, 62  
list comprehension, 27  
logger, 16  
`logging` module, 16  
Markdown, 64  
`MathJax`, 62  
nose, 35  
OpenOffice, 62  
option-value pairs (command line), 28  
`os.system`, 61  
problem class, 49  
pytest, 35  
reading the command line, 28  
refactoring, 7  
relative differences, 37, 69  
replicability, 56, 65  
reproducibility, 56  
`setup.py`, 45  
software testing  
doctests, 34  
nose, 35  
pytest, 35  
test function, 36  
unit testing (class-based), 42  
solver class, 51  
Sphinx (typesetting tool), 63  
`sys.argv`, 27  
test function, 35, 36  
`TestCase` (class in `unittest`), 43  
unit testing, 35, 42  
`unittest`, 42, 43  
Unix wildcard notation, 61  
wildcard notation (Unix), 61  
Word (Microsoft), 62  
wrapper (code), 51