Matrix games

Axel Böhm

September 9, 2021

Introduction

2 Algorithms

Introduction

Given

- Player I (rows, Alice)
- Player II (columns, Bob)
- a payoff matrix $A \in \mathbb{R}^{m \times n}$

Every round

- Alice picks (row) strategy $i \in [m] := \{1, ..., m\}$ Bob picks (col) strategy $j \in [n]$
- 2 Bob pays Alice the amount $a_{i,j}$

zero-sum game

Example: penalty game

Figure: penalty game

Example: prisoners dilemma

	Confess A	Stay quiet A
Confess	6	10
В	6	0
Stay quiet	0	2
В	10	2

Figure

• Alice gets $\min_{j \in [n]} a_{i,j}$

• Alice gets $\max_{j \in [m]} \min_{j \in [n]} a_{i,j}$

- Alice gets $\max_{j \in [m]} \min_{j \in [n]} a_{i,j}$
- $\bullet \ \, \mathsf{Bob} \ \, \mathsf{gets} \ \, \mathsf{min}_{j \in [n]} \, \mathsf{max}_{j \in [m]} \, a_{i,j} \\$

- Alice gets $\max_{j \in [m]} \min_{j \in [n]} a_{i,j}$
- Bob gets $\min_{j \in [n]} \max_{j \in [m]} a_{i,j}$

We claim:

$$\max_{i} \min_{j} a_{i,j} \leq \min_{j} \max_{i} a_{i,j}$$

"Tallest dwarf is not as tall as the smallest giant."

But equality does not hold in general!

$$a_{ij} \leq a_{ij} \qquad \forall i, j$$

$$a_{ij} \le a_{ij}$$
 $\forall i, j$
 $a_{ij} \le \max_{i} a_{ij}$ $\forall i, j$

$$a_{ij} \le a_{ij} \qquad \forall i, j$$
 $a_{ij} \le \max_{i} a_{ij} \qquad \forall i, j$
 $\min_{j} a_{ij} \le \min_{i} \max_{i} a_{ij} \qquad \forall i$

$$a_{ij} \le a_{ij} \qquad \forall i, j$$
 $a_{ij} \le \max_{i} a_{ij} \qquad \forall i, j$
 $\min_{j} a_{ij} \le \min_{i} \max_{i} a_{ij} \qquad \forall i$

Definition

We call (i^*, j^*) a saddle point (or Nash equilibrium) if

$$\max_i a_{ij^*} = a_{i^*j^*} = \min_j a_{i^*j}.$$

These are called pure strategies.

Rock paper scissors

Mixed Strategies

With pure strategies we do not always have a saddle point.

von Neumann (1928) — Mixed strategies

- Alice picks strategies $1, \ldots, m$ with probabilities $x \in \Delta_m$
- Bob picks strategies $1, \ldots, n$ with probabilities $x \in \Delta_n$

Expected gain of Alice is

$$\langle x, Ay \rangle = \sum_{i,j} a_{ij} x_i y_j$$

Mixed Strategies

With pure strategies we do not always have a saddle point.

von Neumann (1928) — Mixed strategies

- Alice picks strategies $1, \ldots, m$ with probabilities $x \in \Delta_m$
- Bob picks strategies $1, \ldots, n$ with probabilities $x \in \Delta_n$

Expected gain of Alice is

$$\langle x, Ay \rangle = \sum_{i,j} a_{ij} x_i y_j$$

Theorem

Saddle point exists Expected gain of Alice = expected loss of Bob

$$\max_{x \in \Delta} \min_{y \in \Delta} \langle x, Ay \rangle = \min_{y \in \Delta} \max_{x \in \Delta} \langle x, Ay \rangle.$$

Stopping criteria

$$\min_{x \in \Delta} \max_{y \in \Delta} \langle x, Ay \rangle =: v$$

$$\max_{y \in \Delta} \min_{x \in \Delta} \langle x, Ay \rangle = v$$

stopping criterion

$$f_p(x) - f_p(x^*) = f_p(x) - v$$

 $f_d(y^*) - f_d(y) = v - f_d(y)$

Before we never had the optimal value!

Solution will always be on the boundary:

$$f_p(x) = \max_{y \in \Delta} \langle A^T x, y \rangle = \max_j \langle A^T x, e_j \rangle$$

Stopping criteria

$$\min_{x \in \Delta} \max_{y \in \Delta} \langle x, Ay \rangle =: v$$

$$\max_{y \in \Delta} \min_{x \in \Delta} \langle x, Ay \rangle = v$$

stopping criterion

$$f_p(x) - f_p(x^*) = f_p(x) - v \le \epsilon/2$$

 $f_d(y^*) - f_d(y) = v - f_d(y) \le \epsilon/2$

Before we never had the optimal value!

Solution will always be on the boundary:

$$f_p(x) = \max_{y \in \Delta} \langle A^T x, y \rangle = \max_j \langle A^T x, e_j \rangle$$

Stopping criteria

$$\min_{x \in \Delta} \max_{y \in \Delta} \langle x, Ay \rangle =: v$$

$$\max_{y \in \Delta} \min_{x \in \Delta} \langle x, Ay \rangle = v$$

stopping criterion

$$f_p(x) - f_p(x^*) = f_p(x) - v \le \epsilon/2$$

$$f_d(y^*) - f_d(y) = v - f_d(y) \le \epsilon/2$$

$$\Rightarrow f_p(x) - f_d(y) \le \epsilon$$

Before we never had the optimal value!

Solution will always be on the boundary:

$$f_p(x) = \max_{y \in \Delta} \langle A^T x, y \rangle = \max_j \langle A^T x, e_j \rangle$$

Consider

$$\min_{x \in \Delta} \max_{y \in \Delta} \langle x, Ay \rangle$$

as a minimization problem

$$\min_{x \in \Delta} \langle x, Ay^* \rangle$$

Then

$$x^* \in \operatorname*{arg\;min}_{y \in \Delta} f_p(x) \Leftrightarrow \langle \nabla f_p(x^*), x - x^* \rangle \geq 0 \quad \forall x \in D$$

Thus

$$\langle A^T y^*, x - x^* \rangle \ge 0 \quad \forall x \in D$$

 $\langle -Ax^*, y - y^* \rangle \ge 0 \quad \forall y \in D$

Concatenate the two conditions to get

$$\left\langle \begin{bmatrix} 0 & A^T \\ -A & 0 \end{bmatrix} \begin{pmatrix} x^* \\ y^* \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} x^* \\ y^* \end{pmatrix} \right\rangle$$

By rewriting
$$z = (x, y)$$
 and $F(z) = [A^T y; Ax]$, then

$$\langle F(z^*), z - z^* \rangle \ge 0 \quad \forall z \in \Delta_n \times \Delta_m := C$$
 (VI)

Variational inequality

If $F = \nabla \varphi$ then (VI) would be equivalent to

$$\min_{C} \varphi$$