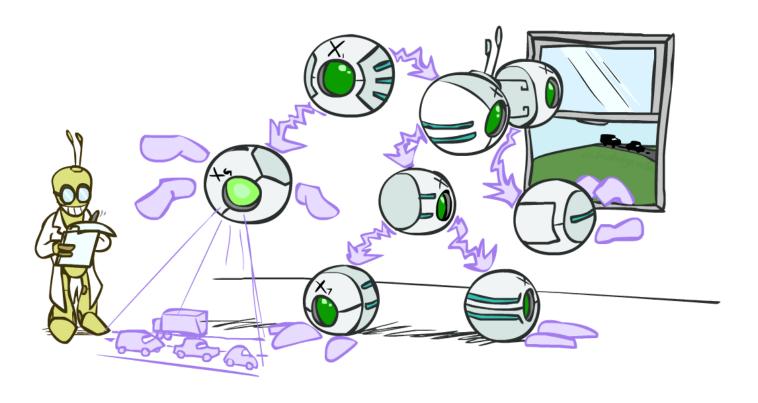
Bayes Nets: Exact Inference



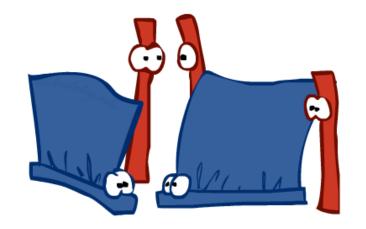
AIMA Chapter 14.4, PRML Chapter 8.4

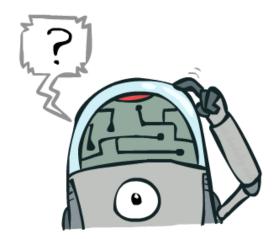
Inference

 Inference: calculating some useful quantity from a probabilistic model (joint probability distribution)

Examples:

- Posterior marginal probability
 - $P(Q|e_1,...,e_k)$
 - E.g., what disease might I have?
- Most likely explanation:
 - $\operatorname{argmax}_{q} P(Q=q | e_1,...,e_k)$
 - E.g., what did he say?







Inference by Enumeration

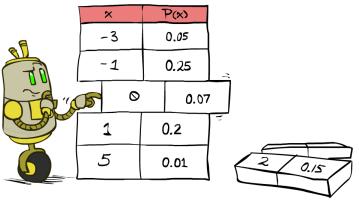
General case:

Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$ Query variable: Q Hidden variables: $H_1 \dots H_r$

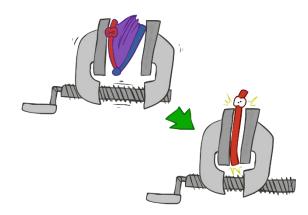
We want:

$$P(Q|e_1 \dots e_k)$$

Step 1: Select the entries consistent with the evidence



Step 2: Sum out H to get joint of Query and evidence



$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} P(Q, h_1 \dots h_r, e_1 \dots e_k)$$

$$X_1, X_2, \dots X_n$$

Step 3: Normalize

$$\times \frac{1}{Z}$$

$$Z = \sum_{q} P(Q, e_1 \cdots e_k)$$

$$Z = \sum_{q} P(Q, e_1 \cdots e_k)$$
$$P(Q|e_1 \cdots e_k) = \frac{1}{Z} P(Q, e_1 \cdots e_k)$$

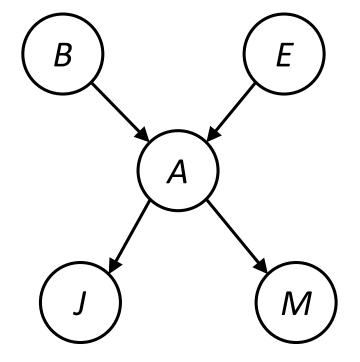
Inference by Enumeration in Bayes Net

- The joint distribution can be computed from a BN by multiplying the conditional distributions
- Then we can do inference by enumeration

$$P(B \mid +j,+m) \propto_B P(B,+j,+m)$$

$$= \sum_{e,a} P(B,e,a,+j,+m)$$

$$= \sum_{e,a} P(B)P(e)P(a|B,e)P(+j|a)P(+m|a)$$



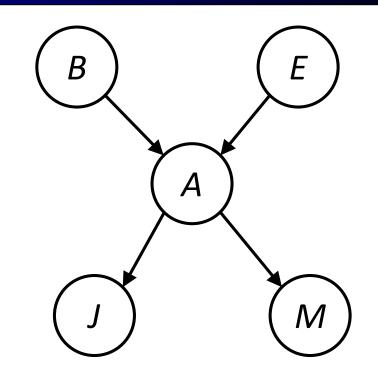
Problem: sums of *exponentially many* products!

Inference by Enumeration in Bayes Net

$$P(B \mid +j,+m) \propto_B P(B,+j,+m)$$

$$= \sum_{e,a} P(B,e,a,+j,+m)$$

$$= \sum_{e,a} P(B)P(e)P(a|B,e)P(+j|a)P(+m|a)$$



$$= P(B)P(+e)P(+a|B,+e)\frac{P(+j|+a)P(+m|+a)}{P(+j|+a)P(+m|+a)} + P(B)P(+e)P(-a|B,+e)\frac{P(+j|-a)P(+m|-a)}{P(+j|-a)P(+m|+a)} + P(B)P(-e)P(-a|B,-e)\frac{P(+j|-a)P(+m|-a)}{P(+j|-a)P(+m|-a)}$$

Lots of repeated subexpressions!

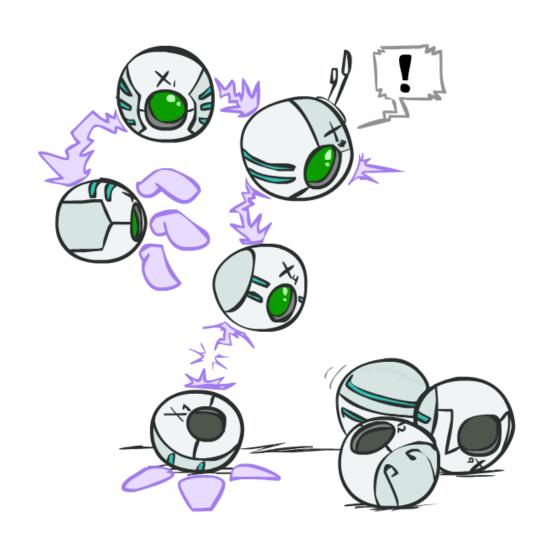
Can we do better?

- Consider uwy + uwz + uxy + uxz + vwy + vwz + vxy +vxz
 - 16 multiplies, 7 adds
 - Lots of repeated subexpressions!
- Rewrite as (u+v)(w+x)(y+z)
 - 2 multiplies, 3 adds
- Idea: Move summations inwards as far as possible

Variable elimination: The basic ideas

- Move summations inwards as far as possible
 - $P(B | j, m) = \alpha \sum_{e,a} P(B) P(e) P(a | B,e) P(j | a) P(m | a)$ = $\alpha P(B) \sum_{e} P(e) \sum_{a} P(a | B,e) P(j | a) P(m | a)$
 - Note: P(a|B,e) isn't a single number, it's a bunch of different numbers depending on the values of a, B and e
 - It's clearer to view the computation with operations on factors (arrays of numbers)

Operations on Factors



Factors

- A factor is a multi-dimensional array to represent $P(Y_1 ... Y_N \mid X_1 ... X_M)$
 - If a variable is assigned (represented with lower-case), its dimension is missing from the array
 - Joint distribution: P(X,Y)
 - Entries P(x,y) for all x, y
 - Sums to 1

- Selected joint: P(x,Y)
 - A slice of the joint distribution
 - Entries P(x,y) for fixed x, all y
 - Sums to P(x)

| P | (T | י י | W | ⁷) |
|---|------------|-----|---|----------------|
| _ | \ — | 7 | | |

| Т | W | Р |
|------|------|-----|
| hot | sun | 0.4 |
| hot | rain | 0.1 |
| cold | sun | 0.2 |
| cold | rain | 0.3 |

| Т | W | Р |
|------|------|-----|
| cold | sun | 0.2 |
| cold | rain | 0.3 |

Factors

- A factor is a multi-dimensional array to represent $P(Y_1 ... Y_N \mid X_1 ... X_M)$
 - If a variable is assigned (represented with lower-case), its dimension is missing from the array
 - Single conditional: P(Y | x)
 - Entries P(y | x) for fixed x, all y
 - Sums to 1

- Family of conditionals:P(X | Y)
 - Multiple conditionals
 - Entries P(x | y) for all x, y
 - Sums to |Y|

| $\overline{}$ | / T T 7 | l 7 | 7 |
|---------------|------------|-----|--------------|
| P | (W) | col | 'd \ |
| T | <i>V V</i> | COi | ω_{J} |

| Т | W | Р |
|------|------|-----|
| cold | sun | 0.4 |
| cold | rain | 0.6 |

| Т | W | Р | |
|------|------|-----|---------------------------------|
| hot | sun | 0.8 | $\bigcap_{D(W) L,A}$ |
| hot | rain | 0.2 | $\Big \int P(W hot)$ |
| cold | sun | 0.4 | |
| cold | rain | 0.6 | $\left \int P(W cold) \right $ |

Factors

- A factor is a multi-dimensional array to represent $P(Y_1 ... Y_N \mid X_1 ... X_M)$
 - If a variable is assigned (represented with lower-case), its dimension is missing from the array
 - Specified family: P(y | X)
 - Entries P(y | x) for fixed y,but for all x
 - Sums to ... who knows!

| Т | W | Р | |
|------|------|-----|------------------------------------|
| hot | rain | 0.2 | $\Big \Big P(rain hot)\Big $ |
| cold | rain | 0.6 | $\left igred P(rain cold) ight $ |

Running Example: Traffic Domain

Random Variables

R: Raining

■ T: Traffic

■ L: Late



| P(R) | |
|------|-----|
| +r | 0.1 |
| -r | 0.9 |

| P(| T | R |) |
|------|---|---|---|
| 1 10 | | + | |

| +r | +t | 0.8 |
|----|----|-----|
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

| +t | + | 0.3 |
|----|----------------|-----|
| +t | - 1 | 0.7 |
| -t | + | 0.1 |
| -t | - | 0.9 |

Running Example: Traffic Domain

Initial factors are local CPTs (one per node)

| +r | 0.1 |
|----|-----|
| -r | 0.9 |

| +r | +t | 0.8 |
|----|----|-----|
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(R)$$
 $P(T|R)$ $P(L|T)$

| +t | + | 0.3 |
|----|---|-----|
| +t | 7 | 0.7 |
| -t | + | 0.1 |
| -t | - | 0.9 |

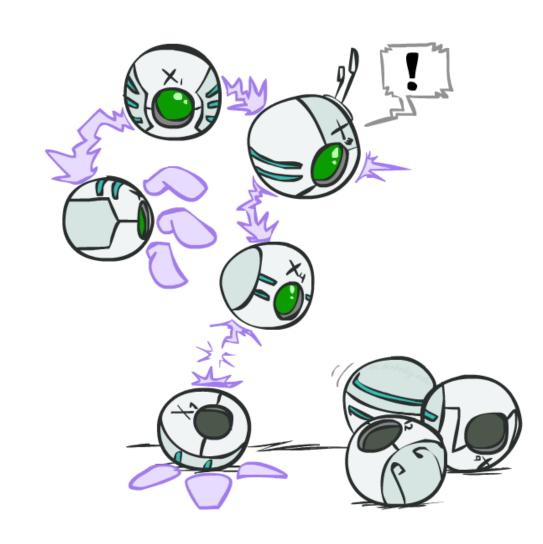
- Any known values are selected
 - E.g. if we know $L = +\ell$, the initial factors are

| +r | 0.1 |
|----|-----|
| -r | 0.9 |

| +r | +t | 0.8 |
|----|----|-----|
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

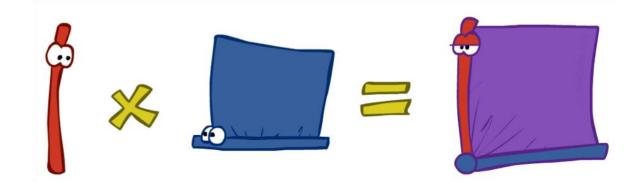
$$P(R)$$
 $P(T|R)$ $P(+\ell|T)$

| | ' ' | |
|----|-----|-----|
| +t | + | 0.3 |
| -t | + | 0.1 |

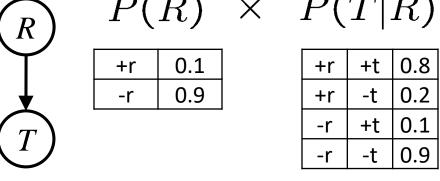


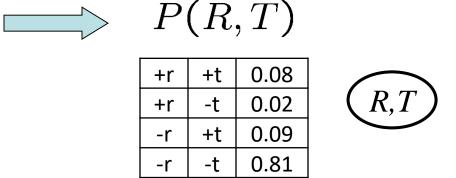
Operation 1: Join Factors

- First basic operation: joining factors
 - Just like a database join
 - Given multiple factors, build a new factor over the union of the variables involved
 - Each entry is computed by pointwise products



Example:

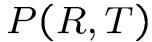




$$\forall r, t : P(r,t) = P(r) \cdot P(t|r)$$

Operation 2: Eliminate

- Second basic operation: eliminating a variable
 - Take a factor and sum out (marginalize) a variable
- Example:



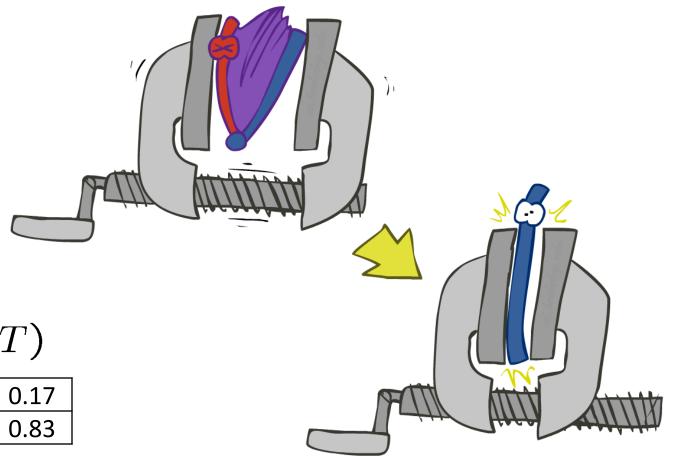
| +r | +t | 0.08 |
|----|----|------|
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |

 $\operatorname{sum} R$

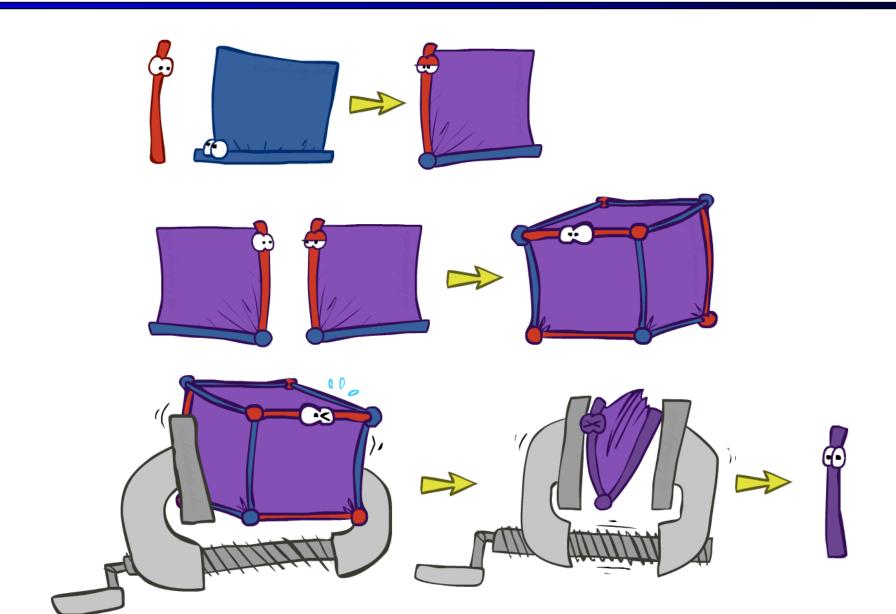


P(T)

| +t | 0.17 |
|----|------|
| -t | 0.83 |

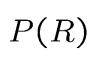


Inference by Enumeration in BN = Multiple Join + Multiple Eliminate



Computing P(L): Multiple Joins





| +r | 0.1 |
|----|-----|
| -r | 0.9 |

P(T|R)

+r

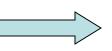
+t 0.8

-t 0.2

+t | 0.1

Join



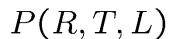


| D | (7 | O | 7 | 7 |
|----------|--------|----------|---|---|
| Γ | igl(I | ι, | 1 |) |

| +r | +t | 0.08 |
|----|----|------|
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |

Join





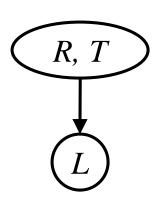
| +r | +t | + | 0.024 |
|----|----|----|-------|
| +r | +t | - | 0.056 |
| +r | -t | +1 | 0.002 |
| +r | -t | - | 0.018 |
| -r | +t | +1 | 0.027 |
| -r | +t | - | 0.063 |
| -r | -t | +1 | 0.081 |
| -r | -t | - | 0.729 |

| D | I | $ T\rangle$ |
|---|-----|-------------|
| 1 | (L) | 1 |

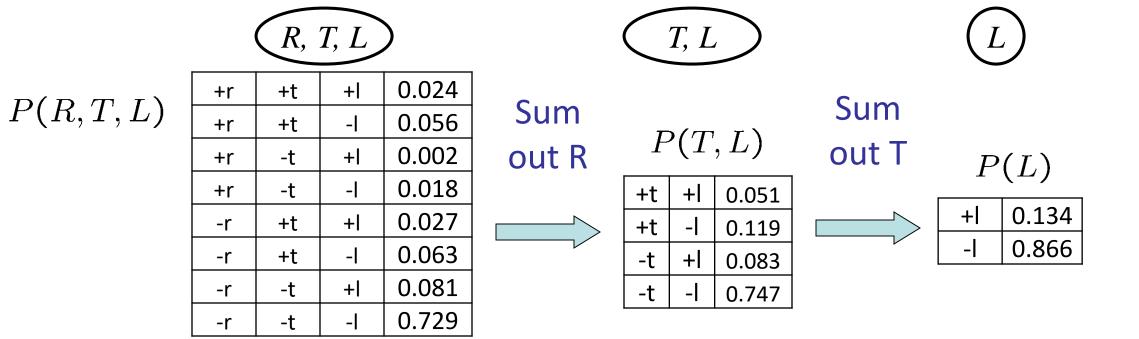
| +t | + | 0.3 |
|----|---|-----|
| +t | - | 0.7 |
| -t | + | 0.1 |
| -t | - | 0.9 |



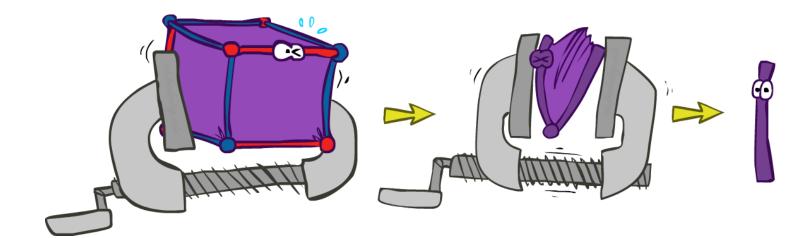
| +t | + | 0.3 |
|----|----------------|-----|
| +t | - - | 0.7 |
| -t | + | 0.1 |
| -t | - | 0.9 |



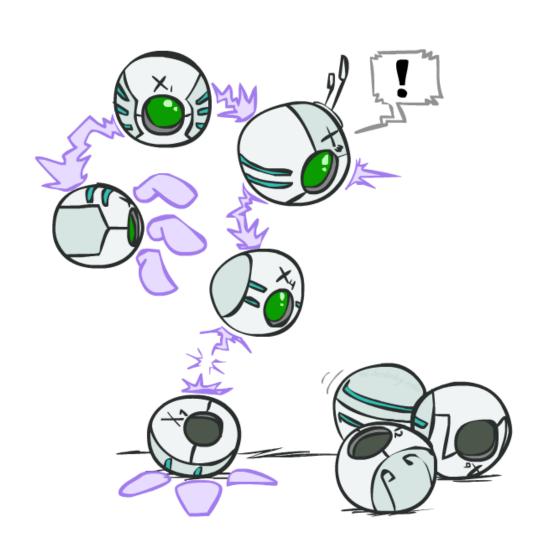
Computing P(L): Multiple Elimination



A factor of exponential size!

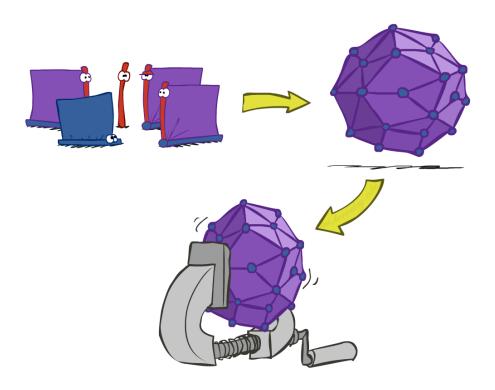


Variable Elimination

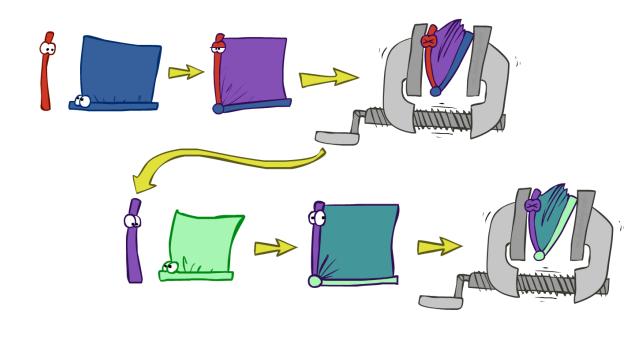


Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables

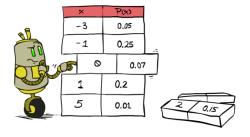


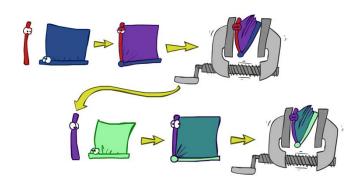
- Idea: interleave joining and elimination!
 - Called "Variable Elimination"
 - Still NP-hard, but usually much faster than inference by enumeration



Variable Elimination

- Query: $P(Q|E_1 = e_1, \dots E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H
 - Join all factors mentioning H
 - Eliminate (sum out) H
- Join all remaining factors and normalize





$$i \times \mathbf{r} = \mathbf{r} \times \frac{1}{Z}$$

Traffic Domain



$$P(L) = ?$$

Inference by Enumeration

Variable Elimination

$$= \sum_{t} P(L|t) \sum_{r} P(r)P(t|r)$$
 Join on r Eliminate r

Variable Elimination



0.1

0.9



Join R



Sum out R



Join T



Sum out T



P(T|R)

+r

-r

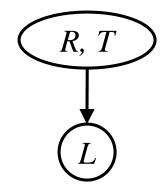
| +r | +t | 0.8 |
|----|----|-----|
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

| $\boldsymbol{L} \setminus \boldsymbol{L} / \boldsymbol{L}$ | P | (L | T |
|--|---|----|---|
|--|---|----|---|

| +t | + | 0.3 |
|----|---|-----|
| +t | - | 0.7 |
| -t | + | 0.1 |
| -t | - | 0.9 |

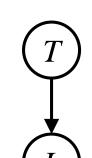
P(R,T)

| +r | +t | 0.08 |
|----|----|------|
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |
| | | • |



| D | 1 | T | 7 | 7) | ١ |
|--------------------------|-----|---|---|----|---|
| $\boldsymbol{\varGamma}$ | (. | L | 1 | | / |

| +t | + | 0.3 |
|----|--------------|-----|
| +t | - | 0.7 |
| -t | + | 0.1 |
| -t | - | 0.9 |



P(T)

+t

-t

0.17

0.83



| +t | + | 0.3 |
|----|----|-----|
| +t | - | 0.7 |
| -t | + | 0.1 |
| -t | -1 | 0.9 |



P(T,L)

| +t | + | 0.051 |
|----|--------------|-------|
| +t | - | 0.119 |
| -t | + | 0.083 |
| -t | - | 0.747 |

| | | \ |
|---|---|---|
| | 1 | 1 |
| | L | 1 |
| • | | |

P(L)

| + | 0.134 |
|---|-------|
| - | 0.866 |

Example

$$P(B|j,m) \propto P(B,j,m)$$

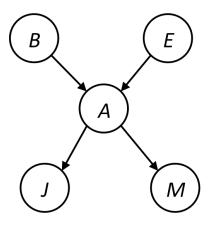
P(B)

P(E)

P(A|B,E)

P(j|A)

P(m|A)



Choose A

P(m|A)





P(j,m|B,E)

P(E)

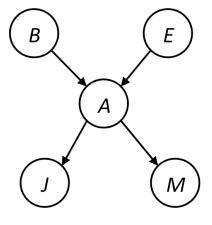
P(j,m|B,E)

Example

P(B)

P(E)

P(j,m|B,E)



Choose E

P(j,m|B,E)





P(j,m|B)

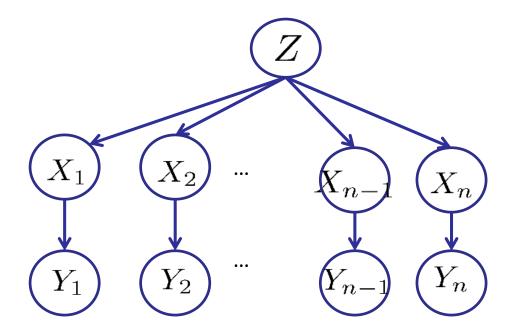
Finish with B





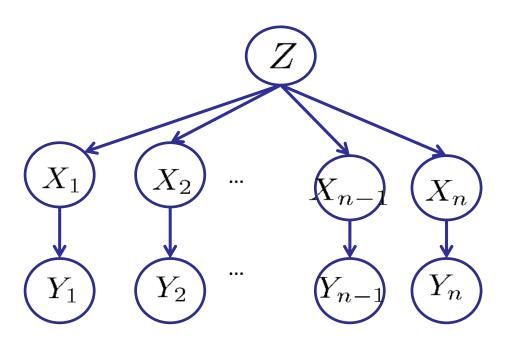
Variable Elimination Ordering

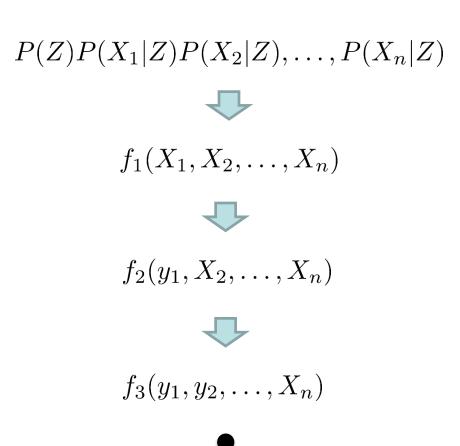
- Query: $P(X_n | y_1,...,y_n)$
- Two different orderings: $Z, X_1, ..., X_{n-1}$ and $X_1, ..., X_{n-1}, Z$.
- What is the size of the maximum factor generated for each of the orderings?



Variable Elimination Ordering

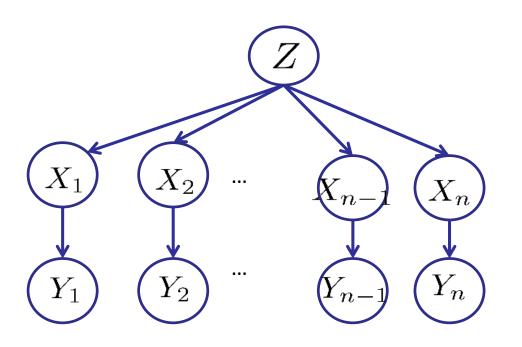
Z, X₁, ..., X_{n-1}

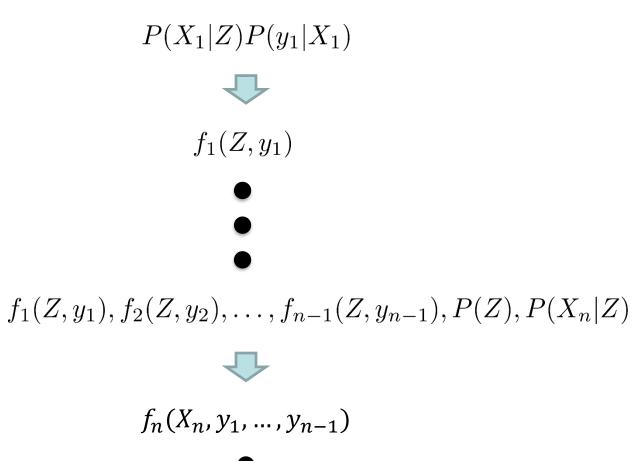




Variable Elimination Ordering

■ X₁, ..., X_{n-1}, Z





VE: Computational Complexity

- The size of the largest factor determines the time and space complexity of VE
- The elimination ordering can greatly affect the size of the largest factor.
 - E.g., previous slide's example 2ⁿ⁺¹ vs. 2²
- Does there always exist an ordering that only results in small factors?
 - No!

Reduction from 3SAT

 $(x_1 \lor x_2 \lor \neg x_3) \land (\neg x_1 \lor x_3 \lor \neg x_4) \land (x_2 \lor \neg x_2 \lor x_4) \land (\neg x_3 \lor \neg x_4 \lor \neg x_5) \land (x_2 \lor x_5 \lor x_7) \land (x_4 \lor x_5 \lor x_6) \land (\neg x_5 \lor x_6 \lor \neg x_7) \land (\neg x_5 \lor \neg x_6 \lor x_7) \land (x_4 \lor x_5 \lor x_6) \land (x_4 \lor x_5 \lor x_6) \land (x_5 \lor x_6 \lor \neg x_7) \land (x_5 \lor \neg x_6 \lor x_7) \land (x_5 \lor x_6 \lor \neg x_7) \land (x_5 \lor x_7) \land (x$

$$P(X_i = 0) = P(X_i = 1) = 0.5$$

$$Y_1 = X_1 \lor X_2 \lor \neg X_3$$

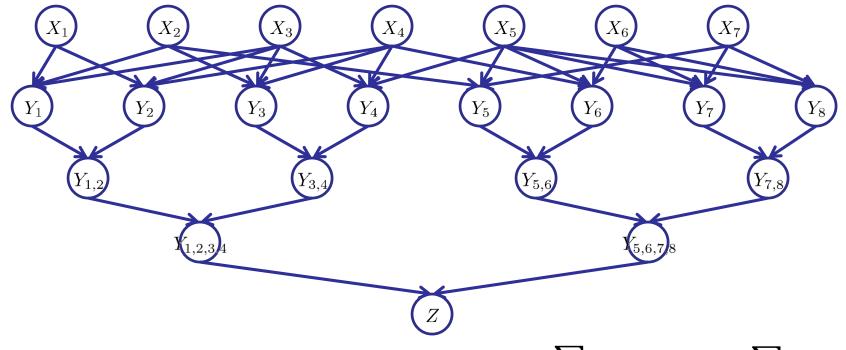
$$Y_8 = \neg X_5 \lor X_6 \lor X_7$$

$$Y_{1,2} = Y_1 \wedge Y_2$$

...

$$Y_{7,8} = Y_7 \wedge Y_8$$

 $Y_{1,2,3,4} = Y_{1,2} \wedge Y_{3,4}$
 $Y_{5,6,7,8} = Y_{5,6} \wedge Y_{7,8}$
 $Z = Y_{1,2,3,4} \wedge Y_{5,6,7,8}$



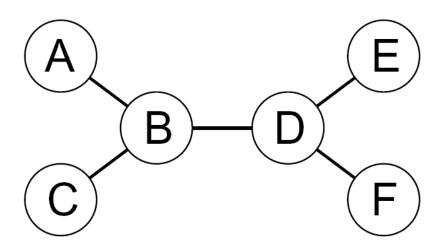
$$P(+z) = \sum_{\mathbf{x},\mathbf{y}} P(\mathbf{x},\mathbf{y},+z) = \sum_{\mathbf{x} \text{ s.t. } z=T} P(\mathbf{x})$$

- P(+z) > 0 iff the sentence is satisfiable \rightarrow NP-hard
- $P(+z) = S \times 0.5^7$ where S is the number of satisfying assignments

→ #P-hard

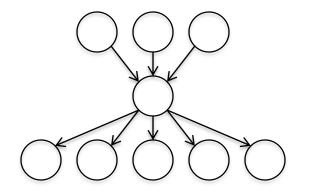
When do we have tractable inference?

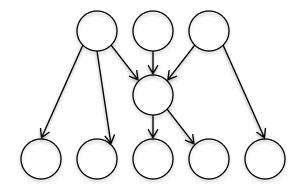
- Recall: Tree-Structured CSPs
 - CSP is NP-hard in general
 - If the constraint graph has no loops (i.e., tree), the CSP can be solved in linear time!

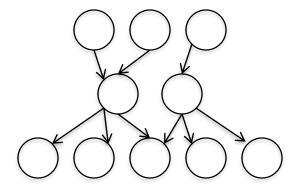


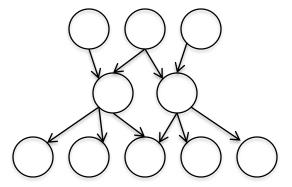
Polytrees

 A polytree is a directed graph with no undirected cycles



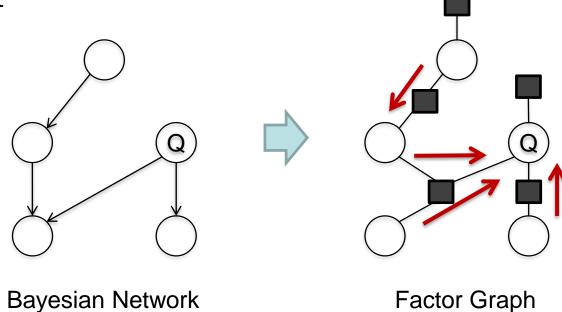






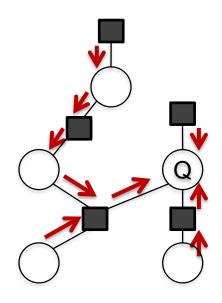
Variable Elimination on Polytrees

- For poly-tree BNs, the complexity of VE is *linear in the BN size* (number of CPT entries) with the following elimination ordering:
 - Convert to a factor graph
 - Take Q as the root
 - Eliminate from the leaves towards the root



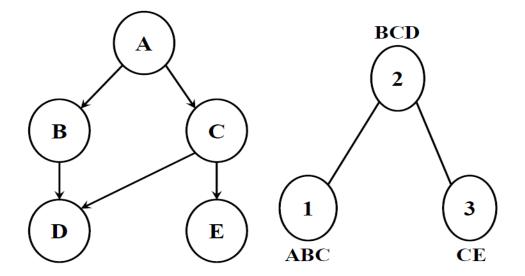
Variable Elimination on Polytrees

- VE for poly-tree BNs is equivalent to
 - Sum-product message passing algorithm or belief propagation algorithm (i.e., passing messages/beliefs from leaf nodes to the root node)
 - "Messages" are just 1d factors resulted from joining/elimination



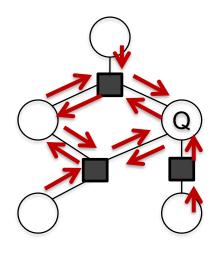
Message Passing on General Graphs

- Exact inference: Junction Tree
 Algorithm
 - Group individual nodes to form cluster nodes in such a way that the resulting network is a polytree (called a junction tree or join tree)
 - Run a sum-product-like algorithm on the junction tree.
 - *Intractable* on graphs with large cluster nodes (i.e., large tree-width).



Message Passing on General Graphs

- Approximate inference: Loopy Belief Propagation
 - Simply pass the messages on the general graph
 - Will not terminate with loops
 - Run until convergence (not guaranteed!)
 - Approximate but tractable for large graphs.
 - Sometime works well, sometimes not at all.



Summary

- Exact inference of Bayesian networks
 - Enumeration
 - exponential complexity
 - Variable Eliminating
 - worst-case exponential complexity, often better
 - VE on polytrees
 - linear complexity
 - = message passing
 - Message passing on general graphs
 - Junction Tree Algorithm
 - Loopy Belief Propagation: no longer exact