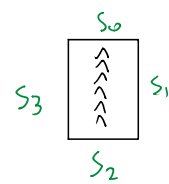
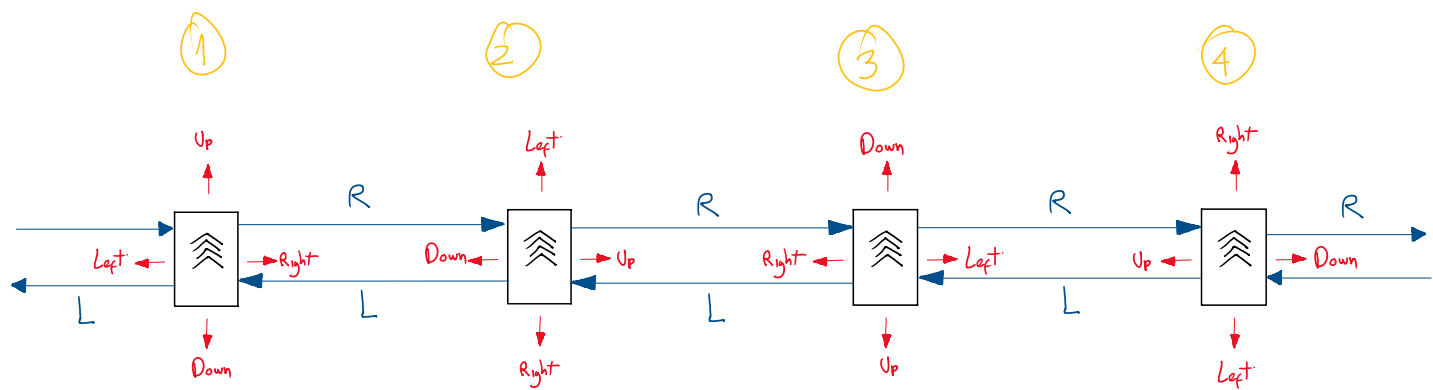


Input  
4 bits: Sensores  
1 = Detecto obstaculo  
0 = No detecto obstaculo  
4 Sensores



Output  
4 bits: Movimientos  
0000 - Idle  
0001 - Fw  
0010 - Back  
0011 - Right  
0100 - Left



# Magma General



In 0123  
xxxX

Out 0xxx

