

Body 1, ..., Body i, ..., Body n

$$(i=1 \dots n) M_i \ddot{\vec{P}}_i = G \left\{ \sum_{j=1}^n M_j \cdot \frac{\vec{P}_j - \vec{P}_i}{|\vec{P}_j - \vec{P}_i|^3} \right\} \quad (\text{Note: if } i=j \Rightarrow \text{very illegal!})$$

Force component direction matrix  $\times$  w

$$\begin{bmatrix} F_{dir} \\ \vdots \end{bmatrix} = \begin{bmatrix} \vec{P}_2 - \vec{P}_1 & \vec{P}_3 - \vec{P}_1 & \cdots & \vec{P}_n - \vec{P}_1 \\ \vec{P}_1 - \vec{P}_2 & \vec{P}_3 - \vec{P}_2 & \cdots & \vec{P}_n - \vec{P}_2 \\ \vec{P}_1 - \vec{P}_3 & \vec{P}_2 - \vec{P}_3 & \cdots & \vec{P}_n - \vec{P}_3 \\ \vdots & \vdots & \vdots & \vdots \\ \vec{P}_1 - \vec{P}_n & \vec{P}_2 - \vec{P}_n & \vec{P}_3 - \vec{P}_n & \cdots & \vec{P}_n - \vec{P}_n \end{bmatrix} \in \mathbb{R}^{3n \times 1} \quad \vec{M} = \begin{bmatrix} M_1 \\ M_2 \\ \vdots \\ M_n \end{bmatrix} \in \mathbb{R}^{n \times 1}$$

$$\therefore [F_{dir}] = -[F_{dir}]^T$$

Position of each body:

$$\vec{P} = \begin{bmatrix} \vec{P}_1^T & \vec{P}_2^T & \cdots & \vec{P}_n^T \end{bmatrix}^T$$

Equation of motion:

$$\frac{d^2}{dt^2} \vec{P} = \frac{d^2}{dt^2} \begin{bmatrix} \vec{P}_1 \\ \vec{P}_2 \\ \vdots \\ \vec{P}_n \end{bmatrix} = G \cdot [F_{dir}] \vec{M}$$

$$= G \begin{bmatrix} F_{dir, row 1} \vec{M} \\ F_{dir, row 2} \vec{M} \\ \vdots \\ F_{dir, row n} \vec{M} \end{bmatrix} = -G \begin{bmatrix} F_{dir, col 1}^T \vec{M} \\ F_{dir, col 2}^T \vec{M} \\ \vdots \\ F_{dir, col n}^T \vec{M} \end{bmatrix}$$

State space:  $\vec{x} = [\vec{P}^T, \dot{\vec{P}}_1^T, \dots, \dot{\vec{P}}_n^T, \frac{d}{dt} \vec{P}_1^T, \frac{d}{dt} \vec{P}_2^T, \dots, \frac{d}{dt} \vec{P}_n^T]^T$

$$\frac{d}{dt} \vec{x} = \begin{bmatrix} \frac{d}{dt} \vec{P} \\ \frac{d^2}{dt^2} \vec{P} \end{bmatrix} = \begin{bmatrix} \frac{d}{dt} \vec{P} \\ G \cdot [F_{dir}] \vec{M} \end{bmatrix}$$