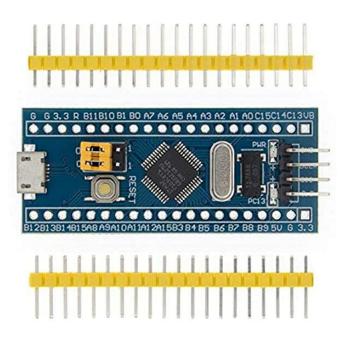
Lab2

ARM CORTEX-M3 STM32



Name: Aya Sayed Abdellah

In this lab I will write a bare-metal software to toggle led is connected to GPIO port C13, To make a GPIO toggling in STM32. After reading its specs I found that:

I need to work with two peripherals:

- RCC (reset and clock control in 0x18 APB2ENR Register in IOPAEN Bit 2) is necessary because the GPIO has disabled clock by default. Its base address is 0x40021000.
- GPIO (general purpose input/output) so I connected it to GPIO Port A with address 0x40010800, in GPIO_PA I have to read 2 in 0x04 CRH Register to active mode pin 13 (from bit 20 to 24) and in 0x0C ODR Register (pin 13)

Now I have all what I need to write application file I call it main.c

Next step it to read also its specs because Some part of startup code dependent on the target processor.

When power is applied to the MCU the Program Counter (PC) value will be 0 which will mappe to 0x08000000 and will therefore start at address 0x08000000. This address is then copied to the Stack Pointer (SP) register for later use.

The Program Counter then steps to the next address which is 0x0800 0004 and expects the address of the reset handler at this location then the next handler from the vector table handler.

Also I need .thumb_func This directive specifies that the following symbol is the name of a Thumb encoded function. This information is necessary in order to allow the assembler and linker to generate correct code for interworking between Arm and Thumb instructions. Because there are 2 types of instructions are provided in this processor are: 16 bit instruction and 32 bit instruction.

So I created a complex startup that consists of :

- 1. Define Interrupt vectors Section
- 2. Copy Data from ROM to RAM
- 3. Initialize Data Area
- 4. Initialize Stack
- 5. Create a reset section and Call main().

Before create it and because of SP initialized automated by the processor we can write startup.s and startup.c that feature is provided only for cortex-M3 and its family. So I wrote the 2 files.

And in the linker file I need to Aligned access memory to Efficiency fetch and execute so I used this command in linker script file (. = ALIGN(4)).

All the above information that I need it to write a bare-metal software to toggle the led let's start...

```
🇧 C:\Users\diese\Desktop\master embedded systems diploma\Unit 3 ( Embedded C )\Assignment\HW 3\Lab ( startup.s )\... 🕒
File Edit Selection Find View Goto Tools Project Preferences Help
                                                                   Linker Script.ld
      Master Embedded System Diploma <Learn in depth>
                   : Aya Sayed
                    : Main program body
     typedef volatile uint32_t vuint32_t;
                                                            //to set bit
     #define AND(value)
                           &=value
                                                            //to AND content of re
     #define OR(value)
                           =value
                                                             //to OR content of reg
     #define ON
     #define OFF
                                                             //LED IS OFF
     #define Delay
                    for( int i=0 ; i<5000 ; i++ ); //Delay Macro
     #define RCC BASE
                           0x40021000
     #define GPIOA_BASE
                           0x40010800
                           *( vuint32_t* )( RCC_BASE + 0x18 )
     #define RCC_APB2ENR
                           *( vuint32_t* )( GPIOA_BASE + 0x04 )
     #define GPIOA_CRH
                           *( vuint32_t* )( GPIOA_BASE + 0x0C )
     #define GPIOA_ODR
     #define RCC_IOPAEN
                           ( 1<<2 )
                           ( 1UL<<13 )
     #define GPIOA13
     typedef union
         vuint32_t
                          all_fields;
         struct
            vuint32 t
                         reversed:13;
            vuint32_t
                          pin_13:1;
         }Spin;
     }R_ODR_t;
     unsigned char g_variables[3] = {1,2,3};
     unsigned char const_variables[3]={1,2,3};
     volatile R_ODR_t* R_ODR = ( volatile R_ODR_t* )( GPIOA_BASE + 0x0C );
         RCC_APB2ENR Set(RCC_IOPAEN);
         GPIOA_CRH AND(0xFF0FFFFF);
         GPIOA_CRH
                   OR(0x00200000);
         while(1)
             R_ODR->Spin.pin_13 = ON ;
             R_ODR->Spin.pin_13 = OFF; Delay
```

Tab Size: 4

Line 1, Column 1

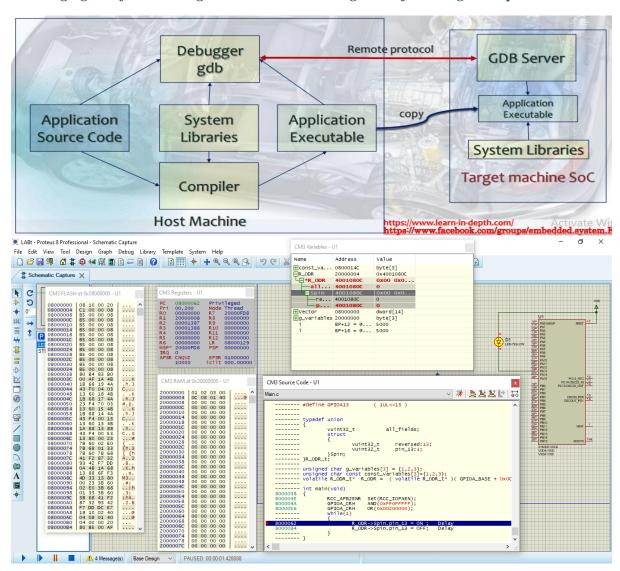
```
C:\Users\diesel\Desktop\master embedded systems diploma\Unit 3 ( Embedded C )\Assignment\HW 3\Lab ( startup.c )\S...
File Edit Selection Find View Goto Tools Project Preferences Help
                                                                                            Startup.c
                     extern uint32_t _E_TEXT;
extern uint32_t _S_DATA;
                     extern uint32_t _E_DATA;
extern uint32_t _S_BSS;
extern uint32_t _S_BSS;
extern uint32_t _Stack_top;
                       void Default_Handler()
                                    Reset_Handler();
                    void NMI_Handler(void)_attribute__((weak, alias("Default_Handler")));
void Hard_Fault_Handler(void)_attribute__((weak, alias("Default_Handler")));
void MM_Fault_Handler(void)_attribute__((weak, alias("Default_Handler")));
void Bus_Fault_Handler(void)_attribute__((weak, alias("Default_Handler")));
void Usage_Fault_Handler(void)_attribute__((weak, alias("Default_Handler")));
void SV_call_Handler(void)_attribute__((weak, alias("Default_Handler")));
void Debug_reserved_Handler(void)_attribute__((weak, alias("Default_Handler")));
void PendSV_Handler(void)_attribute__((weak, alias("Default_Handler")));
void Sys_Tick_Handler(void)_attribute__((weak, alias("Default_Handler")));
void IRQ0_Handler(void)_attribute__((weak, alias("Default_Handler")));
void IRQ1_Handler(void)_attribute__((weak, alias("Default_Handler")));
void IRQ2_Handler(void)_attribute__((weak, alias("Default_Handler")));
                     uint32_t Vector[] __attribute__((section(".vectors"))) = {
  (uint32_t) & stack_top,
  (uint32_t) & Reset_Handler,
  (uint32_t) & NMI_Handler,
  (uint32_t) & Hard_Fault_Handler,
  (uint32_t) & MM_Fault_Handler,
  (uint32_t) & Bus_Fault_Handler,
  (uint32_t) & Bus_Fault_Handler,
  (uint32_t) & Bus_Fault_Handler,
  (uint32_t) & Bus_Fault_Handler
                     (uint32_t) &Bus_Fault_Handler,
(uint32_t) &Usage_Fault_Handler,
(uint32_t) &SV_call_Handler,
(uint32_t) &Debug_reserved_Handler,
(uint32_t) &PendSV_Handler,
(uint32_t) &Sys_Tick_Handler,
(uint32_t) &IRQ0_Handler,
(uint32_t) &IRQ1_Handler,
(uint32_t) &IRQ1_Handler
}.
                       void Reset_Handler(void)
                                    uint32_t DATA_SIZE = (uint8_t*)&_E_DATA - (uint8_t*)&_S_DATA;
uint8_t* P_src = (uint8_t*)&_E_TEXT;
uint8_t* P_dis = (uint8_t*)&_S_DATA;
for( int i=0 ; i<DATA_SIZE ; i++)</pre>
                                                    *((uint8_t*)P_dis++) = *((uint8_t*)P_src++);
                                    uint32_t BSS_SIZE = (uint8_t*)&_E_BSS - (uint8_t*)&_S_BSS;
P_dis = (uint8_t*)&_S_BSS;
for( int i=0 ; i < BSS_SIZE ; i++)</pre>
                                                   *((uint8_t*)P_dis++) = (uint8_t)0;
                                     main();
```

```
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File Edit Selection Find View Goto Tools Project Preferences Help
 ∢▶
      Linker_Script.ld
         Master Embedded System Diploma <Learn in depth>
         file
                         : Linker_Script.ld
         Author
                          : Aya Sayed
         brief
                          : Linker Script program body
        MEMORY
             flash(RX) : ORIGIN = 0x08000000, LENGTH = 128k
             sram(RWX) : ORIGIN = 0x20000000, LENGTH = 20k
        SECTIONS
            .text :{
                 *(.vectors*)
                 *(.text*)
                 E_TEXT = . ;
            }> flash
            .data :{
                 _S_DATA = . ;
                 *(.data*)
                 . = ALIGN(4);
                 _E_DATA = . ;
            }> sram AT> flash
                  S_BSS = .;
                 *(.bss)
                 . = ALIGN(4);
                 _{E_BSS} = .;
                 . = . + 0x1000;
                 _stack_top = . ;
            }> sram
            .rodata :{
                 *(.rodata* )
            }> flash
 MINGW32:/c/Users/diesel/Desktop/master embedded systems diploma/Unit 3 (Embedded C)/Assignment/H...
                                                                                                     diesel@DESKTOP-ET8890F MINGW32 ~/Desktop/master embedded systems diploma/Unit 3 ( Embedded C )/Assignment,
W 3/LAB2
sexport PATH=/c/ST/STM32CubeIDE_1.4.0/STM32CubeIDE/plugins/com.st.stm32cube.ide.mcu.externaltools.gnu-too
ls-for-stm32.7-2018-q2-update.win32_1.4.0.202007081208/tools/bin:$PATH
diesel@DESKTOP-ET889OF MINGW32 ~/Desktop/master embedded systems diploma/Unit 3 ( Embedded C )/Assignment/
W 3/LAB2
$ make
arm-none-eabi-gcc.exe -c -mcpu=cortex-m3 -gdwarf-2 -I . Main.c -o Main.o
arm-none-eabi-gcc.exe -c -mcpu=cortex-m3 -gdwarf-2 -I . Startup.c -o Startup.o
arm-none-eabi-ld.exe -T Linker_Script.ld -Map=output.map Main.o Startup.o -o LAB2_ARM_CORTEX-M3.elf
arm-none-eabi-objcopy.exe -O binary LAB2_ARM_CORTEX-M3.elf LAB2_ARM_CORTEX-M3.bin
diesel@DESKTOP-ET889OF MINGW32 ~/Desktop/master embedded systems diploma/Unit 3 ( Embedded C )/Assignment/
 W 3/LAB2
$ |
```

```
0x000000000200000000
                                                g_variables
                                                R COR
                0x80000000200000004
                0x0000000020000008
                                         0x0 Startup.o
 .data
                0x00000000200000008
                                                 . = ALIGN (0x4)
                0x88888888828888888
                                                 _E_DATA - .
               0x000000000200000008
                                         0x0 load address 0x0000000000000014c
.igot.plt
               0x0000000020000008
                                         0x0 Main.o
.igot.plt
               0x00000000200000008
                                      0x1000 load address 0x0000000000000014c
bes
               execcecco20000008
                                                _S_BSS = .
 *(.bss)
               0x000000000200000008
                                         0x0 Main.o
 .bss
               0x00000000200000008
 .bss
                                         0x0 Startup.o
               0x0000000020000008
                                                . - ALIGN (0x4)
               0x80000000020000008
                                                _E_BSS = .
. = (. + 0x1000)
               0x0000000020001008
 *f111*
               0x8000000020000008
                                      0×1000
               0x0000000020001008
                                                _stack_top = .
.rodata
               0x0000000000000014c
                                         0x3
*(.rodata*)
.rodata
                                         0x3 Main.o
               0x000000000800014c
               0x0000000000000014c
                                                const_variables
LOAD Main.o
LOAD Startup.o
OUTPUT(LAB2_ARM_CORTEX-M3.elf elf32-littlearm)
.rel.dyn
               0x00000000008000150
               0x0000000000000150
.rel.iplt
                                         0x0 Main.o
               0x00000000000000000
.debug info
                                       0x343
               0x00000000000000000
.debug_info
                                       0x19d Main.o
.debug_info
               0x000000000000019d
                                      0x1a6 Startup.o
               .debug_abbrev
                                       0x1c0
.debug abbrev
               0×0000000000000000
                                        0xea Main.o
.debug_abbrev
               0x000000000000000ea
                                        0xd6 Startup.o
.debug_loc
               0xb4
                                        0x38 Main.o
.debug_loc
               0x00000000000000000
               0x00000000000000038
.debug_loc
                                        0x7c Startup.o
               0x00000000000000000
                                        0x40
.debug_aranges
.debug_aranges
                0x20 Main.o
.debug_aranges
               0x20 Startup.o
.debug line
               EbEx®
.debug_line
               0x0000000000000000
                                       0x1df Main.o
               0x800000000000001df
.debug_line
                                       0x1f4 Startup.o
.debug_str
               0×00000000000000000
                                       0x21f
.debug str
               0x00000000000000000
                                       0x196 Main.o
                                       0x1d3 (size before relaxing)
               0x00000000000000196
                                       0x89 Startup.o
 .debug_str
                                       0x204 (size before relaxing)
```

```
0х7ь
.comment
             0x0000000000000000
                                  0x7b Main.o
.comment
                                  0x7c (size before relaxing)
             0х000000000000007ь
                                  0x7c Startup.o
.comment
.ARM.attributes
             0x33
.ARM.attributes
             0x0000000000000000
                                  0x33 Main.o
.ARM.attributes
             0x8000000000000033
                                  0x33 Startup.o
             .debug_frame
                                  0x7c
.debug_frame
             0x00000000000000000
                                  0x2c Main.o
             0x50 Startup.o
.debug_frame
```

now using -gdwarf-2 to debug on Proteus accordding to the following concept.



The previous lab was by startup.c and I repeat it but with startup.s and here it but without copying .data from FLASH to SRAM and initializing .bss with 0.

```
🇧 C:\Users\diese\Desktop\master embedded systems diploma\Unit 3 ( Embedded C )\Assignment\HW 3\Lab ( startup.s )\St... 🕒 💢
File Edit Selection Find View Goto Tools Project Preferences Help
       Master Embedded System Diploma <Learn in depth>
      file
                 : Startup.s
      Author
                     : Aya Sayed
       brief
                     : Startup Assembly program body
       .section .vectors
                             //stack top address
      .word 0x20001000
                             // 1 Reset
     .word reset
      .word Vector handler
                             // 2 NMI
                             // 3 Hard Fault
     .word Vector_handler
     .word Vector_handler
                             // 4 MM Fault
                             // 4 PMM FAULT
// 5 Bus Fault
// 6 Usage Fault
// 7 RESERVED
// 8 RESERVED
// 9 RESERVED
      .word Vector_handler
      .word Vector_handler
      .word Vector_handler
      .word Vector handler
      .word Vector handler
      .word Vector_handler
                             // 10 RESERVED
                             // 11 SV call
      .word Vector handler
                             // 12 Debug reserved
     .word Vector handler
     .word Vector handler
                             // 13 RESERVED
                             // 14 PendSV
     .word Vector handler
                             // 15 Sys Tick
     .word Vector_handler
                             // 16 IRQ0
      .word Vector_handler
      .word Vector_handler
                             // 17 IRQ1
      .word Vector_handler
                             // 18 IRQ2
      .word Vector handler
      .section .text
      _reset: bl main
              ь.
                            //branch label main
      .thumb_func
      Vector_handler:
              b _reset
Line 1, Column 1
                                                                         Spaces: 8
                                                                                    Plain Text
```