```
y= Ae at + yp(t)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             y (t) = [y(o] - yp(o)] e at
                          y(t) = y(0^{-})e^{-at} + y_{p}(t) - y_{p}(0)e^{-at} = [y(0^{-}) - y_{p}(0)]e^{-at} + y_{p}(t)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            y (t) = yp(t)
                                                                                                                                                                                                                                       Zhejiang University - University of Illinois at Urbana-Champaign Institute
                                                                                                                                                                                                                                                                                                ECE-210 Analog Signal Processing Spring 2022
                            y (t) z_{eno} state = y_p(t) - y_p(0) e^{-at}
                                                                                                                                                                                                                                                                                              Homework #5: Submission Deadline 23rrd March (10:00 PM)
                                                                                              1. Consider the following circuit with v(0^-) = 1V and let f(t) = 2e^{-t/3} V. For t = \frac{1}{13}0, obtain:

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    C)
     1 + L = [N(0) - ND (0)] &
                                                           ባኔተጻ \bar{\beta} the zero-input voltage across the capacitor's terminals, v_{\rm ZI}(t),
                                                                                                                               (c) the transient voltage across the capacitor's terminals, v_{tr}(t),
                                                                                                                           (d) the steady state voltage across the capacitor's terminals, v_{ss}(t), and
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   = e - 48t
                                                                                                                             (e) the total voltage across the capacitor's terminals, v(t).
                                                    2. Consider the following circuit with f(t) = 10\cos(\omega t) volts and v(0^-) = v_0 volts.
                            (0) \frac{R}{lb} \frac{dV}{dt} + V = f(t) \frac{dV}{dt} + \frac{lb}{R} V = \frac{lb}{R} cos(wt)
\Rightarrow \frac{dV}{dt} + \frac{lb}{lb} V = \frac{lb}{lb} f(t)
                                                         \Rightarrow \frac{dV}{dt} + \frac{lb}{R}V = \frac{lb}{R}ftt
It is known that for t>0, v(t)=Ae^{-t}+B\cos{(2t)}+C\sin{(2t)} volts.

c) y=(\log\cos(\omega t)\cdot e^{-t})\cdot e^{-t} (b) for 1st order linear ODE.

t(1+i\omega)(a) Write the ODE that governs this system for t>0 in terms of R, v(t), and \omega.

=(\log e^{-t})\cdot e^{-t} (b) Find the value of R. With =(g(t))\cdot e^{-t} of t+C) =(e^{-t})\cdot e^{-t} (c) =(e^{-t})\cdot e^{-t} (b) Find the value of R.
                                                                                        Steady state Phasor
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       フ<u>ほ</u>て-ぬ +awぬ=ア
                                       \frac{|o(t-\overline{t}w)e^{\overline{t}wt}(e)}{|t+w|^2} + Ce^{-\frac{10}{t}} +
                                                                                                                        V_{SS} = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi), \ tom \phi = \lambda_{\overline{b}} \cos(\lambda t - \phi),
                                                                                                                  The different parts of this problem are unrelated:
                                            W=2 C)
  Determine the phasor F of f(t) = -2\sin(2t - \frac{\pi}{3}). Express F in both polar and rectangular (c) Determine the phasor F of f(t) = \cos(3t - \frac{\pi}{2}). Express F in both polar and rectangular co
                                                                                                                                  Express the phasor F=2-j2 in terms of a cosine function f(t) having frequency \omega=3\frac{\mathrm{rad}}{\mathrm{s}}. Express the phasor F=3e^{-j\frac{\pi}{3}} in terms of a cosine function f(t) having frequency \omega=3\frac{\mathrm{rad}}{\mathrm{s}}.
          ={[COS4t+]SMAT
                       +005<del>4</del>t-jsin4T]
        = \cos 4t = \sin (4t + \frac{\pi}{2})^{1}
                                                                                                                           (g) Express the phasor F = 3e^{-j\frac{\pi}{3}} in terms of a cosine function f(t) having frequency \omega = 3\frac{\mathrm{rad}}{\mathrm{s}}.
                       Q.E.D.
                                                                                                                                                                                                                                                                                                                                                                               1) F= 2 ( = - = 1)
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       b) e^{-\hat{j}zt} - e^{\hat{j}zt} = \frac{1}{1}(\cos zt - \hat{j}\sin zt - \cos zt - \hat{j}\sin zt)
                                                                                                                                                                                                                                                                                                                                                                                                                               = 2F 005(3t-11)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         Page 1 of 2
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- 4. Use the phasor method to express the following signals in terms of a single cosine function:
  - (a)  $f(t) = -3\sin(3t) + 3\cos(3t)$ .
  - (b)  $g(t) = 2 \left[ \sin(2t) \sin(2t + \pi/2) \right]$ .

(a) 
$$f(t) = \frac{1}{2}\cos(\frac{1}{2}t) - \frac{1}{2}\sin(\frac{1}{2}t)$$

$$= \frac{1}{3}\overline{p} \left[ \frac{1}{2}\cos(\frac{1}{2}t) - \frac{1}{2}\sin(\frac{1}{2}t) \right]$$

$$= \frac{1}{3}\overline{p} \left[ \cos(\frac{1}{2}t) - \frac{1}{3}\sin(\frac{1}{2}t) \right]$$

$$= \frac{$$