Differential Equations Plus (Math 286)

H71 Find the following convolutions and their Laplace transforms (three answers suffice):

a)
$$t^{2} * t^{3}$$
; b) $J_{0} * J_{0}$; c) $\sin t * \cos(2t)$; d) $u(t-1) * t$.

a) $\int \{t^{2}\} \cdot \int \{t^{2}\} = \int \{t^{2} * t^{3}\} \}$ b) $\int \{J_{0} * J_{0}\} = \int \{J_{0}\} \cdot \int \{J_{0}\} \}$

$$\Rightarrow \frac{2!}{s^{\frac{3}{2}}} \cdot \frac{3!}{s^{4}} = \frac{12}{s^{7}} = \frac{12}{6!} \cdot \frac{6!}{s^{7}} = \frac{1}{s^{2}+1} \Rightarrow \int \{J_{0} * J_{0}\} = \int \{\sin t\} \Rightarrow J_{0} * J_{0} = \sin t$$

$$\Rightarrow t^{2} * t^{3} = \frac{1}{5} t^{5}$$

$$\Rightarrow t^{2} * t^{3} = \frac{1}{5} t^{5} \Rightarrow t^{5$$

H72 Solve the following IVP's with the Laplace transform:

a)
$$y'' + y' + y = u_{\pi}(t) - u_{2\pi}(t)$$
, $y(0) = 1$, $y'(0) = 0$;
b) $y'' + 2y' + y = \begin{cases} \sin(2t) & \text{if } 0 \le t \le \pi/2, \\ 0 & \text{e}^{-t}\mathbf{r} \le e^{-t}\mathbf{r} \le e^{-t}\mathbf$

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b)
$$y'' + 2y' + y = \begin{cases} \sin(2t) & \text{if } 0 \le t \le \pi/2, \\ 0 & \text{if } t > \pi/2, \end{cases}$$
 $y(0) = 1, \ y'(0) = 0.$

- **H73** In each of the following cases, let S be the set of vectors $(\alpha, \beta, \gamma) \in \mathbb{C}^3$ satisfying the given condition. Decide whether S is a subspace of \mathbb{C}^3/\mathbb{C} and, if so, determine the dimension of S.
 - a) $\alpha = 0$;

- b) $\alpha\beta = 0;$ d) $\alpha + \beta = 0;$ f) $\alpha \in \mathbb{R}.$
- c) $\alpha + \beta = 1;$ e) $\alpha = 3\beta \wedge \beta = (2 i)\gamma;$

- **H74** Let P_3 be the vector space (over \mathbb{R}) of polynomials $p(X) \in \mathbb{R}[X]$ of degree at most 3. Repeat the previous exercise for the sets $S \subseteq P_3$ defined by each of the following conditions:
 - a) p(X) has degree 3;

c) p(t) > 0 for 0 < t < 1;

- b) 2p(0) = p(1); d) p(t) = p(1-t) for all $t \in \mathbb{R}$.
- H75 Do Exercises 11 and 20 in [BDM17], Ch. 7.1.
- **H76** Find **S** such that $D = S^{-1}AS$ is a diagonal matrix for

$$\mathbf{A} = \left(\begin{array}{cc} 2 & -1 \\ -1 & 2 \end{array} \right).$$

Show that $\mathbf{A}^k = \mathbf{S}\mathbf{D}^k\mathbf{S}^{-1}$ for $k \in \mathbb{N}$, and use this to obtain explicit formulas for the entries of \mathbf{A}^k .

H77 Optional Exercise

Do Exercise 18 in [BDM17], Ch. 6.5.

H78 Optional Exercise

Repeat Exercises 20, 21 in [BDM17], Ch. 6.6, for the integro-differential equation

$$\phi'(t) = \sin t + \int_0^t \phi(t - \xi) \cos \xi \, d\xi, \quad \phi(0) = 2.$$

Hint: It may be helpful to use the commutativity of the convolution product.

H79 Optional Exercise

Suppose V is a vector space over a field F.

a) Using the vector space axioms, prove the scalar zero law

$$0_F v = 0_V$$
 for all $v \in V$.

b) Similarly, prove the vector zero law

$$a \, 0_V = 0_V$$
 for all $a \in F$.

c) Prove that (-1)x = -x for all $x \in V$.

H80 Optional Exercise

- a) Write down the linear system of equations satisfied by a classical 3×3 magic square and transform this system into row-echelon form. (What is the magic number in this case?)
- b) Use the equations in a) to show that up to obvious symmetries there exists exactly one classical 3×3 magic square.

Due on Fri May 13, 6 pm

The optional exercises can be handed in until Fri May 20, 6 pm.

H76 Find **S** such that $D = S^{-1}AS$ is a diagonal matrix for

$$\mathbf{A} = \left(\begin{array}{cc} 2 & -1 \\ -1 & 2 \end{array} \right).$$

Show that $\mathbf{A}^k = \mathbf{S}\mathbf{D}^k\mathbf{S}^{-1}$ for $k \in \mathbb{N}$, and use this to obtain explicit formulas for the entries of \mathbf{A}^k .

As
$$D = S^{-1}AS \Rightarrow A = SDS^{-1} \Rightarrow A^{K} = \underbrace{SDS^{-1} SDS^{-1} ... SDS^{-1}}_{K + orms} \Rightarrow 0. \pm .0.$$

As $A = \begin{pmatrix} 1 & -1 & -1 \\ -1 & -1 & -1 \end{pmatrix} \Rightarrow \begin{vmatrix} 1 & -1 & -1 \\ -1 & -1 & -1 \end{pmatrix} \Rightarrow \begin{vmatrix} 1 & -1 & -1 \\ -1 & -1 & -1 \end{pmatrix} \Rightarrow \begin{vmatrix} 1 & -1 & -1 \\ -1 & -1 & -1 \end{vmatrix} \Rightarrow A^{K} = SD^{K}S^{-1} = \begin{pmatrix} 1 & -1 & -1 \\ -1 & -1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 3 & -$

H75 Do Exercises 11 and 20 in [BDM17], Ch. 7.1.

$$\begin{aligned} & E_{X,1}| \\ & \text{For Block} \mid \geq \alpha = \frac{d^2x}{dt^2} \Rightarrow m_1\frac{d^2x_1}{dt^2} = m_1\alpha = -k_1x_1+f_1(t)+k_2(x_2^-x_1) & \text{For Block} \mid \geq \sum f_2 = m_1\frac{d^2x_2}{dt^2} = -(k_2tk_2)x_1+k_2x_2+f_1(t) \\ & E_{X,2}\alpha \colon V_1 = L\frac{d^2}{dt} \quad I_C = C\frac{dV}{dt} & = -(k_1tk_2)x_1+k_2x_2+f_1(t) \\ & V_1 = I_1 \cdot R \quad V_2 = I_2R_2 & \Rightarrow L\frac{d^2}{dt} + 2R_1t^2I_2R_2 = 0 \Rightarrow I_1 = I_2t^2I_2 = \frac{V_2}{R} + C\frac{dV}{dt} \end{aligned}$$

H74 Let P_3 be the vector space (over \mathbb{R}) of polynomials $p(X) \in \mathbb{R}[X]$ of degree at most 3. Repeat the previous exercise for the sets $S \subseteq P_3$ defined by each of the following conditions. No. For P(X) = 0 to the polynomials $P(X) \in \mathbb{R}[X]$ of degree at most P(X) = 0 to the previous exercise for the sets P(X) = 0 defined by each of the following conditions. No. For P(X) = 0 to the previous exercise for the sets P(X) = 0 defined by each of the following conditions.

a) p(X) has degree 3; \Rightarrow degree 3 degree 3 degree 3.

c) $p(t) \ge 0 \text{ for } 0 \le t \le 1;$

c) p(x) & Sz thon (+1)p(t)=-p(t) ≤0 for 0 < t <1 ⇒ p(x) is not identically zono on [0,1] ⇒ -p(x) & x ⇒ No.

d): $p(t) = p(t-t) \Rightarrow 0_0 = 0_0 + 0_1 + 0_2 + 0_3$ $0_1 = -0_1 - 20_2 - 30_3$ $0_2 = 0_2 + 30_3$

$$\Rightarrow \begin{pmatrix} 0 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ -0 & 1 \\ 0 & 0 \end{pmatrix} = 0 = 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + 0 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

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$$\Rightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 0 &$$

Firsty. $\begin{cases} 2a_0 = a_0 + a_1 + a_2 + a_3 & \text{or } a_0 - a_1 - a_2 - a_3 = 0 \\ b) & 2p(0) = p(1); \Rightarrow a_0 = a_1 + a_2 + a_3 \\ d) & p(t) = p(1-t) \text{ for all } t \in \mathbb{R}. \end{cases}$ $\begin{cases} a_1 \\ a_2 \\ a_3 \\ a_4 \end{cases} = \begin{pmatrix} -a_1 a_2 - a_3 \\ a_1 \\ a_2 \\ a_3 \end{pmatrix} = a_1 \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} + a_2 \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} + a_2 \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$ $\Rightarrow p(x) = a_1(x + 1) + a_2(x^2 - 1) + a_3(x^3 - 1) +$

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Suppose Visa vector over a field F Suppose V is a vector over a field TA subset $U \subseteq V$ is a subspace of V if U suffifies: $\begin{pmatrix} 0 \\ \beta \\ y \end{pmatrix} = \beta \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad \text{dimsension } \ge \lambda$

- i) U contains Ox
- >) NtN = [x+y; x, y & N] CN
- 3) Fu = fax; aeF; xeujeu

$$\frac{1}{2} = \frac{1}{2} = \frac{1}{2} + \frac{1}{2} = \frac{1}{2} = \frac{1}{2} = \frac{1}{2}$$

b) $\begin{pmatrix} \alpha_1 \\ \beta_1 \\ \gamma_1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\begin{pmatrix} \alpha_2 \\ \beta_2 \\ \gamma_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ $\begin{pmatrix} \alpha_1 \dagger \alpha_2 \\ \beta_1 \dagger \beta_2 \\ \gamma_1 + \gamma_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ The condition β not a subspace.

3) $FN = \int ax_{1}^{2} aeF_{1}^{2} xeV_{2}^{2} \subseteq V$ d) $P_{1} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{1} + P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{2} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{3} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \\ b^{2} \end{pmatrix}$ $\Rightarrow P_{4} = \begin{pmatrix} ax_{1} \\ b^{2} \end{pmatrix}$