# Differential Equations Plus (Math 286)

- **H12** Determine all maximal solutions of  $t^2y'=y^2$  and decide for which points  $(t_0,y_0)\in$  $\mathbb{R}^2$  the IVP  $t^2y'=y^2\wedge y(t_0)=y_0$  has no solution/exactly one solution/more than one solution.
- **H13** Determine the general solution of the following ODE's in terms of y(0) (three answers suffice).

- b) dy/dt = ty + y + t;
- a)  $dy/dt = e^{y+t}$ ; c)  $dy/dt = (\cos t)y + 4\cos t$ ;
- d)  $du/dt = t^m y^n \ (m, n \in \mathbb{Z}).$
- **H14** For the following ODE's, solve the corresponding IVP with y(0) = 1.
- a) dy/dt = -4ty; b)  $dy/dt = ty^3$ ; c) (1+t)dy/dt = 4y.
- **H15** Show that the graph of  $y(t) = a/(de^{-at} + b)$  (a, b, d > 0) is point-symmetric to its inflection point.

Hint: A superb way to solve this exercise is to observe that the mirror image of a solution curve w.r.t. its inflection point represents a solution as well and use the uniqueness of solutions of associated IVP's.

- a) Explain how to adapt the analysis of the harvesting equation in the lecture to H16  $y' = ay^2 + by + c$  with  $a, b, c \in \mathbb{R}$  and a > 0.
  - b) Sketch the solution curves of (i)  $y' = y^2 y + 1$ , (ii)  $y' = y^2 + 2y + 1$ , (iii)  $y' = y^2 + y - 2$  without actually computing solutions. Steady-state solutions and inflection points (if any) should be drawn exactly.
- **H17** The ODE  $y' = a(t)y b(t)y^n$ ,  $n \in \mathbb{R} \setminus \{0,1\}$  is called Bernoulli's differential equation.
  - a) Show that for an appropriate choice of  $\beta \in \mathbb{R}$  the substitution  $z = y^{\beta}$  turns Bernoulli's differential equation into a linear 1st-order ODE (which can be solved by the usual methods).
  - b) Solve the IVP  $y' = 4y y^3 \wedge y(0) = 1$  by the method suggested in a).
  - c) Investigate the asymptotic stability of the steady-state solutions of the ODE in b).

#### **H18** Optional exercise

a) Show that the general (real) solution of y'' = y is  $y(x) = c_1 e^x + c_2 e^{-x}$ ,  $c_1, c_2 \in \mathbb{R}$ .

*Hint:* For a solution y the functions y + y' and y - y' satisfy linear 1st-order ODE's.

b) For  $x \in \mathbb{R}$  let

$$F(x) = \int_0^\infty \frac{\cos(xt)}{t^2 + 1} dt.$$

Show that

$$F'(x) = -\frac{\pi}{2} + \int_0^\infty \frac{\sin(xt)}{t(t^2 + 1)} dt \quad \text{for } x > 0.$$

Hint: Differentiate F under the integral sign and use  $\int_0^\infty \sin(xt)/t \, dt = \int_0^\infty \sin(t)/t \, dt = \pi/2$  for x > 0.

- c) Show that F solves y'' = y on  $(0, \infty)$ .
- d) Determine F from a), c) and F(0), F'(0+), and use the result to evaluate the integral

$$\int_0^\infty \frac{\cos t}{t^2 + 1} \, \mathrm{d}t \,.$$

#### **H19** Optional exercise

The task of this exercise is to show the Cauchy-Hadamard formula

$$R = \frac{1}{L}, \quad L = \limsup_{n \to \infty} \sqrt[n]{|a_n|}$$

(with the conventions  $1/0 = \infty$ ,  $1/\infty = 0$ ) for the radius of convergence R of a (complex) power series  $\sum_{n=0}^{\infty} a_n(z-a)^n$ . Here  $L = \limsup_{n \to \infty} x_n \in [-\infty, +\infty]$  (limit superior) denotes the largest accumulation point of a real sequence  $(x_n)$ , i.e., for every  $\epsilon > 0$  there are only finitely many indexes n satisfying  $x_n \ge L + \epsilon$  but no real number L' < L has this property (with suitable modifications for  $L = \pm \infty$ ).

- a) If  $L = \infty$  (i.e.,  $\sqrt[n]{|a_n|}$  is unbounded), show that  $\sum_{n=0}^{\infty} a_n (z-a)^n$  converges only for z=a.
- b) If L = 0 (i.e.,  $\sqrt[n]{|a_n|}$  converges to zero), show that  $\sum_{n=0}^{\infty} a_n (z-a)^n$  converges for all  $z \in \mathbb{C}$ .
- c) If  $0 < L < \infty$ , show that  $\sum_{n=0}^{\infty} a_n (z-a)^n$  converges for |z-a| < 1/L and diverges for |z-a| > 1/L.

## Due on Fri Oct 15, 6 pm

The optional exercises can be handed in until Fri Oct 22, 6 pm.

### **Solutions**

12 We can rewrite this separable ODE as

$$\frac{dy}{y^2} = \frac{dt}{t^2} \quad (y, t \neq 0)$$

Integrating both sides of the above equation, we get

$$\int_{y_0}^{y} \frac{1}{\eta^2} d\eta = \int_{t_0}^{t} \frac{1}{\tau^2} d\tau$$
$$-\frac{1}{y} + \frac{1}{y_0} = -\frac{1}{t} + \frac{1}{t_0}$$

which gives

$$y(t) = \frac{t_0 y_0}{\frac{t_0 y_0}{t} - (y_0 - t_0)} = \frac{(t_0 y_0)t}{t_0 y_0 - (y_0 - t_0)t}.$$

For t = 0 we must have y(t) = 0 (from  $t^2y' = y^2$ ). There is a constant solution  $y(t) = 0, t \in \mathbb{R}$ .

1)  $t_0 = y_0 \neq 0$ 

$$y(t) = \begin{cases} t, & t \neq 0 \\ 0, & t = 0 \end{cases}$$

And y(0) = 0 fits with the expression y(t) = t, so we can write the solution as y(t) = t,  $t \in \mathbb{R}$ .

There is only one solution.

2)  $t_0 = y_0 = 0$ 

Every solution of the ODE defined at t = 0 must satisfy y(0) = 0 (see above). The non-constant (maximal) solutions are

$$y(t) = \frac{t}{1 - Ct}, \quad C \in \mathbb{R}.$$

with domain  $\mathbb{R}$  if C = 0,  $(-\infty, 1/C)$  if C > 0, and  $(1/C, +\infty)$  if C < 0. In particular there are an infinite number of solutions.

- 3)  $t_0 = 0, y_0 \neq 0$ This IVP contradicts y(0) = 0. Therefore, there is no solution.
- 4)  $t_0 \neq 0, y_0 = 0$ The solution is

$$y(t) = 0$$

Therefore, there is only one solution.

5)  $0 \neq t_0 \neq y_0 \neq 0$ 

$$y(t) = \frac{t}{1 - \frac{y_0 - t_0}{t_0 y_0} t}, \quad t \neq \frac{t_0 y_0}{y_0 - t_0}$$

Therefore, there is only one solution.

In conclusion, the IVP  $t^2y' = y^2 \wedge y(t_0) = y_0$  has

- 1) no solution when  $t_0 = 0$ ,  $y_0 \neq 0$ ;
- 2) infinitely many (maximal) solutions when  $t_0 = y_0 = 0$ ;
- 3) exactly one (maximal) solution otherwise.

Moreover, the maximal solutions are

$$y(t) = 0, t \in \mathbb{R};$$

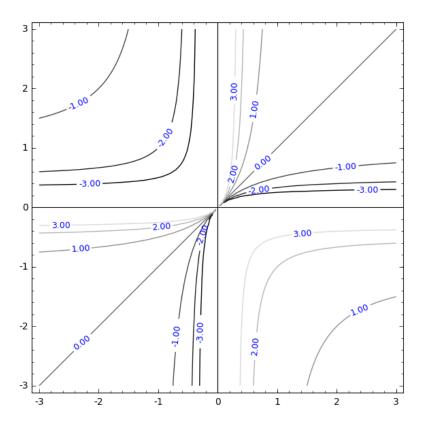
$$y(t) = t, t \in \mathbb{R};$$

$$y_C^-(t) = \frac{t}{1 - Ct}, t \in (-\infty, 1/C);$$

$$y_C^+(t) = \frac{t}{1 - Ct}, t \in (1/C, +\infty).$$

The 3rd and 4th type of solutions exist for any real number  $C \neq 0$ .

A better picture can be obtained by solving y = t/(1 - Ct) for C, which gives C = (y - t)/(ty) and shows that F(t, y) = (y - t)/(ty) provides a first integral for the given ODE.



From the contour plot of F you can see that all non-constant solutions that are defined at t=0 share the same tangent at (0,0). This also follows from  $\frac{\mathrm{d}}{\mathrm{d}t}\frac{t}{1-Ct}=\frac{1}{(1-Ct)^2}$ . Solutions  $y_C^+(t)$  with C>0 fill the 4th quadrant, solutions  $y_C^-(t)$  with C>0 fill the region above y=t in the 1st and 3rd quadrant, etc. All these properties can also be derived with some effort from the formulas.

Remark: With the Existence and Uniqueness Theorems now at hand, we can easily get a complete qualitive picture. Rewriting  $t^2y' = y^2$  as  $y^2 dt - t^2 dy = 0$ , we see that the origin  $(t_0, y_0) = (0, 0)$  is the only singular point, and hence that through any other point there passes precisely one integral curve (solution curve). For points  $(0, y_0)$  with  $y_0 \neq 0$  this is the curve t = 0, which cannot be seen from  $t^2y' = y^2$ , because it can be parametrized only as t(y).

**13** a)

$$e^{-y} \, \mathrm{d}y = e^t \, \mathrm{d}t$$

Integrating both sides of the equation, we get

$$\int_{y(0)}^{y} e^{-r} dr = \int_{0}^{t} e^{s} ds$$
$$-e^{-y} + e^{-y(0)} = e^{t} - 1$$

Finally, we obtain

$$y(t) = -\ln(e^{-y(0)} + 1 - e^t), \quad t < \ln(1 - e^{-y(0)}).$$

Remark: When determining the solution, one can also use indefinite integration  $\int e^{-y} dy = e^t dt + C$  and determine C in terms of y(0). This applies to the subsequent exercises as well.

b) Rewrite the ODE in the form of y' = a(t)y + b(t):

$$y' = (t+1)y + t$$

According to the particular solution formula,

$$y_p(t) = e^{\frac{t^2}{2} + t} \int_0^t s \, e^{-(\frac{s^2}{2} + s)} \, \mathrm{d}s$$

$$= e^{\frac{t^2}{2} + t} \left( \int_0^t (s+1) e^{-(\frac{s^2}{2} + s)} \, \mathrm{d}s - \int_0^t e^{-(\frac{s^2}{2} + s)} \, \mathrm{d}s \right)$$

$$= -e^{\frac{t^2}{2} + t} \left( e^{-(\frac{t^2}{2} + t)} - 1 \right) - e^{\frac{1}{2}} \int_0^t e^{-(\frac{s^2}{2} + s + \frac{1}{2})} \, \mathrm{d}s$$

$$= e^{\frac{t^2}{2} + t} - 1 - e^{\frac{1}{2}} \int_0^t e^{-(\frac{s+1}{\sqrt{2}})^2} \, \mathrm{d}s,$$

and the "homogeneous solution" is

$$y_h(t) = y(0) e^{\frac{t^2}{2} + t}$$

Since  $y_p(0) = 0$ , the general solution in terms of y(0) is

$$y(t) = y(0)e^{\frac{t^2}{2}+t} - 1 - e^{\frac{1}{2}} \int_0^t e^{-\left(\frac{s+1}{\sqrt{2}}\right)^2} ds$$
.

Remark: It is not necessary to rewrite the integrand occurring in  $y_p(t)$  in the particular form shown above, but at least this shows the relation with the incomplete Gauss integral (or the so-called error function). The simple answer is  $y(t) = y_p(t) + y_h(t)$ ,  $t \in \mathbb{R}$ , with  $y_p$ ,  $y_h$  as above.

c) According to the particular solution formula,

$$y_p(t) = e^{\sin(t)} \int_0^t 4\cos(s)e^{-\sin(s)} ds$$
 (1)

$$= -4e^{\sin(t)}(e^{-\sin(t)} - 1) \tag{2}$$

$$=4e^{\sin(t)}-4, (3)$$

and the "homogeneous solution" is

$$y_h(t) = y(0)e^{\sin(t)}.$$

The general solution is then

$$y(t) = (y(0) + 4)e^{\sin(t)} - 4.$$

The general form  $y(t) = Ce^{\sin t} - 4$ ,  $C \in \mathbb{R}$ , also follows from the observation that  $y(t) \equiv -4$  is a particular solution.

d) There is the constant solution y = 0, and for  $y \neq 0$  we can separate:

$$\frac{dy}{y^n} = t^m \, \mathrm{d}t \, .$$

Integrating both sides, we get

$$\int_{y(0)}^{y} \frac{1}{r^n} dr = \int_{0}^{t} s^m ds$$
$$-\frac{1}{(n-1)y^{n-1}} + \frac{1}{(n-1)y(0)^{n-1}} = \frac{t^{m+1}}{m+1}, \quad (n \neq 1, \quad m \neq -1).$$

Then, we obtain the general solution

$$y(t) = \left[ (n-1) \left( \frac{1}{(n-1)y(0)^{n-1}} - \frac{t^{m+1}}{m+1} \right) \right]^{-\frac{1}{n-1}} \quad (n \neq 1, \quad m \neq -1).$$

Next, we deal with the special cases:

i) 
$$n=1, \quad m=-1$$
 
$$\frac{\mathrm{d}y}{y} = \frac{\mathrm{d}t}{t}$$
 
$$\ln|y| = \ln|t| + C$$

Finally, we obtain, with a different parameter  $C' \in \mathbb{R}$ ,

$$y(t) = C't, \quad t \in (-\infty, 0) \text{ or } t \in (0, +\infty).$$

y(0) is not defined in this case.

ii) 
$$n = 1, m \neq -1$$

$$\frac{\mathrm{d}y}{y} = t^m dt$$

Integrating both sides, we get

$$\int_{y(0)}^{y} \frac{1}{r} dr = \int_{0}^{t} s^{m} ds,$$
$$\ln|y| - \ln|y(0)| = \frac{t^{m+1}}{m+1}.$$

Finally, noting that y(t) and y(0) must have the same sign, we obtain

$$y(t) = y(0)e^{\frac{t^{m+1}}{m+1}}, \quad t \in \mathbb{R}.$$

.

iii) 
$$n \neq 1$$
,  $m = -1$ 

$$\frac{\mathrm{d}y}{y^n} = \frac{\mathrm{d}t}{t}$$

Integrate both sides, we get

$$-\frac{1}{(n-1)y^{n-1}} = \ln|t| + C$$

Finally, we obtain

$$y(t) = (-(n-1)(\ln|t| + C))^{-\frac{1}{n-1}}, \quad t < -e^{-C} \text{ or } t > e^{-C}.$$

y(0) is not defined in this case.

### **14** a) dy/dt = -4ty

This is a homogeneous linear ODE, so we get

$$y(t) = Ce^{-2t^2}$$

Plugging into the IVP y(0) = 1, we can obtain the solution as

$$y(t) = e^{-2t^2}, \quad t \in \mathbb{R}.$$

### b) $dy/dt = ty^3$

This is a separable ODE, so we can write

$$\frac{dy}{y^3} = tdt$$

$$\int_{1}^{y} \frac{1}{r^{3}} dr = \int_{0}^{t} s ds$$

The solution is

$$y(t) = (1 - t^2)^{-\frac{1}{2}}, -1 < t < 1.$$

c) (1+t)dy/dt = 4yRewrite the ODE as

$$y' = \frac{4}{t+1}y.$$

We use the "homogeneous solution formula" to get

$$y(t) = Ce^{4\ln|t+1|} = C(t+1)^4.$$

Plugging into the IVP y(0) = 1, we obtain the solution as

$$y(t) = (t+1)^4, \quad t \in \mathbb{R}.$$

15 With the Hint, we want to prove that the mirror image of a solution curve w.r.t. its inflection point represents a solution as well and use the uniqueness of solutions of associated IVP's.

The function of the mirror image is

$$g(t) = \frac{a}{b} - \frac{a}{de^{-a(2t_h - t)} + b}$$

where  $t_h = (\ln d - \ln b)/a$ .

First, we prove that g(t) is a solution to the ODE  $y' = ay - by^2$ .

$$g'(t) = -\frac{a^2 d e^{a(2t_h - t)}}{(d e^{a(2t_h - t)} + b)^2}$$

and

$$\begin{split} ag(t) - bg^2(t) &= \frac{a^2}{b} - \frac{a^2}{de^{-a(2t_h - t)} + b} - b(\frac{a^2}{b^2} - \frac{2a^2}{b(de^{-a(2t_h - t)} + b)} + \frac{a^2}{(de^{-a(2t_h - t)} + b)^2}) \\ &= \frac{-a^2de^{-a(2t_h - t)} - a^2b + 2a^2b - a^2b}{(de^{-a(2t_h - t)} + b)^2} \\ &= -\frac{a^2de^{-a(2t_h - t)}}{(de^{-a(2t_h - t)} + b)^2} \end{split}$$

Thus,  $g'(t) = ag(t) - bg^2(t)$ , which means g(t) is also a solution to the ODE  $y' = ay - by^2$ . Then, we will use the uniqueness of the solution of th IVP  $y' = ay - by^2 \wedge y(t_h) = a/2b$ . Since the original solution curve has the inflection point  $(t_h, a/2b)$ , it shares the same IVP with the mirror image g(t). The logistic equation has a unique solution for any given IVP, so y(t) = g(t).

Remark: The computation can be simplified a little by using the observation that y(t) solves  $y' = ay - by^2$  iff  $t \mapsto y(t - t_0)$ ,  $t_0 \in \mathbb{R}$ , does.

16 a) It should be noted that the analysis in the lecture used the notation  $y' = ay - by^2 - h$ , where a, b, h > 0. However, the parabola  $f(y) = y' = ay^2 + by + c$ , a > 0, is a vertically flipped version of that considered in the lecture. This discrepancy will lead to different behaviors of the solution curves.

The discriminant is  $\Delta = b^2 - 4ac$ . For  $\Delta \geq 0$ , there are the steady-state solutions

$$y_1 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

$$y_2 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

where  $0 < y_1 \le y_2$ .

i)  $c < b^2/4a$ 

If the initial condition  $y(t_0)$  satisfies  $y_1 < y(t_0) < y_2$ , then y(t) decreases and  $\lim_{t\to\infty} y(t) = y_1$ .

If  $y(t_0) > y_2$ , then y(t) increases to  $\infty$ . If  $y(t_0) < y_1$ , then y(t) increases and  $\lim_{t\to\infty} y(t) = y_1$ .

- ii)  $c = b^2/4a$ If  $y(t_0) > -b/2a$ , then y(t) increases to  $\infty$ . If  $y(t_0) < -b/2a$ , then y(t) increases and  $\lim_{t\to\infty} y(t) = y_1$ .
- iii)  $c > b^2/4a$  Regardless of the initial condition, y(t) will increase to  $\infty$ .
- b) i)  $y' = y^2 y + 1$

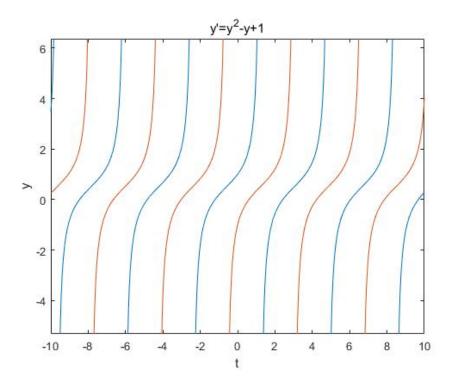


Figure 1:  $y' = y^2 - y + 1$ 

ii) 
$$y' = y^2 + 2y + 1$$

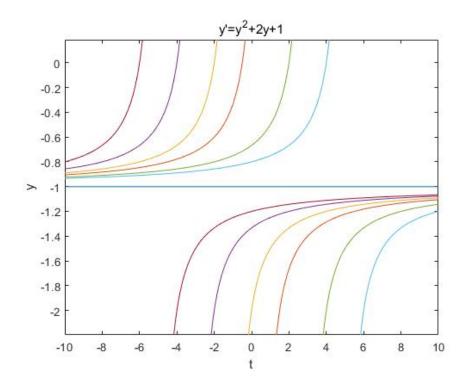


Figure 2:  $y' = y^2 + 2y + 1$ 

iii) 
$$y' = y^2 + y - 2$$

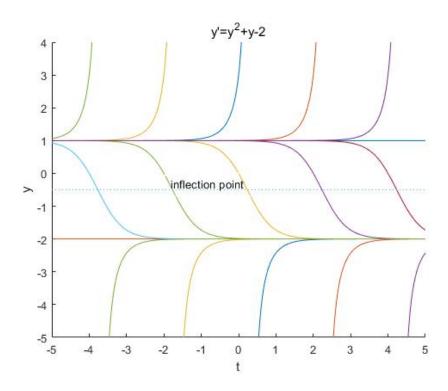


Figure 3:  $y' = y^2 + y - 2$ 

17 a) We can write

$$\frac{dz}{dt} = \beta y^{\beta - 1} \frac{dy}{dt}.$$

Then, we get

$$\frac{dy}{dt} = \frac{1}{\beta} y^{1-\beta} \frac{dz}{dt}.$$

Substituting the above expression into the ODE, we get

$$\frac{1}{\beta}y^{1-\beta}\frac{dz}{dt} = a(t)y - b(t)y^n,$$

$$z' = \beta a(t)y^{\beta} - \beta b(t)y^{n+\beta-1},$$

$$z' = \beta a(t)z - \beta b(t)y^{n+\beta-1}.$$

Then, setting  $\beta = 1 - n$ , we can obtain the 1st-order linear ODE

$$z' = \beta a(t)z - \beta b(t)$$

for  $z(t) = y(t)^{1-n}$ . Depending on n, the 1-1 correspondence between solutions of both ODEs may only hold for a smaller domain, e.g., for general n > 1 we need to restrict to y > 0 (except for certain integers n).

b) Setting  $\beta = 1 - 3 = -2$ , we can rewrite the ODE as

$$z' = -8z + 2$$
.

The corresponding IVP is  $z(0) = y(0)^{-2} = 1$ . Then, we can get its solution as

$$z(t) = \frac{3}{4}e^{-8t} + \frac{1}{4}.$$

Since  $z = y^{\beta} = y^{-2}$ ,

$$y(t) = \pm z(t)^{-\frac{1}{2}} = \pm \left(\frac{3}{4}e^{-8t} + \frac{1}{4}\right)^{-\frac{1}{2}}$$

Because y(0) = 1, we eliminate the negative solution, leaving

$$y(t) = \left(\frac{3}{4}e^{-8t} + \frac{1}{4}\right)^{-\frac{1}{2}} = \frac{2}{\sqrt{1+3e^{-8t}}}, \quad t \in \mathbb{R}.$$

c) The steady-state solution is z(t) = 1/4, corresponding to  $y(t) = \pm 2$ . The general solution to the ODE in b) is  $y(t) \equiv 0$  and the non-constant solutions

$$y_1(t) = -\left[\left(y^{-2}(0) - \frac{1}{4}\right)e^{-8t} + \frac{1}{4}\right]^{-\frac{1}{2}},$$

and

$$y_2(t) = \left[ \left( y^{-2}(0) - \frac{1}{4} \right) e^{-8t} + \frac{1}{4} \right]^{-\frac{1}{2}}.$$

 $\lim_{t\to\infty} y_1(t) = -2$ , and  $\lim_{t\to\infty} y_1(t) = 2$ .

If the initial condition is  $y(0) = y_0 < 0$ , then the solution will be  $y_1(t)$ , so  $\lim_{t\to\infty} y(t) = -2$ ;

if the initial condition is  $y(0) = y_0 > 0$ , then the solution will be  $y_2(t)$ , so  $\lim_{t\to\infty} y(t) = 2$ .

This shows that both y = -2 and y = 2 are asymptotically stable.

The third steady state solution  $y(t) \equiv 0$  is unstable. This follows from the cases y(0) > 0 and y(0) < 0 covered above.

#### 18 a) We have

$$(y + y')' = y' + y'' = y' + y = y + y',$$
  
 $(y - y')' = y' - y'' = y' - y = -(y - y'),$ 

i.e., z = y + y' satisfies z' = z and w = y - y' satisfies w' = -w. From the theory of 1st-order linear ODE's it follows that  $z(x) = y(x) + y'(x) = c_1 e^x$ ,  $w(x) = y(x) - y'(x) = c_2 e^{-x}$  for some  $c_1, c_2 \in \mathbb{R}$ .  $\Longrightarrow y(x) = \frac{1}{2}(c_1 e^x + c_2 e^{-x}) = (c_1/2)e^x + (c_2/2)e^{-x}$ , which is of the required form.

b) From the lecture recall that F is continuous on  $\mathbb{R}$  and can be differentiated under the integral sign for x > 0. Thus for x > 0 we have

$$F'(x) = -\int_0^\infty \frac{t \sin(xt)}{t^2 + 1} dt = -\int_0^\infty \frac{t^2 \sin(xt)}{t(t^2 + 1)} dt = -\int_0^\infty \frac{(t^2 + 1 - 1)\sin(xt)}{t(t^2 + 1)} dt$$
$$= -\int_0^\infty \frac{\sin(xt)}{t} dt + \int_0^\infty \frac{\sin(xt)}{t(t^2 + 1)} dt.$$

The first integral is actually independent of x, since

$$\int_0^\infty \frac{\sin(xt)}{t} = \int_0^\infty \frac{\sin s}{(s/x)x} \, \mathrm{d}s = \int_0^\infty \frac{\sin s}{s} \, \mathrm{d}s, \qquad \text{(Subst. } s = xt, \, \mathrm{d}s = x \, \mathrm{d}t)$$

and has the value  $\pi/2$ , as we know from the Calculus III fnal exam.

c) Differentiating the expression in b) again under the integral sign, we obtain

$$F''(x) = \int_0^\infty \frac{\mathrm{d}}{\mathrm{d}x} \frac{\sin(xt)}{t(t^2+1)} \, \mathrm{d}t = \int_0^\infty \frac{t \cos(xt)}{t(t^2+1)} \, \mathrm{d}t = \int_0^\infty \frac{\cos(xt)}{t^2+1} \, \mathrm{d}t = F(x).$$

This is justified, since

$$\left| \frac{\mathrm{d}}{\mathrm{d}x} \frac{\sin(xt)}{t(t^2 + 1)} \right| = \frac{|\cos(xt)|}{t^2 + 1} \le \frac{1}{t^2 + 1} = \Phi(t),$$

which is independent of x and integrable over  $(0, \infty)$ .

d) According to a) and c) we have

$$F(x) = c_1 e^x + c_2 e^{-x},$$
  
 $F'(x) = c_1 e^x - c_2 e^{-x}$ 

for some  $c_1, c_2 \in \mathbb{R}$  and x > 0. Since F is continuous in 0, the first identity holds also for x = 0 and gives  $c_1 + c_2 = F(0) = \int_0^\infty \frac{\mathrm{d}t}{t^2 + 1} = \pi/2$ .

Since

$$\left| \frac{\sin(xt)}{t(t^2+1)} \right| \le \frac{1}{t(t^2+1)} = \Phi(t),$$

which is independent of x and integrable over  $(0, \infty)$ , we get

$$F'(0+) = -\frac{\pi}{2} + \int_0^\infty \lim_{x \downarrow 0} \frac{\sin(xt)}{t(t^2+1)} dt = -\frac{\pi}{2} + \int_0^\infty 0 dt = -\frac{\pi}{2}$$

On the other hand,  $F'(0+) = \lim_{x\downarrow 0} (c_1 e^x - c_2 e^{-x}) = c_1 - c_2$ , so that  $c_1 - c_2 = -\pi/2$ . It follows that  $c_1 = 0$ ,  $c_2 = \pi/2$ . Hence  $F(x) = (\pi/2)e^{-x}$  for  $x \ge 0$  and

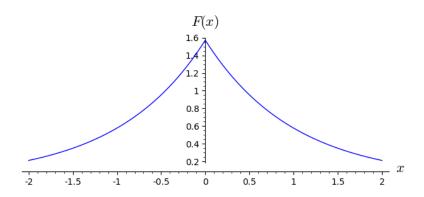
$$\int_0^\infty \frac{\cos t}{t^2 + 1} \, \mathrm{d}t = F(1) = \frac{\pi}{2e}.$$

Remarks: This exercise is based on a video from the Youtube channel "Flammable Maths", who's author Jens Fehlau has shot several nice videos with quite nontrivial evaluations of interesting integrals.

Since F is even, we have  $F(x) = (\pi/2)e^{-|x|}$  for  $x \in \mathbb{R}$ . At x = 0 the function F is not differentiable, although the right-hand side of the integral representation

$$F'(x) = -\int_0^\infty \frac{t\sin(xt)}{t^2 + 1} dt, \quad \text{valid for } x \neq 0,$$

evaluates to zero at x = 0.



Numerically,  $\pi/(2e) \approx 0.5778636748954609$ . This differs only slightly from the Euler-Mascheroni constant  $\gamma = \lim_{n \to \infty} (1 + 1/2 + 1/3 + \dots + 1/n - \ln(n)) \approx 0.5772156649015329$ , so that perhaps someone who computes the integral  $\int_0^\infty \frac{\cos t}{t^2 + 1} \, dt$  numerically but doesn't know about the exact evaluation is mislead to conjecture that it has the value  $\gamma$ .

19 First a remark on the cases  $L = \pm \infty$ . If  $(x_n)$  is unbounded then (and only then) for every  $R \in \mathbb{R}$  there exist infinitely many indexes n such that  $x_n > R$ , and hence it is natural to call  $+\infty$  an accumulation point of  $(x_n)$  and set  $L = +\infty$  in this case. On the other hand, if  $(x_n)$  diverges to  $-\infty$  then (and only then) for every  $R \in \mathbb{R}$  there exist only finitely many indexes n such that  $x_n > R$ , but of course infinitely many indexes n such that  $x_n < R$ , and hence it is natural to call  $-\infty$  an accumulation point of  $(x_n)$  and set  $L = -\infty$  in this case, since there is no other accumulation point. The case  $L = -\infty$  doesn't occur for nonnegative sequences like  $x_n = \sqrt[n]{|a_n|}$ .

a) Suppose the power series converges for some  $z_1 \neq a$  and set  $r = |z_1 - a|$ , which is then > 0. Since  $\sum a_n(z_1 - a)^n$  converges, there exists a constant M > 1 such that  $|a_n(z_1 - a)^n| = |a_n| r^n \leq M$  for all n. Hence

$$\sqrt[n]{|a_n|} \le \frac{\sqrt[n]{M}}{r} \le \frac{M}{r}$$
 for all  $n$ ,

contradicting the unboundedness of  $\sqrt[n]{|a_n|}$ .

b) Assume  $\lim_{n\to\infty} \sqrt[n]{|a_n|} = 0$ . Then for every  $\epsilon > 0$  there exists  $N \in \mathbb{N}$  such that  $|a_n| < \epsilon^n$  for n > N. Now let  $z \in \mathbb{C} \setminus \{a\}$  be arbitary and r = |z - a|, i.e.,  $|a_n(z - a)^n| = |a_n| r^n$ . Setting  $\epsilon = 1/(2r)$  and denoting by N the corresponding response, we get

$$|a_n| r^n \le \left(\frac{1}{2r}\right)^n r^n = \frac{1}{2^n} \quad \text{for } n > N.$$

Since  $\sum 2^{-n}$  converges, the series  $\sum a_n(z-a)^n$  converges absolutely by the comparison test. In particular  $\sum a_n(z-a)^n$  converges for all  $z \in \mathbb{C}$  (including z=a, of course).

c) Suppose first that  $z \neq a$  satisfies r = |z - a| < 1/L. Then L < 1/r, and hence there exist  $\theta \in (0,1)$  and  $N \in \mathbb{N}$  such that  $\sqrt[n]{|a_n|} \leq \theta/r$  for all n > N. (The number  $\theta$  need only satisfy  $L < \theta/r < 1/r$ , i.e.,  $\theta \in (rL,1)$ . Then there can be only finitely many n such that  $\sqrt[n]{|a_n|} > \theta/r$ .) From this we obtain  $|a_n| r^n \leq \theta^n$  for n > N and can use the comparison test with the convergent series  $\sum \theta^n$  to conclude that  $\sum_{n=0}^{\infty} a_n (z-a)^n$  converges.

Next suppose r = |z - a| > 1/L. Then 1/r < L, and hence  $\sqrt[n]{|a_n|} > 1/r$  for infinitely many n. Thus  $|a_n| r^n > 1$  for infinitely many n, implying the divergence of  $\sum_{n=0}^{\infty} a_n (z - a)^n$ . (Since convergence requires  $|a_n| r^n \to 0$ .)