# 嵌入式系统设计方法—— Lab5

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# 编译安装 busybox

• busybox 版本: 1.22.0

### 遇到问题及解决方案

#### RLIMIT\_FSIZE undeclared

#### 如下图所示:

#### 解决方案

就是在 libbb.h 加一句

#include "sys/resource.h"

2.

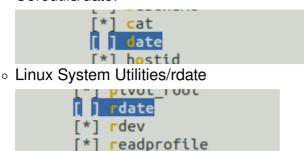
#### 解决方案

3. rdate

```
/usr/bin/ld: debianutils/lib.a(mktemp.o): in function `mktemp_main':
mktemp.c:(.text.mktemp_main+0xa6): 警告: the use of `mktemp' is dangerous, better use `mkstemp' or `mkdtemp'
/usr/bin/ld: util-linux/lib.a(rdate.o): in function `rdate_main':
rdate.c:(.text.rdate_main+0x117): undefined reference to `stime'
/usr/bin/ld: coreutils/lib.a(date.o): in function `date_main':
date.c:(.text.date_main+0x27e): undefined reference to `stime'
collect2: error: ld returned 1 exit status
make: *** [Makefile:716: busybox_unstripped] 错误 1
```

解决方案: 干脆不要勾选:

Coreutils/date:



#### 至此 busybox 编译安装完成

```
./_install/usr/sbin/svlogd -> ../../bin/busybox
./_install/usr/sbin/telnetd -> ../../bin/busybox
./_install/usr/sbin/tftpd -> ../../bin/busybox
./_install/usr/sbin/ubiattach -> ../../bin/busybox
./_install/usr/sbin/ubidetach -> ../../bin/busybox
./_install/usr/sbin/ubimkvol -> ../../bin/busybox
./_install/usr/sbin/ubirmvol -> ../../bin/busybox
./_install/usr/sbin/ubirsvol -> ../../bin/busybox
./_install/usr/sbin/ubirsvol -> ../../bin/busybox
./_install/usr/sbin/ubirsvol -> ../../bin/busybox
./_install/usr/sbin/ubiupdatevol -> ../../bin/busybox
./_install/usr/sbin/udhcpd -> ../../bin/busybox
./_install/usr/sbin/udhcpd -> ../../bin/busybox
./_install/usr/sbin/udhcpd -> ../../bin/busybox
./_install/usr/sbin/udhcpd -> ../../bin/busybox
```

# 构建根文件系统

1. 创建所需目录:

mkdir dev etc home lib mnt proc root sys tmp var -p

2. 在创建的根文件系统的 etc目录下创建inittab文件:

touch etc/inittab
vim etc/inittab

写入

```
#this is run first except when booting in single-user mode.
::sysinit:/etc/init.d/rcS
# /bin/sh invocations on selected ttys
::respawn:-/bin/sh
# Start an "askfirst" shell on the console (whatever that may be)
::askfirst:-/bin/sh
# Stuff to do when restarting the init process
::restart:/sbin/init
# Stuff to do before rebooting
::ctrlaltdel:/sbin/reboot
::shutdown:/sbin/swapoff -a
```

#### 3. 构建 init.d 及其内容

mkdir etc/init.d/ -p touch etc/init.d/rcS vim etc/init.d/rcS

#### 写入:

#### #!/bin/sh

#This is the first script called by init process /bin/mount -a echo /sbin/mdev>/proc/sys/kernel/hotplug mdev -s

#### 4. 构建 fstab 及其内容

touch etc/fstab

Louc	II ELC/ISLAD
vim	etc/fstab

#device	mount-point	type	options	dump	fsck order
proc	/proc	proc	defaults	0	0
tmpfs	/tmp	tmpfs	defaults	0	0
sysfs	/sys	sysfs	defaults	0	0
tmpfs	/dev	tmpfs	defaults	0	0

#### 5. 创建 profile 文件

touch etc/profile vim etc/profile

```
#!/bin/sh
export HOSTNAME=pb18111697
export USER=root
export HOME=root
export PS1="[$USER@$HOSTNAME \W]\# "
#export PS1="[\[\033[01;32m\]$USER@\[\033[00m\]\[\033[01;34m\]$HOSTNAME\[\033[00m\]\'PATH=/bin:/sbin:/usr/bin:/usr/sbin
LD_LIBRARY_PATH=/lib:/usr/lib:$LD_LIBRARY_PATH
export PATH LD_LIBRARY_PATH
```

#### 6. 添加动态库支持

#### 查找位置:

```
armlinuxgccpath=$(which arm-none-linux-gnueabi-gcc)
armlinuxgccpath=${armlinuxgccpath%/*}/..
cp $armlinuxgccpath/arm-none-linux-gnueabi/libc/lib lib -ra
```

```
embed/lab5/rootfs$ armlinuxgccpath=$(which arm-none-linux-gnueabi-gcc)
(torch1.4) rabbit@rabbit:~/embed/lab5/rootfs$ armlinuxgccpath=${armlinuxgccpath%/*}/.
(torch1.4) rabbit@rabbit:~/embed/lab5/rootfs$ cp $armlinuxgccpath/arm-none-linux-gnueabi/libc/lib lib -ra
(torch1.4) rabbit@rabbit:~/embed/lab5/rootfs$ ls
(torch1.4) rabbit@rabbit:~/embed/lab5/rootfs$ cd lib/
(torch1.4) rabbit@rabbit:~/embed/lab5/rootfs/lib$ ls
                            libgcc_s.so.1
                                                      libnss_nisplus-2.8.so
libanl-2.8.so
libanl.so.1
                                                      libpcprofile.so
libBrokenLocale-2.8.so libnsl-2.8.so libBrokenLocale.so.1 libnsl.so.1
                                                      libpthread-2.8.so
                                                      libpthread.so.0
                            libnss_compat-2.8.so libresolv-2.8.so libnss_compat.so.2 libresolv.so.2
                           libnss_dns-2.8.so
                                                      libSegFault.so
                                                      libthread_db-1.0.so
                            libnss_hesiod.so.2 libthread_db.so.1 libutil-2.8.so
libdl-2.8.so
libdl.so.2
```

# 创建镜像 image 文件

使用飞凌官方提供的 mkyaffs2image-nand2g 来生成. 见如下命令:

```
mkyaffs2image-nand2g rootfs rootfs.yaffs2
```

其中 rootfs 是刚才所生成的根文件系统的路径, rootfs.yaffs2 是生成的文件名.

### 烧写

烧写过程和第一次实验无异.

- 1. 开启 sd 卡启动模式
- 2. 烧写
- 3. 开启 nand 启动模式
- 4. 打开设备

# 启动系统并测试

### 遇到问题及解决方案

遇到了一个问题: modprobe 的地方有点问题,如下:

```
request_module: runaway loop modprobe binfmt-464c request_module: runaway loop modprobe binfmt-464c
```

我尝试取消勾选 modprobe. 但毫无效果.

查阅了参考资料,在 busybox 中配置交叉编译的 prefix 后才成功.

```
(arm-linux-) Cross Compiler prefix
```

### 测试

成功启动后.

- 1. 首先可以看到主机名是我设置了的 pb18111697
- 2. 然后执行我提前放入的 HelloWorld, 结果如期.

```
fixmap : 0xfff00000 - 0xfffe0000
                                          896 kB)
           : 0xff600000 - 0xffe00000
                                            8 MB)
   vmalloc : 0xd0800000 - 0xf4000000
                                        ( 568 MB)
   lowmem : 0xc0000000 - 0xd0000000
                                        ( 256 MB)
    pkmap : 0xbfe00000 - 0xc0000000
                                          2 MB)
   modules : 0xbf000000 - 0xbfe00000
                                          14 MB)
     .init : 0xc0008000 - 0xc0036000
                                       ( 184 kB)
      .text : 0xc0036000 - 0xc07d4434
                                       (7802 kB)
     .data : 0xc07d6000 - 0xc082eaf0
                                        ( 355 kB)
      .bss : 0xc082eb14 - 0xc08b1124
                                        ( 522 kB)
SCSI subsystem initialized
-----[ cut here ]----
WARNING: at drivers/gpio/gpiolib.c:101 gpio_ensure_requested+0x58/0x124()
---[ end trace da227214a82491b7 ]---
type=2000 audit(0.190:1): initialized
Hello, world
Creating 4 MTD partitions on "NAND 2GiB 1.8V 8-bit":
```

```
0x0000000000000-0x000000200000 : "Bootloader'
0x000000500000-0x000001e00000 : "Kernel"
0x000001e00000-0x00000e600000 : "File System"
0x00000e600000-0x000040000000 : "User"
mcp2515 spi1.0: MCP251x didn't enter in conf mode after reset
mcp2515 spi1.0: probe failed
dm9000 dm9000.0: read wrong id 0x01010101
s3c g2d probe called
s3c_g2d_probe Success
Registering the dns_resolver key type
can't run '/etc/init.d/rcS': Permission denied
Please press Enter to activate this console.
[root@pb18111697 ]# ls
HelloWorld etc
                        linuxrc
                                    ргос
                                                sys
                                                            var
bin
            home
                        lost+found
                                    root
                                                 tmp
dev
            lib
                        mnt
                                    sbin
                                                 usr
[root@pb18111697 ]# ./HelloWorld
Hello, World!
[root@pb18111697 ]#
```

# 实验总结

本次实验让我学会了如何构建,生成,并烧写一个根文件系统,收获颇丰.