Learn-In-Depth

Be Professional in Embedded System

Assignment-3

Lesson-3

Name : Ayat Mohamed

LAB_1:

- GDB
  - first ,we will run a versatilepb board, and then use -s -S for debug the board

```
Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_diploma/C_programming/Unit_3/Lesson_3/lab1 (master)
$ qemu-system-arm -M versatilepb -m 128 -nographic -kernel learn_in_depth.elf
Learn_in_depth : Ayat mohamed

Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_diploma/C_programming/Unit_3/Lesson_3/lab1 (master)
$ qemu-system-arm -M versatilepb -m 128 -nographic -s -S -kernel learn_in_depth.elf
```

  - then open an another terminal to run the gdb server
  - use file·elf no file·bin ,because the file·elf contains the debug info·

```
MINGW64:/e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_diploma/C_programming/Unit_3/Lesson_3/lab1

Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_diploma/C_programming/Unit_3/Lesson_3/lab1 (master)
$ arm-none-eabi-gdb.exe learn_in_depth.elf
GNU gdb (GNU Tools for Arm Embedded Processors 7-2017-q4-major) 8.0.50.20171128-git
Copyright (C) 2017 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law.  Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-w64-mingw32 --target=arm-none-eabi".
Type "show configuration" for configuration details.
For bug reporting instructions, please see:
<http://www.gnu.org/software/gdb/bugs/>.
Find the GDB manual and other documentation resources online at:
<http://www.gnu.org/software/gdb/documentation/>.
For help, type "help".
Type "apropos word" to search for commands related to "word"...
Reading symbols from learn_in_depth.elf...done.
(gdb)
```

-to connect to gdb server we should have the IP address and port #

-in this case the server will be our localhost and port # is 1234

```
(gdb) target remot localhost:1234
Remote debugging using localhost:1234
reset () at startup.s:3
3           ldr sp,=stack_top
(gdb)
```

-to display the current pc

-this command displays no of instructions and the location of current pc ,it located at rest symbol·

```
(gdb) display/3i $pc
1: x/3i $pc
=> 0x10000 <reset>:     ldr     sp, [pc, #4]    ; 0x1000c <stop+4>
   0x10004 <reset+4>:   bl      0x10010 <main>
   0x10008 <stop>:      b       0x10008 <stop>
(gdb)
```

-to but a break point at main

```
(gdb) b main
Breakpoint 1 at 0x10018: file App.c, line 7.
(gdb)
```

-if we want to add a break point at a certain address

-this address is related with context switch before main

```
(gdb) b *0x10010
Breakpoint 2 at 0x10010: file App.c, line 6.
(gdb)
```

```
(gdb) si
reset () at startup.s:4
4           bl main
1: x/3i $pc
=> 0x10004 <reset+4>:   bl      0x10010 <main>
   0x10008 <stop>:      b       0x10008 <stop>
   0x1000c <stop+4>:    andeq   r1, r1, r8, asr #2
(gdb)
```

```
(gdb) print str_buffer[0]
$1 = 76 'L'
(gdb)
```

-if you want to watch the variable ,use watch "var_name"

```
(gdb) watch str_buffer
Hardware watchpoint 3: str_buffer
(gdb)
```

-if we want to know our location ,use "where"

```
(gdb) where
#0  reset () at startup.s:4
(gdb)
```

```
(gdb) info breakpoints
Num     Type           Disp Enb Address    What
1       breakpoint     keep y   0x00010018 in main at App.c:7
2       breakpoint     keep y   0x00010010 in main at App.c:6
3       hw watchpoint  keep y              str_buffer
(gdb)
```

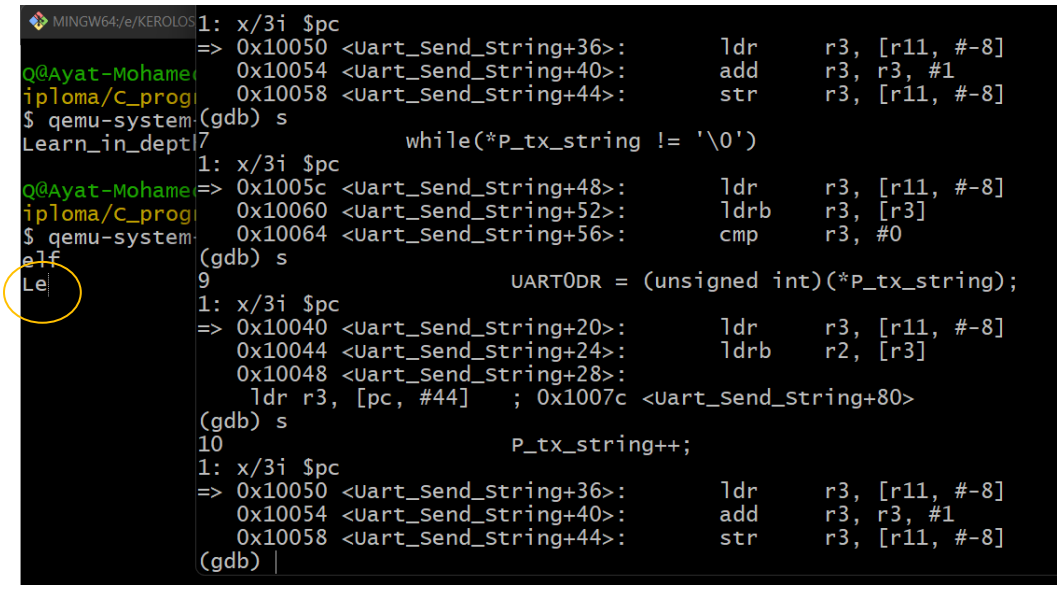
-if you want to delete a specific breakpoint, use "delete bp_name".

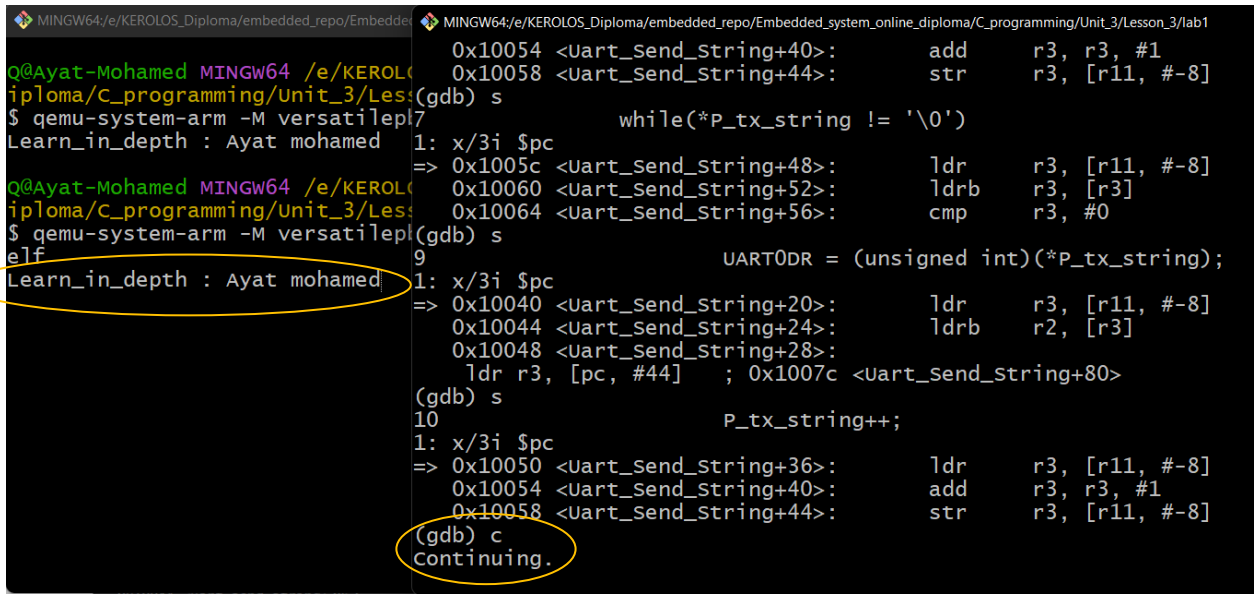
```
(gdb) b main
Note: breakpoint 1 also set at pc 0x10018.
```

-if we want to continue to our break point use

“c”->continue

-and we use “s” to step until UART.c finish ,after this we will find the string is transmitted and printed in terminal





- *MakeFile*

```
#@copyright : Ayat
CC=arm-none-eabi-
CFLAGS=-mcpu=arm926ej-s -g
INCS=-I .
LIBS=
SRC=$(wildcard *.c)
OBJ=$(SRC:.c=.o)
AS=$(wildcard *.s)
AsOBJ=$(AS:.s=.o)
Project_name=learn_in_depth

All: $(Project_name).bin
    @echo "****DONE****"
$(AsOBJ): $(AS)
    $(CC)as.exe $(CFLAGS) $< -o $@

%.o: %.c
    $(CC)gcc.exe -c $(CFLAGS) $(INCS) $< -o $@

$(Project_name).elf: $(OBJ) $(AsOBJ)
    $(CC)ld.exe -T linker_script.ld $(LIBS) $(OBJ) $(AsOBJ) -o $@

$(Project_name).bin: $(Project_name).elf
    $(CC)objcopy.exe -O binary $< $@

clean_all:
    rm *.o *.bin *.elf

clean:
    rm *.bin *.elf

```

```
Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_d
iploma/C_programming/Unit_3/Lesson_3/lab1 (master)
$ make clean_all
rm *.o *.bin *.elf

Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_d
iploma/C_programming/Unit_3/Lesson_3/lab1 (master)
$ make
arm-none-eabi-gcc.exe -c -mcpu=arm926ej-s -g -I . App.c -o App.o
arm-none-eabi-gcc.exe -c -mcpu=arm926ej-s -g -I . UART.c -o UART.o
arm-none-eabi-as.exe -mcpu=arm926ej-s -g startup.s -o startup.o
arm-none-eabi-ld.exe -T linker_script.ld  App.o UART.o startup.o -o learn_in_dep
th.elf
arm-none-eabi-objcopy.exe -O binary learn_in_depth.elf learn_in_depth.bin
****DONE****
```

LAB_2 :part(1)with startup.s

-Board name : STM32f103c8t6(Cortex-M3)

- the entry point to this board is 0x08000000

-this address contains the SP value if address that points to stack in (SRAM)

-in the begin we should define all vector Handlers in vector table in section called ".vector"

-in the first we will defined first word as a value of SP is 0x20001000 within the range of SRAM.

-According to the specs , the vector table must start after SP, by defining vector handlers after SP word.

-Startup.s

```
/*
startup_cortexM3.s
Author : Ayat Mohamed
*/
.section .vectors          /* vectors sections */
.word 0X20001000           /* 7ot el 32 bit bel rakam dah el howa -> sp */
.word _reset               /* ba3d el 0X20001000 b 4 byte hy3mel jump 3ala el reset section
                              w el word hyt7at feha el symbol dah (_reset)*/
.word _vector_handler      /* NMI*/
.word _vector_handler      /* fault handler*/
.word _vector_handler      /* usage fault*/
.word _vector_handler      /* reserved */
.word _vector_handler      /* reserved */
.word _vector_handler      /* reserved */
.word _vector_handler      /* reserved */
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler
.word _vector_handler

.section .text
_reset:
    bl main
    b .                 //34an yfdal fel main()

.thumb_func
_vector_handler:
    b _reset
```

-linker_script.ld

-According to specs the FLASH memory start with 0x08000000 and the SRAM ox02000000.

```
/* Author : Ayat mohamed
   Linker_script : cortex_M3
 */

MEMORY
{
   FLASH(RX) : ORIGIN = 0x08000000 , LENGTH = 128K
   SRAM(RWX) : ORIGIN = 0x20000000 , LENGTH = 20K
}

SECTIONS
{
   .text :
   {
      *(.vectors*)
      *(.text*)
      *(.rodata)
      _E_text = .;
   }>FLASH
   .data :
   {

      *(.data)

   }>FLASH
   .bss :
   {
      *(.bss)
   }>SRAM
}
```

LAB_2:part(2)with startup.c

-As we said before, when the entry point is the address of SP, we can write the startup.c

- Define Interrupt vectors Section 2

-Copy Data from ROM to RAM

-Initialize Data Area and Initialize Stack

-Create a reset section and Call main( )

-Startup.c

```c
/*
    Author : Ayat Mohamed
    object : startup.c
*/

#include <stdint.h>
void Reset_Handler();
extern int main(void);
extern uint32_t _stack_top;
void Default_Handler()
{
    Reset_Handler();
}

void NMI_Handler() __attribute__((weak,alias("Default_Handler")));;
void H_Fault_Handler() __attribute__((weak,alias("Default_Handler")));;
void MM_Fault_Handler() __attribute__((weak,alias("Default_Handler")));;
void Bus_Fault() __attribute__((weak,alias("Default_Handler")));;
void Usage_Fault_Handler()__attribute__((weak,alias("Default_Handler")));;

uint32_t vectors[] __attribute__((section(".vectors")))={
    (uint32_t) &_stack_top,
    (uint32_t) &Reset_Handler,
    (uint32_t) &NMI_Handler,
    (uint32_t) &H_Fault_Handler,
    (uint32_t) &MM_Fault_Handler,
    (uint32_t) &Bus_Fault,
    (uint32_t) &Usage_Fault_Handler,
};

extern uint32_t _E_text;
extern uint32_t _S_DATA;
extern uint32_t _E_DATA;
extern uint32_t _S_bss;
extern uint32_t _E_bss;
```

```c
void Reset_Handler()
{
    // copy data section from flash to SRAM
    uint32_t DATA_Size = (unsigned char*)&_E_DATA - (unsigned char*)&_S_DATA ;
    unsigned char * P_src = (unsigned char *)&_E_text;
    unsigned char  * P_dst= (uint8_t*)&_S_DATA;
    for (int i = 0 ;  i < DATA_Size ; i ++)
    {
        *((unsigned char*)P_dst++) = *((unsigned char*)P_src++);
    }
    //init .bss section in SRAM = 0;
    uint32_t BSS_Size = (unsigned char*)&_E_bss - (unsigned char*)&_S_bss;
    unsigned char* bss_dst= (unsigned char*)&_S_bss;
    for (int i = 0 ;  i < BSS_Size ; i ++)
    {
        *((unsigned char*)bss_dst++) = (unsigned char)0x00;
    }
    //jump on main
    main();
}

```

-in linker we are defined some variables to make the memory boundaries at start and end od each section of the memory to know the size .

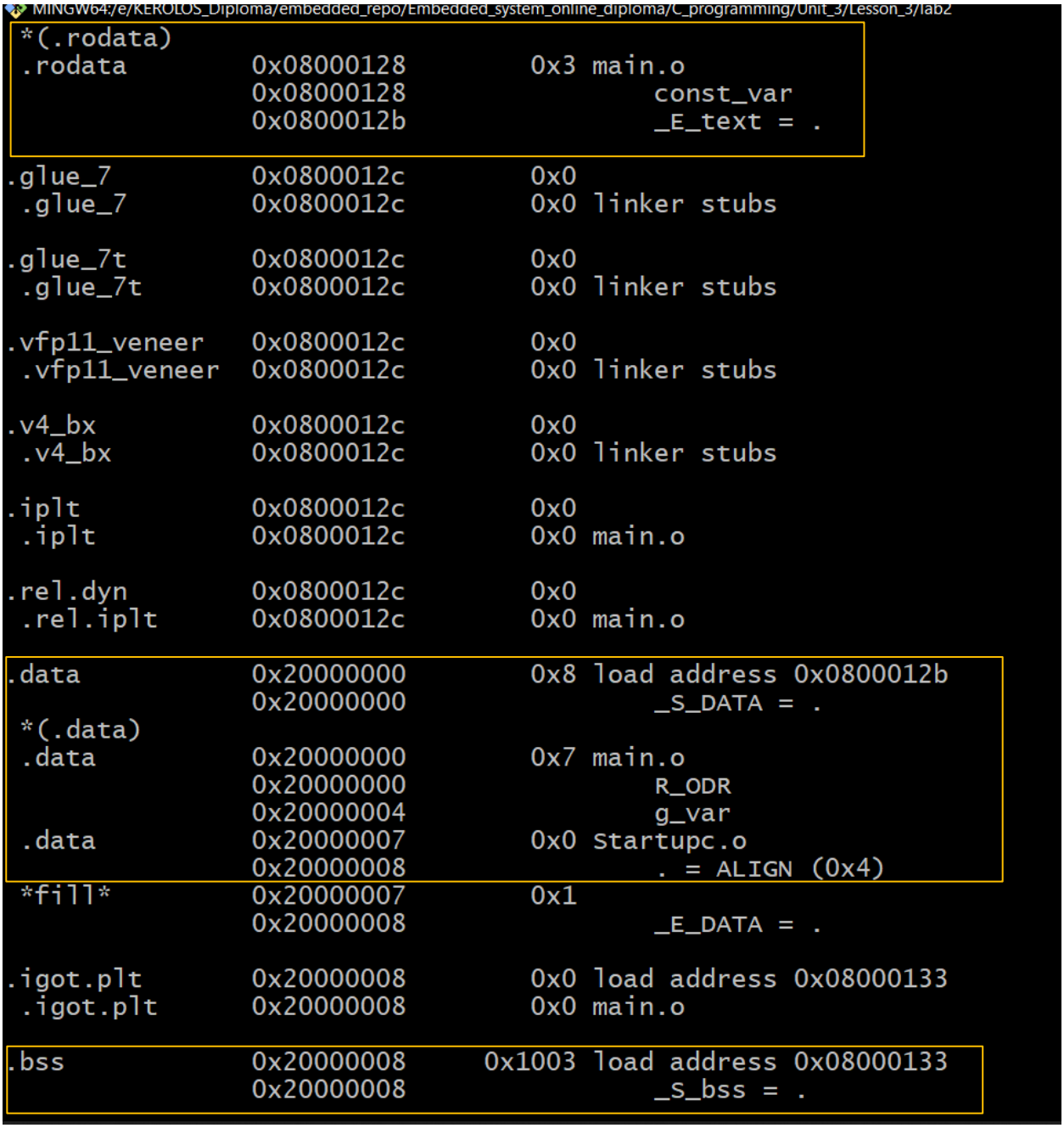
```
/* Author : Ayat mohamed
   Linker_script : cortex_M3
 */

MEMORY
{
   FLASH(RX) : ORIGIN = 0x08000000 , LENGTH = 128K
   SRAM(RWX) : ORIGIN = 0x20000000 , LENGTH = 20K
}
SECTIONS
{
   .text :
   {
      *(.vectors*)
      *(.text*)
      *(.rodata)
      _E_text = .;
   }>FLASH
   .data :
   {
       _S_DATA = .;
      *(.data)
      . = ALIGN(4);
      _E_DATA = .;
   }>SRAM AT> FLASH
   .bss :
   {
       _S_bss = .;
      *(.bss)
      _E_bss = .;
      . = ALIGN(4);
      . = . + 0X1000;
      _stack_top = .;
   }>SRAM
}
```

-the sections of memories

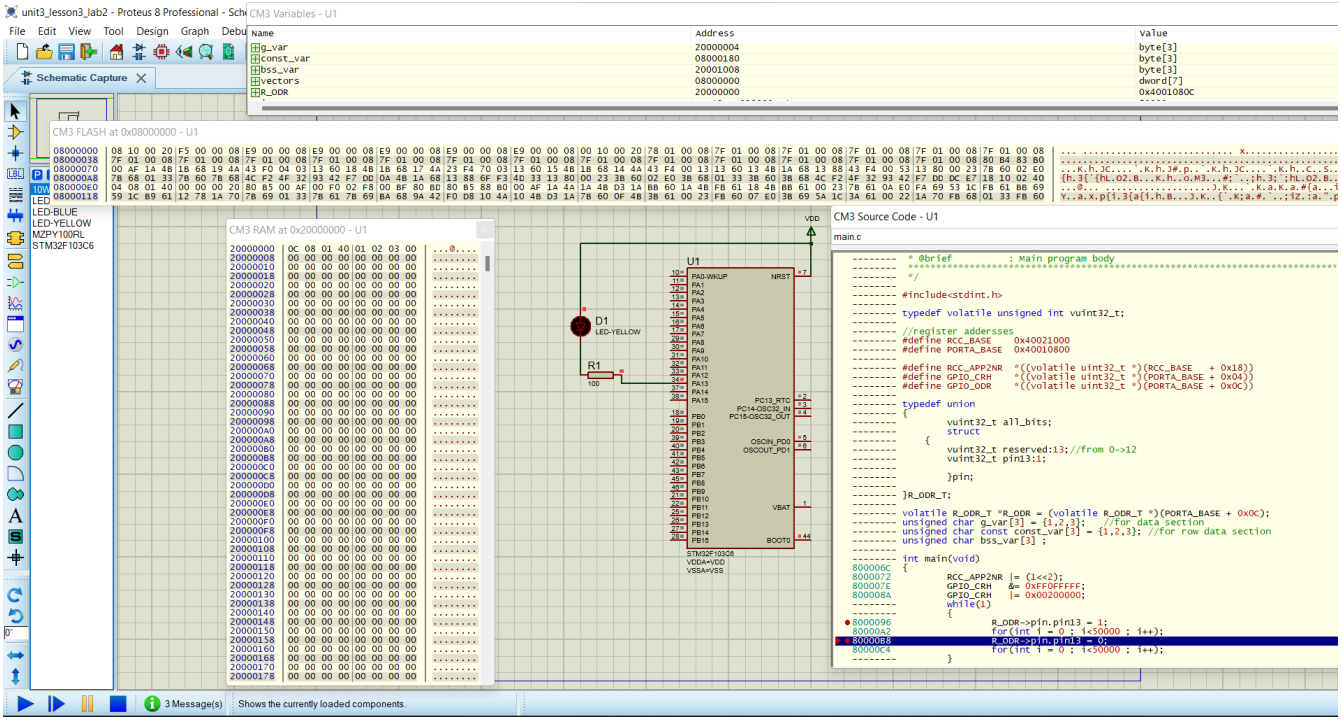
```
Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_d
iploma/C_programming/Unit_3/Lesson_3/lab2 (master)
$ arm-none-eabi-objdump.exe -h learn_in_depth_cortexM3.elf

learn_in_depth_cortexM3.elf:     file format elf32-littlearm

Sections:
Idx Name          Size      VMA       LMA       File off  Algn
  0 .text         00000183  08000000  08000000  00010000  2**2
                  CONTENTS, ALLOC, LOAD, READONLY, CODE
  1 .data         00000008  20000000  08000183  00020000  2**2
                  CONTENTS, ALLOC, LOAD, DATA
  2 .bss          00001003  20000008  0800018b  00020008  2**2
                  ALLOC
  3 .debug_info   00000388  00000000  00000000  00020008  2**0
                  CONTENTS, READONLY, DEBUGGING
  4 .debug_abbrev 000001df  00000000  00000000  00020390  2**0
                  CONTENTS, READONLY, DEBUGGING
  5 .debug_loc    000000b4  00000000  00000000  0002056f  2**0
                  CONTENTS, READONLY, DEBUGGING
  6 .debug_aranges 00000060  00000000  00000000  00020628  2**3
                  CONTENTS, READONLY, DEBUGGING
  7 .debug_line   0000025d  00000000  00000000  00020688  2**0
                  CONTENTS, READONLY, DEBUGGING
  8 .debug_str    000001f3  00000000  00000000  000208e5  2**0
                  CONTENTS, READONLY, DEBUGGING
  9 .comment      0000007e  00000000  00000000  00020ad8  2**0
                  CONTENTS, READONLY
 10 .ARM.attributes 00000031  00000000  00000000  00020b56  2**0
                  CONTENTS, READONLY
 11 .debug_frame  0000007c  00000000  00000000  00020b88  2**2
                  CONTENTS, READONLY, DEBUGGING
```

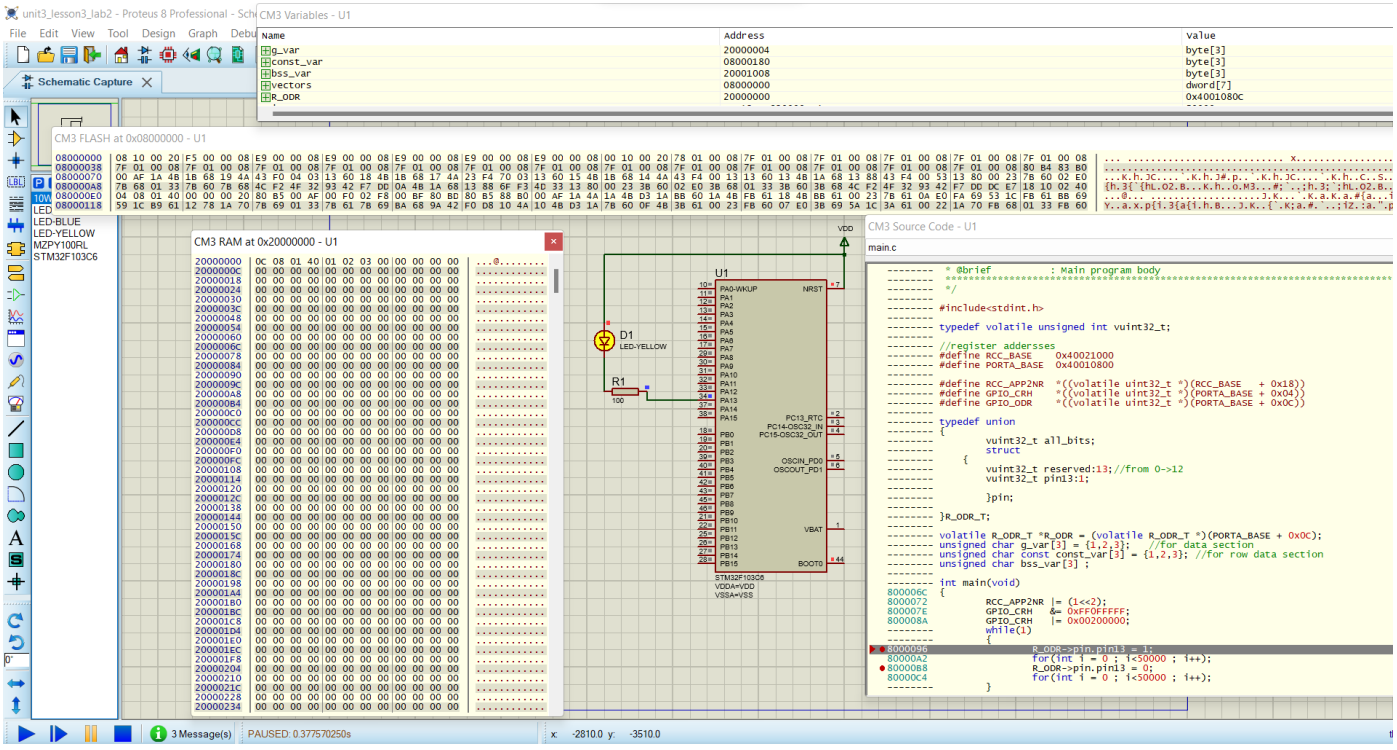
-Map File

```
Q@Ayat-Mohamed MINGW64 /e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_diploma/C_programming/Unit_3/Le
$ arm-none-eabi-ld.exe -T linker_script.ld main.o Startupc.o -o learn_in_depth_cortexM3.elf -MAP=Map_file.map

Allocating common symbols
Common symbol       size              file

bss_var             0x3               main.o

Memory Configuration

Name             Origin             Length             Attributes
FLASH            0x08000000         0x00020000         xr
SRAM             0x20000000         0x00005000         xrw
*default*        0x00000000         0xffffffff

Linker script and memory map


.text           0x08000000      0x12b
 *(.vectors*)
 .vectors       0x08000000       0x1c Startupc.o
                0x08000000                vectors
 *(.text*)
 .text          0x0800001c       0x7c main.o
                0x0800001c                main
 .text          0x08000098       0x90 Startupc.o
                0x08000098                H_Fault_Handler
                0x08000098                MM_Fault_Handler
                0x08000098                Usage_Fault_Handler
                0x08000098                Bus_Fault
                0x08000098                Default_Handler
                0x08000098                NMI_Handler
                0x080000a4                Reset_Handler
```


MINGW64:/e/KEROLOS_Diploma/embedded_repo/Embedded_system_online_diploma/C_programming/Unit_3/Lesson_3/lab2
*(.rodata)
.rodata 0x08000128 0x3 main.o
0x08000128 const_var
0x0800012b _E_text = .
.glue_7 0x0800012c 0x0
.glue_7 0x0800012c 0x0 linker stubs
.glue_7t 0x0800012c 0x0
.glue_7t 0x0800012c 0x0 linker stubs
.vfp11_veneer 0x0800012c 0x0
.vfp11_veneer 0x0800012c 0x0 linker stubs
.v4_bx 0x0800012c 0x0
.v4_bx 0x0800012c 0x0 linker stubs
.iplt 0x0800012c 0x0
.iplt 0x0800012c 0x0 main.o
.rel.dyn 0x0800012c 0x0
.rel.iplt 0x0800012c 0x0 main.o
.data 0x20000000 0x8 load address 0x0800012b
0x20000000 _S_DATA = .
*(.data)
.data 0x20000000 0x7 main.o
0x20000000 R_ODR
0x20000004 g_var
.data 0x20000007 0x0 Startupc.o
0x20000008 . = ALIGN (0x4)
fill 0x20000007 0x1
0x20000008 _E_DATA = .
.igot.plt 0x20000008 0x0 load address 0x08000133
.igot.plt 0x20000008 0x0 main.o
.bss 0x20000008 0x1003 load address 0x08000133
0x20000008 _S_bss = .

-Simulation


unit3_lesson3_lab2 - Proteus 8 Professional - Sch
CM3 Variables - U1
Name
Address
Value
g_var
20000004
byte[3]
const_var
08000180
byte[3]
bss_var
20001008
byte[3]
vectors
08000000
dword[7]
R_ODR
20000000
0x4001080C
Schematic Capture
CM3 FLASH at 0x08000000 - U1
CM3 RAM at 0x20000000 - U1
CM3 Source Code - U1
main.c
LED-BLUE
LED-YELLOW
MZPY100RL
STM32F103C6
D1
LED-YELLOW
R1
100
U1
STM32F103C8
3 Message(s)
Shows the currently loaded components.


unit3_lesson3_lab2 - Proteus 8 Professional - Sch
CM3 Variables - U1
Name
Address
Value
g_var
20000004
byte[3]
const_var
08000180
byte[3]
bss_var
20001008
byte[3]
vectors
08000000
dword[7]
R_ODR
20000000
0x4001080C
Schematic Capture
CM3 FLASH at 0x08000000 - U1
CM3 RAM at 0x20000000 - U1
CM3 Source Code - U1
main.c
LED-BLUE
LED-YELLOW
MZPY100RL
STM32F103C6
D1
LED-YELLOW
R1
100
U1
STM32F103C8
3 Message(s)
PAUSED: 0.377570250s
x: -2810.0 y: -3510.0