

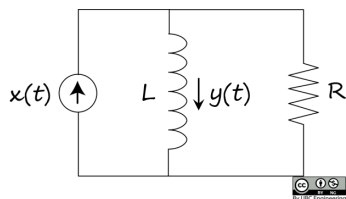
For each of the signals given in the table below, indicate whether it is periodic or not. For the periodic signals, write the following seven coefficients in a comma separated list as: $X_0, X_1, X_2, X_3, X_4, X_5, X_6$ and enter 0 for each coefficient that you find to be zero. If it is not possible to calculate the Fourier Series coefficients, enter NA.

	Signal	Periodic/A	efficients
1	$13 + 8\cos(10\pi t) + 12\cos(30t + \frac{\pi}{5})$	[?/Periodic/]	-
2	$[11 + \cos(2\pi t)]\sin(10\pi t + \frac{\pi}{2})$	[?/Periodic/]	-
3	$9 + \sin(3t + \frac{\pi}{9}) + 3\cos(5t) + 6\cos(3t) + 7\sin(6t)$	[?/Periodic/]	-

Correct Answers:

- Aperiodic
- NA
- Periodic
- 0, 0, 0, 0, $e^{(j\pi/2)/(4*j)}$, $11*e^{(j\pi/2)/(2*j)}$, $e^{(j\pi/2)/(4*j)}$
- Periodic
- 9, 0, 0, $e^{(j\pi/9)/(2*j)+3}$, 0, 1.5, $7/(2*j)$

Consider an LTI system that is implemented as an RL circuit shown in the figure below ($R = 10 \Omega$, $L = 11 H$). The input signal, $x(t)$, is generated by the current source and the output, $y(t)$, is measured as the current through the inductor.



a) Find the differential equation that describes this system.
_____.

To enter the first ($\frac{dy(t)}{dt}$) or second ($\frac{d^2y(t)}{dt^2}$) derivatives of a function $y(t)$, use “yp” and “ypp” respectively. Also enter “y” for $y(t)$.

b) Find the frequency response of the system, $H(\omega)$.

$H(\omega) =$ _____. Enter ω as w.

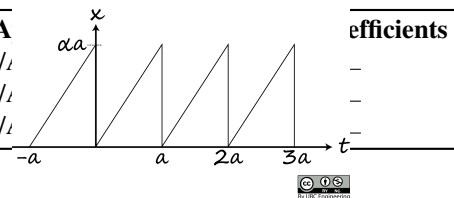
c) Suppose that the current source produces current $x(t) = \cos(t)$. What is the inductor’s current?

$y(t) =$ _____

Correct Answers:

- $1.1*yp+y = x$
- $1/(1+1.1*j*w)$
- $0.672673*\cos(t+(-0.832981))$

A periodic signal, $x(t)$ is given in the figure below, where $a = 6$, and $\alpha = 4$.



a) Find an equation for $x_c(t)$, the signal that describes one cycle of $x(t)$, in terms of the unit step function $u(t)$. $x_c(t) =$ _____

b) Find the Laplace transform, $X_c(s)$ of the signal in part a. $X_c(s) =$ _____

c) Calculate the Fourier Series coefficients of the signal $x(t)$, X_k for $k \neq 0$ using the Laplace transform from part b. $X_k =$ _____

d) Is it possible to find the Fourier Series coefficient, X_0 using the Laplace transform method? [?/Yes/No] e) Compute the Fourier Series coefficient, X_0 , using the integral definition. $X_0 =$ _____

Part d will only be marked correct if part c is correct.

Correct Answers:

- $4*t*[u(t)-u(t-6)]$
- $4*[1/(s^2)*[1-e^{(-6*s)}]-6/s*e^{(-6*s)}]$
- $24*j/(2*\pi*k)$
- No
- 12

JY Note (Feb 6, 2019): Question slightly edited to remove ambiguity in frequency response.

The frequency response of an LTI system is:

$$|H(\omega)| = \begin{cases} 10 & |\omega| \leq 5 \\ 0 & \text{otherwise} \end{cases}$$

$$\angle H(\omega) = \begin{cases} -\frac{\pi}{2} & \omega \geq 0 \\ \frac{\pi}{2} & \omega < 0 \end{cases}$$

Given a periodic input signal with the Fourier series of $x(t) = \sum_{k=1}^{\infty} \frac{5}{k^3} \cos(\frac{4kt}{2})$, find the steady state response of the system, $y_{ss}(t)$.

$y_{ss}(t) =$ _____

Correct Answers:

- $50 * [\cos(4 * t / 2 - \pi / 2) + 0.125 * \cos(8 * t / 2 - \pi / 2)]$

JY Note (Feb 6, 2019): Please assume the fundamental frequency is 2π rad/s even though the random numbers some students have result in a different value.

Consider a causal LTI system whose input, $x(t)$, and output, $y(t)$, are related by the differential equation, $\frac{d}{dt}y(t) + 3y(t) = 6x(t)$.

Given the input signal $x(t) = \sin(26\pi t) + \cos(12\pi t + \frac{\pi}{2})$, find the Fourier series representation of the output as in $y(t) = \sum_{k=-\infty}^{\infty} b_k e^{jk\omega_0 t}$, and enter the values of b_k in the table below.

b_{-26}	_____
b_{-13}	_____
b_{-12}	_____
b_{-6}	_____
b_{-1}	_____
b_0	_____
b_1	_____
b_6	_____
b_{12}	_____
b_{13}	_____
b_{26}	_____

Correct Answers:

- 0
- $-6 / [2 * j * (3 - 2 * j * 13 * \pi)]$
- 0
- $6 * e^{(-j * \pi / 2)} / (6 - 4 * j * 6 * \pi)$
- 0
- 0
- 0
- $6 * e^{(j * \pi / 2)} / (6 + 4 * j * 6 * \pi)$

- 0
- $6 / [2 * j * (3 + 2 * j * 13 * \pi)]$
- 0

The transfer function of an LTI system is given by: $H(s) = \frac{Y(s)}{X(s)} = \frac{s + 8}{s^2 + 4s + 9}$

Given the input $x(t) = 4 + \cos(t + \frac{\pi}{8})$, use the eigenfunction property of the LTI system to find the steady-state output.

$y_{ss}(t) =$ _____

Correct Answers:

- $3.55556 + 0.901388 * \cos(t + 0.0534065)$

Let $x(t)$ be a periodic signal of fundamental frequency $\omega_0 = \frac{2\pi}{T_0}$ that has Fourier series coefficients, X_k . For each of the signals $y(t)$ given in the table below, first determine if they are periodic or not. Then, for the periodic signals, determine their period in terms of T_0 , and calculate their Fourier coefficients Y_0 and Y_k in terms of X_0 and X_k , the corresponding Fourier coefficients of $x(t)$.

In your answers, enter “Xk” for X_k and “X0” for X_0 , “w” for ω_0 , and “T” for T_0 . Enter “NA” for the aperiodic signals.

Signal, $y(t)$	Periodic/Aperiodic	Period	Y_0	Y_k
$9x(t) - 9$	[?/Periodic/Aperiodic]	_____	_____	_____
$x(\pi t) + 4x(t - 3)$	[?/Periodic/Aperiodic]	_____	_____	_____
$x(t - 5) + 3x(t)$	[?/Periodic/Aperiodic]	_____	_____	_____

Correct Answers:

- Periodic
- T or $2 * \pi / w$
- $9 * X_0 - 9$
- $9 * X_k$
- Aperiodic
- NA
- NA
- NA
- Periodic
- T or $2 * \pi / w$
- $4 * X_0$
- $(3 + e^{(-5i) * k * 2 * \pi / T}) * X_k$ or $(3 + e^{(-5i) * k * w}) * X_k$