



GALAHAD

GLS

USER DOCUMENTATION

GALAHAD Optimization Library version 3.0

1 SUMMARY

GALAHAD_GLS is a suite of Fortran 95 procedures for solving sparse unsymmetric system of linear equations. Given a sparse matrix $\mathbf{A} = \{a_{ij}\}_{m \times n}$, this subroutine solves the system $\mathbf{Ax} = \mathbf{b}$ (or optionally $\mathbf{A}^T \mathbf{x} = \mathbf{b}$). The matrix \mathbf{A} can be rectangular.

This Fortran 95 code offers additional features to the Fortran 77 HSL code MA33 which it calls. The storage required for the factorization is chosen automatically and, if there is insufficient space for the factorization, more space is allocated and the factorization is repeated. The package also returns the number of entries in the factors and has facilities for identifying the rows and columns that are treated specially when the matrix is singular or rectangular.

ATTRIBUTES — Versions: GALAHAD_GLS_single, GALAHAD_GLS_double. **Remark:** GALAHAD_GLS is a Fortran 95 encapsulation of the core subroutines from the HSL Fortran 77 package MA33 and offers some additional facilities. The user interface is designed to be equivalent to a subset of the more recent HSL package HSL_MA48, so many features of the two packages may be used interchangeably. **Uses:** GALAHAD_SMT, MA33 from HSL. **Date:** March 2006. **Origin:** Interface by N. I. M. Gould, Rutherford Appleton Laboratory, documentation follows that of I.S. Duff and J.K. Reid, *ibid*. **Language:** Fortran 95.

2 HOW TO USE THE PACKAGE

Access to the package requires a USE statement such as

Single precision version

```
USE GALAHAD_GLS_single
```

Double precision version

```
USE GALAHAD_GLS_double
```

If it is required to use both modules at the same time, the derived types (Section 2.1) and the subroutines (Section 2.2) must be renamed on one of the USE statements.

There are four principal subroutines for user calls:

1. The subroutine GLS_INITIALIZE must be called to initialize the structure for the factors. It may also be called to set default values for the components of the control structure. If non-default values are wanted for any of the control components, the corresponding components should be altered after the call to GLS_INITIALIZE.
2. GLS_ANALYSE accepts the pattern of A and chooses pivots for Gaussian elimination using a selection criterion to preserve sparsity. It will optionally find an ordering to block triangular form and exploit that structure. An option exists to restrict pivoting to the diagonal, which might reduce fill-in and operations if the matrix has a symmetric structure. It is possible to perform an analysis without generating the factors, in which case data on the costs of a subsequent factorization are returned to the user. It is also possible to request that a set of columns are pivoted on last in which case a subsequent factorization can avoid factorization operations on the earlier columns.
3. GLS_SOLVE uses the factors generated by GLS_ANALYSE to solve a system of equations $\mathbf{Ax} = \mathbf{b}$ or $\mathbf{A}^T \mathbf{x} = \mathbf{b}$.

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4. `GLS_FINALIZE` reallocates the arrays held inside the structure for the factors to have size zero. It should be called when all the systems involving its matrix have been solved unless the structure is about to be used for the factors of another matrix.

There is an auxiliary subroutine for user calls after a successful factorization:

5. `GLS_SPECIAL_ROWS_AND_COLS` identifies the rows and columns that are treated specially when the matrix is singular or rectangular. It is for use following a call of `GLS_ANALYSE`.

2.1 The derived data types

Six derived data types are accessible from the package.

2.1.1 The derived data type for holding the matrix

The derived data type `SMT_TYPE` is used to hold the matrix. The components of `SMT_TYPE` used are:

`M` is an `INTEGER` scalar which holds the number of rows m of the matrix A . **Restriction:** $M \geq 1$.

`N` is an `INTEGER` scalar which holds the number of columns n of the matrix A . **Restriction:** $N \geq 1$.

`NE` is an `INTEGER` scalar which holds the number of matrix entries. **Restriction:** $NE \geq 0$.

`VAL` is a `REAL` (double precision in `GALAHAD_GLS_double`) pointer array of length at least `NE`, the leading part of which holds the values of the entries. Duplicate entries are summed.

`ROW` is an `INTEGER` pointer array of length at least `NE`, the leading part of which holds the row indices of the entries.

`COL` is an `INTEGER` pointer array of length at least `NE`, the leading part of which holds the column indices of the entries.

2.1.2 The derived data type for holding control parameters

The derived data type `GLS_CONTROL` is used to hold controlling data. Default values may be obtained by calling `GLS_initialize` (see Section 2.2.1). The components of `GLS_CONTROL` are:

`LP` is an `INTEGER` scalar used by the subroutines as the output unit for error messages. If it is negative, these messages will be suppressed. The default value is 6.

`WP` is an `INTEGER` scalar used by the subroutines as the output unit for warning messages. If it is negative, these messages will be suppressed. The default value is 6.

`MP` is an `INTEGER` scalar used by the subroutines as the output unit for diagnostic printing. If it is negative, these messages will be suppressed. The default value is 6.

`LDIAG` is an `INTEGER` scalar used by the subroutines to control diagnostic printing. If `LDIAG` is less than 1, no messages will be output. If the value is 1, only error messages will be printed. If the value is 2, then error and warning messages will be printed. If the value is 3, scalar data and a few entries of array data on entry and exit from each subroutine will be printed. If the value is greater than 3, all data will be printed on entry and exit. This output comes from the Fortran 77 MA33 routines called by `GALAHAD_GLS`. The default value is 2.

`LA` is an `INTEGER` scalar used by `GLS_ANALYSE`. `LA` is set to `FILL_IN * NE` by `GLS_ANALYSE`. The default for `FILL_IN` is 3 but, if the user knows that there may be significant fill-in during factorization, it may be efficient to increase this value.

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MAXLA is an **INTEGER** scalar used by **GLS_ANALYSE**. An error return occurs if the real array that holds data for the factors is too small and reallocating it to have size changed by the factor **MULTIPLIER** would make its size greater than **MAXLA**. The default value is **HUGE(0)**.

MULTIPLIER is a **REAL** (double precision in **GALAHAD_GLS_double**) scalar used by **GLS_ANALYSE** when a real or integer array that holds data for the factors is too small. The array is reallocated with its size changed by the factor **MULTIPLIER**. The default value is **2.0**.

REDUCE is a **REAL** (double precision in **GALAHAD_GLS_double**) scalar that reduces the size of previously allocated internal workspace arrays if they are larger than currently required by a factor of **REDUCE** or more. The default value is **2.0**.

SWITCH is an **REAL** (double precision in **GALAHAD_GLS_double**) scalar used by **GLS_ANALYSE** to control the switch from sparse to full matrix processing when factorizing the diagonal blocks. The switch is made when the ratio of number of entries in the reduced matrix to the number that it would have as a full matrix is greater than **SWITCH**. A value greater than **1.0** is treated as **1.0**. The default value is **0.5**.

U is a **REAL** (double precision in **GALAHAD_GLS_double**) scalar that is used by **GLS_ANALYSE**. It holds the threshold parameter for the pivot control. The default value is **0.01**. For problems requiring greater than average numerical care a higher value than the default would be advisable. Values greater than **1.0** are treated as **1.0** and less than **0.0** as **0.0**.

DROP is a **REAL** (double precision in **GALAHAD_GLS_double**) scalar that is used by **GLS_ANALYSE**. Any entry whose modulus is less than **DROP** will be dropped from the factorization. The factorization will then require less storage but will be inaccurate. The default value is **0.0**.

TOLERANCE is a **REAL** (double precision in **GALAHAD_GLS_double**) scalar that is used by **GLS_ANALYSE**. If it is set to a positive value, any pivot whose modulus is less than **TOLERANCE** will be treated as zero. the factorization. The default value is **0.0**.

CGCE is a **REAL** (double precision in **GALAHAD_GLS_double**) scalar that is used by **GLS_SOLVE**. It is used to monitor the convergence of the iterative refinement. If successive corrections do not decrease by a factor of at least **CGCE**, convergence is deemed to be too slow and **GLS_SOLVE** terminates with **SINFO%FLAG** set to **-8**. The default value is **0.5**.

PIVOTING is a **INTEGER** scalar that is used to control numerical pivoting by **GLS_ANALYSE**. If **PIVOTING** has a positive value, each pivot search is limited to a maximum of **PIVOTING** columns. If **PIVOTING** is set to the value **0**, a full Markowitz search technique is used to find the best pivot. This is usually only a little slower, but can occasionally be very slow. It may result in reduced fill-in. The default value is **3**.

DIAGONAL_PIVOTING is a **LOGICAL** scalar used by **GLS_ANALYSE** to limit pivoting to the diagonal. It will do so if **DIAGONAL_PIVOTING** is set to **.TRUE..** Its default value is **.FALSE..**

FILL_IN is an **INTEGER** scalar used by **GLS_ANALYSE** to determine the initial storage allocation for the matrix factors. It will be set to **FILL_IN** times the value of **MATRIX%NE**. The default value is **3**.

BTF is an **INTEGER** scalar used by **GLS_ANALYSE** to define the minimum size of a block of the block triangular form other than the final block. If block triangularization is not wanted, **BTF** should be set to a value greater than or equal to $\max(M, N)$. Block triangulation will only be attempted for square ($M = N$) matrices. A non-positive value is regarded as the value **1**. For further discussion of this variable, see Section 2.5. The default value is **1**.

STRUCT is a **LOGICAL** scalar used by **GLS_ANALYSE**. If **STRUCT** is set to **.TRUE..**, the subroutine will exit immediately structural singularity is detected. The default value is **.FALSE..**

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`FACTOR_BLOCKING` is an INTEGER scalar used by `GLS_ANALYSE` to determine the block size used for the Level 3 BLAS within the full factorization. If it is set to 1, Level 1 BLAS is used, if to 2, Level 2 BLAS is used. The default value is 32.

`SOLVE_BLAS` is an INTEGER scalar used by `GLS_SOLVE` to determine whether Level 2 BLAS is used ($\text{SOLVE_BLAS} > 1$) or not ($\text{SOLVE_BLAS} \leq 1$). The default value is 2.

`MAXIT` is an INTEGER scalar used by `GLS_SOLVE` to limit the number of refinement iterations. If `MAXIT` is set to zero then `GLS_SOLVE` will not perform any error analysis or iterative refinement. The default value is 10.

2.1.3 The derived data type for holding informational parameters from the analysis phase

The derived data type `GLS_AINFO` is used to hold parameters that give information about the progress and needs of the analysis phase of the algorithm. The components of `GLS_AINFO` are:

`FLAG` is an INTEGER scalar. The value zero indicates that the subroutine has performed successfully. For nonzero values, see Section 2.3.1.

`MORE` is an INTEGER scalar that provides further information in the case of an error, see Section 2.3.1.

`OOR` is an INTEGER scalar which is set to the number of entries with one or both indices out of range.

`DUP` is an INTEGER scalar which is set to the number of duplicate entries.

`DROP` is an INTEGER scalar which is set to the number of entries dropped from the data structure.

`STAT` is an INTEGER scalar. In the case of the failure of an allocate or deallocate statement, it is set to the `STAT` value.

`OPS` is a REAL (double precision in `GALAHAD_GLS_double`) scalar which is set to the number of floating-point operations required by the factorization.

`RANK` is an INTEGER scalar that gives an estimate of the rank of the matrix.

`STRUC_RANK` is an INTEGER scalar that, if `BTF` is less than or equal to `N`, holds the structural rank of the matrix. If $\text{BTF} > \text{N}$, `STRUC_RANK` is set to $\min(\text{M}, \text{N})$.

`LEN_ANALYSE` is an INTEGER scalar that gives the number of REAL (double precision in `GALAHAD_GLS_double`) and INTEGER words required for the analysis.

`LEN_FACTORIZE` is an INTEGER scalar that gives the number of REAL (double precision in `GALAHAD_GLS_double`) and INTEGER words required for successful subsequent factorization assuming the same pivot sequence and set of dropped entries can be used.

`NCMPA` is an INTEGER scalar that holds the number of compresses of the internal data structure performed by `GLS_ANALYSE`. If `NCMPA` is fairly large (say greater than 10), performance may be very poor.

`LBLOCK` is an INTEGER scalar that holds the order of the largest non-triangular block on the diagonal of the block triangular form. If the matrix is rectangular, `LBLOCK` will hold the number of rows.

`SBLOCK` is an INTEGER scalar that holds the sum of the orders of all the non-triangular blocks on the diagonal of the block triangular form. If the matrix is rectangular, `SBLOCK` will hold the number of columns.

`TBLOCK` is an INTEGER scalar that holds the total number of entries in all the non-triangular blocks on the diagonal of the block triangular form.

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2.1.4 The derived data type for holding informational parameters from the factorization phase

The derived data type `GLS_FINFO` is used to hold parameters that give information about the progress and needs of the factorization phase of the algorithm. The components of `GLS_FINFO` are:

`FLAG` is an `INTEGER` scalar. The value zero indicates that the subroutine has performed successfully. For nonzero values, see Section 2.3.2.

`MORE` is an `INTEGER` scalar that provides further information in the case of an error, see Section 2.3.2.

`STAT` is an `INTEGER` scalar. In the case of the failure of an `allocate` or `deallocate` statement, it is set to the `STAT` value.

`OPS` is a `REAL` (double precision in `GALAHAD_GLS_double`) scalar which is set to the number of floating-point operations required by the factorization.

`DROP` is an `INTEGER` scalar which is set to the number of entries dropped from the data structure.

`LEN_FACTORIZE` is an `INTEGER` scalar that gives the number of `REAL` (double precision in `GALAHAD_GLS_double`) and `INTEGER` words required for successful subsequent factorization assuming the same pivot sequence and set of dropped entries can be used.

`SIZE_FACTOR` is an `INTEGER` scalar that gives the number of entries in the matrix factors.

`RANK` is an `INTEGER` scalar that gives an estimate of the rank of the matrix.

2.1.5 The derived data type for holding informational parameters from the solution phase

The derived data type `GLS_SINFO` is used to hold parameters that give information about the progress and needs of the solution phase of the algorithm. The components of `GLS_SINFO` are:

`FLAG` is an `INTEGER` scalar. The value zero indicates that the subroutine has performed successfully. For nonzero values, see Section 2.3.3.

`MORE` is an `INTEGER` scalar that provides further information in the case of an error, see Section 2.3.3.

`STAT` is an `INTEGER` scalar. In the case of the failure of an `allocate` or `deallocate` statement, it is set to the `STAT` value.

2.1.6 The derived data type for the factors of a matrix

The derived data type `GLS_FACTORS` is used to hold the factors of a matrix, and has private components.

2.2 Argument lists and calling sequences

We use square brackets `[]` to indicate `OPTIONAL` arguments.

2.2.1 The initialization subroutine

The initialization subroutine must be called for each structure used to hold the factors. It may also be called for a structure used to control the subroutines. Each argument is optional. A call with no arguments has no effect.

```
CALL GLS_initialize( ([FACTORS] [,CONTROL])
```

`FACTORS` is optional, scalar, of `INTENT(OUT)` and of type `GLS_FACTORS`. On exit, its pointer array components will be null. Without such initialization, these components are undefined and other calls are likely to fail.

`CONTROL` is optional, scalar, of `INTENT(OUT)` and of type `GLS_CONTROL`. On exit, its components will have been given the default values specified in Section 2.1.2.

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2.2.2 To analyse the sparsity pattern and factorize the matrix

```
CALL GLS_ANALYSE( MATRIX, FACTORS, CONTROL, AINFO, FINFO )
```

MATRIX is scalar, of INTENT(IN) and of type SMT_TYPE. The user must set the components M, N, NE, ROW, COL, and VAL, and they are not altered by the subroutine. **Restrictions:** $\text{MATRIX\%M} \geq 1$, $\text{MATRIX\%N} \geq 1$, and $\text{MATRIX\%NE} \geq 0$.

FACTORS is scalar, of INTENT(INOUT) and of type GLS_FACTORS. It must have been initialized by a call to GLS_INITIALIZE or have been used for a previous calculation. In the latter case, the previous data will be lost but the pointer arrays will not be reallocated unless they are found to be too small.

CONTROL is scalar, of INTENT(IN) and of type GLS_CONTROL. Its components control the action, as explained in Section 2.1.2.

AINFO is scalar, of INTENT(OUT) and of type GLS_AINFO. Its components provide information about the execution, as explained in Section 2.1.3.

FINFO is scalar, of INTENT(OUT) and of type GLS_FINFO. If present, the call to GLS_ANALYSE will compute and store the factorization of the matrix. Its components provide information about the execution of the factorization, as explained in Section 2.1.4.

2.2.3 To solve a set of equations

```
CALL GLS_SOLVE( MATRIX, FACTORS, RHS, X, CONTROL, SINFO[, TRANS] )
```

MATRIX is scalar, of INTENT(IN) and of type SMT_TYPE. It must be unaltered since the call to GLS_ANALYSE and is not altered by the subroutine.

FACTORS is scalar, of INTENT(IN) and of type GLS_FACTORS. It must be unaltered since the call to GLS_ANALYSE and is not altered by the subroutine.

RHS is an array of shape (n) of INTENT(IN) and of type REAL (double precision in GALAHAD_GLS_double). It must be set by the user to the vector **b**.

X is an array of shape (n) of INTENT(OUT) and of type REAL (double precision in GALAHAD_GLS_double). On return it holds the solution **x**.

CONTROL is scalar, of INTENT(IN) and of type GLS_CONTROL. Its components control the action, as explained in Section 2.1.2.

SINFO is scalar, of INTENT(OUT) and of type GLS_SINFO. Its components provide information about the execution, as explained in Section 2.1.5.

TRANS is scalar, optional, of INTENT(IN) and of type INTEGER. If present $\mathbf{A}^T \mathbf{x} = \mathbf{b}$ is solved, otherwise the solution is obtained for $\mathbf{Ax} = \mathbf{b}$.

2.2.4 The termination subroutine

All previously allocated arrays are deallocated as follows:

```
CALL GLS_FINALIZE( FACTORS, CONTROL, INFO )
```

FACTORS is scalar, of INTENT(INOUT) and of type GLS_FACTORS. On exit, its pointer array components will have been deallocated. Without such finalization, the storage occupied is unavailable for other purposes. In particular, this is very wasteful if the structure goes out of scope on return from a procedure.

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CONTROL is scalar, of **INTENT (IN)** and of type **GLS_CONTROL**. Its components control the action, as explained in Section 2.1.2.

INFO is scalar, of **INTENT (OUT)** and of type **INTEGER**. On return, the value 0 indicates success. Any other value is the **STAT** value of an **ALLOCATE** or **DEALLOCATE** statement that has failed.

2.2.5 To identify the rows and columns that are treated specially following a successful factorization

```
CALL GLS_SPECIAL_ROWS_AND_COLS ( FACTORS, RANK, ROWS, COLS, INFO )
```

FACTORS is scalar, of **INTENT (IN)** and of type **GLS_FACTORS**. It must be unaltered since the call to **GLS_ANALYSE** and is not altered by the subroutine.

RANK is an **INTEGER** variable that need not be set by the user. On return, it holds the calculated rank of the matrix (it is the rank of the matrix actually factorized).

ROWS is an **INTEGER** array of length **M** that need not be set by the user. On return, it holds a permutation. The indices of the rows that are taken into account when solving $\mathbf{Ax} = \mathbf{b}$ are **ROWS**(*i*), $i \leq \mathbf{RANK}$.

COLS is an **INTEGER** array of length **N** that need not be set by the user. On return, it holds a permutation. The indices of the columns that are taken into account when solving $\mathbf{Ax} = \mathbf{b}$ are **COLS**(*j*), $j \leq \mathbf{RANK}$.

INFO is an **INTEGER** variable that need not be set by the user. On return, its value is 0 if the call was successful, -1 if the allocation of a temporary array failed, or -2 if the subsequent deallocation failed.

2.3 Warning and error messages

2.3.1 When performing the analysis

A successful return from the analysis phase within **GLS_ANALYSE** is indicated by **AINFO%FLAG** having the value zero. A negative value is associated with an error message which will be output on unit **CONTROL%LP**. Possible negative values are:

- 1 Value of **MATRIX%M** out of range. $\mathbf{MATRIX\%M} < 1$. **AINFO%MORE** is set to value of **MATRIX%M**.
- 2 Value of **MATRIX%N** out of range. $\mathbf{MATRIX\%N} < 1$. **AINFO%MORE** is set to value of **MATRIX%N**.
- 3 Value of **MATRIX%NE** out of range. $\mathbf{MATRIX\%NE} < 0$. **AINFO%MORE** is set to value of **MATRIX%NE**.
- 4 Failure of an allocate or deallocate statement. **AINFO%STAT** is set to the **STAT** value.
- 5 On a call with **STRUCT** having the value **.TRUE.**, the matrix is structurally rank deficient. The structural rank is given by **STRUC_RANK**.

A positive flag value is associated with a warning message which will be output on unit **AINFO%WP**. Possible positive values are:

- 1 Index (in **MATRIX%ROW** or **MATRIX%COL**) out of range. Action taken by subroutine is to ignore any such entries and continue. **AINFO%OOR** is set to the number of such entries. Details of the first ten are optionally printed on unit **CONTROL%MP**.
- 2 Duplicate indices. Action taken by subroutine is to sum corresponding reals. **AINFO%DUP** is set to the number of duplicate entries. Details of the first ten are optionally printed on unit **CONTROL%MP**.
- 3 Combination of a 1 and a 2 warning.

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- 4 The matrix is rank deficient with estimated rank `AINFO%RANK`.
- 5 Combination of a 1 and a 4 warning.
- 6 Combination of a 2 and a 4 warning.
- 7 Combination of a 1, a 2, and a 4 warning.
- 16 More space required than initial allocation. Size of LA used is given in `AINFO%MORE`.
- 17 to 23 Combination of warnings that sum to this total.

2.3.2 When factorizing the matrix

A successful return from the factorization phase within `GLS_ANALYSE` is indicated by `FINFO%FLAG` having the value zero. A negative value is associated with an error message which will be output on unit `CONTROL%LP`. In this case, no solution will have been calculated. Possible negative values are:

- 1 Value of `MATRIX%M` differs from the `GLS_ANALYSE` value. `FINFO%MORE` holds value of `MATRIX%M`.
- 2 Value of `MATRIX%N` differs from the `GLS_ANALYSE` value. `FINFO%MORE` holds value of `MATRIX%N`.
- 3 Value of `MATRIX%NE` out of range. `MATRIX%NE < 0`. `FINFO%MORE` holds value of `MATRIX%NE`.
- 4 Failure of an allocate or deallocate statement. `FINFO%STAT` is set to the `STAT` value.
- 7 The real array that holds data for the factors needs to be bigger than `CONTROL%MAXLA`.
- 10 `GLS_FACTORIZE` has been called without a prior call to `GLS_ANALYSE`.

A positive flag value is associated with a warning message which will be output on unit `CONTROL%MP`. In this case, a factorization will have been calculated.

- 4 Matrix is rank deficient. In this case, `FINFO%RANK` will be set to the rank of the factorization. In the subsequent solution, all columns in the singular block will have the corresponding component in the solution vector set to zero.
- 16 More space required than initial allocation. Size of LA used is given in `FINFO%MORE`.
- 20 Combination of a 4 and a 16 warning.

2.3.3 When using factors to solve equations

A successful return from `GLS_SOLVE` is indicated by `SINFO%FLAG` having the value zero. A negative value is associated with an error message which will be output on unit `CONTROL%LP`. In this case, the solution will not have been completed. Possible negative values are:

- 1 Value of `MATRIX%M` differs from the `GLS_ANALYSE` value. `SINFO%MORE` holds value of `MATRIX%M`.
- 2 Value of `MATRIX%N` differs from the `GLS_ANALYSE` value. `SINFO%MORE` holds value of `MATRIX%N`.
- 3 Value of `MATRIX%NE` out of range. `MATRIX%NE < 0`. `SINFO%MORE` holds value of `MATRIX%NE`.
- 10 `GLS_SOLVE` has been called without a prior call to `GLS_ANALYSE`.

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2.4 Rectangular and rank deficient matrices

Rectangular matrices are handled by the code although no attempt is made at prior block triangularization. Rank deficient matrices are also factorized and a warning flag is set (AINFO%FLAG or FINFO%FLAG set to 4). If CONTROL%STRUCT is set to .TRUE., then an error return occurs (AINFO%FLAG = -5) if block triangularization is attempted and the matrix is structurally singular.

The package identifies a square submatrix of \mathbf{A} that it considers to be nonsingular. When solving $\mathbf{Ax} = \mathbf{b}$, equations outside this submatrix are ignored and solution components that correspond to columns outside the submatrix are set to zero. GLS_SPECIAL_ROWS_AND_COLS identifies the rows and columns of this submatrix from stored integer data.

It should be emphasized that the primary purpose of the package is to solve square nonsingular sets of equations. The rank is determined from the number of pivots that are not small or zero. There are more reliable (but much more expensive) ways of determining numerical rank.

2.5 Block upper triangular form

Many large unsymmetric matrices can be permuted to the form

$$\mathbf{PAQ} = \begin{pmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} & \cdot & \cdot & \cdot & \cdot \\ & \mathbf{A}_{22} & \cdot & \cdot & \cdot & \cdot \\ & & \mathbf{A}_{33} & \cdot & \cdot & \cdot \\ & & & \cdot & \cdot & \cdot \\ & & & & \cdot & \cdot \\ & & & & & \mathbf{A}_{\ell\ell} \end{pmatrix}$$

whereupon the system

$$\mathbf{Ax} = \mathbf{b} \quad (\text{or } \mathbf{A}^T \mathbf{x} = \mathbf{b})$$

can be solved by block back-substitution giving a saving in storage and execution time if the matrices \mathbf{A}_{ii} are much smaller than \mathbf{A} .

Since it is not very efficient to process a small block (for example a 1 by 1 block), any block of size less than CONTROL%BTF other than the final block is merged with its successor.

2.6 Badly-scaled systems

If the user's input matrix has entries differing widely in magnitude, then an inaccurate solution may be obtained. In such cases, the user is advised to first use the HSL package MC29A/AD to obtain scaling factors for the matrix and then explicitly scale it prior to calling this package.

3 GENERAL INFORMATION

Use of common: None.

Workspace: Provided automatically by the module.

Other routines called directly: MC13E/ED, MC20A/AD, MC21B/BD, MA33A/AD, MA33C/CD.

Other modules used directly: GALAHAD_SMT_single/double.

Input/output: Error, warning and diagnostic messages only. Error messages on unit CONTROL%LP and warning and diagnostic messages on unit CONTROL%WP and CONTROL%MP, respectively. These have default value 6, and printing of these messages is suppressed if the relevant unit number is set negative. These messages are also suppressed if GLS_CONTROL%LDIAG is less than 1.

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Restrictions: $\text{MATRIX\%M} \geq 1, \text{MATRIX\%N} \geq 1, \text{MATRIX\%NE} \geq 0$.

Portability: ISO Fortran 95.

4 METHOD

A version of sparse Gaussian elimination is used. Subroutine GLS_ANALYSE calls MA33A/AD to compute a pivot ordering for the decomposition of A into sparse LU factors. Pivoting is used to preserve sparsity in the factors. Each pivot a_{pj} is required to satisfy a stability test

$$|a_{pj}| \geq u \max_i |a_{ij}|$$

within the reduced matrix, where u is the threshold held in CONTROL%U, with default value 0.01. The subroutine then computes the numerical factors based on the chosen pivot order. Subroutine GLS_SOLVE uses the factors found by GLS_ANALYSE to solve systems of equations by calling MA33C/CD.

A discussion of the design of the predecessor to the MA33 routines called by this package is given by Duff and Reid, *ACM Trans Math Software* **5**, 1979, pp 18-35.

5 EXAMPLE OF USE

We illustrate the use of the package on the solution of the single set of equations

$$\begin{pmatrix} 3.14 & 7.5 & & \\ 4.1 & 3.2 & 0.3 & \\ & 1.0 & 4.1 & \end{pmatrix} \mathbf{x} = \begin{pmatrix} 1.0 \\ 2.0 \\ 3.0 \end{pmatrix}$$

(note that this example does not illustrate all the facilities). Then we may use the following code

```
! THIS VERSION: GALAHAD 2.1 - 22/03/2007 AT 09:00 GMT.
PROGRAM GALAHAD_GLS_example
USE GALAHAD_GLS_DOUBLE
IMPLICIT NONE
INTEGER, PARAMETER :: wp = KIND( 1.0D+0 )
INTEGER :: i, info, m, n, ne, rank
TYPE ( SMT_TYPE ) :: MATRIX
TYPE ( GLS_CONTROL ) :: CONTROL
TYPE ( GLS_AINFO ) :: AINFO
TYPE ( GLS_FINFO ) :: FINFO
TYPE ( GLS_SINFO ) :: SINFO
TYPE ( GLS_FACTORS ) :: FACTORS
INTEGER, ALLOCATABLE, DIMENSION( : ) :: ROWS, COLS
REAL ( KIND = wp ), ALLOCATABLE, DIMENSION( : ) :: B, X

! Read matrix order and number of entries

READ( 5, * ) m, n, ne
MATRIX%m = m ; MATRIX%n = n ; MATRIX%ne = ne

! Allocate arrays of appropriate sizes

ALLOCATE( MATRIX%VAL( ne ), MATRIX%ROW( ne ), MATRIX%COL( ne ) )
ALLOCATE( B( m ), X( n ), ROWS( m ), COLS( n ) )

! Read matrix
```

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```

      READ( 5, * ) ( MATRIX%ROW( i ), MATRIX%COL( i ), MATRIX%VAL( i ), i = 1, ne )

! Initialize the structures

      CALL GLS_initialize( FACTORS, CONTROL )

! Analyse and factorize

      CALL GLS_analyse( MATRIX, FACTORS, CONTROL, AINFO, FINFO )
      IF ( AINFO%flag < 0 ) THEN
        WRITE( 6, '( A, I0 )' )
        ' Failure of GLS_ANALYSE with AINFO%flag = ', AINFO%flag
        STOP
      END IF

! Write row and column reorderings

      CALL GLS_special_rows_and_cols( FACTORS, rank, ROWS, COLS, info )
      WRITE( 6, "( A, /, ( 10I5 ) )" ) ' row orderings:', ROWS( : rank )
      WRITE( 6, "( A, /, ( 10I5 ) )" ) ' column orderings:', COLS( : rank )

! Read right-hand side and solve system

      READ( 5, * ) B( : m )

      CALL GLS_solve( MATRIX, FACTORS, B, X, CONTROL, SINFO )
      IF ( SINFO%flag == 0 ) WRITE( 6, '( A, /, ( 6ES11.3 ) )' )
        ' Solution of set of equations without refinement is', X

! Now solve the transposed system

! READ( 5, * ) B( : m )

! CALL GLS_solve( MATRIX, FACTORS, B, X, CONTROL, SINFO, trans = 1 )
! IF ( SINFO%flag == 0 ) WRITE( 6, '( A, /, ( 6ES11.3 ) )' )
! ' Solution of set of transposed equations without refinement is', X

! Clean up

      DEALLOCATE( MATRIX%VAL, MATRIX%ROW, MATRIX%COL )
      CALL GLS_FINALIZE( FACTORS, CONTROL, INFO )

      END PROGRAM GALAHAD_GLS_example

```

with the following data

3	3	7
1	1	3.14
2	3	0.30
3	3	4.1
2	1	4.1
1	2	7.5
3	2	1.0
2	2	3.2
1.0	2.0	3.0

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This produces the following output:

```

row orderings:
  1    2    3
column orderings:
  1    2    3
2 wi    1.0000000000000000
2 wi    0.6942675159235669
2 wi    3.1053038353782245
Solution of set of equations without refinement is
4.886E-01 -7.122E-02  7.491E-01
150 W    1.0000000000000000  2.0000000000000000  3.0000000000000000
f,1 1 3
180 W    -0.3885350318471334  2
180 W    2.9823205487392523  3
250 W    0.1680490141015751  2
250 W    9.9044280950172592E-02  1
310 W    9.9044280950172592E-02  0.1680490141015751  0.7194110477486653
Solution of set of transposed equations without refinement is
9.904E-02  1.680E-01  7.194E-01

```

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