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// C++ implementation of the approach
// #include <bits/stdc++.h>
#include <iostream>
#define MAX_VERTICES 20
#define SIZE 10

using namespace std;

// Class for queue
class Queue
{
    int arr[MAX_VERTICES]; // array to store Queue elements
    int capacity; // maximum capacity of the Queue
    int front; // front points to front element in the Queue (if
any)
    int rear; // rear points to last element in the Queue
    int count; // current size of the Queue

public:
    Queue(int size = SIZE); // constructor
    // ~Queue(); // destructor

    int dequeue();
    void enqueue(int x);
    int peek();
    int size();
    bool isEmpty();
    bool isFull();
};

// Constructor to initialize Queue
Queue::Queue(int size)
{
    for(int i=0; i<size; i++)
        arr[i] = 0;
    front = 0;
    rear = -1;
    count=0;
    capacity = MAX_VERTICES;
}

// Utility function to remove front element from the Queue
int Queue::dequeue()
{
    // check for Queue underflow
    if (isEmpty())
    {
        cout << "Queue UnderFlow\n";
        return -1; // -1 means Queue was empty
    }

    int removed = arr[front];

    front = (front + 1) % capacity;
}

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        count--;
        return removed;
    }

// Utility function to add an item to the Queue
void Queue::enqueue(int item)
{
    // check for Queue overflow
    if (isFull())
    {
        cout << "Queue OverFlow\n";
        return;
    }

//    cout << "Inserting " << item << '\n';

    rear = (rear + 1) % capacity;
    arr[rear] = item;
    count++;
}

// Utility function to return front element in the Queue
int Queue::peek()
{
    if (isEmpty())
    {
        cout << "Queue UnderFlow\n";
        return -1; // -1 means Queue is empty
    }
    return arr[front];
}

// Utility function to check if the Queue is empty or not
bool Queue::isEmpty()
{
    return (count == 0);
}

// Utility function to check if the Queue is full or not
bool Queue::isFull()
{
    return (count == capacity);
}

class Graph {

    // Number of vertex
    int v;

    // Number of edges

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        int e;

        // Adjacency matrix
        int adj[MAX_VERTICES][MAX_VERTICES]; // assume maximum number
of vertices=20

public:
    // To create the initial adjacency matrix
    Graph(int v, int e);

    // Function to insert a new edge
    void addEdge(int start_v, int end_v);

    // Function to display the BFS traversal
    void BFS(int start);
};

// Function to fill the empty adjacency matrix
Graph::Graph(int v, int e)
{
    this->v = v;
    this->e = e;
    for (int row = 0; row < v; row++) {
        for (int column = 0; column < v; column++) {
            adj[row][column] = 0;
        }
    }
}

// Function to add an edge to the graph
void Graph::addEdge(int start_v, int end_v)
{
    // Considering a bidirectional edge (undirected graph)
    adj[start_v][end_v] = 1;
    adj[end_v][start_v] = 1;
}

// Function to perform BFS on the graph
void Graph::BFS(int start)
{
    // Visited vector to so that
    // a vertex is not visited more than once
    // Initializing the vector to false as no
    // vertex is visited at the beginning
    bool visited[MAX_VERTICES] = {false};
    // vector<bool> visited(v, false);
    Queue q;
    // vector<int> q;
    q.enqueue(start);

    // Set source as visited
    visited[start] = true;

    int u;
    while (!q.isEmpty()) {
        u = q.dequeue();
    }
}

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        // Print the current node
        cout << u << " ";
    // For every adjacent vertex to the current vertex
        for (int v1 = 0; v1 < v; v1++) {
            if (adj[u][v1] == 1 && (!visited[v1])) // if
node v1 is adjacent to u and not visited
            {

                // Push the adjacent node to the Queue
                q.enqueue(v1);

                // Set v1 as visited
                visited[v1] = true;
            }
        }
    }
}

// Driver code
int main()
{
    int v = 8, e = 4;

    // Create the graph
    Graph G(v, e);
    G.addEdge(1, 2);
    G.addEdge(1, 5);
    G.addEdge(2, 6);
    G.addEdge(5, 6);
    G.addEdge(6, 4);
    G.addEdge(5, 3);
//    G.addEdge(5, 6);

    G.BFS(1);
}

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