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**BSCS-5** 

Lab #08

## **LAB MANUAL CODES:**

## Lab Code: 1

```
#include<stdio.h>
#include<unistd.h>
int main(void)
{
  printf("The PID of this process (PID)= %d\n", getpid());
  printf("The PID of Parent process (PPID)= %d\n", getppid());
  return 0;
}
```

## **Output:**

```
student@student-virtual-machine:-$ pico p1.c
student@student-virtual-machine:-$ gcc p1.c -o p1
student@student-virtual-machine:-$ ./p1
The PID of this process (PID)= 2257
The PID of Parent process (PPID)= 1949
student@student-virtual-machine:-$
```

## Lab Code: 2

```
#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
int main(void)
{
   fork();
   int x=5;
   pid_t pid = getpid();
   printf("Value of X in PID= %d is %d\n",pid,x);
   return 0;
}
```

```
student@student-virtual-machine:-$ pico p2.c
student@student-virtual-machine:-$ gcc p2.c -o p2
student@student-virtual-machine:-$ ./p2
Value of X in PID= 2355 is 5
Value of X in PID= 2356 is 5
```

### Lab Code: 3

```
#include <stdio.h>
#include <unistd.h>
int main() {
    int pid = fork();
    if (pid == 0) {
        printf("I'm the child! My PID is %d\n", getpid());
    } else {
        printf("I'm the parent! My PID is %d and my child's PID is %d\n", getpid(), pid);
    }
    return 0;
}
```

# **Output:**

```
student@student-virtual-machine: $ pico p3.c
student@student-virtual-machine: $ gcc p3.c -o p3
student@student-virtual-machine: $ ./p3
I'm the parent! My PID is 2414 and my child's PID is 2415
I'm the child! My PID is 2415
```

### Lab Code: 4

```
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>
int main(int argc, char *argv[])
{
    printf("PID of ex1.c = %d\n", getpid());
    char *args[] = {"Hello", NULL};
    execv("./ex2", args);

    printf("Back to ex1.c");
    return 0;
}
```

**Output:** 

```
student@student-virtual-machine:-$ pico p4.c
student@student-virtual-machine:-$ gcc p4.c -o p4
student@student-virtual-machine:-$ ./p4
PID of ex1.c = 2477
Back to ex1.cstudent@student-virtual-machine:-$
```

### Lab Code: 5

```
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>

int main(int argc, char *argv[])
{
    printf("We are in ex2.c\n");
    printf("PID of ex2.c = %d\n", getpid());
    return 0;
}
```

# **Output:**

```
student@student-virtual-machine:-$ pico p5.c
student@student-virtual-machine:-$ gcc p5.c -o p5
student@student-virtual-machine:-$ ./p5
We are in ex2.c
PID of ex2.c = 2550
```

### Lab Code: 6

```
#include<stdio.h>
#include<unistd.h>
#include<stdlib.h>

int main(void)
{
    printf("The PID of this process (PID)= %d\n", getpid());
    exit(0);
    printf("The PID of Parent process (PPID)= %d\n", getppid());
    return 0;
```

```
student@student-virtual-machine:-$ pico p6.c
student@student-virtual-machine:-$
student@student-virtual-machine:-$ gcc p6.c -o p6
student@student-virtual-machine:-$ ./p6
The PID of this process (PID)= 2621
```

### Lab Code: 7

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/wait.h>
int main() {
  pid_t pid = fork();
  if (pid == 0) {
     // Child process
     printf("Child: I'm working...\n");
     sleep(2); // simulate work
     printf("Child: I'm done!\n");
     exit(0);
  } else {
    // Parent process
     printf("Parent: Waiting for child to finish...\n");
     wait(NULL); // wait for the child
     printf("Parent: Child has finished. I can continue.\n");
  return 0;
```

## **Output:**

```
student@student-virtual-machine:-$ pico p7.c
student@student-virtual-machine:-$ gcc p7.c -o p7
student@student-virtual-machine:-$ ./p7
Parent: Waiting for child to finish...
Child: I'm working...
Child: I'm done!
Parent: Child has finished. I can continue.
```

# **TASKS**

**Task: 01** 

Write a C++ program that uses two fork() calls . Each process should:

1. Print its process ID (PID) and a loop value from 1 to 20.

### **Code:**

```
#include <stdio.h>
#include <unistd.h>
int main() {
    int pid = fork();

    if (pid == 0) {
        printf("I'm the child! My PID is %d\n", getpid());
    } else {
        printf("I'm the parent! My PID is %d and my child's PID is %d\n", getpid(), pid);
    }

    for (int i = 0; i < 20; i++) {
        printf("%d\n", i + 1);
    }

    int pid2 = fork();
    if (pid2 == 0) {
        printf("Second fork - I'm a new child! My PID is %d\n", getpid());
    } else {
        printf("I'm the parent! My PID is %d and my child's PID is %d\n", getpid(), pid2);
    }

    return 0;
}</pre>
```

```
17
18
19
20
I'm the parent! My PID is 4810 and my child's PID is 4812
Second fork - I'm a new child! My PID is 4812
student@student-virtual-machine: $ Second fork - I'm a new child! My PID is 4813
I'm the parent! My PID is 4811 and my child's PID is 4813
```

#### **Task: 02**

Write a C++ program that creates three child processes using the fork() system call. Each child process should:

- 1. Print its own process ID (PID) and its parent process ID (PPID).
- 2. Terminate using exit().
- 3. After creating the child processes, the parent process should print its own PID.

#### Code:

```
#include <stdio.h>
#include <unistd.h>
#include <stdib.h>

int main() {
    pid_t pid;

    for (int i = 0; i < 3; ++i) {
        pid = fork();

        if (pid < 0) {
            perror("Fork failed");
            exit(1);
        } else if (pid == 0) {
            // Chtld process
            printf("Child Process %d: PID = %d, PPID = %d\n", i+1, getpid(), getppid());
        exit(0);
      }

      // Parent continues to next iteration
}

// Only parent reaches this point
      printf("Parent Process: PID = %d\n", getpid());
      return 0;
}</pre>
```

```
student@student-virtual-machine:-$ pico prgm2.c
student@student-virtual-machine:-$ gcc prgm2.c -o p2
student@student-virtual-machine:-$ ./p2
Child Process 1: PID = 4988, PPID = 4987
Parent Process: PID = 4987
Child Process 2: PID = 4989, PPID = 1082
Child Process 3: PID = 4990, PPID = 1082
student@student-virtual-machine:-$
```

### **Task: 03**

Explain the working of system calls with its types and examples according to your understanding.

System calls are like bridges between a user program and the operating system (OS) kernel. Programs can't directly talk to hardware (like printer, memory, CPU). They **ask the OS to do it** for them using system calls. Examples:

- Read/write from files
- Start or stop processes
- Send messages over a network
- Access devices like scanners or printers

### **Types of System Calls (with Examples):**

#### 1. Process Control

Used to create, terminate, or manage processes.

### Examples:

```
fork() – creates a new child process
```

exec() – runs a new program inside a process

wait() – waits for a child process to finish

exit() – ends a process

#### 2. File Management

Used to work with files (create, open, read, write, etc.)

### Examples:

open(), read(), write(), close()

### 3. Device Management

Access or control hardware devices.

### Examples:

ioctl(), read(), write() (used with device drivers)

## 4. Information Maintenance

Get or set system data like time, process ID, user ID, etc.

Examples:

getpid(), getpid(), getuid()

## **5. Communication**

For sending and receiving information between processes (Inter-process communication).

Examples:

pipe(), shmget(), msgget()