

Dynamic Table Slides

Mitsunori Ogiwara

A **dynamic table** is a table of variable size, where an **expansion** (or a **contraction**) is caused when the load factor has become larger (or smaller) than a fixed threshold.

Let the expansion threshold be 1 and the expansion rate be 2; that is, *the table size is doubled when an item is to be inserted when the table is full.*

Let the contraction threshold be $1/4$ and the contraction rate be $1/2$; that is, *the table size is halved when an item is to be eliminated when the table is exactly $1/4$ full.*

When these operations take place we *create a new table* and move all the elements from the old one to the new one.

Suppose that there are n calls of insertion and deletion are made, what is the average cost of each operation?

If the size is kept the same the cost is $O(1)$.

If the size is doubled from M to $2M$, the actual cost is $M + 1$. The time that it takes for the next table size change to occur is *at least M steps for doubling* and *at least $M/2$ steps for halving*. So the actual cost can be spread over the next $M/2$ “normal” steps. This gives an amortized cost of $O(1)$.

If the size is halved from M to $M/2$, the actual cost is $M/4$. The time that it takes for the next table size change to occur is *at least $M/4$ steps for doubling* and *at least $M/8$ steps for halving*. So the actual cost can be spread over the next $M/8$ steps to yield an amortized cost of $O(1)$.

For each i , $1 \leq i \leq n$, define c_i to be the number of insertions and deletions that are executed at the i -th operation, and define

$$\Phi_i = \begin{cases} 2\text{num}_i - \text{size}_i & \text{if } \alpha_i \geq \frac{1}{2}, \\ \frac{\text{size}_i}{2} - \text{num}_i & \text{if } \alpha_i < \frac{1}{2}, \end{cases}$$

Here size_i is the table size, num_i is the number of elements in the table, and α_i is the ratio $\text{num}_i/\text{size}_i$ after the i -th operation.

Note that

- at time 0, the table is empty, so $\Phi_0 = 0$,
- for all i , $\Phi_i \geq 0$, and thus, $\Phi_n \geq \Phi_0$, and
- $\Phi_n \leq 2n - n = n$, so the contribution of the potential function to the amortized cost is at most 1.

Here $m = \text{num}_{i-1}$ and $s = \text{size}_{i-1}$

(a) $\alpha_{i-1} = 1$: Here $m = s$.

$$\frac{c_i}{m+1} \mid \frac{\Phi_i}{2(m+1)-2s} \mid \frac{\Phi_{i-1}}{2m-s} \parallel \frac{\hat{c}_i}{3}$$

(b) $\frac{1}{2} \leq \alpha_{i-1} < 1$:

$$\frac{c_i}{1} \mid \frac{\Phi_i}{2(m+1)-s} \mid \frac{\Phi_{i-1}}{2m-s} \parallel \frac{\hat{c}_i}{3}$$

(c) $\alpha_i = \frac{1}{2}$: Here $m+1 = \frac{s}{2}$.

$$\frac{c_i}{1} \mid \frac{\Phi_i}{2(m+1)-s} \mid \frac{\Phi_{i-1}}{s/2-m} \parallel \frac{\hat{c}_i}{0}$$

(d) $\alpha_i < \frac{1}{2}$:

$$\frac{c_i}{1} \mid \frac{\Phi_i}{s/2-m-1} \mid \frac{\Phi_{i-1}}{s/2-m} \parallel \frac{\hat{c}_i}{0}$$

So the amortized cost of insertion is $O(1)$.

(a) $\alpha_i \geq \frac{1}{2}$:

$$\begin{array}{c|c|c||c} c_i & \Phi_i & \Phi_{i-1} & \hat{c}_i \\ \hline 1 & 2(m-1) - s & 2m - s & -1 \end{array}$$

(b) $\alpha_{i-1} = \frac{1}{2}$: Here $2m = s$.

$$\begin{array}{c|c|c||c} c_i & \Phi_i & \Phi_{i-1} & \hat{c}_i \\ \hline 1 & \frac{s}{2} - (m-1) & 2m - s & 2 \end{array}$$

(c) $\frac{1}{4} < \alpha_{i-1} \leq \frac{1}{2}$:

$$\begin{array}{c|c|c||c} c_i & \Phi_i & \Phi_{i-1} & \hat{c}_i \\ \hline 1 & s/2 - (m-1) & s/2 - m & 2 \end{array}$$

(d) $\alpha_{i-1} = \frac{1}{4}$: $m = \frac{s}{4}$ and $\alpha_i < \frac{1}{2}$.

$$\begin{array}{c|c|c||c} c_i & \Phi_i & \Phi_{i-1} & \hat{c}_i \\ \hline m & s/4 - (m-1) & s/2 - m & 1 \end{array}$$

So the amortized cost of deletion is $O(1)$.