

# ***Design and Analysis of Algorithms***

## **Divide and Conquer**

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## *Merge Sort (Divide and Conquer)*

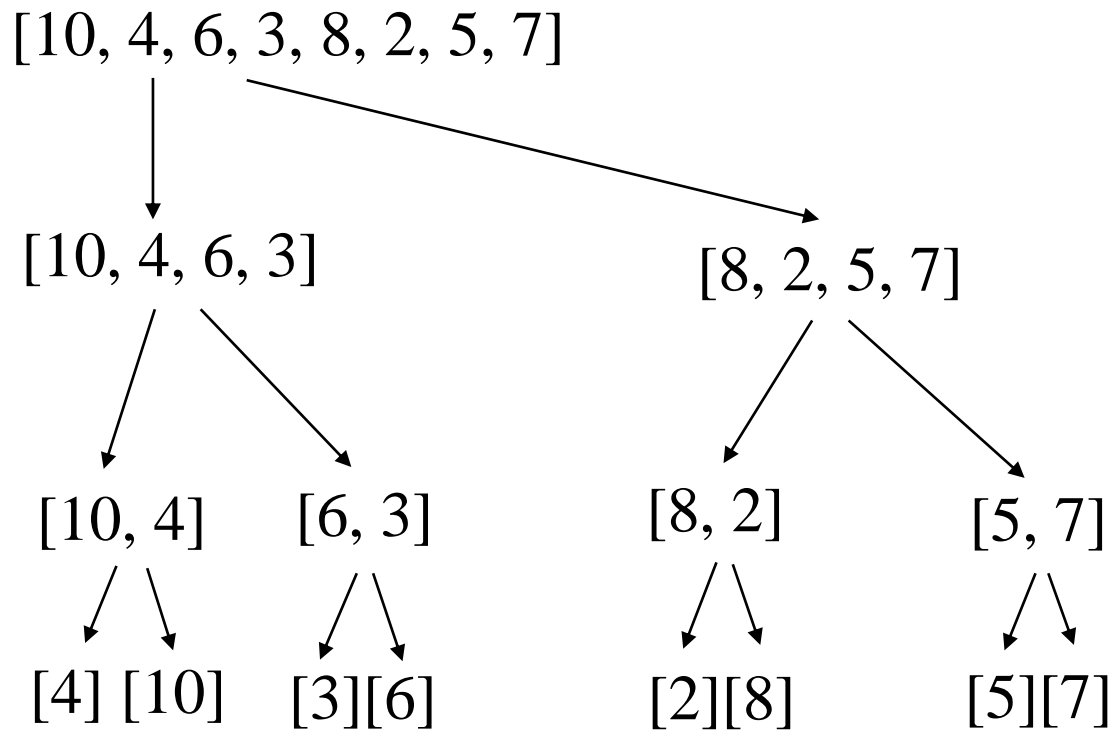
**MERGE-SORT**  $A[1 \dots n]$

1. If  $n = 1$ , done.
2. Recursively sort  $A[1 \dots \lceil n/2 \rceil]$   
and  $A[\lceil n/2 \rceil + 1 \dots n]$ .
3. “*Merge*” the 2 sorted lists.

*Key subroutine:* **MERGE**

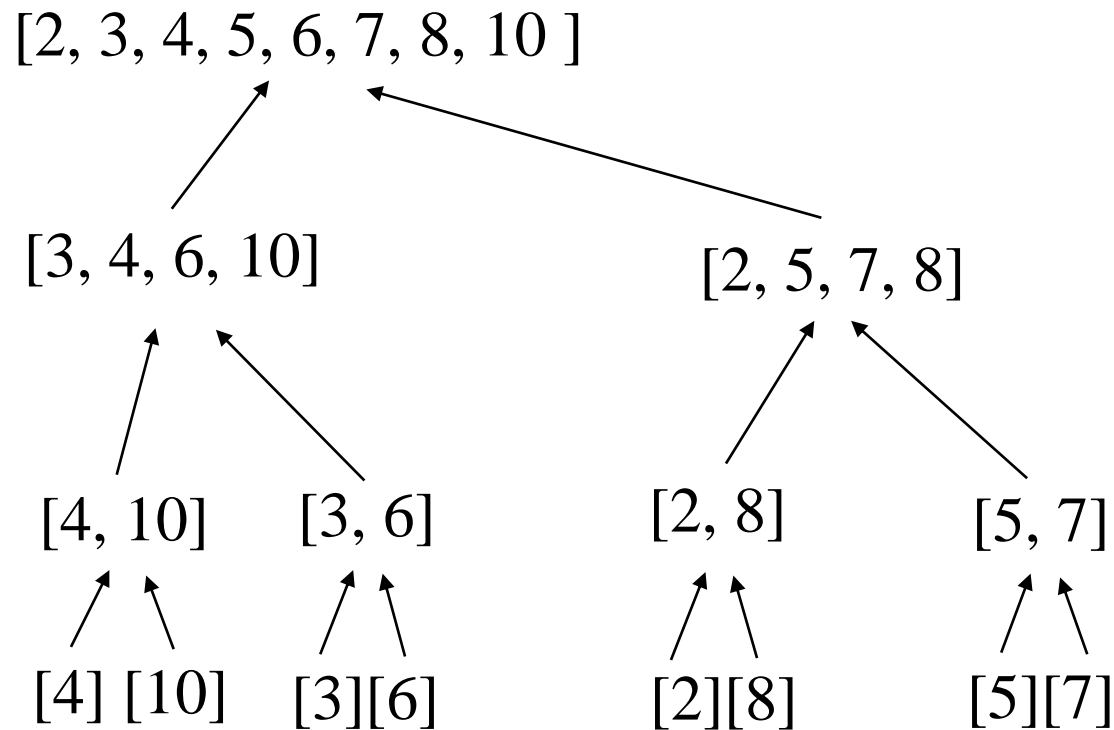
## Example

- Partition into lists of size  $n/2$



## *Example Cont'd*

- Merge**



# Analysis of Merge Sort

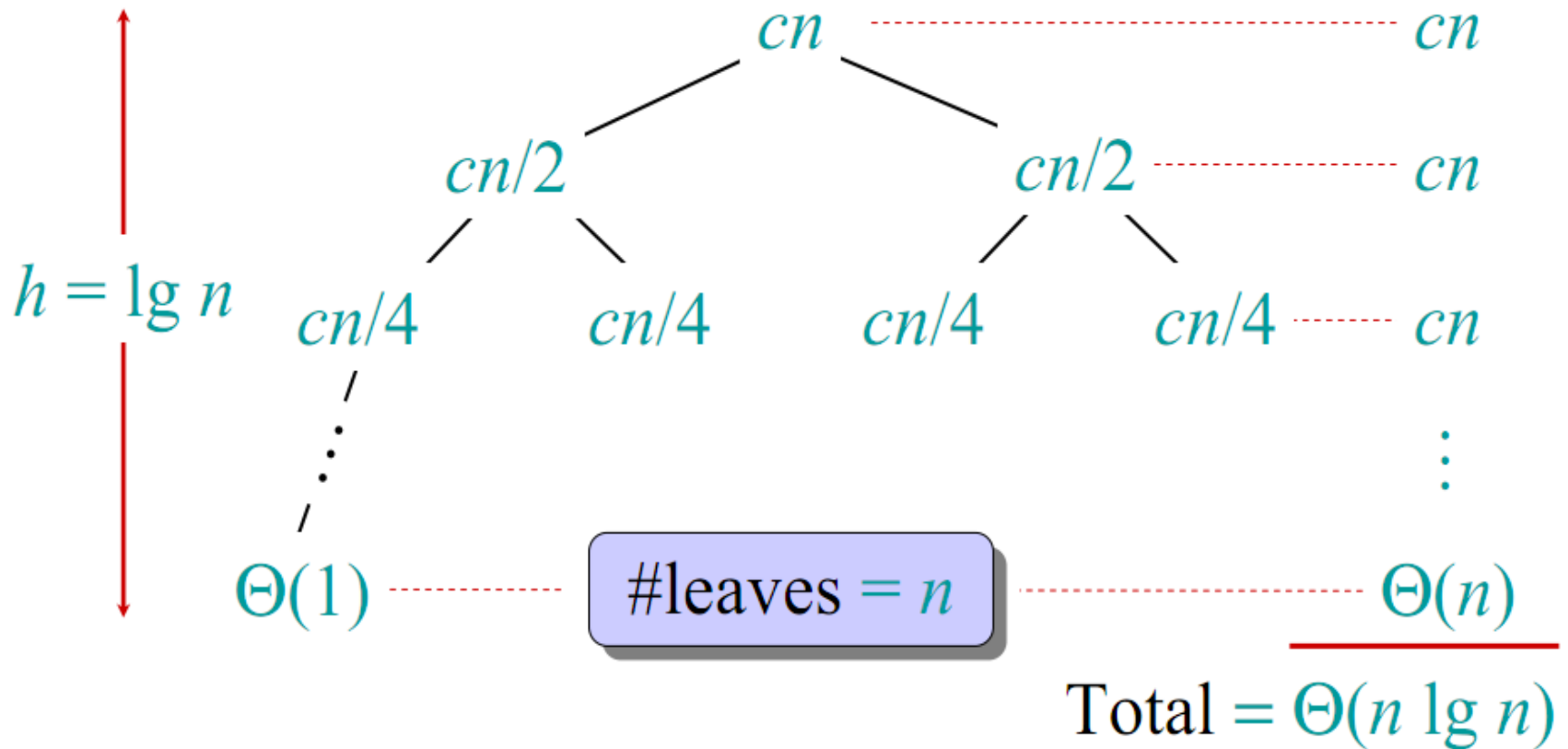
$T(n)$	<b>MERGE-SORT</b> $A[1 \dots n]$
$\Theta(1)$	1. If $n = 1$ , done.
$2T(n/2)$	2. Recursively sort $A[1 \dots \lceil n/2 \rceil]$ and $A[\lceil n/2 \rceil + 1 \dots n]$ .
<i>Abuse</i> $\Theta(n)$	3. <b><i>Merge</i></b> the 2 sorted lists

***Sloppiness:*** Should be  $T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor)$ ,  
but it turns out not to matter asymptotically.

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1; \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

# Visual Representation of the Recurrence for Merge Sort

Solve  $T(n) = 2T(n/2) + cn$ , where  $c > 0$  is constant.



# ***Time Complexity (Using Master Theorem)***

- **Recurrence Relation**

$$T(n)=2T(n/2) + n$$

**Using Master Theorem applying case 2:**

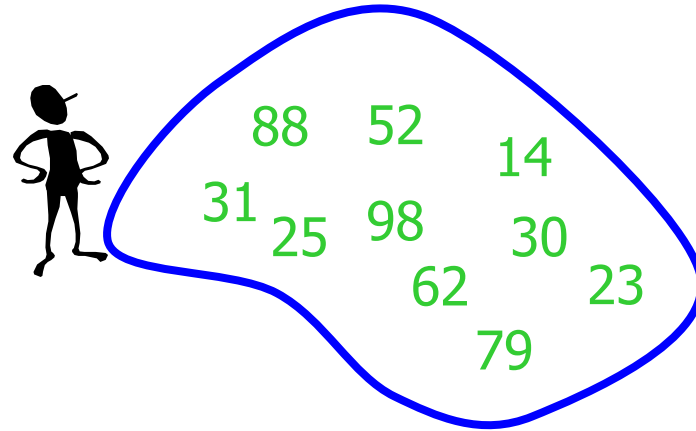
$$\Theta\left(n^{\log_b a} \log n\right)$$

**So time complexity is  $O(n \log n)$**

- $\Theta(n \lg n)$  grows more slowly than  $\Theta(n^2)$
- Therefore, merge sort asymptotically beats insertion sort in the worst case.
- In practice, merge sort beats insertion sort for  $n \geq 3$



# Quick Sort

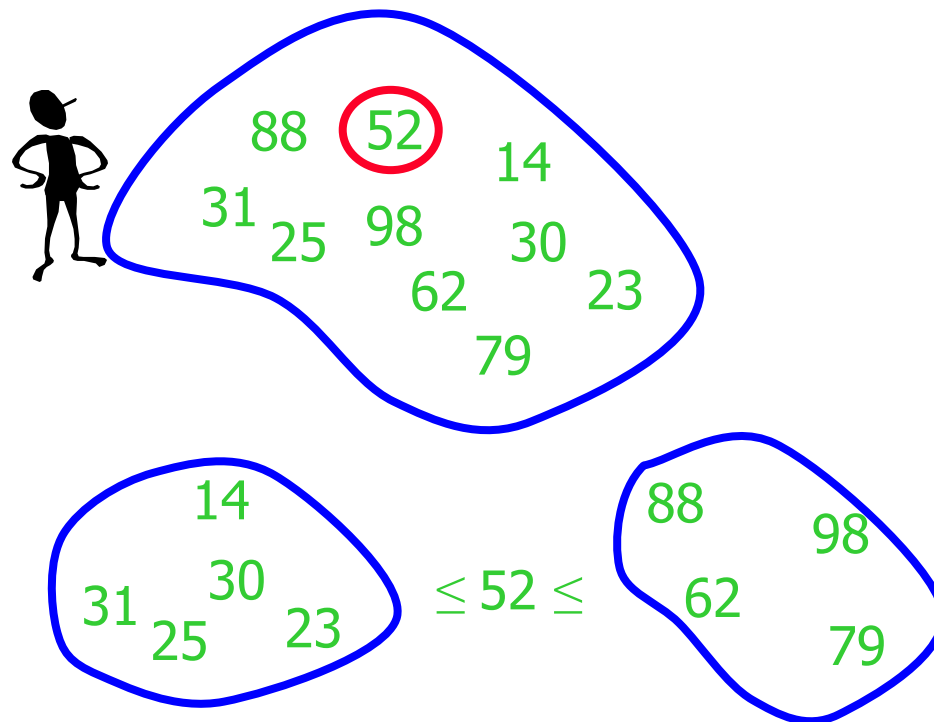


Divide and Conquer

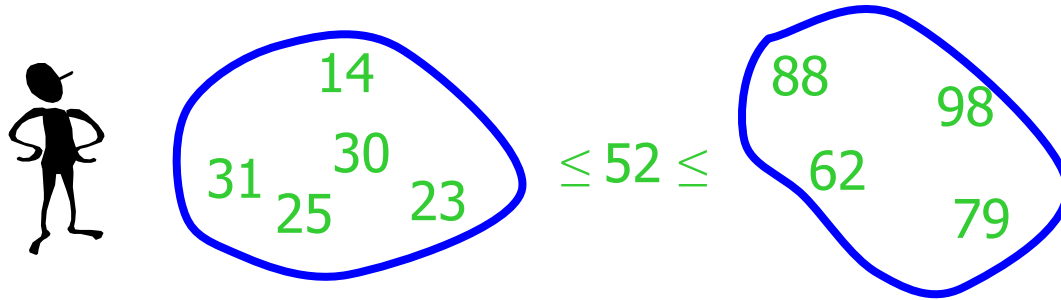


# Quick Sort

Partition set into two using  
randomly chosen pivot



# Quick Sort



sort the first half.



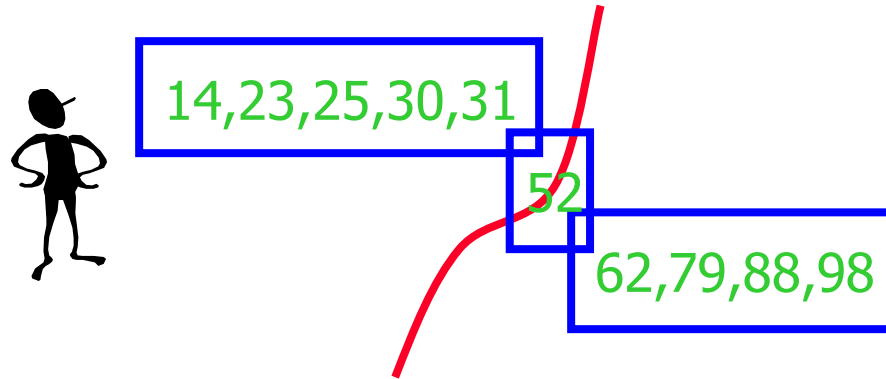
14,23,25,30,31

sort the second half.



62,79,98,88

# Quick Sort



Glue pieces together.

14, 23, 25, 30, 31, 52, 62, 79, 88, 98

# Quicksort

- Quicksort pros [advantage]:
  - Sorts in place
  - Sorts  $O(n \lg n)$  in the average case
  - Very efficient in practice , it' s quick
  - And the worst case doesn' t happen often ... sorted
- Quicksort cons [disadvantage]:
  - Sorts  $O(n^2)$  in the worst case

# Quicksort

- Another divide-and-conquer algorithm:
- **Divide:**  $A[p \dots r]$  is partitioned (rearranged) into two nonempty subarrays  $A[p \dots q-1]$  and  $A[q+1 \dots r]$  s.t. each element of  $A[p \dots q-1]$  is less than or equal to each element of  $A[q+1 \dots r]$ . Index  $q$  is computed here, called pivot.
- **Conquer:** two subarrays are sorted by recursive calls to quicksort.
- **Combine:** unlike merge sort, no work needed since the subarrays are sorted in place already.

# Quicksort Code

P: first element

r: last element

Quicksort(A, p, r)

```
{  
    if (p < r)  
    {  
        q = Partition(A, p, r)  
        Quicksort(A, p, q-1)  
        Quicksort(A, q+1, r)  
    }  
}
```

- Initial call is Quicksort(A, 1,  $n$ ), where  $n$  is the length of A

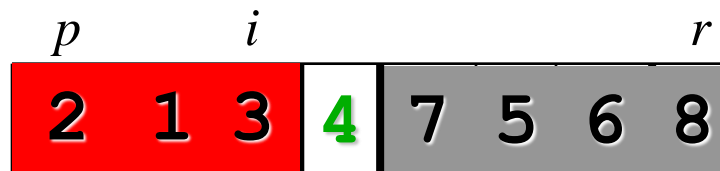
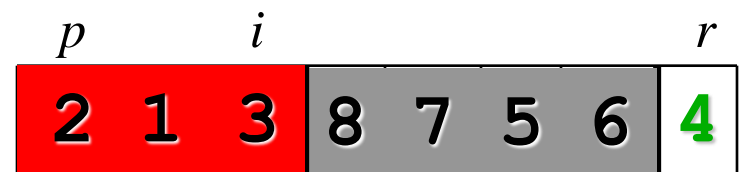
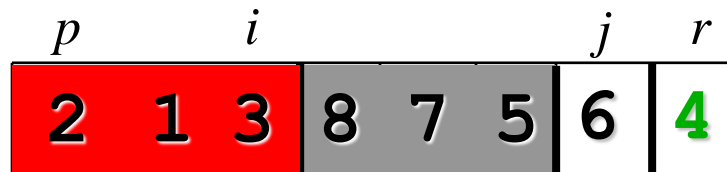
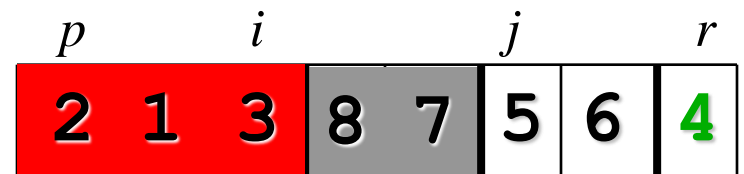
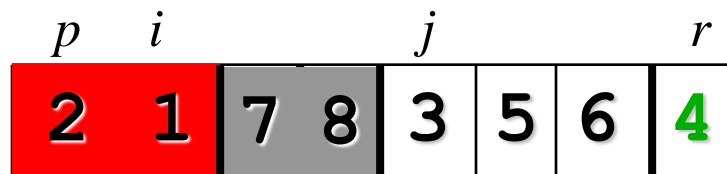
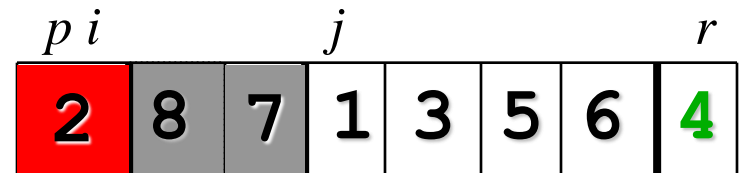
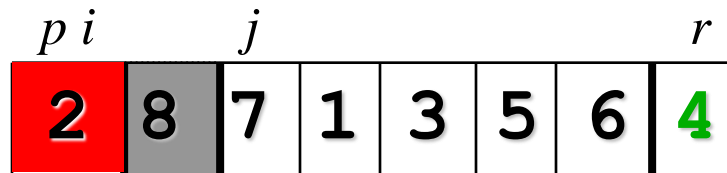
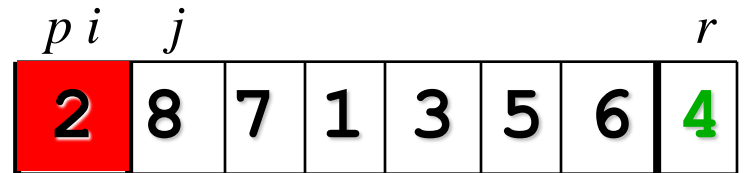
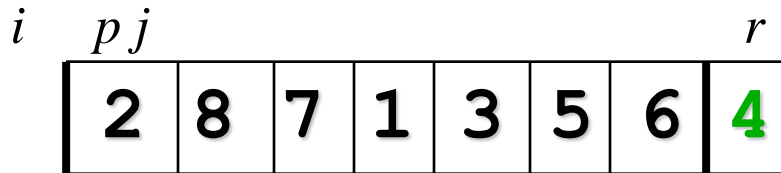
# *Partition*

- Clearly, all the action takes place in the `partition()` function
  - Rearranges the subarray in place
  - End result:
    - Two subarrays
    - All values in first subarray  $\leq$  all values in second
  - Returns the index of the “pivot” element separating the two subarrays



# Partition Example

$A = \{2, 8, 7, 1, 3, 5, 6, 4\}$



## *Partition Example Explanation*

- **Red** shaded elements are in the first partition with values  $\leq x$  (pivot)
- **Gray** shaded elements are in the second partition with values  $\geq x$  (pivot)
- The unshaded elements have not yet been put in one of the first two partitions
- The final **white** element is the pivot

# Partition Code

```
Partition(A, p, r)
```

```
{  
    x = A[r]                // x is pivot  
    i = p - 1  
    for j = p to r - 1  
    {  
        do if A[j] <= x  
        then  
            {  
                i = i + 1  
                exchange A[i] ↔ A[j]  
            }  
    }  
    exchange A[i+1] ↔ A[r]  
    return i+1  
}
```

*partition() runs in  $O(n)$  time*

# *Choice Of Pivot*

Three ways to choose the pivot:

- Pivot is **rightmost** element in list that is to be sorted
  - When sorting  $A[6:20]$ , use  $A[20]$  as the pivot
  - Textbook implementation does this
- **Randomly** select one of the elements to be sorted as the pivot
  - When sorting  $A[6:20]$ , generate a random number  $r$  in the range  $[6, 20]$
  - Use  $A[r]$  as the pivot

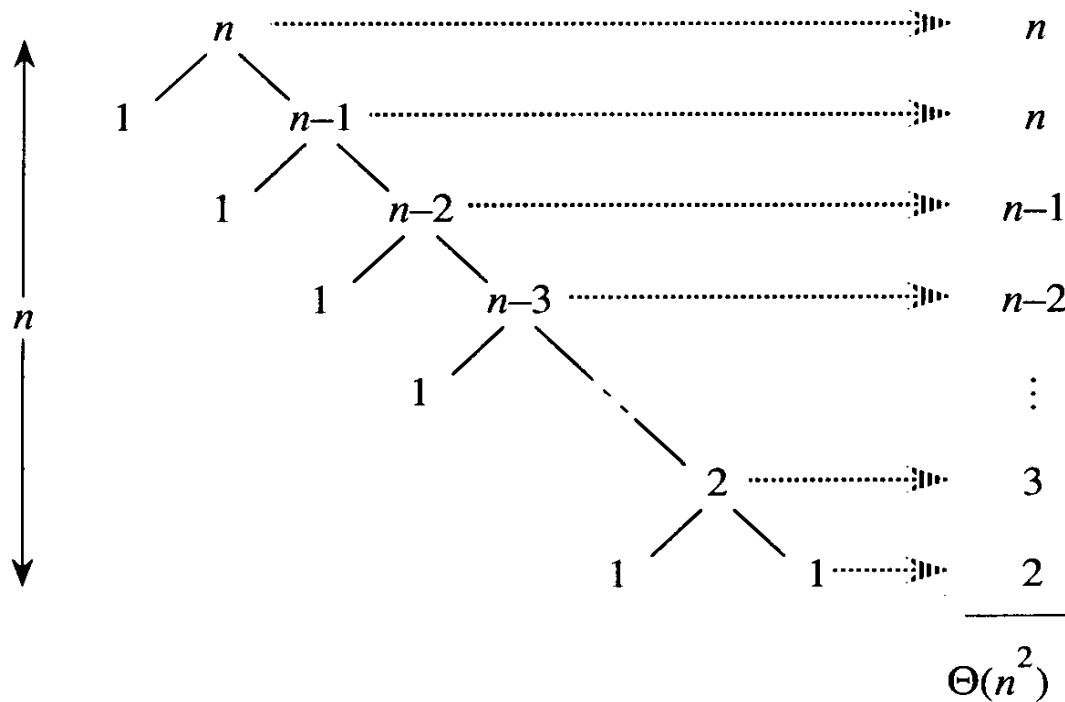
# Choice Of Pivot

- **Median-of-Three rule** - from the leftmost, middle, and rightmost elements of the list to be sorted, select the one with median key as the pivot
  - When sorting  $A[6:20]$ , examine  $A[6]$ ,  $A[13]$   $((6+20)/2)$ , and  $A[20]$
  - Select the element with median (i.e., middle) key
  - If  $A[6].key = 30$ ,  $A[13].key = 2$ , and  $A[20].key = 10$ ,  $A[20]$  becomes the pivot
  - If  $A[6].key = 3$ ,  $A[13].key = 2$ , and  $A[20].key = 10$ ,  $A[6]$  becomes the pivot

# Worst Case Partitioning

- The running time of quicksort depends on whether the **partitioning** is **balanced or not**.
- $\Theta(n)$  time to partition an array of  $n$  elements
- Let  $T(n)$  be the time needed to sort  $n$  elements
- $T(0) = T(1) = c$ , where  $c$  is a constant
- When  $n > 1$ ,
  - $T(n) = T(|\text{left}|) + T(|\text{right}|) + \Theta(n)$
- $T(n)$  is maximum (**worst-case**) when either  $|\text{left}| = 0$  or  $|\text{right}| = 0$  following each partitioning

# Worst Case Partitioning



**Figure 8.2** A recursion tree for QUICKSORT in which the PARTITION procedure always puts only a single element on one side of the partition (the worst case). The resulting running time is  $\Theta(n^2)$ .

# Worst Case Partitioning

- **Worst-Case Performance (unbalanced):**

- $T(n) = T(0) + T(n-1) + \Theta(n)$

- partitioning takes  $\Theta(n)$

- $= \Theta(n^2)$

$$\sum_{k=1}^n k = 1 + 2 + \dots + n = n(n+1)/2 = \Theta(n^2)$$

- **This occurs when**

- the input is completely sorted

- **or when**

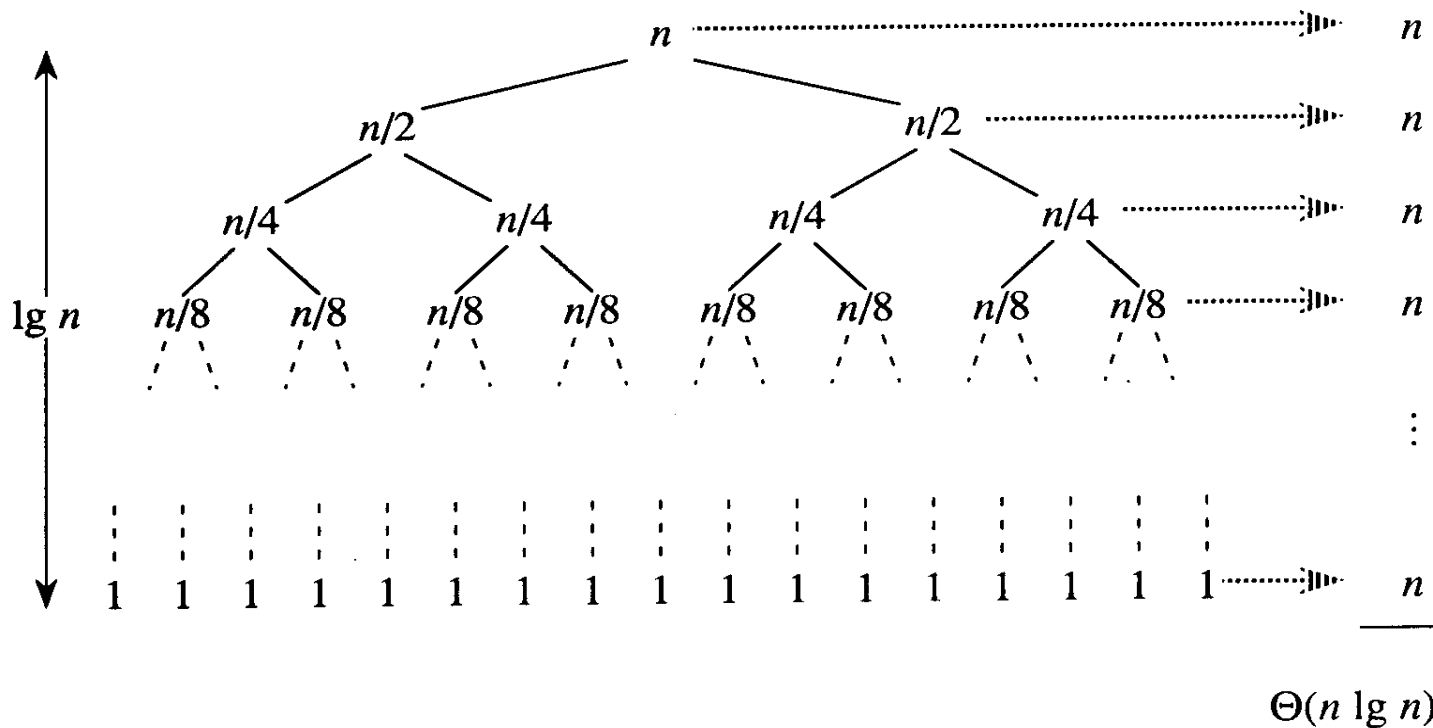
- the pivot is always the smallest (largest) element



## **Best Case Partition**

- When the partitioning procedure produces two regions of **size  $n/2$** , we get the a balanced partition with best case performance:
  - $T(n) = 2T(n/2) + \Theta(n) = \Theta(n \lg n)$
- Average complexity is also  $\Theta(n \lg n)$

# Best Case Partitioning



**Figure 8.3** A recursion tree for QUICKSORT in which PARTITION always balances the two sides of the partition equally (the best case). The resulting running time is  $\Theta(n \lg n)$ .

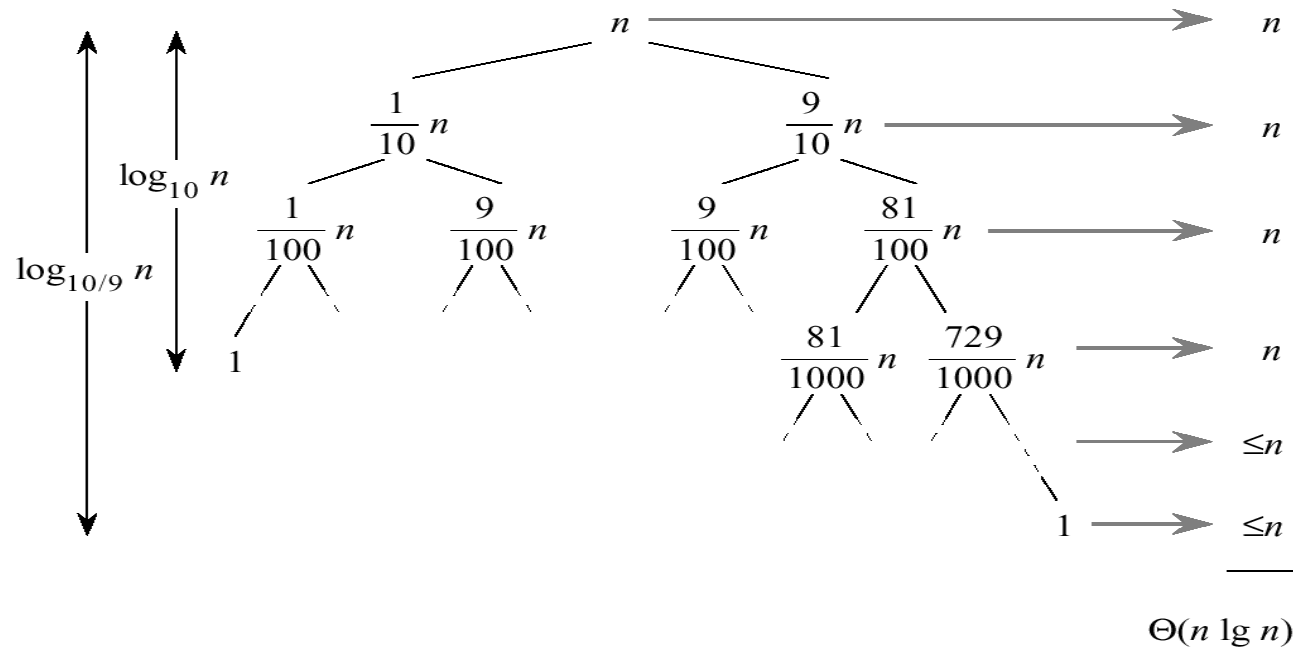
# Average Case

- Assuming **random input**, average-case running time is much closer to  $\Theta(n \lg n)$  than  $\Theta(n^2)$
- First, a more intuitive explanation/example:
  - Suppose that `partition()` always produces a **9-to-1 proportional split**. This looks quite unbalanced!
  - The recurrence is thus:
$$T(n) = T(9n/10) + T(n/10) + \Theta(n) = \Theta(n \lg n)?$$

[Using recursion tree method to solve]

# Average Case

$$T(n) = T(n/10) + T(9n/10) + \Theta(n) = \Theta(n \log n)$$



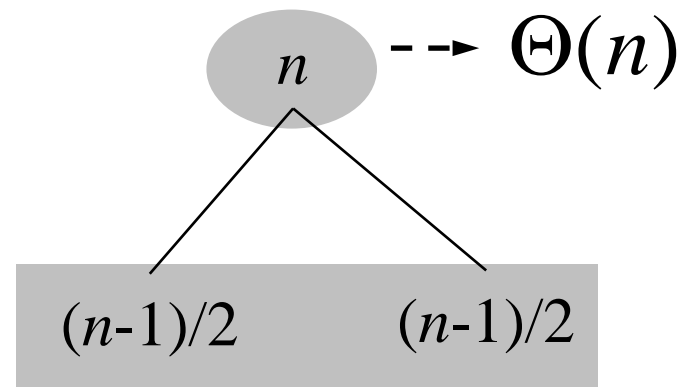
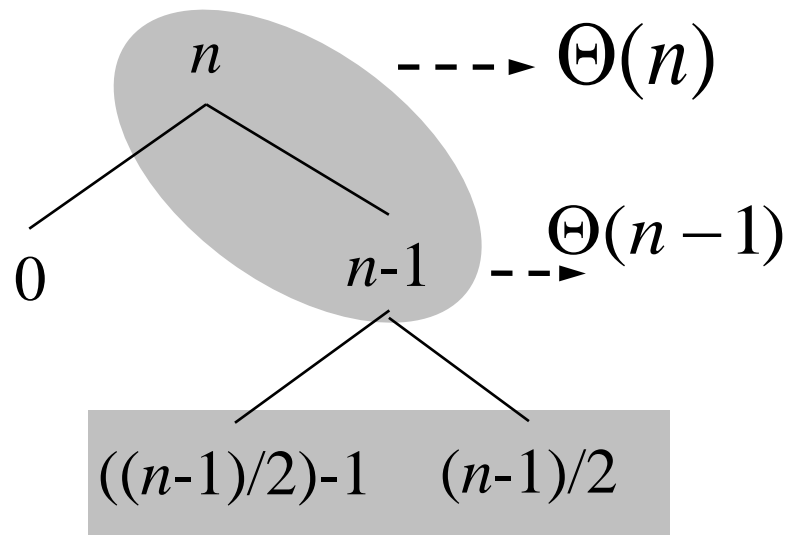
## Average Case

- Every level of the tree has cost  $cn$ , until a boundary condition is reached at depth  $\log_{10} n = \Theta(\lg n)$ , and then the levels have cost at most  $cn$ .
- The recursion terminates at depth  $\log_{10/9} n = \Theta(\lg n)$ .
- The total average cost of quicksort is therefore  $O(n \lg n)$ .

$$\log_b(x) = \frac{\log_k(x)}{\log_k(b)}.$$

# Average Case

- What happens if we **bad-split root node**, then **good-split** the resulting size  $(n-1)$  node?
  - We end up with **three** subarrays, size
    - $0, ((n-1)/2)-1, (n-1)/2$
  - Combined **cost of splits** =  $\Theta(n) + \Theta(n-1) = \Theta(n)$



# Intuition for the Average Case

- Suppose, we alternate **lucky and unlucky** cases to get an **average** behavior

$$L(n) = 2U(n/2) + \Theta(n) \quad \text{lucky}$$

$$U(n) = L(n-1) + \Theta(n) \quad \text{unlucky}$$

we consequently get

$$L(n) = 2(L(n/2 - 1) + \Theta(n/2)) + \Theta(n)$$

$$= 2L(n/2 - 1) + \Theta(n)$$

$$= \Theta(n \log n)$$

The combination of good and bad splits would result in

**$T(n) = O(n \lg n)$** , but with slightly **larger constant** hidden by the O-notation.

# Randomized Quicksort

- An algorithm is *randomized* if its behavior is determined not only by the input but also by values produced by a *random-number generator*.
- **Exchange**  $A[r]$  with an element chosen at random from  $A[p...r]$  in Partition.
- This ensures that the pivot element **is equally likely to be any of input** elements.
- We can sometimes add randomization to an algorithm in order to obtain good average-case performance over all inputs.



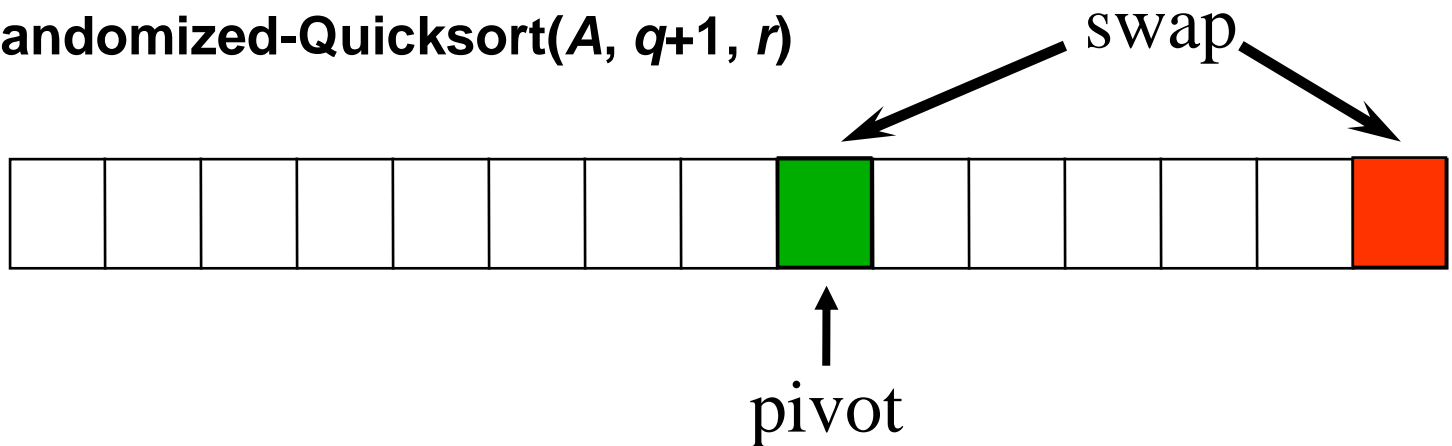
# Randomized Quicksort

## Randomized-Partition( $A, p, r$ )

1.  $i \leftarrow \text{Random}(p, r)$
2. exchange  $A[r] \leftrightarrow A[i]$
3. return Partition( $A, p, r$ )

## Randomized-Quicksort( $A, p, r$ )

1. if  $p < r$
2.   then  $q \leftarrow \text{Randomized-Partition}(A, p, r)$
3.       Randomized-Quicksort( $A, p, q-1$ )
4.       Randomized-Quicksort( $A, q+1, r$ )



# *Review: Analyzing Quicksort*

- *What will be the **worst case** for the algorithm?*
  - **Partition is always unbalanced**
- *What will be the **best case** for the algorithm?*
  - **Partition is balanced**

# Summary: Quicksort

- In worst-case, efficiency is  $\Theta(n^2)$ 
  - But easy to avoid the worst-case
- On average, efficiency is  $\Theta(n \lg n)$
- Better space-complexity than mergesort.
- In practice, runs fast and widely used

# *Linear Time Sorting*

- **Count Sort**
- **Radix Sort**
- **Bucket Sort**

# Counting Sort

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- Counting Sort was invented by H.H.Seward in 1954.
- All the sorting algorithms introduced so far share an interesting property : the sorted order they determine is based only on comparisons between the input elements.

## Assumptions of Counting Sort:

- Counting sort assumes that each of the input element is an Integer and lies in the range 1 to  $k$ , for some integer  $k$ .

When  $k = O(n)$  then the sort runs in  $O(n)$  time

Determine how many elements are less than an element  $x$

Then place  $x$  directly in its correct position

# Counting Sort Algorithm

**for**  $i \leftarrow 1$  **to**  $k$

**do**  $C[i] \leftarrow 0$  **k**

**for**  $j \leftarrow 1$  **to**  $\text{length}[A]$

**do**  $C[A[j]] \leftarrow C[A[j]] + 1$  **n**

**for**  $i \leftarrow 2$  **to**  $k$

**do**  $C[i] \leftarrow C[i] + C[i-1]$  **k**

**for**  $j \leftarrow \text{length}[A]$  **downto**  $1$

**do**  $B[C[A[j]]] \leftarrow A[j]$

$C[A[j]] \leftarrow C[A[j]] - 1$  **n**



- Example for Counting Sort:

	1	2	3	4	5	6	7	8
A	3	6	4	1	3'	4'	1'	4''

	1	2	3	4	5	6
C	2	0	2	3	0	1

	1	2	3	4	5	6
C	2	2	4	7	7	8

	1	2	3	4	5	6
C	2	2	4	7	7	8

	1	2	3	4	5	6	7	8
B							4''	

	1	2	3	4	5	6
C	2	2	4	6	7	8

	1	2	3	4	5	6	7	8
B		1'					4''	

	1	2	3	4	5	6
C	1	2	4	6	7	8

	1	2	3	4	5	6	7	8
B		1'				4'	4''	



- Example Cont...d

	1	2	3	4	5	6	7	8
A	3	6	4	1	3'	4'	1'	4''

	1	2	3	4	5	6
C	1	2	4	5	7	8

	1	2	3	4	5	6	7	8
B		1'		3'		4'	4''	

	1	2	3	4	5	6
C	1	2	3	5	7	8

	1	2	3	4	5	6	7	8
B	1	1'		3'		4'	4''	

	1	2	3	4	5	6
C	0	2	3	5	7	8

	1	2	3	4	5	6	7	8
B	1	1'		3'	4	4'	4''	

- Example Cont...d

	1	2	3	4	5	6	7	8
A	3	6	4	1	3'	4'	1'	4''

	1	2	3	4	5	6
C	0	2	3	4	7	8

	1	2	3	4	5	6	7	8
B	1	1'		3'	4	4'	4''	6

	1	2	3	4	5	6
C	0	2	3	4	7	7

	1	2	3	4	5	6	7	8
B	1	1'	3	3'	4	4'	4''	6

	1	2	3	4	5	6
C	0	2	2	4	7	7

<u>Output Array</u>		1	2	3	4	5	6	7	8
B	1	1'	3	3'	4	4'	4''	6	

# Running Time of Counting Sort

---

Running Time  $T(n) = O(k+n)$

Counting Sort beats the lower bound of  $\Omega(n \lg n)$  as it is not a comparison sort.

# Bucket Sort

---

- Bucket sort runs in linear time on the average.
- Bucket sort assumes that the inputs are uniformly distributed over the interval  $[0,1)$ .
- Basic idea:
  1. Divide the interval  $[0,1)$  into  $n$  equal-sized buckets.
  2. Distribute the  $n$  elements into the buckets.
  3. Sort the elements in each bucket.
  4. Concatenate the buckets in order.



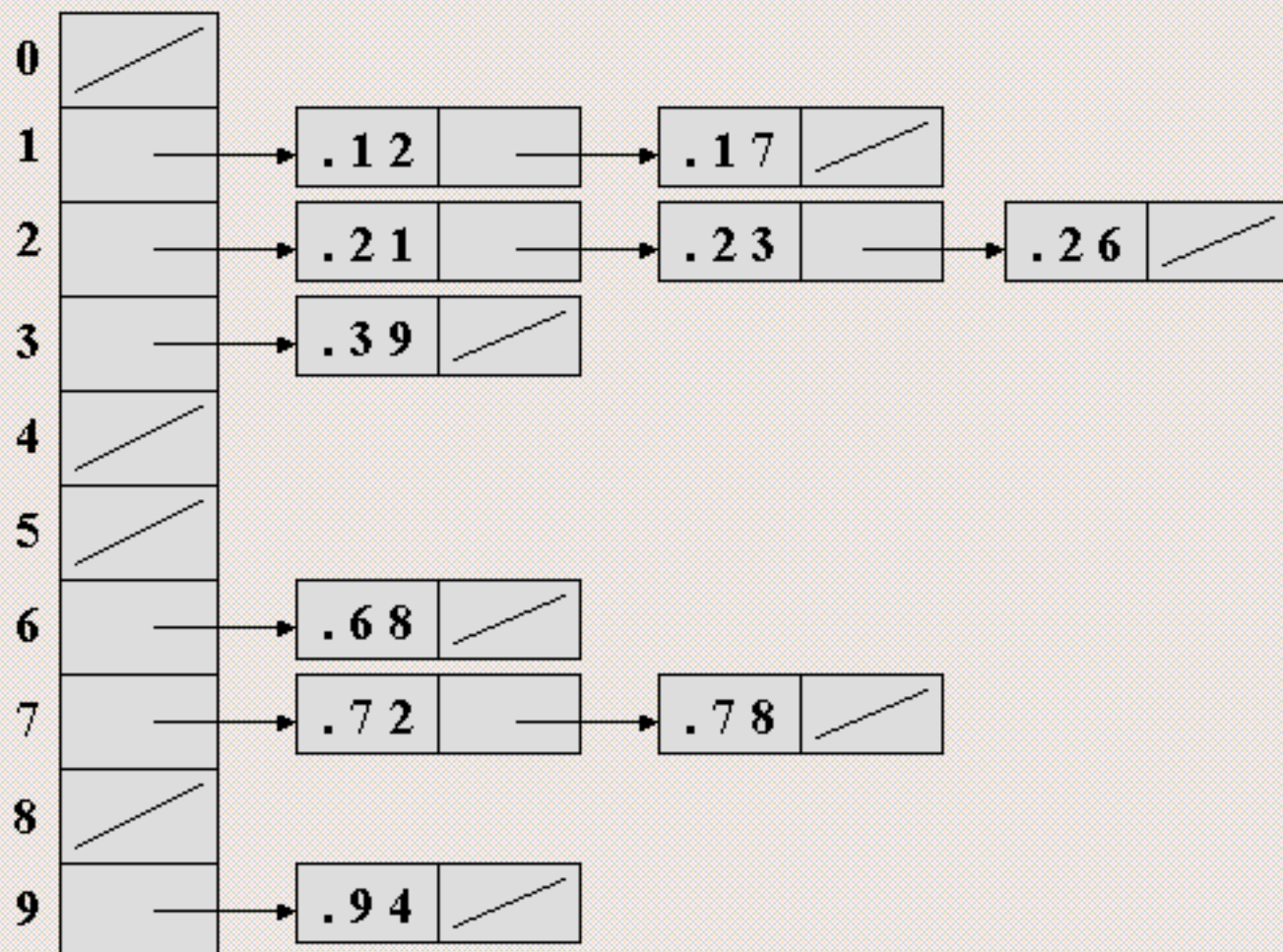
**N=10**

**Bucket  $i$  holds values in the interval  $[i/10, (i+1)/10]$**

**A**

. 7 8
. 1 7
. 3 9
. 2 6
. 7 2
. 9 4
. 2 1
. 1 2
. 2 3
. 6 8

**B**



# Pseudo Code

---

Bucket-Sort(A)

- 1  $n \leftarrow \text{length}[A]$
- 2 **for**  $i \leftarrow 1$  **to**  $n$
- 3     **do** insert  $A[i]$  into list  $B \lfloor \frac{nA[i]}{n} \rfloor$
- 4 **for**  $i \leftarrow 0$  **to**  $n - 1$
- 5     **do** sort list  $B[i]$  with insertion sort
- 6 concatenate the lists  $B[0], B[1], \dots, B[n-1]$  together in order

# Radix sort

---

This algorithm was used by old card-sorting machines.  
( computers, not Black Jack )

Sorting on the least significant digit first, then the second,...

Only  $d$  passes through the array are required to sort.  
 $d$ =the number of digits in every element

## Pseudocode:

---

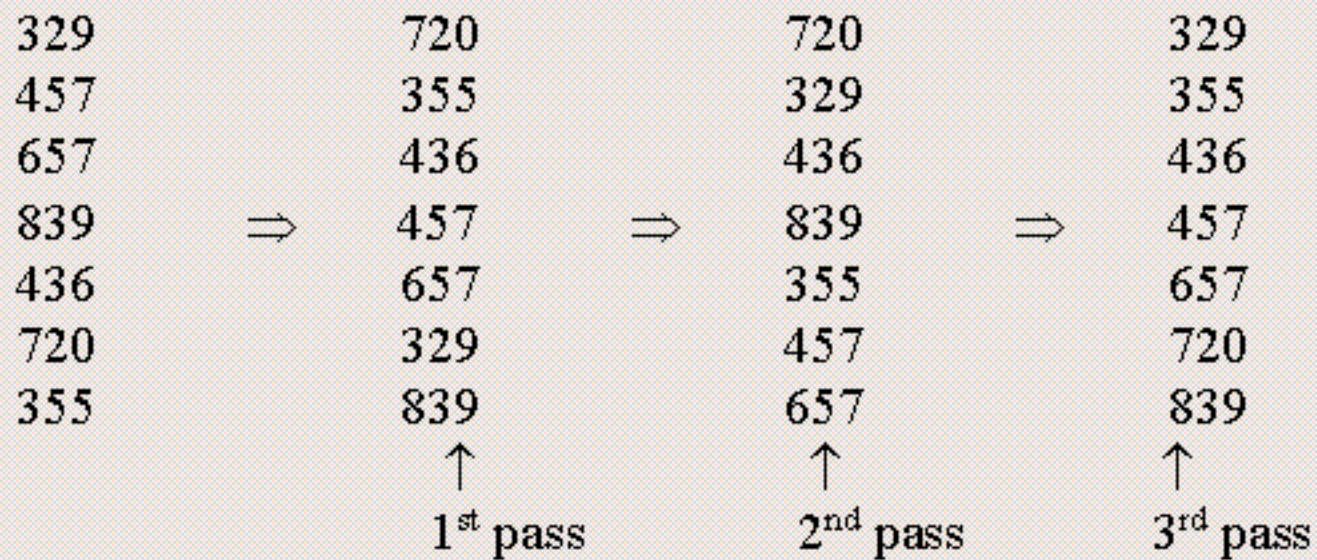
### Radix-Sort (A,d)

- 1 for  $i \leftarrow 1$  to  $d$
- 2     do use a stable sort to sort array A on digit  $i$



## Example:

---



## T(n): Running time

---

Consider d as a constant

- For d-digit number, every digit is in the range from 1 to k
- When k is not too large, use counting sort as the stable sort
- Running time = running time of stable sort  $\times$  d

$$T(n) = d \times \Theta(n+k) = \Theta(dn+dk)$$

k and d: constant

$$T(n) = \Theta(n)$$