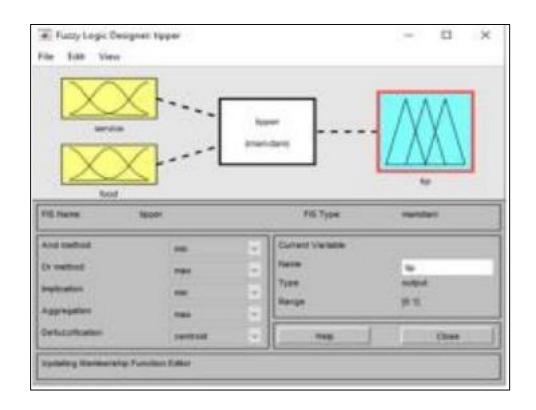
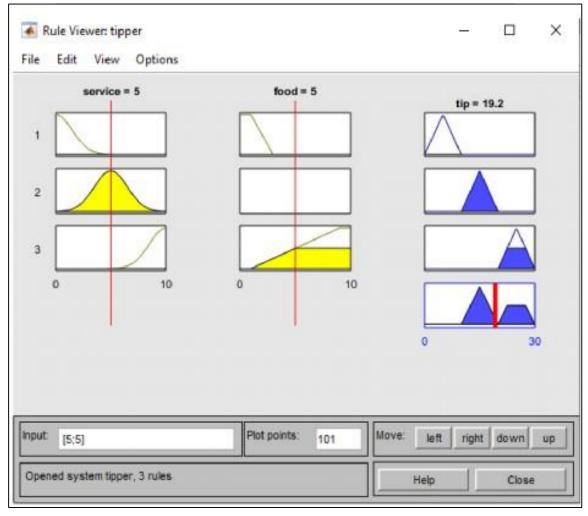
LAB SESSION 10

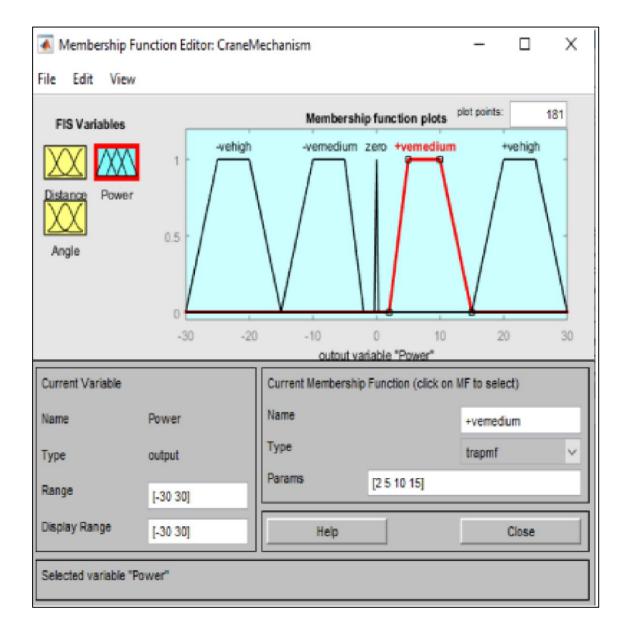
- 1) Implement the following rule set in matlab, to control the mechanism of a crane.
- IF Distance is far AND Angle is zero THEN apply pos medium Power
- IF Distance is far AND Angle is neg_small THEN apply pos_high Power
- IF Distance is medium AND Angle is neg small THEN apply pos high Power
- IF Distance is medium AND Angle is neg_big THEN apply pos_medium Power
- IF Distance is close AND Angle is pos_small THEN apply neg_medium Power ☐ IF Distance is close AND Angle is neg_small THEN apply pos_medium Power
- IF Distance is close AND Angle is zero THEN apply zero Power
- IF Distance is zero AND Angle is zero THEN apply zero Power
- IF Distance is zero AND Angle is pos_small THEN apply neg_medium Power ☐ Develop a fuzzy logic based application of your choice.

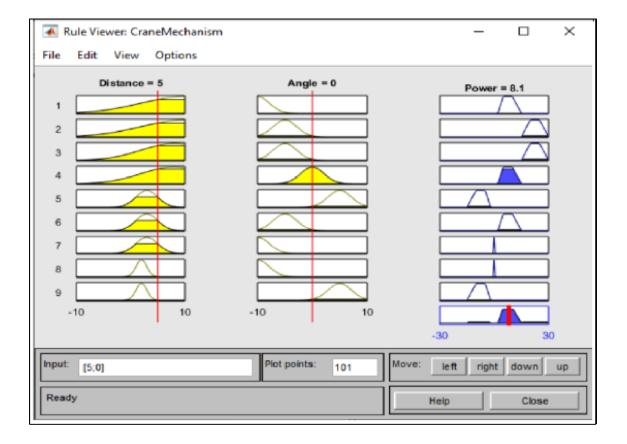
THE BASIC TIPPPING PROBLEM





2) Attach the screenshots of FIS editor, membership functions of all input & output parameters, rule editor and rule viewer.





- 3) Implement the following rule set in matlab, to control the mechanism of a fuzzy logic based washing machine.
- If clothe material is soft and status is clean then apply low power for less cycle time.
- If clothe material is soft and status is dirty then apply low power for long cycle time.
- If clothe material is medium and status is dirty then apply medium power for long cycle time.
- If clothe material is hard and status is clean then apply medium power for long cycle time.
- If clothe material is hard and status is dirty then apply high power for long cycle time.
- 4) Attach the screenshots of FIS editor, membership functions of all input & output parameters, rule

editor and rule viewer.

