

MicroKernel

v1.0.0

Table of contents

- [Overview](#)
- [Versions](#)
- [Main features](#)
- [Kernel interface](#)
 - [initKernel method](#)
 - [addThread method](#)
 - [startScheduler method](#)
- [Synchronization primitives](#)
 - [Mutex](#)
 - [Semaphore](#)
- [Simple Example](#)

Overview

MicroKernel is a simple kernel implementation for Cortex-M based microcontrollers. It provides concurrency and some synchronization primitives.

Versions

Table 1 - Library versions.

Version	Release date	What's new
1.0.0	08.02.2025	First version.

Main features

MicroKernel provides a few main concurrency features.

- Main concurrency implementation with a simple scheduler and context switching. Please see the section [kernel](#) for detailed information.
- Mutex for critical sections. Please see the the section [Mutex](#) for detailed information.
- Semaphore for critical sections. Please see the the section [Semaphore](#) for detailed information.

Following diagram shows main code flow of usage :

Kernel interface

Kernel interface is declared in **kernel.h** file.

```
/// Initialize kernel.
int initKernel(int maxNumberOfThreads);

/// Add new thread to kernel scheduler.
int addThread(void (*threadFunc)(), int stackSize);

/// Start scheduler.
int startScheduler(int periodMilliseconds);
```

initKernel method

Initializes the kernel. It is the function that should be called before all kernel related initializations including synchronization primitives creation.

```
int initKernel(int maxNumberOfThreads);
```

Parameter	Value
maxNumberOfThreads	Max number of thread. It is better to not give huge numbers because kernel will allocate thread control blocks as many as max thread number.

Returns: 0 if kernel initialized properly or -1 if there was an error.

addThread method

Adds new thread to kernel scheduler. Before calling **addThread()** please ensure that **initThread()** is executed properly.

```
int addThread(void (*threadFunc)(), int stackSize);
```

Parameter	Value
threadFunc	Function pointer to thread function.
stackSize	Required stack size in bytes for thread.

Returns: 0 if the thread is added properly or -1 if there was an error.

startScheduler method

After initialization of kernel and adding threads, it is ready to start scheduler to start concurrency for these added threads. Please note that **startScheduler** does not return in case of non error situation.

```
int startScheduler(int periodMilliseconds);
```

Parameter	Value
periodMilliseconds	Scheduler interval in milliseconds.

Returns: -1 if it is not started, in case of proper execution this function does not return.

Synchronization primitives

MicroKernel provides elementary synchronization primitives mutex and semaphore.

Mutex

Mutex interface is declared in **Mutex.h** file.

```
/// Create an instance.
Mutex_t* Mutex_create();

/// Destroy an instance.
void Mutex_destroy(Mutex_t *self);

/// Lock the mutex.
void Mutex_lock(Mutex_t *self);

/// Unlock the mutex.
void Mutex_unlock(Mutex_t *self);
```

Mutex_create method

Creates the instance of mutex.

```
Mutex_t* Mutex_create();
```

Returns: the address of created mutex or NULL in error.

Mutex_destroy method

Destroys the mutex instance.

```
void Mutex_destroy(Mutex_t *self);
```

Parameter	Value
self	Address of instance.

Mutex_lock

Locks the mutex. In case mutex already locked, it will block current thread from execution with a busy wait until the instance is unlock.

```
void Mutex_lock(Mutex_t *self);
```

Parameter	Value
self	Address of instance.

Mutex_unlock

Unlocks the locked mutex. If mutex is already unlock it will return directly.

```
void Mutex_unlock(Mutex_t *self);
```

Parameter	Value
self	Address of instance.

Semaphore

Semaphore interface is declared in **Semaphore.h** file.

```
/// Create an instance.
Semaphore_t* Semaphore_create(int32_t initialValue, uint32_t maxValue);

/// Destroy an instance.
void Semaphore_destroy(Semaphore_t *self);

/// Release the semaphore.
void Semaphore_release(Semaphore_t *self);

/// Acquire the semaphore.
void Semaphore_acquire(Semaphore_t *self);
```

Semaphore_create method

Creates the semaphore instance.

```
Semaphore_t* Semaphore_create(int32_t initialValue, uint32_t maxValue);
```

Parameter	Value
initialValue	Initial value of semaphore.
maxValue	Max value of semaphore.

Returns: the address of created semaphore or NULL in error.

Semaphore_destroy method

Destroys the semaphore instance.

```
void Semaphore_destroy(Semaphore_t *self);
```

Semaphore_release method

Releases the semaphore. It will wake all threads waiting related semaphore. After waking up threads, it will directly force to scheduler choose new thread.

```
void Semaphore_release(Semaphore_t *self);
```

Parameter	Value
self	Address of instance.

Semaphore_acquire method

Acquires the semaphore. If related semaphore has value 0, this will put current thread to sleep unlike mutex implementation semaphore implementation wont make any busy wait. Sleeping thread will be waken up when semaphore value is bigger than 0.

Parameter	Value
self	Address of instance.

Simple example

Following code shows simplest example for **MicroKernel** usage. It implements single producer single consumer multi threaded application scenario.

```
#include "kernel.h"
#include "Mutex.h"
#include "Semaphore.h"

#define THREAD_STACK_SIZE_BYTES 100
#define MAX_NUM_THREAD 10
#define SCHEDULAR_PERIOD_MS 10

uint32_t g_sharedData = 0;
Mutex_t *g_sharedDataMutex = NULL;
Semaphore_t *g_dataAvailableSem = NULL;

void producerThreadFunc()
{
    while (1)
    {
        Mutex_lock(g_sharedDataMutex);
        g_sharedData++;
    }
}
```

```

    Mutex_unlock(g_sharedDataMutex);

    // Signal that new data is available
    Semaphore_release(g_dataAvailableSem);
}
}

void consumerThreadFunc()
{
    uint32_t readValue = 0;
    while (1)
    {
        // wait until data is available
        Semaphore_acquire(g_dataAvailableSem);

        Mutex_lock(g_sharedDataMutex);
        readValue = g_sharedData;
        Mutex_unlock(g_sharedDataMutex);
    }
}

int main(void)
{
    initKernel(MAX_NUM_THREAD);

    g_sharedDataMutex = Mutex_create();

    g_dataAvailableSem = Semaphore_create(0, 1); // Initial value 0, max value 1.

    addThread(producerThreadFunc, THREAD_STACK_SIZE_BYTES);
    addThread(consumerThreadFunc, THREAD_STACK_SIZE_BYTES);

    startScheduler(SCHEDULAR_PERIOD_MS);

    return 0; // Code execution never reaches here
}

```