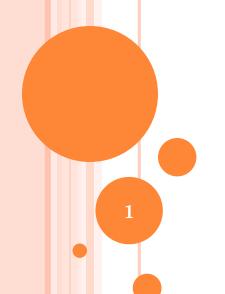
# OBSTRUCTIONS IN VESSELS IN FUNDUS IMAGES



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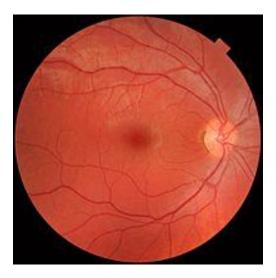
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## INTRODUCTION

- What is the Fundus Image?
  - Representation of interior surface of the eye
  - Fundus image is obtained by taking a photo of the vessels with the fundus camera



## **MOTIVATION**

- Developing accurate software to reduce doctor effort.
- Preventing the retinal emboli-induced illnesses.
- Main application area is the hospital

## PREVIOUS STUDIES

- Unfortunately, there is no software which has a similar purpose with this project.
- There are some methods for the segmentation part;
  - Ant Colony System Algorithm
  - Image Matting Technique
  - Gabor Filter Method

## PURPOSE OF THE PROJECT

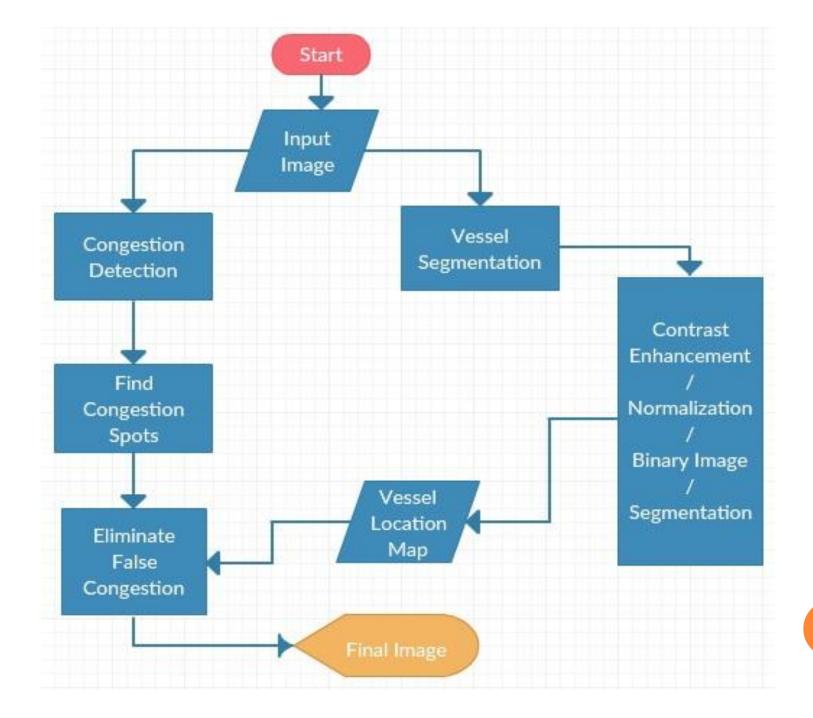
- Find the congestion spots
- Eliminate the human error

#### PROBLEM

• Obstructions are most likely to be small spots which are hard to detect

 Even a slightest mistake can lead bigger problems

- Our algorithm to find a solution for the problems mentioned above divided into 2 parts;
  - 1. Segmentation Part
  - 2. Congestion Detection Part

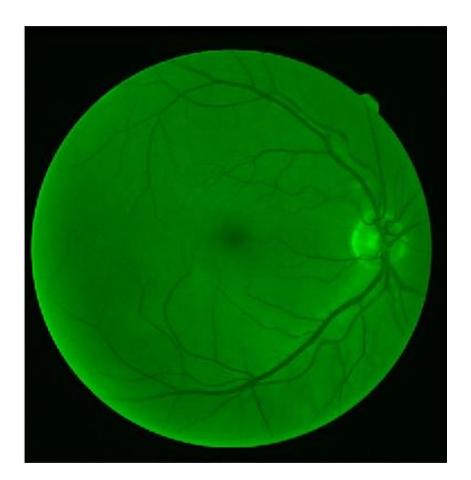


- Segmentation Part
  - Simply increases our project's accuracy and precision
  - After the segmentation process is done, congestion detection process just matches the congestion spots with the vessel locations.

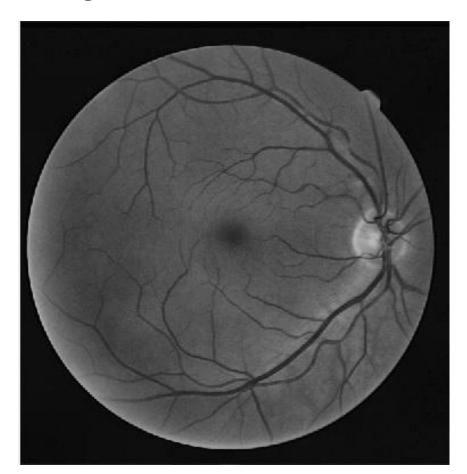
Solution will be explained shortly.

- Contrast Enhancement
  - Segmentation process starts with enhancing the image. Firstly, green channel is extracted then, gray scale of the image is extracted.
  - Green channel is considered to be best among the other channels. It has the least noise in it and shows vessels much more properly.

• Green Channel Image



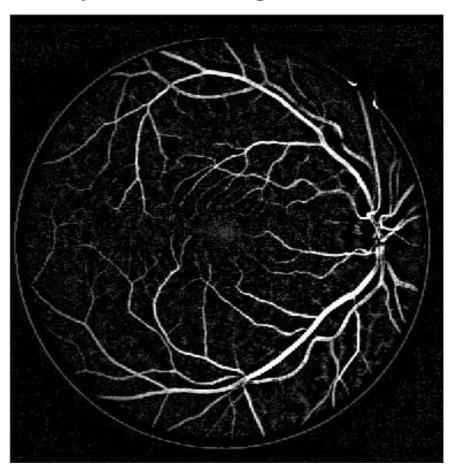
o Gray Scale Image



#### Normalization

- This process is here to get the maximum amount of quality in the fundus image possible.
- After normalization process, gray scale of the image is extracted.

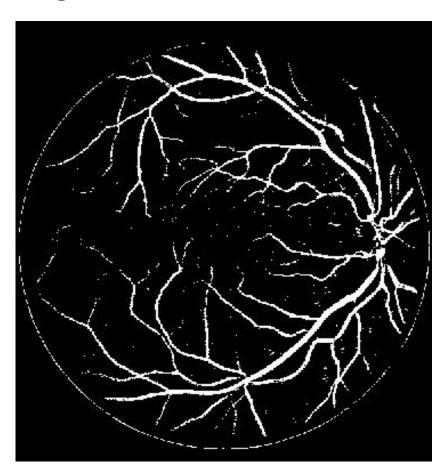
Normalized Gray Scale Image



#### Binarization

• In this step, we get the binarized version of the normalized image in this process. Later on this image is sent to the segmentation process to extract vessel location map consisting of 1's and 0's.

Binarized Image



- Congestion Detection Part
  - Defines the main purpose of our project



- Congestion Detection Part
  - Not all of the spots declared as congestion are actually congestion points.
  - There may be some noise interfering the input image.
  - Noise in the input image can be confused with congestion points.
  - In order to eliminate this, our project simply matches each of the congestion spots coordinates with the vessel location map.

## FUTURE WORK

#### • Feedback Mechanism

• Simply allows the doctor to check if found congestion spots are actually congestion spots or not.

#### Automatic Diagnosis

• Software will rate the current status of the patient by checking the number of congestions in the retinal image and predicts a diagnosis.

#### REFERENCES

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## THANK YOU FOR LISTENING!

