

Implementation of Φ_1 in SFINCS

January 29, 2016

EUTERPE old equations vs new equations

We want to modify the implementation of the old EUTERPE equations [1] in SFINCS to the new equations [2].

The old equations for the particle trajectories and the drift-kinetic equation are

$$\dot{\mathbf{R}} = v_{\parallel} \mathbf{b} - \frac{\nabla \Phi_0 \times \mathbf{b}}{B} \quad (1)$$

$$\dot{v}_{\parallel} = -\frac{q}{m} \mathbf{b} \cdot \nabla \Phi_1 - \mu \mathbf{b} \cdot \nabla B - \frac{v_{\parallel}}{B^2} (\mathbf{b} \times \nabla B) \cdot \nabla \Phi_0 \quad (2)$$

$$\dot{\mu} = 0 \quad (3)$$

and

$$\begin{aligned} & \frac{\partial f_1}{\partial t} + \dot{\mathbf{R}} \cdot \nabla f_1 + \dot{v}_{\parallel} \frac{\partial f_1}{\partial v_{\parallel}} - C = \\ & = -f_M \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] (\mathbf{v}_d + \mathbf{v}_{E1}) \cdot \nabla \psi - \frac{q}{m} \frac{f_M}{v_{\text{th}}^2} (v_{\parallel} \mathbf{b} + \mathbf{v}_d) \cdot (\nabla \Phi_0 + \nabla \Phi_1). \end{aligned} \quad (4)$$

The new equations are

$$\dot{\mathbf{R}} = v_{\parallel} \mathbf{b} - \frac{\nabla \Phi_0 \times \mathbf{b}}{B} \quad (5)$$

$$\dot{v}_{\parallel} = -\frac{q}{m} \mathbf{b} \cdot \nabla \Phi_1 - \mu \mathbf{b} \cdot \nabla B - \frac{v_{\parallel}}{B^2} (\mathbf{b} \times \nabla B) \cdot \nabla \Phi_0 \quad (6)$$

$$\dot{\mu} = 0 \quad (7)$$

and

$$\begin{aligned} & \frac{\partial f_1}{\partial t} + \dot{\mathbf{R}} \cdot \nabla f_1 + \dot{v}_{\parallel} \frac{\partial f_1}{\partial v_{\parallel}} - C = \\ & = -f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} + \frac{q}{T} \Phi_1 \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] (\mathbf{v}_d + \mathbf{v}_{E1}) \cdot \nabla \psi. \end{aligned} \quad (8)$$

Here we have the definitions

$$\Phi(\psi, \theta, \varphi) \equiv \Phi_0(\psi) + \Phi_1(\theta, \varphi), \quad (9)$$

$$\mathbf{v}_d = \frac{m}{q} \frac{\mu B + v_{\parallel}^2}{B^2} \mathbf{b} \times \nabla B, \quad (10)$$

$$\mathbf{v}_{E1} = -\frac{\nabla \Phi_1 \times \mathbf{b}}{B}, \quad (11)$$

$$f_0 = f_M \exp(-q\Phi_1/T) = \frac{n_0(\psi)}{(2\pi)^{3/2} v_{\text{th}}^3} \exp\left[-\frac{(v_{\parallel}^2 + v_{\perp}^2)}{2v_{\text{th}}^2}\right] \exp(-q\Phi_1/T), \quad (12)$$

$$q = Ze \text{ and } v_{\text{th}}^2 = T/m.$$

The only differences appear in the RHS:s of Eqs. 4 and 8:

Firstly, f_M has been replaced by f_0 containing the $\exp(-q\Phi_1/T)$ factor.

Secondly, some of the terms have been modified. We rewrite the RHS of 8:

$$\begin{aligned} \text{RHS}_{\text{NEW}} &= -f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} + \frac{q}{T} \Phi_1 \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] (\mathbf{v}_d + \mathbf{v}_{E1}) \cdot \nabla \psi = \\ &= -f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] (\mathbf{v}_d + \mathbf{v}_{E1}) \cdot \nabla \psi + \\ &\quad - f_0 \frac{q}{T} \Phi_1 \frac{1}{T} \frac{\partial T}{\partial \psi} (\mathbf{v}_d + \mathbf{v}_{E1}) \cdot \nabla \psi = \\ &= -f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_d \cdot \nabla \psi + \\ &\quad - f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_{E1} \cdot \nabla \psi - f_0 \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} \mathbf{v}_{E1} \cdot \nabla \psi + \\ &\quad - f_0 \frac{q}{T} \Phi_1 \frac{\nabla T}{T} \cdot (\mathbf{v}_d + \mathbf{v}_{E1}) = \\ &= -f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_d \cdot \nabla \psi + \\ &\quad - f_0 \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_{E1} \cdot \nabla \psi + \\ &\quad - f_0 \frac{q}{T} \left[\nabla \Phi_0 \cdot \mathbf{v}_{E1} + \Phi_1 \frac{\nabla T}{T} \cdot \mathbf{v}_d + \Phi_1 \frac{\nabla T}{T} \cdot \mathbf{v}_{E1} \right]. \quad (13) \end{aligned}$$

Similarly, the RHS of 4 is rewritten as:

$$\begin{aligned} \text{RHS}_{\text{OLD}} &= -f_M \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] (\mathbf{v}_d + \mathbf{v}_{E1}) \cdot \nabla \psi - \frac{q}{m} \frac{f_M}{v_{\text{th}}^2} (v_{\parallel} \mathbf{b} + \mathbf{v}_d) \cdot (\nabla \Phi_0 + \nabla \Phi_1) = \\ &= -f_M \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_d \cdot \nabla \psi + \\ &\quad -f_M \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_{E1} \cdot \nabla \psi + \\ &\quad -f_M \frac{q}{T} [v_{\parallel} \mathbf{b} \cdot \nabla \Phi_1 + \mathbf{v}_d \cdot \nabla \Phi_1]. \quad (14) \end{aligned}$$

Comparing RHS_{NEW} to RHS_{OLD} we see that, apart from $f_M \rightarrow f_0$, only the terms in red have changed.

Implementation in SFINCS

The only part of the drift-kinetic equation block we need to modify is the RHS, where we need to update the red terms and substitute $f_M \rightarrow f_0$. SFINCS had earlier neglected the $\mathbf{v}_d \cdot \nabla \Phi_1$ -term which is small in the standard ρ_* -expansion. The RHS that was implemented is (see Matt's ISHW poster, also note that $\mathbf{v}_E \cdot \nabla \psi = \mathbf{v}_{E1} \cdot \nabla \psi$)

$$\begin{aligned} \text{RHS}_{\text{SFINCS,OLD}} &= -f_M \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \frac{q}{T} \frac{\partial \Phi_0}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_d \cdot \nabla \psi + \\ &\quad -f_M \left[\frac{1}{n} \frac{\partial n}{\partial \psi} + \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \frac{1}{T} \frac{\partial T}{\partial \psi} \right] \mathbf{v}_E \cdot \nabla \psi - f_M \frac{q}{T} v_{\parallel} \mathbf{b} \cdot \nabla \Phi_1. \quad (15) \end{aligned}$$

We thus replace

$$v_{\parallel} \mathbf{b} \cdot \nabla \Phi_1 \quad (16)$$

with

$$\nabla \Phi_0 \cdot \mathbf{v}_E + \Phi_1 \frac{\nabla T}{T} \cdot \mathbf{v}_d + \Phi_1 \frac{\nabla T}{T} \cdot \mathbf{v}_E, \quad (17)$$

and make the substitution

$$f_M \rightarrow f_0 = f_M \exp(-q\Phi_1/T). \quad (18)$$

REMARK: In EUTERPE Φ_1 is only an unknown in the quasi-neutrality equation, in the kinetic equation it is an input which means that there are no nonlinearities. It also means that the exponential in f_0 is not expanded in the kinetic equation. Are all terms in Eq. 17 feasible to implement in SFINCS? E.g. is it a problem that the $\Phi_1 \frac{\nabla T}{T} \cdot \mathbf{v}_E$ -term contains 3 factors with Φ_1 ?

REMARK: Because of f_0 it seems as all terms which contain Φ_1 are now nonlinear. Does it make sense to have both switches includePhi1 and nonlinear available in SFINCS?

Quasi-neutrality equation

In EUTERPE Φ_1 is calculated from quasi-neutrality by expanding the exponential, assuming adiabatic electrons and neglecting the impurities:

$$n_s = n_{s0}(\psi) \exp(-q_s \Phi_1 / T_s) + n_{s1}, \quad (19)$$

$$\sum_s Z_s n_s = 0, \quad (20)$$

$$\Rightarrow 0 \simeq \sum_s Z_s [n_{s0} (1 - q_s \Phi_1 / T_s) + n_{s1}] \Leftrightarrow$$

$$\sum_s Z_s [n_{s0} + n_{s1}] = \sum_s \frac{Z_s^2 e}{T_s} \Phi_1 n_{s0}.$$

Since $n_{s0}(\psi)$ is obtained by integrating the Maxwellian f_{Ms} over velocity space we must have

$$\sum_s Z_s n_{s0} = 0,$$

which yields

$$\sum_s Z_s n_{s1} - \Phi_1 \sum_s \frac{Z_s^2 e}{T_s} n_{s0} = 0. \quad (21)$$

With kinetic ions, adiabatic electrons ($n_{e1} = 0$) and neglecting impurities we obtain

$$\Phi_1 = \frac{T_e}{e} \left[\frac{T_e}{T_i} n_{i0} + n_{e0} \right]^{-1} n_{i1}. \quad (22)$$

Implementation in SFINCS

For a first benchmark, we want to implement the same equations as EUTERPE in SFINCS.

REMARK: This is not a very generic quasi-neutrality equation so it is possible that we might want to change it in SFINCS later.

In the code we add an adiabatic species which only enters into the quasi-neutrality equation, and neglect its collisional impact on the kinetic species (the effect of ion-electron collisions is small compared to ion-ion collisions). Moreover, we will only consider the first of the kinetic species in quasi-neutrality and neglect the rest. This is implemented by modifying the LHS of the row corresponding to quasi-neutrality in the block-matrix structure of Matt's ISHW poster, adding the adiabatic term to the Φ_1 -column and removing all kinetic species except the first.

REMARK: It feels a bit weird to remove species from quasi-neutrality, even if the impurity density is small. Does this mean that we should removed the check that the input densities are quasi-neutral and instead check that $n_{i0}(\psi) = n_{e0}(\psi)$ in the input?

The equation we will implement in SFINCS is thus

$$Z_i n_{i1} - \Phi_1 \left[\frac{Z_i^2 e}{T_i} n_{i0} + \frac{Z_e^2 e}{T_e} n_{e0} \right] = 0. \quad (23)$$

We note that

$$n_s = n_{s0}(\psi) \exp(-q_s \Phi_1/T_s) + n_{s1} = \int d^3v f_{Ms} \exp(-q_s \Phi_1/T_s) + \int d^3v f_{1s} = d^3v f_{0s} + d^3v f_{1s}. \quad (24)$$

The velocity integration in SFINCS is done in $(x, \xi) = (v/v_s, v_{\parallel}/v)$, and

$$\int d^3v = 2\pi v_s^3 \int_0^\infty dx x^2 \int_{-1}^1 d\xi \quad (25)$$

(note that $v_s^2 = 2T_s/m_s$ differs from Jose's notation $v_{\text{th}}^2 = T/m$). Using SFINCS normalizations $n_s = \bar{n}\hat{n}_s$, $T_s = \bar{T}\hat{T}_s$, $v_s/\bar{v} = \sqrt{\hat{T}_s/\hat{m}_s}$, $f_s = \bar{n}\hat{f}_s/\bar{v}^3$, we find

$$\hat{n}_s = 2\pi \left(\hat{T}_s/\hat{m}_s\right)^{3/2} \int_0^\infty dx x^2 \int_{-1}^1 d\xi \hat{f}_s. \quad (26)$$

Also using $\Phi_1 = \bar{\Phi}\hat{\Phi}_1$ and $\alpha = e\bar{\Phi}/\bar{T}$ we can write Eq. 23

$$Z_i \hat{n}_{i1} - \alpha \hat{\Phi}_1 \left[\frac{Z_i^2}{\hat{T}_i} \hat{n}_{i0} + \frac{Z_e^2}{\hat{T}_e} \hat{n}_{e0} \right] = 0 \quad (27)$$

and finally obtain

$$\left[2\pi Z_i \left(\hat{T}_i/\hat{m}_i\right)^{3/2} \int_0^\infty dx x^2 \int_{-1}^1 d\xi \hat{f}_{i1} \right] - \alpha \hat{\Phi}_1 \left[\frac{Z_i^2}{\hat{T}_i} \hat{n}_{i0} + \frac{Z_e^2}{\hat{T}_e} \hat{n}_{e0} \right] = 0. \quad (28)$$

This is the equation we will implement in the code, but adding a λ to make the system square.

REMARK: Is the 2π factor correct in Eq. 28? It is not in the former implementation of quasi-neutrality, but in that situation it could be divided away.

References

- [1] J. M. García-Regaña, R. Kleiber, C. D. Beidler, Y. Turkin, H. Maaßberg and P. Helander, *Plasma Phys. Control. Fusion* **55** (2013) 074008.
- [2] J. M. García-Regaña, C. D. Beidler, Y. Turkin, R. Kleiber, P. Helander, H. Maaßberg, J. A. Alonso and J. L. Velasco, *arXiv:1501.03967* (2015).
- [3] Landreman M, Smith H M, Mollén A and Helander P 2014 *Phys. Plasmas* **21** 042503