NTV

Consider the momentum equation summed over species,

$$\mathbf{J} \times \mathbf{B} - \nabla \cdot \mathbf{P} = \nabla \cdot (\rho \mathbf{V} \mathbf{V}) + \frac{\partial (\rho \mathbf{V})}{\partial t}.$$
 (1)

We write

$$B = B_0 + B_1, \tag{2}$$

$$J = J_0 + J_1, \tag{3}$$

$$\mathbf{P} = p_0(\psi)\mathbf{I} + p_1(\psi)\mathbf{I} + \mathbf{\Pi},\tag{4}$$

where

$$\mathbf{J}_0 \times \mathbf{B}_0 = p_0'(\psi) \nabla \psi. \tag{5}$$

Subtracting Eq. (5) from Eq. (1), we obtain

$$\frac{\partial \rho \mathbf{V}}{\partial t} = \mathbf{J}_1 \times \mathbf{B}_0 + \mathbf{J}_0 \times \mathbf{B}_1 - \nabla p_1 - \nabla \cdot (\rho \mathbf{V} \mathbf{V} + \mathbf{M} + \mathbf{\Pi}). \tag{6}$$

where we have used the vector identity $\nabla B_1^2 = 2\mathbf{B}_1 \cdot \nabla \mathbf{B}_1 + 2\mathbf{B}_1 \times \nabla \times \mathbf{B}_1$ to write $\mathbf{J}_1 \times \mathbf{B}_1 = -\nabla \cdot \mathbf{M}$, with

$$\mathbf{M} = \frac{1}{\mu_0} \left(\frac{1}{2} B_1^2 \mathbf{I} - \mathbf{B}_1 \mathbf{B}_1 \right). \tag{7}$$

The two components of Eq. (6) in the directions along B_0 and J_0 are particularly interesting as we shall see, because several terms disappear upon taking the flux surface average. Observe that

$$\langle \boldsymbol{B}_0 \cdot \boldsymbol{J}_0 \times \boldsymbol{B}_1 \rangle = \langle \boldsymbol{B}_1 \cdot \nabla p_0 \rangle = -\langle (\nabla \times \boldsymbol{A}_1) \cdot \nabla p_0 \rangle = \langle \nabla \cdot (\nabla p_0 \times \boldsymbol{A}_1) \rangle = 0,$$
 (8)

$$\langle \boldsymbol{J}_0 \cdot \boldsymbol{J}_1 \times \boldsymbol{B}_0 \rangle = -\langle \boldsymbol{J}_1 \cdot \nabla p_0 \rangle = \frac{1}{\mu_0} \langle (\nabla \times \boldsymbol{B}_1) \cdot \nabla p_0 \rangle = -\langle \nabla \cdot (\nabla p_0 \times \boldsymbol{B}_1) \rangle = 0, \quad (9)$$

$$\langle \boldsymbol{B}_0 \cdot \nabla p_1 \rangle = \langle \nabla \cdot (\boldsymbol{B}_0 p_1) \rangle = 0,$$
 (10)

$$\langle \mathbf{J}_0 \cdot \nabla p_1 \rangle = \langle \nabla \cdot (\mathbf{J}_0 p_1) \rangle = 0 \tag{11}$$

if we neglect the displacement current. The flux surface average of the scalar product of Eq. (6) with B_0 and J_0 yields

$$\frac{\partial \langle \rho \mathbf{V} \cdot \mathbf{B}_0 \rangle}{\partial t} = -\langle \nabla \cdot (\rho \mathbf{V} \mathbf{V} + \mathbf{M} + \mathbf{\Pi}) \cdot \mathbf{B}_0 \rangle, \qquad (12)$$

$$\frac{\partial \langle \rho \mathbf{V} \cdot \mathbf{J}_0 \rangle}{\partial t} = -\langle \nabla \cdot (\rho \mathbf{V} \mathbf{V} + \mathbf{M} + \mathbf{\Pi}) \cdot \mathbf{J}_0 \rangle.$$
 (13)

Consequently, the same type of expression also holds for any linear combination $L = \alpha B_0 + \beta J_0$ of B_0 and J_0 ,

$$\frac{\partial \langle \rho \mathbf{V} \cdot \mathbf{L} \rangle}{\partial t} = -\langle \nabla \cdot (\rho \mathbf{V} \mathbf{V} + \mathbf{M} + \mathbf{\Pi}) \cdot \mathbf{L} \rangle \tag{14}$$

Axisymmetry

In axisymmetry we can express \boldsymbol{B} and \boldsymbol{J} as

$$\mathbf{B}_0 = F(\psi)\nabla\phi + \nabla\phi \times \nabla\psi, \tag{15}$$

$$\mathbf{J}_0 = -p_0'(\psi)\frac{\partial \mathbf{r}}{\partial \phi} + K(\psi)\mathbf{B}_0, \tag{16}$$

where ϕ is the geometrical toroidal angle. The flux surface average of the parallel component of Eq. (16) gives us $K(\psi) = (\langle \mathbf{J}_0 \cdot \mathbf{B}_0 \rangle + p_0' F)/\langle B^2 \rangle$. We are interessed in the toroidal torque on the plasma, so in Eq. (14) we chose

$$\mathbf{L} = R\hat{\phi} = \frac{\partial \mathbf{r}}{\partial \phi} = -\frac{1}{p_0'} \mathbf{J}_0 + \frac{K}{p_0'} \mathbf{B}_0 \tag{17}$$

Non-axisymmetry

For any 3D magnetic configuration, we would now like to define a generalised vector \mathbf{L} , which in the limit of axisymmetry becomes $R\hat{\phi}$. One way to ensure that this limit is satisfied is to require the streamlines of \mathbf{L} to close on themselves toroidally. This also makes sense because we are not interested in any net poloidal torque component.

In Hamada coordinates (V, ϑ, φ) , the streamlines of both \mathbf{B}_0 and \mathbf{J}_0 are straight, i.e. \mathbf{B}_0 and \mathbf{J}_0 are linear combinations of $\partial \mathbf{r}/\partial \vartheta$ and $\partial \mathbf{r}/\partial \varphi$. The sought linear combination of \mathbf{B}_0 and \mathbf{J}_0 whose streamlines close on themselves toroidally is thus $\mathbf{e}_{\varphi} = \partial \mathbf{r}/\partial \varphi$. Because of the above mentioned reasons, \mathbf{e}_{φ} becomes parallel to $\hat{\phi}$ in the limit of axisymmetry (note that $\nabla \varphi$ does not become parallel to $\hat{\phi}$). Therefore, since $\nabla \cdot \mathbf{e}_{\varphi} = 0$ and $\nabla \cdot R\hat{\phi} = 0$, we conclude that $\mathbf{e}_{\varphi} \to cR\hat{\phi}$, and the constant c = 1 because φ and φ are both 2π periodic.

We now want to determine the constants α and β in $L = e_{\varphi} = \alpha B_0 + \beta J_0$. In Hamada coordinates, we can express B_0 and J_0 as

$$\mathbf{B}_{0} = \nabla \psi \times \nabla \vartheta + \iota(\psi) \nabla \varphi \times \nabla \psi = I(\psi) \nabla \vartheta + G(\psi) \nabla \varphi + \nabla H(\psi, \vartheta, \varphi), \tag{18}$$

$$\mathbf{J}_0 = I'(\psi)\nabla\psi \times \nabla\vartheta - G'(\psi)\nabla\varphi \times \nabla\psi. \tag{19}$$

Moreover, the Jacobian is a flux function, so

$$V'(\psi) = \int_{0}^{2\pi} d\vartheta \int_{0}^{2\pi} d\varphi \frac{1}{\nabla \psi \cdot \nabla \vartheta \times \nabla \varphi} = \frac{4\pi^{2}}{\nabla \psi \cdot \nabla \vartheta \times \nabla \varphi}$$
(20)

$$e_{\varphi} = \frac{\nabla \psi \times \nabla \vartheta}{\nabla \psi \cdot \nabla \vartheta \times \nabla \varphi} = \frac{V'}{4\pi^2} \nabla \psi \times \nabla \vartheta,$$
 (21)

and equilibrium implies

$$\mathbf{J}_0 \times \mathbf{B}_0 = -\frac{1}{\mu_0} (\iota I' + G')(\nabla \psi \cdot \nabla \vartheta \times \nabla \varphi) \nabla \psi = p_0' \nabla \psi$$
 (22)

$$\iota I' + G' = -\frac{V'}{4\pi^2} \mu_0 p_0' \tag{23}$$

The equation $\boldsymbol{e}_{\varphi} = \alpha \boldsymbol{B}_0 + \beta \boldsymbol{J}_0$ becomes

$$\frac{V'}{4\pi^2}\nabla\psi\times\nabla\vartheta = \alpha\left(\nabla\psi\times\nabla\vartheta + \iota\nabla\varphi\times\nabla\psi\right) + \beta\left(I'\nabla\psi\times\nabla\vartheta - G'\nabla\varphi\times\nabla\psi\right) \tag{24}$$

yielding

$$\alpha = \frac{4\pi^2}{V'} \frac{G'}{G' + \iota I'} = -\mu_0 p_0' \frac{G'}{(G' + \iota I')^2}, \tag{25}$$

$$\beta = \frac{4\pi^2}{V'} \frac{\iota}{G' + \iota I'} = -\mu_0 p_0' \frac{\iota}{(G' + \iota I')^2}, \tag{26}$$

i.e.,

$$\boldsymbol{e}_{\varphi} = -\frac{\mu_0 p_0'}{(G' + \iota I')^2} \left(\iota \boldsymbol{J}_0 + G' \boldsymbol{B}_0 \right). \tag{27}$$

Note that in the expressions for α and β , the flux functions $G(\psi)$ and $I(\psi)$ are the same as in Boozer coordinates (ψ, θ, ζ) , where

$$\boldsymbol{B}_0 = \nabla \psi \times \nabla \theta + \iota \nabla \zeta \times \nabla \psi = I(\psi) \nabla \theta + G(\psi) \nabla \zeta + \kappa(\psi, \theta, \zeta) \nabla \psi. \tag{28}$$

The toroidal viscosity

We now turn our attention to the toroidal viscosity term in Eq. (14),

$$\langle \boldsymbol{e}_{\varphi} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle = \alpha \langle \boldsymbol{B} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle + \beta \langle \boldsymbol{J} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle. \tag{29}$$

where we have dropped the index 0 on \boldsymbol{B}_0 , \boldsymbol{J}_0 and p_0 . First, we note that $\boldsymbol{\Pi} = \tilde{p}(\mathbf{I}/3 - B^{-2}\boldsymbol{B}\boldsymbol{B})$, where $\tilde{p} \equiv p_{\perp} - p_{\parallel}$, which implies that

$$\nabla \cdot \mathbf{\Pi} = \frac{1}{3} \nabla \tilde{p} - \nabla \frac{\tilde{p}}{B^2} \cdot \mathbf{B} \mathbf{B} - \tilde{p} \left(B^{-1} \nabla B + \frac{\mu_0}{B^2} \nabla p \right)$$
 (30)

$$\boldsymbol{B} \cdot \nabla \cdot \boldsymbol{\Pi} = -\frac{2}{3} \boldsymbol{B} \cdot \nabla \tilde{p} + \frac{\tilde{p}}{B} \nabla B \tag{31}$$

$$\langle \boldsymbol{B} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle = \langle \tilde{p} \nabla_{\parallel} B \rangle \tag{32}$$

$$\langle \boldsymbol{J} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle = -\left\langle J_{\parallel} B \boldsymbol{B} \cdot \nabla \frac{\tilde{p}}{B^2} \right\rangle - \left\langle \frac{\tilde{p}}{B} \boldsymbol{J} \cdot \nabla B \right\rangle$$
 (33)

In the last expression, we can replace \boldsymbol{J} with $\boldsymbol{J} = J_{\parallel} B^{-1} \boldsymbol{B} + p' B^{-2} (\boldsymbol{B} \times \nabla \psi)$ where $\nabla \cdot \boldsymbol{J} = 0$ gives $\boldsymbol{B} \cdot \nabla (J_{\parallel}/B) = 2p' B^{-3} \boldsymbol{B} \times \nabla \psi \cdot \nabla B$. If we also use that $\langle a\boldsymbol{B} \cdot \nabla b \rangle = -\langle b\boldsymbol{B} \cdot \nabla a \rangle$, we can write

$$\langle \boldsymbol{J} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle = \left\langle \frac{\tilde{p}}{B^{2}} \boldsymbol{B} \cdot \nabla (J_{\parallel} B) \right\rangle - \left\langle \frac{\tilde{p}}{B^{2}} J_{\parallel} \boldsymbol{B} \cdot \nabla B \right\rangle - p' \left\langle \frac{\tilde{p}}{B^{3}} \boldsymbol{B} \times \nabla \psi \cdot \nabla B \right\rangle =$$

$$= \left\langle \frac{\tilde{p}}{B^{2}} J_{\parallel} \boldsymbol{B} \cdot \nabla B \right\rangle + p' \left\langle \frac{\tilde{p}}{B^{3}} \boldsymbol{B} \times \nabla \psi \cdot \nabla B \right\rangle =$$

$$= \frac{1}{2} \left\langle \frac{\tilde{p}}{B^{2}} \boldsymbol{B} \cdot \nabla (J_{\parallel} B) \right\rangle. \tag{34}$$

We obtain

$$\langle \boldsymbol{e}_{\varphi} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle = \frac{-\mu_0 p'}{(G' + \iota I')^2} \left(G' \left\langle \tilde{p} \nabla_{\parallel} B \right\rangle + \frac{\iota}{2} \left\langle \frac{\tilde{p}}{B} \nabla_{\parallel} (J_{\parallel} B) \right\rangle \right) \tag{35}$$

Implementation

Define a normalised torque

$$\tau = \langle \boldsymbol{e}_{\varphi} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle \frac{(G' + \iota I')^{2}}{-\mu_{0} p'^{2}} = \frac{G'}{p'} \left\langle \tilde{p} \nabla_{\parallel} B \right\rangle + \frac{\iota}{2p'} \left\langle \frac{\tilde{p}}{B} \nabla_{\parallel} (J_{\parallel} B) \right\rangle$$
(36)

To calculate this, we first need to determine the quantity $u \equiv J_{\parallel}/(Bp')$ from the equation

$$\boldsymbol{B} \cdot \nabla u = 2B^{-3}\boldsymbol{B} \times \nabla \psi \cdot \nabla B, \tag{37}$$

which in Boozer coordinates corresponds to

$$\left(\iota \frac{\partial u}{\partial \theta} + \frac{\partial u}{\partial \zeta}\right) = 2\frac{1}{B^3} \left(G\frac{\partial B}{\partial \theta} - I\frac{\partial B}{\partial \zeta}\right). \tag{38}$$

In SFINCS normalisation, we have $G = \hat{G}\bar{R}\bar{B}$, $B = \hat{B}\bar{B}$, $u = \hat{u}\bar{R}/\bar{B}$ and

$$\left(\iota \frac{\partial \hat{u}}{\partial \theta} + \frac{\partial \hat{u}}{\partial \zeta}\right) = 2 \frac{1}{\hat{B}^3} \left(\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta}\right). \tag{39}$$

The torque becomes (denote $\gamma \equiv G'/p'$)

$$\tau = \gamma \left\langle \frac{\tilde{p}}{B\sqrt{g}} \left(\iota \frac{\partial B}{\partial \theta} + \frac{\partial B}{\partial \zeta} \right) \right\rangle + \frac{\iota}{2} \left\langle \frac{\tilde{p}}{B^2 \sqrt{g}} \left(\iota \frac{\partial (uB^2)}{\partial \theta} + \frac{\partial (uB^2)}{\partial \zeta} \right) \right\rangle =$$

$$= \gamma \int d\theta d\zeta \frac{\tilde{p}}{B} \left(\iota \frac{\partial B}{\partial \theta} + \frac{\partial B}{\partial \zeta} \right) + \frac{\iota}{2} \int d\theta d\zeta \frac{\tilde{p}}{B^2} \left(\iota \frac{\partial (uB^2)}{\partial \theta} + \frac{\partial (uB^2)}{\partial \zeta} \right) =$$

$$= \int d\theta d\zeta \frac{\tilde{p}}{B^2} \left[\gamma B \left(\iota \frac{\partial B}{\partial \theta} + \frac{\partial B}{\partial \zeta} \right) + \frac{\iota}{2} \left(\iota \frac{\partial (uB^2)}{\partial \theta} + \frac{\partial (uB^2)}{\partial \zeta} \right) \right]$$

$$(40)$$

In the normalisations used in the SFINCS single species documentation,

$$\tilde{p} = p_{\perp} - p_{\parallel} = m \int d^{3}v \ f\left(\frac{v_{\perp}^{2}}{2} - v_{\parallel}^{2}\right) = \frac{2\Delta\hat{T}^{3/2}n}{\sqrt{\pi}\hat{\psi}_{a}} \int_{-1}^{1} d\xi \int_{0}^{\infty} dx \ x^{2}\hat{f}m\left(\frac{v_{\perp}^{2}}{2} - v_{\parallel}^{2}\right) = \\
= \left\{m\left(\frac{v_{\perp}^{2}}{2} - v_{\parallel}^{2}\right) = \hat{T}\bar{T}\frac{x^{2}}{2}(1 - 3\xi^{2}) = -\hat{T}\bar{T}x^{2}P_{2}(\xi)\right\} = \\
= -\bar{T}n\frac{2\Delta\hat{T}^{5/2}}{\sqrt{\pi}\hat{\psi}_{a}} \int_{-1}^{1} d\xi \int_{0}^{\infty} dx \ x^{4}P_{2}(\xi)\hat{f}. \tag{41}$$

Note the following about the Legendre polynomial P_2 ,

$$\int_{-1}^{1} d\xi P_2^2(\xi) = \frac{2}{5},\tag{42}$$

so that with

$$\hat{f} = \sum_{l=0}^{\infty} f_l P_l(\xi) \tag{43}$$

we obtain

$$\int_{-1}^{1} d\xi P_2(\xi) \hat{f} = \frac{2}{5} f_2. \tag{44}$$

If we define $\gamma = \hat{\gamma} \bar{R} / \bar{B}$ we can write

$$\tau = -\bar{T}n\frac{2\Delta\hat{T}^{5/2}\bar{R}}{\sqrt{\pi}\hat{\psi}_a\bar{B}}\int d\theta d\zeta \frac{\tilde{p}}{\hat{B}^2} \left[\hat{\gamma}B\left(\iota\frac{\partial\hat{B}}{\partial\theta} + \frac{\partial\hat{B}}{\partial\zeta}\right) + \frac{\iota}{2}\left(\iota\frac{\partial(\hat{u}\hat{B}^2)}{\partial\theta} + \frac{\partial(\hat{u}\hat{B}^2)}{\partial\zeta}\right)\right] \frac{2}{5}\int_0^\infty dx \ x^4f_2$$
(45)

Define $\hat{i} = (I'/p')(\bar{B}/\bar{R})$ and

$$\hat{\tau} = \frac{1}{\bar{n}\bar{T}} \langle \boldsymbol{e}_{\varphi} \cdot \nabla \cdot \boldsymbol{\Pi} \rangle = \frac{\tau}{\bar{n}\bar{T}} \frac{-\mu_0 p'^2}{(G' + \iota I')^2} = \frac{\tau}{\bar{n}\bar{T}} \frac{4\pi^2 p'}{V'(G' + \iota I')} = \tau \frac{\bar{B}}{\bar{n}\bar{T}\bar{R}} \frac{4\pi^2}{V'(\hat{\gamma} + \iota \hat{\iota}\hat{\iota})} = \\
= -\hat{n} \frac{2\Delta \hat{T}^{5/2}}{\sqrt{\pi} \hat{\psi}_a(\hat{\gamma} + \iota \hat{\iota}\hat{\iota})} \frac{4\pi^2}{V'} \int d\theta d\zeta \frac{\tilde{p}}{\hat{B}^2} \left[\hat{\gamma} B \left(\iota \frac{\partial \hat{B}}{\partial \theta} + \frac{\partial \hat{B}}{\partial \zeta} \right) + \frac{\iota}{2} \left(\iota \frac{\partial (\hat{u}\hat{B}^2)}{\partial \theta} + \frac{\partial (\hat{u}\hat{B}^2)}{\partial \zeta} \right) \right] \frac{2}{5} \int_0^{\infty} dx \ x^4 f_2 \tag{46}$$