December 19, 2013 Matt Landreman

Technical Documentation for SFINCS with multiple species

Introduction

In this document, we detail the equations implemented in SFINCS: the Stellarator Fokker-Planck Iterative Neoclassical Conservative Solver. The normalizations and input and output quantities are also defined.

Kinetic equation

We begin with the following drift-kinetic equation:

$$\left(\upsilon_{\parallel}\mathbf{b} + \mathbf{v}_{E} + \mathbf{v}_{ms}\right) \cdot \nabla_{\mu,W_{s}} f_{s1} - C_{s} \left\{f_{s1}\right\} = -\mathbf{v}_{ms} \cdot \nabla_{W_{s}} f_{sM} + \frac{Z_{s}e}{T_{s}} \upsilon_{\parallel} \frac{\langle E_{\parallel}B \rangle B}{\langle B^{2} \rangle} f_{sM}$$

$$\tag{1}$$

where s denotes species, $\mu = v_{\perp}^2 / (2B)$

$$W_s = \frac{v^2}{2} + \frac{Z_s e\Phi}{m_s} \tag{2}$$

is the total energy, Z_s is the charge in units of the proton charge e , T_s is the temperature, m_s is the mass, $\mathbf{v}_{\scriptscriptstyle E}$ is the $\mathbf{E} \times \mathbf{B}$ drift,

$$\mathbf{v}_{ms} = \left(\upsilon_{\parallel} / \Omega\right) \nabla_{\mu,\upsilon} \times \left(\upsilon_{\parallel} \mathbf{b}\right) = \frac{\upsilon_{\perp}^{2}}{2\Omega_{s} B^{2}} \mathbf{B} \times \nabla B + \frac{\upsilon_{\parallel}^{2}}{\Omega_{s}} \nabla \times \mathbf{b}$$
(3)

is the magnetic drift, $\Omega_s = Z_s eB/(m_s c)$ is the gyrofrequency (which is negative for electrons with Z=-1), and c is the speed of light. Subscripts on partial derivatives indicate quantities held fixed in differentiation. We assume the electrostatic potential Φ is a flux function to the order of interest. The total distribution function is $f_s = f_{sM} + f_{s1}$ where

$$f_{sM} = n_s \left(\psi \right) \left[\frac{m_s}{2\pi T_s \left(\psi \right)} \right]^{3/2} \exp \left(-\frac{m_s v^2}{2T_s \left(\psi \right)} \right). \tag{4}$$

In (1), C_s is the collision operator linearized about the Maxwellian f_{sM} for each species. We neglect contributions from the inductive electric field to \mathbf{v}_E , writing $\mathbf{v}_E = \left(c \, / \, B^2\right) \left(d\Phi \, / \, d\psi\right) \mathbf{B} \times \nabla \psi$ where $2\pi \psi$ is the toroidal flux. Let $\upsilon_s = \sqrt{2T_s \, / \, m_s}$ be the thermal speed, and let $x_s = \upsilon \, / \, \upsilon_s$.

The independent variables used in SFINCS are $(\theta, \zeta, x_s, \xi)$ where $\xi = v_{\parallel} / v$. Changing velocity variables to (x_s, ξ) on the left side of (1),

$$\dot{\mathbf{r}}_{s} \cdot \nabla_{x_{s},\xi} f_{s1} + \dot{x}_{s} \left(\frac{\partial f_{s1}}{\partial x_{s}} \right)_{\mathbf{r},\xi} + \dot{\xi}_{s} \left(\frac{\partial f_{s1}}{\partial \xi} \right)_{\mathbf{r},x_{s}} - C_{s} \left\{ f_{s1} \right\} = -\mathbf{v}_{ms} \cdot \nabla_{W_{s}} f_{sM} + \frac{Z_{s} e}{T_{s}} \upsilon_{\parallel} \frac{\langle E_{\parallel} B \rangle B}{\langle B^{2} \rangle} f_{sM}$$
 (5)

where

$$\dot{\mathbf{r}}_{s} = \mathbf{v}_{\parallel} \mathbf{b} + \mathbf{v}_{E} + \mathbf{v}_{ms} \,, \tag{6}$$

$$\dot{x}_{s} = \left(\nu_{\parallel} \mathbf{b} + \mathbf{v}_{E} + \mathbf{v}_{ms}\right) \cdot \left(\nabla_{\mu, W_{s}} x_{s}\right),\tag{7}$$

and

$$\dot{\xi}_{s} = \left(\upsilon_{\parallel} \mathbf{b} + \mathbf{v}_{E} + \mathbf{v}_{ms}\right) \cdot \left(\nabla_{\mu, W_{s}} \xi\right). \tag{8}$$

Applying ∇_{W_s} to (2) we find

$$\nabla_W x_s = -\frac{x_s}{m_s \upsilon_s^2} \nabla T - \frac{Z_s e}{2T_s x_s} \nabla \Phi , \qquad (9)$$

so (7) simplifies to

$$\dot{x}_{s} = \left(\mathbf{v}_{ms} \cdot \nabla \psi\right) \left(-\frac{x_{s}}{2T_{s}} \frac{dT_{s}}{d\psi} - \frac{Z_{s}e}{2T_{s}x_{s}} \frac{d\Phi}{d\psi}\right). \tag{10}$$

Similarly, applying ∇_{μ,W_s} to $\mu=\upsilon_s^2x_s^2\left(1-\xi^2\right)/\left(2B\right)$, we find

$$\nabla_{\mu,W_s} \xi = -\frac{Z_s e}{2T_s x_s^2 \xi} \left(1 - \xi^2 \right) \nabla \Phi - \frac{\left(1 - \xi^2 \right)}{\xi} \frac{1}{2B} \nabla B. \tag{11}$$

Thus, (8) may be written

$$\dot{\xi} = -\frac{Z_s e}{2T_s x_s^2 \xi} \left(1 - \xi^2\right) \frac{d\Phi}{d\psi} \mathbf{v}_{ms} \cdot \nabla \psi - \frac{\left(1 - \xi^2\right)}{\xi} \frac{1}{2B} \left(\upsilon_{\parallel} \mathbf{b} + \mathbf{v}_{E} + \mathbf{v}_{ms}\right) \cdot \nabla B. \tag{12}$$

Noting

$$\mathbf{v}_{ms} \cdot \nabla \psi = -\frac{T_s c}{Z_s e B^3} x_s^2 \left(1 + \xi^2 \right) \mathbf{B} \times \nabla \psi \cdot \nabla B \tag{13}$$

then the two electric field terms in (12) may be combined to give

$$\dot{\xi}_{s} = -\frac{\left(1 - \xi^{2}\right)}{\xi} \frac{1}{2B} \upsilon_{\parallel} \mathbf{b} \cdot \nabla B + \xi \left(1 - \xi^{2}\right) \frac{c}{2B^{3}} \frac{d\Phi}{d\psi} \mathbf{B} \times \nabla \psi \cdot \nabla B - \frac{\left(1 - \xi^{2}\right)}{\xi} \frac{1}{2B} \mathbf{v}_{ms} \cdot \nabla B. \tag{14}$$

In the present implementation of SFINCS, the ${\bf v}_{\it ms}$ terms in (6) and (14) are neglected, as is the $dT_{\it s}/d\psi$ term in (10). (This last term must be dropped in order to maintain conservation of μ .) We are then left with

$$\dot{\mathbf{r}}_{s} = \upsilon_{\parallel} \mathbf{b} + \frac{c}{B^{2}} \frac{d\Phi}{d\psi} \mathbf{B} \times \nabla \psi , \qquad (15)$$

$$\dot{x}_s = \frac{c}{2B^3} \frac{d\Phi}{d\psi} x_s \left(1 + \xi^2 \right) \mathbf{B} \times \nabla \psi \cdot \nabla B , \qquad (16)$$

$$\dot{\xi}_{s} = -x_{s} \left(1 - \xi^{2} \right) \frac{\upsilon_{s}}{2B^{2}} \mathbf{B} \cdot \nabla B + \xi \left(1 - \xi^{2} \right) \frac{c}{2B^{3}} \frac{d\Phi}{d\psi} \mathbf{B} \times \nabla \psi \cdot \nabla B. \tag{17}$$

These are the same terms as in the last section of the appendix of Ref. [1].

We can verify that (15)-(17) still conserve μ :

$$\dot{\mu} = \frac{d}{dt} \left(\frac{T_s x_s^2 \left(1 - \xi^2 \right)}{m_s B} \right) = \frac{T_s}{m_s} \frac{d}{dt} \left(\frac{x_s^2 \left(1 - \xi^2 \right)}{B} \right)$$

$$= \frac{T_s}{m_s} \left\{ 2 \frac{1 - \xi^2}{B} x_s \dot{x}_s - 2\xi \frac{x_s^2}{B} \dot{\xi} - \frac{x_s^2}{B^2} \left(1 - \xi^2 \right) \dot{\mathbf{r}}_s \cdot \nabla B \right\}$$

$$= 0$$
(18)

As shown in the appendix of Ref. [1], (15)-(17) do not conserve W because the radial magnetic drift has been dropped. However, in an axisymmetric or quasisymmetric field, (15)-(17) do conserve a combination of energy and canonical momentum.

To compare various effective particle trajectories, the code allows the $d\Phi/d\psi$ terms in (16) and (17) to be turned off, in which case

$$\dot{x}_{s} = 0, \tag{19}$$

$$\dot{\xi}_s = -x_s \left(1 - \xi^2 \right) \frac{\upsilon_s}{2B^2} \mathbf{B} \cdot \nabla B \,. \tag{20}$$

For comparison with DKES, SFINCS allows the option of using

$$\dot{\mathbf{r}}_{s} = \upsilon_{\parallel} \mathbf{b} + \frac{c}{\langle B^{2} \rangle} \frac{d\Phi}{d\psi} \mathbf{B} \times \nabla \psi , \qquad (21)$$

in place of (15).

One further option allowed in the code is to also include a term

$$-f_{s1}\frac{2c}{B^3}\frac{d\Phi}{d\psi}\mathbf{B} \times \nabla \psi \cdot \nabla B = f_{s1}\nabla \cdot \mathbf{v}_E$$
 (22)

on the left-hand side of (5). The rationale for including this term is that it allows the left-hand side of (5) to be put into a conservative form when (19)-(20) are used:

$$\nabla_{x_{s},\xi} \cdot (f_{s1}\dot{\mathbf{r}}_{s}) + \left(\frac{\partial}{\partial \xi}\right)_{\mathbf{r},x_{s}} \left[f_{s1}\dot{\xi}_{s}\right] - C_{s}\left\{f_{s1}\right\} = -\mathbf{v}_{ms} \cdot \nabla_{W_{s}}f_{sM} + \frac{Z_{s}e}{T_{s}} \upsilon_{\parallel} \frac{\langle E_{\parallel}B\rangle B}{\langle B^{2}\rangle} f_{sM}. \tag{23}$$

For the rest of these notes, we will include the term (22) multiplied by α_{cons} , so α_{cons} will be either 0 or 1.

Now consider the magnetic field in Boozer coordinates:

$$\mathbf{B} = \nabla \psi \times \nabla \theta + i \nabla \zeta \times \nabla \psi \,, \tag{24}$$

where t = 1/q is the rotational transform with q the safety factor, and

$$\mathbf{B} = \beta \nabla \psi + G \nabla \zeta + I \nabla \theta \,, \tag{25}$$

where $G(\psi) = 2i_p / c$, $I(\psi) = 2i_t / c$, $i_p(\psi)$ is the poloidal current outside the flux surface, and $i_t(\psi)$ is the toroidal current inside the flux surface. Notice $\mathbf{B} \cdot \nabla \theta = t \mathbf{B} \cdot \nabla \zeta$. The product of (24) with (25) gives the Jacobian

$$\nabla \psi \times \nabla \theta \cdot \nabla \zeta = \frac{B^2}{G + I} = \mathbf{B} \cdot \nabla \zeta. \tag{26}$$

Notice also that

$$\mathbf{B} \cdot \nabla X = \mathbf{B} \cdot \nabla \zeta \left[i \frac{\partial X}{\partial \theta} + \frac{\partial X}{\partial \zeta} \right]$$
 (27)

for any quantity X, and

$$\mathbf{B} \times \nabla \psi \cdot \nabla B = \mathbf{B} \cdot \nabla \zeta \left[G \frac{\partial B}{\partial \theta} - I \frac{\partial B}{\partial \zeta} \right]. \tag{28}$$

The kinetic equation (5) with (15)-(17) is thus equivalent to

$$\frac{\dot{\theta}_{s} \frac{\partial f_{s1}}{\partial \theta} + \dot{\zeta}_{s} \frac{\partial f_{s1}}{\partial \zeta} + \dot{x}_{s} \frac{\partial f_{s1}}{\partial x_{s}} + \dot{\xi}_{s} \frac{\partial f_{s1}}{\partial \xi} - C_{s} \{f_{s1}\} - \alpha_{cons} f_{s1} \frac{2c}{B^{3}} \frac{d\Phi}{d\psi} \mathbf{B} \cdot \nabla \zeta \left[G \frac{\partial B}{\partial \theta} - I \frac{\partial B}{\partial \zeta} \right] }{d\Psi} = \frac{T_{s} c}{Z_{s} e B^{3}} x_{s}^{2} \left(1 + \xi^{2} \right) \mathbf{B} \cdot \nabla \zeta \left[G \frac{\partial B}{\partial \theta} - I \frac{\partial B}{\partial \zeta} \right] f_{sM} \left[\frac{1}{n_{s}} \frac{dn_{s}}{d\psi} + \frac{Z_{s} e}{T_{s}} \frac{d\Phi}{d\psi} + \left(x_{s}^{2} - \frac{3}{2} \right) \frac{1}{T_{s}} \frac{dT_{s}}{d\psi} \right] + \frac{Z_{s} e}{T_{s}} \upsilon_{\parallel} \frac{\langle E_{\parallel} B \rangle B}{\langle B^{2} \rangle} f_{sM} \tag{29}$$

where

$$\dot{\theta}_{s} = \left[\frac{\upsilon_{s} x_{s} \xi}{B} \iota + \frac{cG}{B^{2}} \frac{d\Phi}{d\psi} \right] \mathbf{B} \cdot \nabla \zeta , \qquad (30)$$

$$\dot{\zeta}_{s} = \left[\frac{\upsilon_{s} x_{s} \xi}{B} - \frac{Ic}{B^{2}} \frac{d\Phi}{d\psi} \right] \mathbf{B} \cdot \nabla \zeta , \qquad (31)$$

$$\dot{x}_{s} = \frac{c}{2B^{3}} \frac{d\Phi}{d\psi} x_{s} \left(1 + \xi^{2} \right) \mathbf{B} \cdot \nabla \zeta \left[G \frac{\partial B}{\partial \theta} - I \frac{\partial B}{\partial \zeta} \right], \tag{32}$$

$$\dot{\xi}_{s} = -x_{s} \left(1 - \xi^{2} \right) \frac{\upsilon_{s}}{2B^{2}} \mathbf{B} \cdot \nabla \zeta \left[\imath \frac{\partial B}{\partial \theta} + \frac{\partial B}{\partial \zeta} \right] + \xi \left(1 - \xi^{2} \right) \frac{c}{2B^{3}} \frac{d\Phi}{d\psi} \mathbf{B} \cdot \nabla \zeta \left[G \frac{\partial B}{\partial \theta} - I \frac{\partial B}{\partial \zeta} \right]. \quad (33)$$

Normalizations

Let's suppose we are given T_s , $dT_s/d\psi_N$, n_s , $dn_s/d\psi_N$, $d\Phi/d\psi_N$, $B(\theta,\zeta)$, t, G, I, $\psi_a=\psi\left(\psi_N=1\right)$, and $\left\langle E_\parallel B\right\rangle$ where ψ_N is the normalized toroidal flux. The flux at the last closed flux surface is ψ_a , so the dimensional flux ψ is related to ψ_N by $\psi=\psi_N\psi_a$. The input quantities are specified in terms of some species-independent dimensions \overline{T} (e.g. eV), \overline{n} (e.g. $10^{20}/\text{m}^3$), $\overline{\Phi}$ (e.g. kV), \overline{B} (e.g. T), \overline{R} (e.g. m), and \overline{m} (typically the proton or deuteron mass). In other words, the quantities we are actually given are

$$\hat{m}_{s} = m_{s} / \overline{m}, \qquad (34)$$

$$\hat{T}_{c} = T_{c} / \overline{T} , \qquad (35)$$

$$\hat{n}_{s} = n_{s} / \overline{n} , \qquad (36)$$

$$d\hat{T}_{s} / d\psi_{N} = \left(dT_{s} / d\psi_{N} \right) / \overline{T} , \qquad (37)$$

$$d\hat{n}_{s} / d\psi_{N} = \left(dn_{s} / d\psi_{N} \right) / \overline{n} , \qquad (38)$$

$$d\hat{\Phi} / d\psi_{N} = \left(d\Phi / d\psi_{N} \right) / \overline{\Phi} \,, \tag{39}$$

$$\hat{B} = B / \overline{B} \,, \tag{40}$$

$$\hat{G} = G / (\overline{R}\overline{B}), \tag{41}$$

$$\hat{I} = I / (\overline{R}\overline{B}), \tag{42}$$

$$\hat{\psi}_{a} = \psi_{a} / \left(\overline{B} \overline{R}^{2} \right), \tag{43}$$

and

$$\hat{E} = \left\langle E_{\parallel} B \right\rangle \frac{\bar{R}}{\bar{\Phi} \bar{B}} \,. \tag{44}$$

Notice $\psi = \psi_N \hat{\psi}_a \overline{R}^2 \overline{B}$, and so

$$\frac{dX}{d\psi} = \frac{1}{\hat{\psi}_a \bar{R}^2 \bar{B}} \frac{dX}{d\psi_N} \tag{45}$$

for any flux function X.

It will be useful to define the following combinations of normalization constants:

$$\overline{\upsilon} = \sqrt{2\overline{T}/\overline{m}} \,, \tag{46}$$

$$\Delta = \frac{\overline{m}c\overline{\upsilon}}{e\overline{R}\overline{R}} \tag{47}$$

(which resembles $\rho_* = \rho / R$),

$$\alpha = \frac{e\overline{\Phi}}{\overline{T}},\tag{48}$$

$$\omega = \frac{c\overline{\Phi}}{\overline{\nu}\overline{R}\overline{R}} = \frac{\Delta\alpha}{2},\tag{49}$$

and a normalized collisionality

$$V_n = \overline{V}\overline{R} / \overline{U} \tag{50}$$

where \overline{V} is the dimensional collisionality at the reference parameters:

$$\overline{V} = \frac{4\sqrt{2\pi}\overline{n}e^4 \ln \Lambda}{3\overline{m}^{1/2}\overline{T}^{3/2}}.$$
 (51)

We assume $\ln \Lambda$ has the same value for all species. It will be useful to notice

$$\mathbf{B} \cdot \nabla \zeta = \frac{\overline{B}}{\overline{R}} \frac{\hat{B}^2}{\hat{G} + \iota \hat{I}}.$$
 (52)

We define a normalized distribution function \hat{f}_s as follows:

$$f_{s1} = \frac{\overline{n}}{\overline{D}^3} \, \hat{f}_s \,. \tag{53}$$

Notice the normalization is the same for each species. Also notice that the normalization is different than in the original 1-species version of SFINCS.

The kinetic equation (29) for each species is made dimensionless by multiplying through by

$$\frac{\overline{\upsilon}^3}{\overline{n}} \frac{\overline{B}}{\overline{\upsilon} \mathbf{B} \cdot \nabla \zeta} \,. \tag{54}$$

(this normalization too is slightly different than in the 1-species version of SFINCS.) We then obtain

$$\begin{bmatrix}
\frac{\hat{T}_{s}^{1/2}x_{s}\xi}{\hat{m}_{s}^{1/2}\hat{B}}t + \frac{\alpha\Delta\hat{G}}{2\hat{\psi}_{a}\hat{B}^{2}}\frac{d\hat{\Phi}}{d\psi_{N}} \end{bmatrix} \frac{\partial\hat{f}_{s}}{\partial\theta} \\
\begin{bmatrix}
\frac{\hat{T}_{s}^{1/2}x_{s}\xi}{\hat{m}_{s}^{1/2}\hat{B}} - \frac{\alpha\Delta\hat{I}}{2\hat{\psi}_{a}\hat{B}^{2}}\frac{d\hat{\Phi}}{d\psi_{N}} \end{bmatrix} \frac{\partial\hat{f}_{s}}{\partial\zeta} \\
+ \frac{\alpha\Delta}{4\hat{\psi}_{a}\hat{B}^{3}}\frac{d\hat{\Phi}}{d\psi_{N}}x_{s}(1+\xi^{2}) \left[\hat{G}\frac{\partial\hat{B}}{\partial\theta} - \hat{I}\frac{\partial\hat{B}}{\partial\zeta}\right] \frac{\partial\hat{f}_{s}}{\partial\chi_{s}} \\
+ \left\{-x_{s}(1-\xi^{2})\frac{\hat{T}_{s}^{1/2}\hat{B}^{2}}{2\hat{m}_{s}^{1/2}\hat{B}^{2}} \left[t\frac{\partial\hat{B}}{\partial\theta} + \frac{\partial\hat{B}}{\partial\zeta}\right] + \xi(1-\xi^{2})\frac{\alpha\Delta}{4\hat{\psi}_{a}\hat{B}^{3}}\frac{d\hat{\Phi}}{d\psi_{N}} \left[\hat{G}\frac{\partial\hat{B}}{\partial\theta} - \hat{I}\frac{\partial\hat{B}}{\partial\zeta}\right]\right\} \frac{\partial\hat{f}_{s}}{\partial\xi} \\
- \frac{\hat{G}+t\hat{I}}{\hat{B}^{2}}v_{n}\frac{1}{v}C_{s}\left\{\hat{f}_{s}\right\} - \alpha_{cons}\frac{d\hat{\Phi}}{d\psi_{N}}\frac{\Delta\alpha}{\hat{\psi}_{a}\hat{B}^{3}} \left[\hat{G}\frac{\partial\hat{B}}{\partial\theta} - \hat{I}\frac{\partial\hat{B}}{\partial\zeta}\right]\hat{f}_{s} \\
= \frac{\Delta\hat{n}_{s}\hat{T}_{s}}{2\pi^{3/2}\hat{\psi}_{a}Z_{s}\hat{B}^{3}} \left(\frac{\hat{m}_{s}}{\hat{T}_{s}}\right)^{3/2}x_{s}^{2}(1+\xi^{2}) \left[\hat{G}\frac{\partial\hat{B}}{\partial\theta} - \hat{I}\frac{\partial\hat{B}}{\partial\zeta}\right]e^{-x_{s}^{2}} \left[\frac{1}{\hat{n}_{s}}\frac{d\hat{n}_{s}}{d\psi_{N}} + \frac{\alpha Z_{s}}{\hat{T}_{s}}\frac{d\hat{\Phi}}{d\psi_{N}} + \left(x_{s}^{2} - \frac{3}{2}\right)\frac{1}{\hat{T}_{s}}\frac{d\hat{T}_{s}}{d\psi_{N}}\right] \\
+\alpha\frac{\hat{G}+t\hat{I}}{\hat{B}}\frac{Z_{s}}{\hat{T}_{s}^{2}}x_{s}\xi\hat{E}\frac{1}{\langle\hat{B}^{2}\rangle}\frac{\hat{n}_{s}\hat{m}_{s}}{\pi^{3/2}}e^{-x_{s}^{2}}$$
(55)

where $\hat{C}_{s}\left\{\hat{f}_{s}\right\} = \overline{v}^{-1}C_{s}\left\{\hat{f}_{s}\right\}$.

Legendre discretization

SFINCS uses a collocation discretization in the x_s , θ , and ζ coordinates, but a modal discretization in the ξ coordinate. In other words, the distribution function is known at certain grid points in x_s , θ , and ζ , but it is expanded as modes in ξ . We employ the following modal expansion in terms of Legendre polynomials $P_{\ell}(\xi)$:

$$\hat{f}_s = \sum_{\ell} f_{s,\ell} P_{\ell}(\xi). \tag{56}$$

We discretize the kinetic equation (55) by applying

$$\frac{2L+1}{2}\int_{-1}^{1}d\xi \,P_L(\xi)(\quad \cdot \quad). \tag{57}$$

To evaluate the various integrals that result, the following identities may be used:

$$\frac{2L+1}{2} \int_{-1}^{1} d\xi \, \xi P_L(\xi) P_\ell(\xi) = \frac{L+1}{2L+3} \delta_{L+1,\ell} + \frac{L}{2L-1} \delta_{L-1,\ell}, \tag{58}$$

$$\frac{2L+1}{2} \int_{-1}^{1} d\xi \, \left(1+\xi^{2}\right) P_{L}(\xi) P_{\ell}(\xi) = \frac{2\left\lfloor 3L^{2}+3L-2\right\rfloor}{\left(2L+3\right)\left(2L-1\right)} \delta_{L,\ell} + \frac{L-1}{2L-3} \frac{L}{2L-1} \delta_{L-2,\ell} + \frac{L+2}{2L+5} \frac{L+1}{2L+3} \delta_{L+2,\ell}, \tag{59}$$

$$\frac{2L+1}{2} \int_{-1}^{1} d\xi \, \left(1-\xi^{2}\right) P_{L}(\xi) \frac{dP_{\ell}}{d\xi} = \frac{(L+1)(L+2)}{2L+3} \delta_{L+1,\ell} - \frac{(L-1)L}{2L-1} \delta_{L-1,\ell}, \tag{60}$$

$$\frac{2L+1}{2} \int_{-1}^{1} d\xi \left(1-\xi^{2}\right) \xi P_{L}(\xi) \frac{dP_{\ell}}{d\xi} = \frac{(L+1)L}{(2L-1)(2L+3)} \delta_{L,\ell} + \frac{(L+3)(L+2)(L+1)}{(2L+5)(2L+3)} \delta_{L+2,\ell} - \frac{L(L-1)(L-2)}{(2L-3)(2L-1)} \delta_{L-2,\ell}, \qquad (61)$$

$$\frac{2L+1}{2} \int_{-1}^{1} d\xi P_{L}(\xi) \xi = \delta_{L,1}, \qquad (62)$$

and

$$\frac{2L+1}{2} \int_{-1}^{1} d\xi \ P_L(\xi) \left(1+\xi^2\right) = \frac{4}{3} \delta_{L,0} + \frac{2}{3} \delta_{L,2}. \tag{63}$$

As a result, (55) may be written

$$\sum_{\ell} M_{s,L,\ell} \hat{f}_{s,\ell} = R_{s,L} \tag{64}$$

where

$$M_{s,L,\ell} = \dot{\theta}_{s,L,\ell} \frac{\partial}{\partial \theta} + \dot{\zeta}_{s,L,\ell} \frac{\partial}{\partial \zeta} + M_{s,L,\ell}^{(\xi)} + \dot{x}_{s,L,\ell} \frac{\partial}{\partial x_s} - v_n \frac{\left(\hat{G} + \iota \hat{I}\right)}{\hat{B}^2} \hat{C}_{s,L} \delta_{L,\ell} + \alpha_{cons} \delta_{L,\ell} Y, \qquad (65)$$

$$\dot{\theta}_{s,L,\ell} = \frac{\hat{T}_{s}^{1/2} x_{s}}{\hat{m}_{s}^{1/2} \hat{B}} i \left[\frac{L+1}{2L+3} \delta_{L+1,\ell} + \frac{L}{2L-1} \delta_{L-1,\ell} \right] + \frac{\alpha \Delta \hat{G}}{2 \hat{\psi}_{a} \hat{B}^{2}} \frac{d\hat{\Phi}}{d\psi_{N}} \delta_{L,\ell}$$
(66)

$$\dot{\zeta}_{s,L,\ell} = \frac{\hat{T}_{s}^{1/2} x_{s}}{\hat{m}_{s}^{1/2} \hat{B}} \left[\frac{L+1}{2L+3} \delta_{L+1,\ell} + \frac{L}{2L-1} \delta_{L-1,\ell} \right] - \frac{\alpha \Delta \hat{I}}{2 \hat{\psi}_{s} \hat{B}^{2}} \frac{d\hat{\Phi}}{d\psi_{N}} \delta_{L,\ell}$$
(67)

$$M_{s,L,\ell}^{(\xi)} = -x_s \frac{\hat{T}_s^{1/2}}{2\hat{m}_s^{1/2}\hat{B}^2} \left[\iota \frac{\partial \hat{B}}{\partial \theta} + \frac{\partial \hat{B}}{\partial \zeta} \right] \left[\frac{(L+1)(L+2)}{2L+3} \delta_{L+1,\ell} - \frac{(L-1)L}{2L-1} \delta_{L-1,\ell} \right]$$

$$+\frac{\alpha\Delta}{4\hat{\psi}_{a}\hat{B}^{3}}\frac{d\hat{\Phi}}{d\psi_{N}}\left[\hat{G}\frac{\partial\hat{B}}{\partial\theta}-\hat{I}\frac{\partial\hat{B}}{\partial\zeta}\right]\left[\frac{(L+1)L}{(2L-1)(2L+3)}\delta_{L,\ell} + \frac{(L+3)(L+2)(L+1)}{(2L+5)(2L+3)}\delta_{L+2,\ell} - \frac{L(L-1)(L-2)}{(2L-3)(2L-1)}\delta_{L-2,\ell}\right]$$
(68)

$$\dot{x}_{s,L,\ell} = \frac{\alpha \Delta}{4\hat{\psi}_{a}\hat{B}^{3}} \frac{d\hat{\Phi}}{d\psi_{N}} x_{s} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right] \begin{bmatrix} \frac{2[3L^{2} + 3L - 2]}{(2L + 3)(2L - 1)} \delta_{L,\ell} \\ + \frac{L - 1}{2L - 3} \frac{L}{2L - 1} \delta_{L-2,\ell} + \frac{L + 2}{2L + 5} \frac{L + 1}{2L + 3} \delta_{L+2,\ell} \end{bmatrix}, \quad (69)$$

$$Y = -\frac{d\hat{\Phi}}{d\psi_N} \frac{\Delta \alpha}{\hat{\psi}_a \hat{B}^3} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right], \tag{70}$$

and

$$R_{s,L} = \frac{\Delta \hat{n}_{s} \hat{T}_{s}}{2\pi^{3/2} \hat{\psi}_{a} Z_{s} \hat{B}^{3}} \left(\frac{\hat{m}_{s}}{\hat{T}_{s}} \right)^{3/2} x_{s}^{2} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right] e^{-x_{s}^{2}} \left[\frac{1}{\hat{n}_{s}} \frac{d\hat{n}_{s}}{d\psi_{N}} + \frac{\alpha Z_{s}}{\hat{T}_{s}} \frac{d\hat{\Phi}}{d\psi_{N}} + \left(x_{s}^{2} - \frac{3}{2} \right) \frac{1}{\hat{T}_{s}} \frac{d\hat{T}_{s}}{d\psi_{N}} \right] \left[\frac{4}{3} \delta_{L,0} + \frac{2}{3} \delta_{L,2} \right]$$

$$+ \alpha \frac{\hat{G} + t\hat{I}}{\hat{B}} \frac{Z_{s}}{\hat{T}_{s}^{2}} x_{s} \xi \hat{E} \frac{1}{\langle \hat{B}^{2} \rangle} \frac{\hat{n}_{s} \hat{m}_{s}}{\pi^{3/2}} e^{-x_{s}^{2}} \delta_{L,1}$$

$$(71)$$

Collision operator

The total collision operator for species a is a sum of collision operators with each species:

$$C_a = \sum_b C_{ab} . (72)$$

The linearized Fokker-Planck collision operator for each pair of species may be written

$$C_{ab} = C_{ab}^{L} + C_{ab}^{E} + C_{ab}^{F}, (73)$$

where the Lorentz part of the collision term is

$$C_{ab}^{L} = \frac{v_{Dab}}{2} \frac{\partial}{\partial \xi} \left(1 - \xi^{2} \right) \frac{\partial f_{a1}}{\partial \xi}$$
 (74)

with

$$v_{Dab} = \frac{\Gamma_{ab} n_b}{v^3} \left[\text{erf} \left(x_b \right) - \Psi \left(x_b \right) \right], \tag{75}$$

$$\Gamma_{ab} = \frac{4\pi Z_a^2 Z_b^2 e^4 \ln \Lambda}{m_a^2} \,, \tag{76}$$

$$\Psi(x_b) = \frac{\operatorname{erf}(x_b) - x_b \operatorname{erf}'(x_b)}{2x_b^2}.$$
 (77)

The energy scattering contribution is

$$C_{ab}^{E} = V_{\parallel ab} \left[\frac{\upsilon^{2}}{2} \frac{\partial^{2} f_{a1}}{\partial \upsilon^{2}} - x_{b}^{2} \left(1 - \frac{m_{a}}{m_{b}} \right) \upsilon \frac{\partial f_{a1}}{\partial \upsilon} \right] + V_{Dab} \upsilon \frac{\partial f_{a1}}{\partial \upsilon} + 4\pi \Gamma_{ab} \frac{m_{a}}{m_{b}} f_{Mb} f_{a1}$$
 (78)

where

$$\nu_{\parallel ab} = 2 \frac{\Gamma_{ab} n_b}{\nu^3} \Psi(x_b). \tag{79}$$

The field term is

$$C_{ab}^{F} = \Gamma_{ab} f_{Ma} \left[\frac{2v^{2}}{v_{a}^{4}} \frac{\partial^{2} G_{b1}}{\partial v^{2}} - \frac{2v}{v_{a}^{2}} \left(1 - \frac{m_{a}}{m_{b}} \right) \frac{\partial H_{b1}}{\partial v} - \frac{2}{v_{a}^{2}} H_{b1} + 4\pi \frac{m_{a}}{m_{b}} f_{b1} \right]$$
(80)

where the potentials are defined by

$$\nabla_{\nu}^{2} H_{b1} = -4\pi f_{b1} \tag{81}$$

and

$$\nabla_{\nu}^{2} G_{b1} = 2H_{b1}. \tag{82}$$

We write the field term as

$$C_{ab}^{F} = C_{ab}^{H} + C_{ab}^{G} + C_{ab}^{D} (83)$$

where

$$C_{ab}^{G} = \Gamma_{ab} f_{Ma} \frac{2\nu^2}{\nu^4} \frac{\partial^2 G_{b1}}{\partial \nu^2}$$
(84)

$$C_{ab}^{H} = \Gamma_{ab} f_{Ma} \left[-\frac{2\upsilon}{\upsilon_a^2} \left(1 - \frac{m_a}{m_b} \right) \frac{\partial H_{b1}}{\partial \upsilon} - \frac{2}{\upsilon_a^2} H_{b1} \right]$$
 (85)

$$C_{ab}^{D} = \Gamma_{ab} f_{Ma} 4\pi \frac{m_a}{m_b} f_{b1} = \frac{\Gamma_{ab} n_a}{\upsilon_a^3} \exp\left(-x_a^2\right) \frac{4}{\pi^{1/2}} \frac{m_a}{m_b} f_{b1}$$
 (86)

The Poisson equations that define the potentials are (for Legendre mode $P_{\ell}(\xi)$)

$$\frac{\partial}{\partial x_b} x_b^2 \frac{\partial H_{b1}}{\partial x_b} - \ell (\ell + 1) H_{b1} = -4\pi \upsilon^2 f_{b1}$$
(87)

$$\frac{\partial}{\partial x_b} x_b^2 \frac{\partial G_{b1}}{\partial x_b} - \ell (\ell + 1) G_{b1} = 2 \upsilon^2 H_{b1}. \tag{88}$$

Let us define

$$\hat{H}_{b1} = H_{b1} / \upsilon_b^2 \tag{89}$$

$$\hat{G}_{b1} = G_{b1} / v_b^4 \tag{90}$$

so the defining equations for the potentials become

$$\frac{\partial}{\partial x_b} x_b^2 \frac{\partial \hat{H}_{b1}}{\partial x_b} - \ell \left(\ell + 1\right) \hat{H}_{b1} = -4\pi x_b^2 f_{b1} \tag{91}$$

$$\frac{\partial}{\partial x_b} x_b^2 \frac{\partial \hat{G}_{b1}}{\partial x_b} - \ell \left(\ell + 1\right) \hat{G}_{b1} = 2x_b^2 \hat{H}_{b1}. \tag{92}$$

Next, recall that in the kinetic equation (65), we need to evaluate

$$\hat{C}_{ab} = \frac{1}{V} C_{ab} \tag{93}$$

where \overline{v} is defined in (51). It is convenient to note

$$\frac{\Gamma_{ab}}{\overline{v}} = \frac{3\sqrt{\pi}}{4} \frac{1}{\overline{n}} \frac{Z_a^2 Z_b^2}{\hat{T}_a^{3/2} \hat{m}_a^{1/2}} \upsilon_a^3$$
(94)

Expanding $\hat{C}_{ab} = \hat{C}^L_{ab} + \hat{C}^E_{ab} + \hat{C}^F_{ab}$ as before,

$$\hat{C}_{ab}^{L} = \frac{\hat{v}_{Dab}}{2} \frac{\partial}{\partial \xi} \left(1 - \xi^2 \right) \frac{\partial f_{a1}}{\partial \xi}$$
(95)

where

$$\hat{v}_{Dab} = \frac{3\sqrt{\pi}}{4} \frac{\hat{n}_b Z_a^2 Z_b^2}{\hat{T}_a^{3/2} \hat{m}_a^{1/2}} \frac{1}{x_a^3} \left[\text{erf} \left(x_b \right) - \Psi \left(x_b \right) \right]$$
 (96)

The energy scattering component is

$$\hat{C}_{ab}^{E} \left\{ f_{a1} \right\} = \frac{3\sqrt{\pi}}{4} \frac{\hat{n}_{b} Z_{a}^{2} Z_{b}^{2}}{\hat{T}_{a}^{3/2} \hat{m}_{a}^{1/2}} + \left\{ -2 \frac{\hat{T}_{a}}{\hat{T}_{b}} \frac{\hat{m}_{b}}{\hat{m}_{a}} \Psi(x_{b}) \left(1 - \frac{\hat{m}_{a}}{\hat{m}_{b}} \right) + \frac{1}{x_{a}^{2}} \left[\operatorname{erf}(x_{b}) - \Psi(x_{b}) \right] \right\} \frac{\partial f_{a1}}{\partial x_{a}} + \frac{4}{\sqrt{\pi}} \left(\frac{\hat{T}_{a}}{\hat{T}_{b}} \right)^{3/2} \left(\frac{\hat{m}_{b}}{\hat{m}_{a}} \right)^{1/2} e^{-x_{b}^{2}} f_{a1}$$

$$(97)$$

The diagonal term is

$$\hat{C}_{ab}^{D} = 3 \frac{\hat{n}_a Z_a^2 Z_b^2}{\hat{T}_a^{3/2} \hat{m}_a^{1/2}} \frac{\hat{m}_a}{\hat{m}_b} \exp(-x_a^2) f_{b1}$$
(98)

In the cross-species case, this term is no longer identical to the f_{a1} term in energy scattering (as it is in the same-species case).

The G term in the collision operator is

$$\hat{C}_{ab}^{G} = \frac{3}{2\pi} \frac{\hat{n}_{a} Z_{a}^{2} Z_{b}^{2}}{\hat{T}_{a}^{3/2} \hat{m}_{a}^{1/2}} \left(\frac{\hat{T}_{b}}{\hat{T}_{a}} \frac{\hat{m}_{a}}{\hat{m}_{b}} \right)^{2} e^{-x_{a}^{2}} x_{b}^{2} \frac{\partial^{2} \hat{G}_{b1}}{\partial x_{b}^{2}}
= \frac{3}{2\pi} \frac{\hat{n}_{a} Z_{a}^{2} Z_{b}^{2}}{\hat{T}_{a}^{3/2} \hat{m}_{a}^{1/2}} \left(\frac{\hat{T}_{b}}{\hat{T}_{a}} \frac{\hat{m}_{a}}{\hat{m}_{b}} \right) e^{-x_{a}^{2}} x_{a}^{2} \frac{\partial^{2} \hat{G}_{b1}}{\partial x_{b}^{2}}.$$
(99)

Although in principle we would also be free to write

$$\hat{C}_{ab}^{G} = \frac{3}{2\pi} \frac{\hat{n}_{a} Z_{a}^{2} Z_{b}^{2}}{\hat{T}_{a}^{3/2} \hat{m}_{a}^{1/2}} \left(\frac{\hat{T}_{b}}{\hat{T}_{a}} \frac{\hat{m}_{a}}{\hat{m}_{b}}\right)^{2} e^{-x_{a}^{2}} x_{a}^{2} \frac{\partial^{2} \hat{G}_{b1}}{\partial x_{a}^{2}}$$
(100)

(i.e. replacing $x_b \to x_a$ in two places), the resulting expression is less convenient because we compute \hat{G}_{b1} on the x_b grid, and so it is easier to differentiate with respect to x_b .

The H collision term is

$$\hat{C}_{ab}^{H} = -\frac{3}{2\pi} \frac{\hat{n}_{a} Z_{a}^{2} Z_{b}^{2}}{\hat{T}_{a}^{3/2} \hat{m}_{a}^{1/2}} \frac{\hat{T}_{b}}{\hat{T}_{a}} \frac{\hat{m}_{a}}{\hat{m}_{b}} e^{-x_{a}^{2}} \left[\left(1 - \frac{\hat{m}_{a}}{\hat{m}_{b}} \right) x_{b} \frac{\partial \hat{H}_{b1}}{\partial x_{b}} + \hat{H}_{b1} \right]$$
(101)

Output quantities

Flux surface average:

For any quantity X, the flux surface average can be computed from

$$\langle X \rangle = \frac{1}{\hat{V}'} \int_0^{2\pi} d\theta \int_0^{2\pi} d\zeta \, \frac{X}{\hat{B}^2} \tag{102}$$

where

$$VPrimeHat = \hat{V}' = \int_0^{2\pi} d\theta \int_0^{2\pi} d\zeta \, \frac{1}{\hat{R}^2} \,. \tag{103}$$

Notice

$$FSABHat 2 = \left\langle \hat{B}^2 \right\rangle = \frac{4\pi^2}{\hat{V}'}.$$
 (104)

Density perturbation

SFINCS returns the density carried in \hat{f}_{s1} :

densityPerturbation =
$$\frac{1}{n} \int d^3 v f_{s1} = 4\pi \left(\frac{\hat{T}_s}{\hat{m}_s}\right)^{3/2} \int_0^\infty dx_s x_s^2 \hat{f}_{s,L=0}. \tag{105}$$

Upon flux surface averaging, we obtain

FSADensityPerturbation =
$$\left\langle \frac{1}{n} \int d^3 v f_{s1} \right\rangle$$

$$= \frac{1}{\hat{V}'} \int_0^{2\pi} d\theta \int_0^{2\pi} d\zeta \, \frac{\text{densityPerturbation}}{\hat{B}^2}. \tag{106}$$

Pressure perturbation

SFINCS also returns the pressure in \hat{f}_{s1} , normalized to the reference pressure $\overline{n}\overline{T}$:

$$\begin{aligned} \text{pressurePerturbation} &= \frac{1}{\overline{n}} \frac{m_s}{3} \int d^3 v \, v^2 f_{s1} \\ &= \frac{8\pi \hat{m}_s}{3} \left(\frac{\hat{T}_s}{\hat{m}_s} \right)^{5/2} \int_0^\infty dx_s x_s^4 \hat{f}_{s,L=0}. \end{aligned} \tag{107}$$

Upon flux surface averaging, we obtain

$$\begin{split} \text{FSAPressurePerturbation} &= \left\langle \frac{1}{n\overline{T}} \frac{m_s}{3} \int d^3 \upsilon \upsilon^2 f_{s1} \right\rangle \\ &= \frac{1}{\hat{V}'} \int_0^{2\pi} d\theta \int_0^{2\pi} d\zeta \, \frac{\text{pressurePerturbation}}{\hat{B}^2}. \end{split} \tag{108}$$

Flow

We choose to normalize the parallel flow at each point as follows:

flow =
$$\frac{1}{\overline{n}\overline{v}} \int d^3v \, v_{\parallel} f_{s1} = \frac{4\pi}{3} \left(\frac{\hat{T}_s}{\hat{m}_s} \right)^2 \int_0^{\infty} dx_s x_s^3 \hat{f}_{s,L=1}.$$
 (109)

Both numerical and analytic calculations often employ the weights average flow $\langle V_{\parallel}B\rangle$. In SFINCS, this quantity is normalized in the following way:

$$FSABFlow = \frac{1}{\overline{n}\overline{v}\overline{B}} \left\langle B \int d^3 v \, v_{\parallel} f \right\rangle = \frac{1}{\hat{V}'} \int_0^{2\pi} d\theta \int_0^{2\pi} d\zeta \, \frac{flow}{\hat{B}}. \tag{110}$$

Particle flux

The following expression is useful for evaluating the radial fluxes:

$$\mathbf{v}_{ms} \cdot \nabla \psi = -\overline{\upsilon} \overline{R} \overline{B} \frac{\Delta \hat{T}_{s}}{2Z_{s} \hat{B}} x_{s}^{2} \left(1 + \xi^{2}\right) \frac{1}{\hat{G} + \iota \hat{I}} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right]. \tag{111}$$

We may write the radial particle flux as

$$\left\langle \int d^{3} \upsilon f_{s1} \mathbf{v}_{ms} \cdot \nabla \psi \right\rangle = -\overline{n} \overline{\upsilon} \overline{R} \overline{B} \frac{\pi \Delta \hat{T}_{s}}{Z_{s} \hat{V}'} \left(\frac{\hat{T}_{s}}{\hat{m}_{s}} \right)^{3/2} \frac{1}{\hat{G} + \iota \hat{I}} \int_{0}^{2\pi} d\theta \int_{0}^{2\pi} d\zeta \frac{1}{\hat{B}^{3}} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right]$$

$$\times \int_{-1}^{1} d\xi \int_{0}^{\infty} dx_{s} \hat{f}_{s} x_{s}^{4} \left(1 + \xi^{2} \right).$$
(112)

Using

$$\int_{-1}^{1} d\xi \ P_L(\xi) (1 + \xi^2) = \frac{8}{3} \delta_{L,0} + \frac{4}{15} \delta_{L,2}$$
 (113)

then

$$\left\langle \int d^3 v f_{s1} \mathbf{v}_{ms} \cdot \nabla \psi \right\rangle = \overline{n} \overline{v} \overline{R} \overline{B} \left(\text{particleFlux} \right) \tag{114}$$

where

$$\begin{aligned} \text{particleFlux} &= -\frac{\pi \Delta \hat{T}_{s}}{Z_{s} \hat{V}'} \left(\frac{\hat{T}_{s}}{\hat{m}_{s}} \right)^{3/2} \frac{1}{\hat{G} + \iota \hat{I}} \int_{0}^{2\pi} d\theta \int_{0}^{2\pi} d\zeta \frac{1}{\hat{B}^{3}} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right] \\ &\times \int_{0}^{\infty} dx_{s} x_{s}^{4} \left[\frac{8}{3} \hat{f}_{s,L=0} + \frac{4}{15} \hat{f}_{s,L=2} \right]. \end{aligned} \tag{115}$$

Momentum flux

We may write a radial momentum flux as

$$\left\langle \int d^{3} \upsilon f_{s1} m_{s} \upsilon_{\parallel} \mathbf{v}_{ms} \cdot \nabla \psi \right\rangle = -\overline{n} \overline{m} \overline{\upsilon}^{2} \overline{R} \overline{B} \frac{\pi \Delta \hat{T}_{s}}{Z_{s} \hat{V}'} \left(\frac{\hat{T}_{s}}{\hat{m}_{s}} \right)^{2} \frac{\hat{m}_{s}}{\hat{G} + \iota \hat{I}} \int_{0}^{2\pi} d\theta \int_{0}^{2\pi} d\zeta \frac{1}{\hat{B}^{3}} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right]$$

$$\times \int_{-1}^{1} d\xi \int_{0}^{\infty} dx_{s} \hat{f}_{s} x_{s}^{5} \xi \left(1 + \xi^{2} \right).$$

$$(116)$$

Using

$$\int_{-1}^{1} d\xi \, P_L(\xi) \, \xi \left(1 + \xi^2 \right) = \frac{16}{15} \, \delta_{L,1} + \frac{4}{35} \, \delta_{L,3} \tag{117}$$

then

$$\left\langle \int d^3 v f_{sl} v_{\parallel} \mathbf{v}_{ms} \cdot \nabla \psi \right\rangle = \overline{n} \overline{m} \overline{v}^2 \overline{R} \overline{B} \left(\text{momentumFlux} \right) \tag{118}$$

where

$$\begin{aligned} \text{momentumFlux} &= -\frac{\pi \Delta \hat{T}_{s}}{Z_{s} \hat{V}'} \left(\frac{\hat{T}_{s}}{\hat{m}_{s}} \right)^{2} \frac{\hat{m}_{s}}{\hat{G} + \iota \hat{I}} \int_{0}^{2\pi} d\theta \int_{0}^{2\pi} d\zeta \, \frac{1}{\hat{B}^{3}} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right] \\ &\times \int_{0}^{\infty} dx_{s} x_{s}^{5} \left[\frac{16}{15} \hat{f}_{s,L=1} + \frac{4}{35} \hat{f}_{s,L=3} \right]. \end{aligned} \tag{119}$$

Heat flux

We may write the radial energy flux as

$$\left\langle \int d^{3} \upsilon f_{s1} \frac{m_{s} \upsilon^{2}}{2} \mathbf{v}_{ms} \cdot \nabla \psi \right\rangle = -\overline{n} \overline{m} \overline{\upsilon}^{3} \overline{R} \overline{B} \frac{\pi \Delta \hat{T}_{s} \hat{m}_{s}}{2Z_{s} \hat{V}'} \left(\frac{\hat{T}_{s}}{\hat{m}_{s}} \right)^{5/2} \frac{1}{\hat{G} + \iota \hat{I}} \int_{0}^{2\pi} d\theta \int_{0}^{2\pi} d\zeta \frac{1}{\hat{B}^{3}} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right] (120)$$

$$\times \int_{1}^{1} d\xi \int_{0}^{\infty} dx_{s} \hat{f}_{s} x_{s}^{6} (1 + \xi^{2}).$$

Using (113), then

$$\left\langle \int d^3 v f_{s1} \frac{m_s v^2}{2} \mathbf{v}_{ms} \cdot \nabla \psi \right\rangle = \overline{n} \overline{m} \overline{v}^3 \overline{R} \overline{B} \left(\text{heatFlux} \right)$$
 (121)

where

$$\begin{aligned} \text{heatFlux} &= -\frac{\pi \Delta \hat{T}_s \hat{m}_s}{2Z_s \hat{V}'} \left(\frac{\hat{T}_s}{\hat{m}_s} \right)^{5/2} \frac{1}{\hat{G} + \iota \hat{I}} \int_0^{2\pi} d\theta \int_0^{2\pi} d\zeta \, \frac{1}{\hat{B}^3} \left[\hat{G} \frac{\partial \hat{B}}{\partial \theta} - \hat{I} \frac{\partial \hat{B}}{\partial \zeta} \right] \\ &\times \int_0^{\infty} dx_s \hat{f}_s x_s^6 \left[\frac{8}{3} \hat{f}_{s,L=0} + \frac{4}{15} \hat{f}_{s,L=2} \right]. \end{aligned} \tag{122}$$

Parallel current

The current is normalized as follows:

$$j_{\parallel} = \sum_{s} Z_{s} e n_{s} V_{\parallel s} = \sum_{s} Z_{s} e \int d^{3} v f_{s1} v_{\parallel} = e \overline{n} \overline{v} (j \text{Hat})$$

$$(123)$$

S0

$$jHat = \frac{1}{e\overline{n}\overline{v}} \sum_{s} Z_{s} e \int d^{3}v f_{s1} v_{\parallel} = \sum_{s} Z_{s} (flow_{s}).$$
 (124)

We also form the average $\langle \mathbf{B} \cdot \mathbf{j} \rangle$ which is associated with the bootstrap current:

$$\left\langle \mathbf{B} \cdot \mathbf{j} \right\rangle = \left\langle \sum_{s} Z_{s} e n_{s} B V_{\parallel s} \right\rangle = \left\langle B \sum_{s} Z_{s} e \int d^{3} \upsilon f_{s1} \upsilon_{\parallel} \right\rangle = e \overline{n} \overline{\upsilon} \overline{B} \left(\text{FSABjHat} \right) \tag{125}$$

where

$$FSABjHat = \frac{1}{e\overline{n}\overline{v}\overline{B}} \left\langle B \sum_{s} Z_{s} e \int d^{3}v f_{s1} v_{\parallel} \right\rangle = \sum_{s} Z_{s} \left(FSABFlow_{s} \right). \tag{126}$$