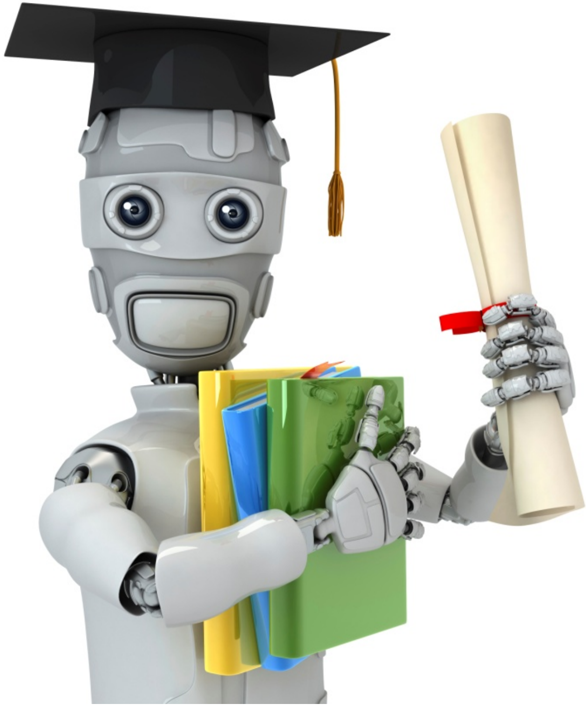
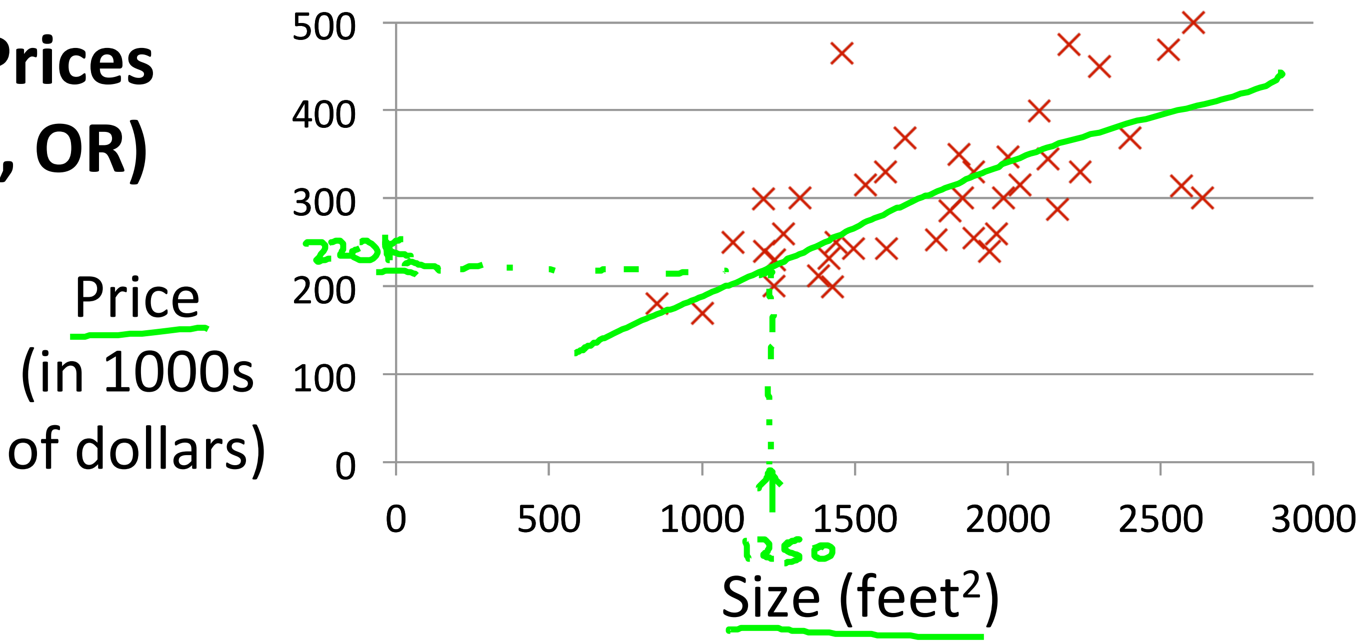


Machine Learning

Linear regression with one variable

Model representation

Housing Prices (Portland, OR)



<u>Supervised Learning</u>

Given the "right answer" for each example in the data.

<u>Regression Problem</u>

Predict real-valued output

Classification: Discrete-valued output

Andrew Ng

Training set of housing prices (Portland, OR)

Size in feet^2 (x)	Price ($) in 1000's (y)
2104	460
1416	232
1534	315
852	178
…	…

$m = 47$

Notation:

- **m** = Number of training examples
- **x**'s = "input" variable / features
- **y**'s = "output" variable / "target" variable

(x, y) - one training example

$(x^{(i)}, y^{(i)})$ - i^{th} training example

$x^{(1)} = 2104$

$x^{(2)} = 1416$

$y^{(1)} = 460$

Andrew Ng

Training Set

Feeding the training set
to the algorithm to
learn from

Learning Algorithm

Mapping from size of house
to estimated price

Size of house → h → Estimated price

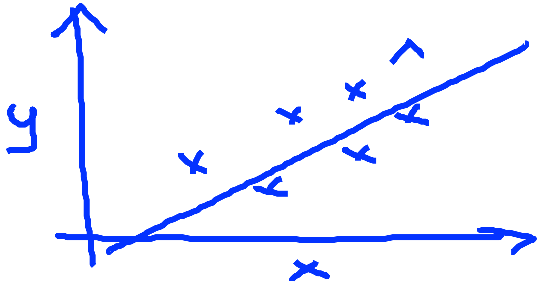
$\underline{x}$ $\underline{\text{hypothesis}}$ $\underline{\text{(estimated value of } y)}$

h maps from x's to y's.

How do we represent h ?

$h_\theta(x) = \underline{\theta_0 + \theta_1 x}$

Shorthand: $h(x)$

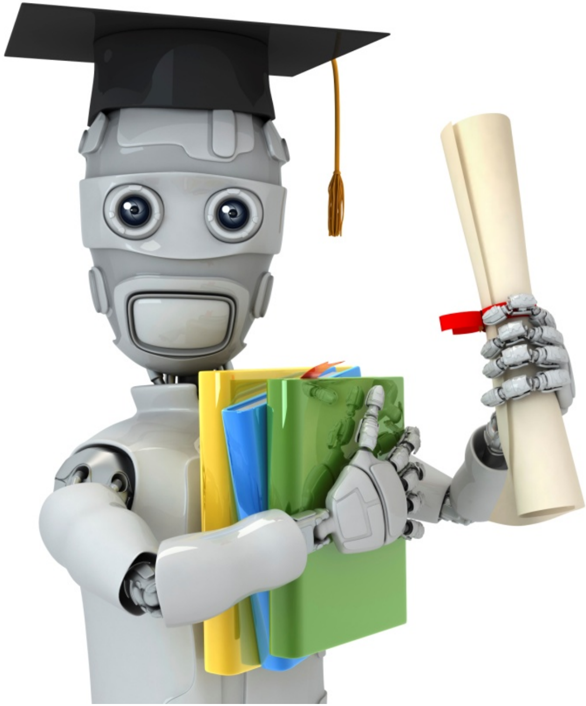


$h(x) = \theta_0 + \theta_1 x$

Linear regression with one variable. (x)

Univariate linear regression.

one variable



Machine Learning

Linear regression with one variable

Cost function

Training Set

Size in feet^2 (x)	**Price ($) in 1000's (y)**
2104	460
1416	232
1534	315
852	178
…	…

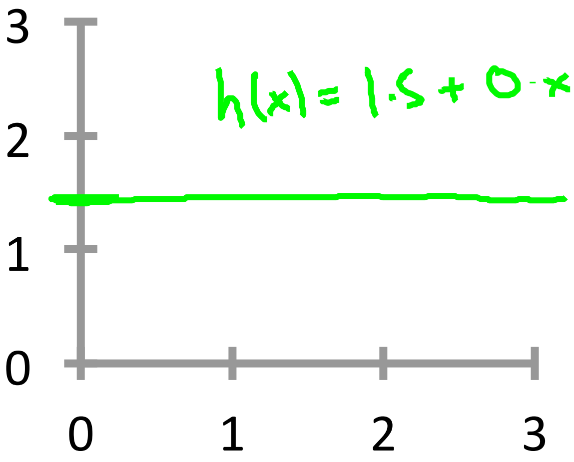
m = 47

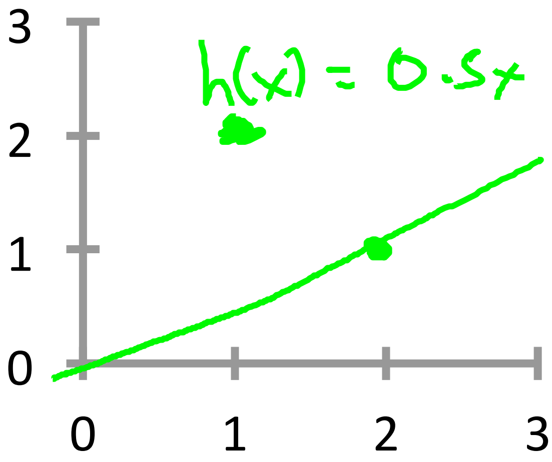
Hypothesis: $h_\theta(x) = \theta_0 + \theta_1 x$

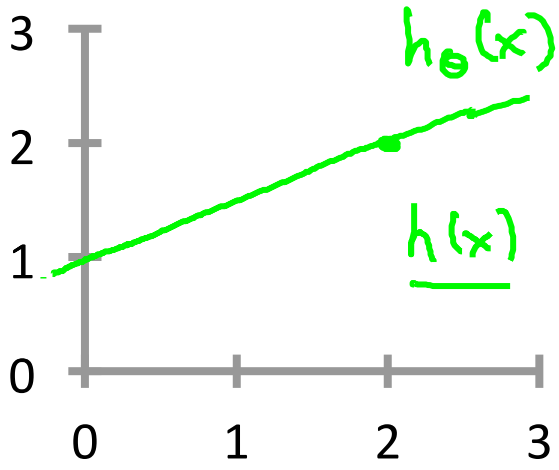
θ_i's: Parameters

How to choose θ_i's ?

$h_\theta(x) = \theta_0 + \theta_1 x$



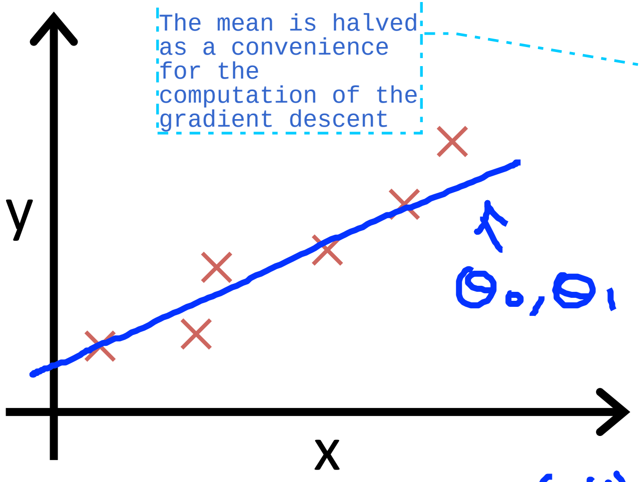




→ $\theta_0 = 1.5$
→ $\theta_1 = 0$

→ $\theta_0 = 0$
→ $\theta_1 = 0.5$

→ $\theta_0 = 1$
→ $\theta_1 = 0.5$



1/2m for minimization

The mean is halved as a convenience for the computation of the gradient descent

Prediction

training examples

$$\underset{\theta_0, \theta_1}{\text{minimize}} \ \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)} \right)^2$$

$$h_\theta(x^{(i)}) = \theta_0 + \theta_1 x^{(i)}$$

$(x^{(i)}, y^{(i)})$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)} \right)^2$$

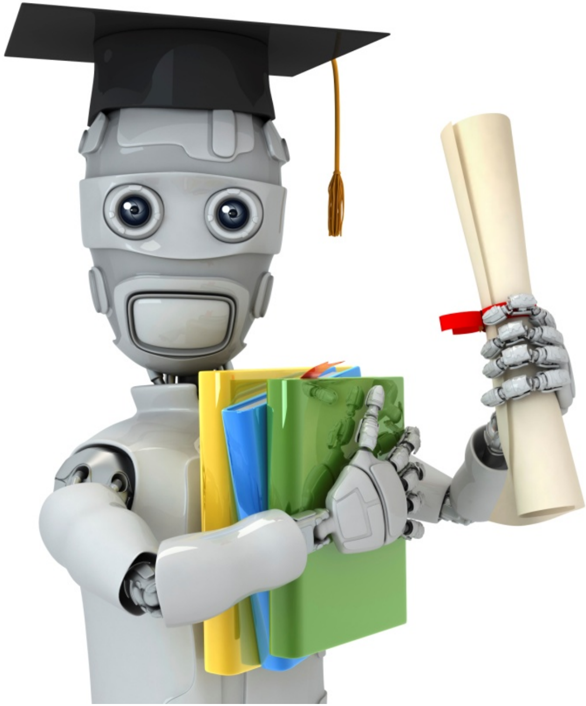
$$\underset{\theta_0, \theta_1}{\text{minimize}} \ \underbrace{J(\theta_0, \theta_1)}_{\text{Cost function}}$$

Squared error function

Idea: Choose θ_0, θ_1 so that $h_\theta(x)$ is close to y for our training examples (x, y)

x, y

Andrew Ng



Machine Learning

Linear regression with one variable

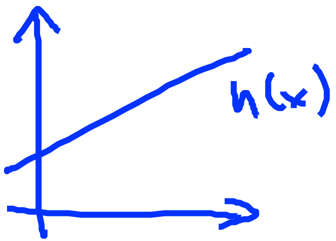
Cost function intuition I

Hypothesis:

$$h_\theta(x) = \theta_0 + \theta_1 x$$

Parameters:

$$\theta_0, \theta_1$$



Cost Function:

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

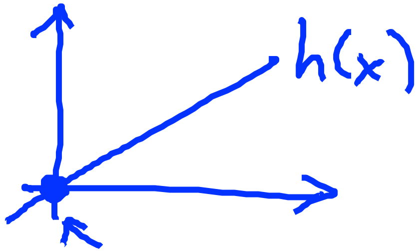
Goal: $\underset{\theta_0, \theta_1}{\text{minimize}}\ J(\theta_0, \theta_1)$

Simplified

$$h_\theta(x) = \theta_1 x$$

$\theta_0 = 0$

$$\theta_1$$



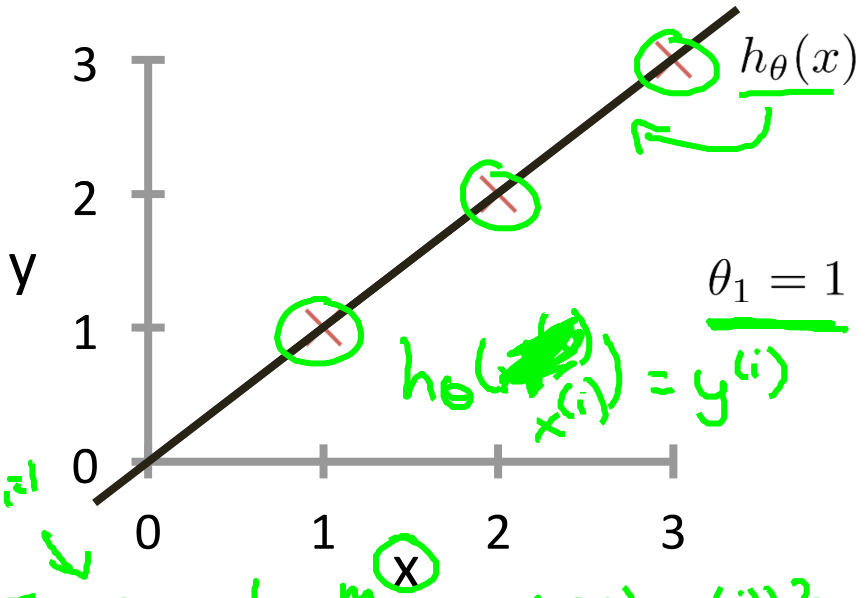
$$J(\theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

$\theta, x^{(i)}$

$\underset{\theta_1}{\text{minimize}}\ J(\theta_1)$

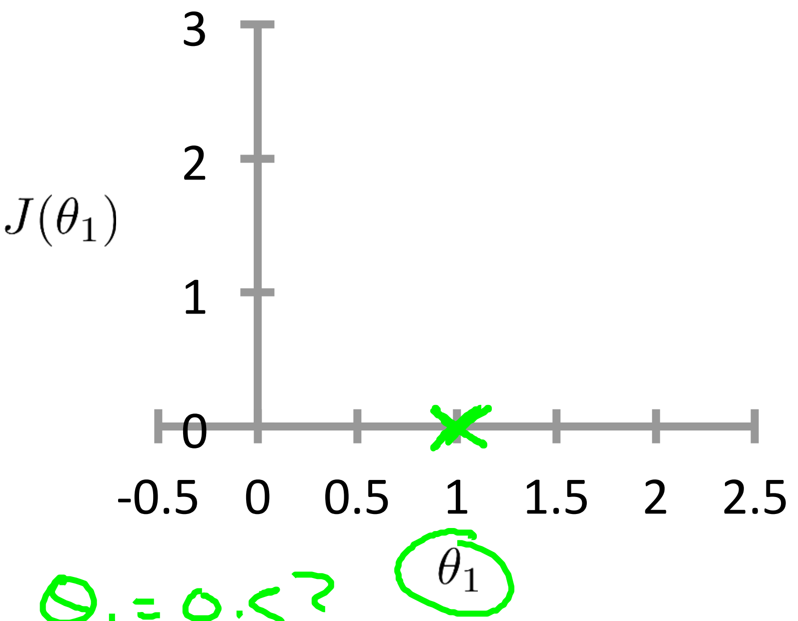
$\rightarrow h_\theta(x)$

(for fixed θ_1, this is a function of x)



$\rightarrow J(\theta_1)$

(function of the parameter θ_1)



$$J(\theta_1) = \frac{1}{2m}\sum_{i=1}^{m}\left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

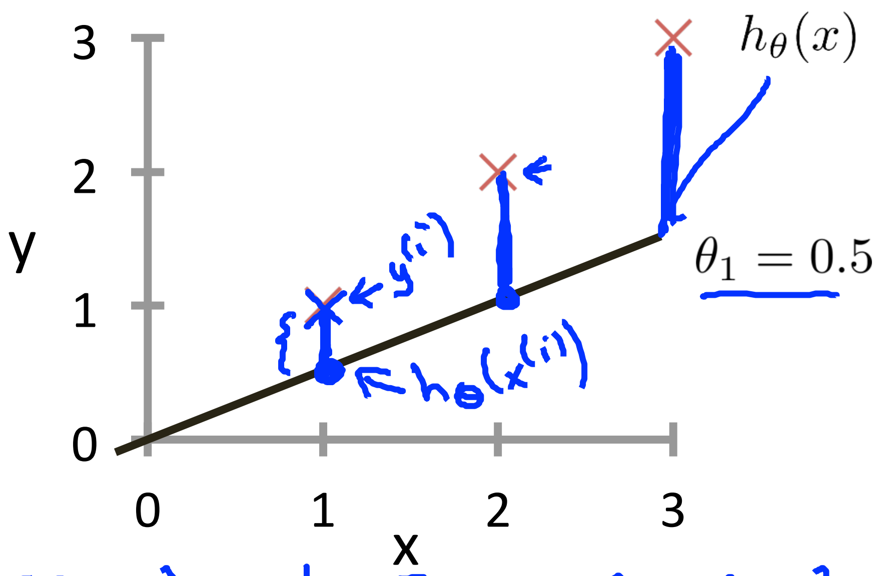
$$= \frac{1}{2m}\sum_{i=1}^{m}\left(\theta_1 x^{(i)} - y^{(i)}\right)^2 = \frac{1}{2m}(0^2 + 0^2 + 0^2) = 0^2$$

$\theta_1 = 0.5$?

$J(1) = 0$

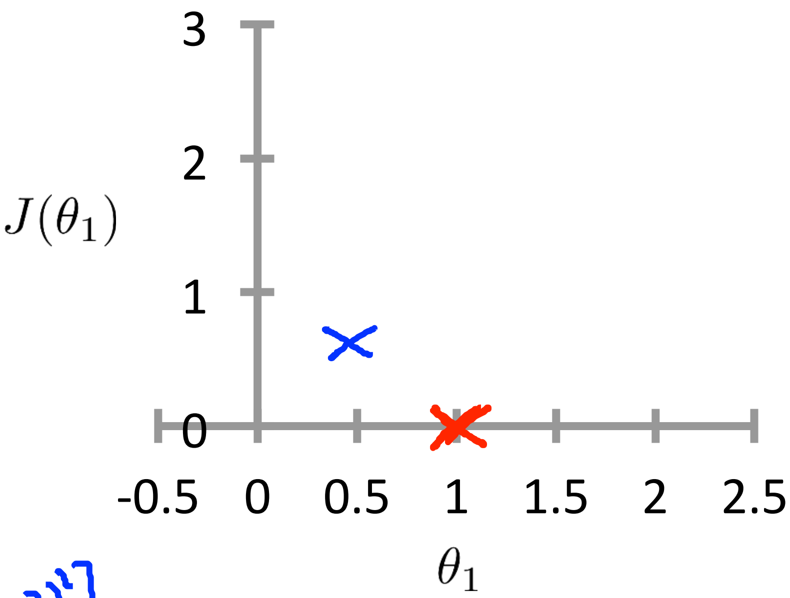
$h_\theta(x)$

(for fixed θ_1, this is a function of x)



$J(\theta_1)$

(function of the parameter θ_1)



$J(0.5) = \frac{1}{2m}\left[(0.5-1)^2 + (1-2)^2 + (1.5-3)^2\right]$

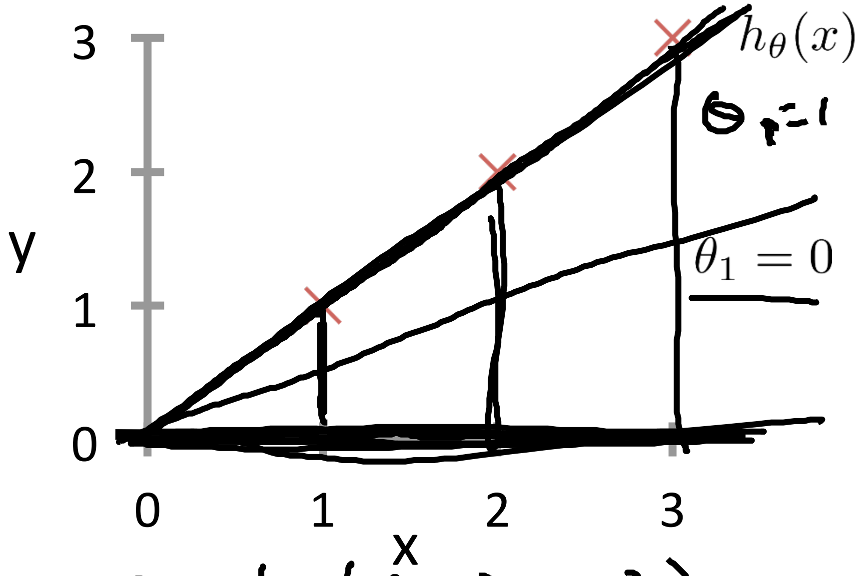
$= \frac{1}{2\times 3}(3.5) = \frac{3.5}{6} \approx 0.58$

$\theta_1 = 0?$

$J(0) = ?$ = 14/6

$h_\theta(x)$

(for fixed θ_1, this is a function of x)

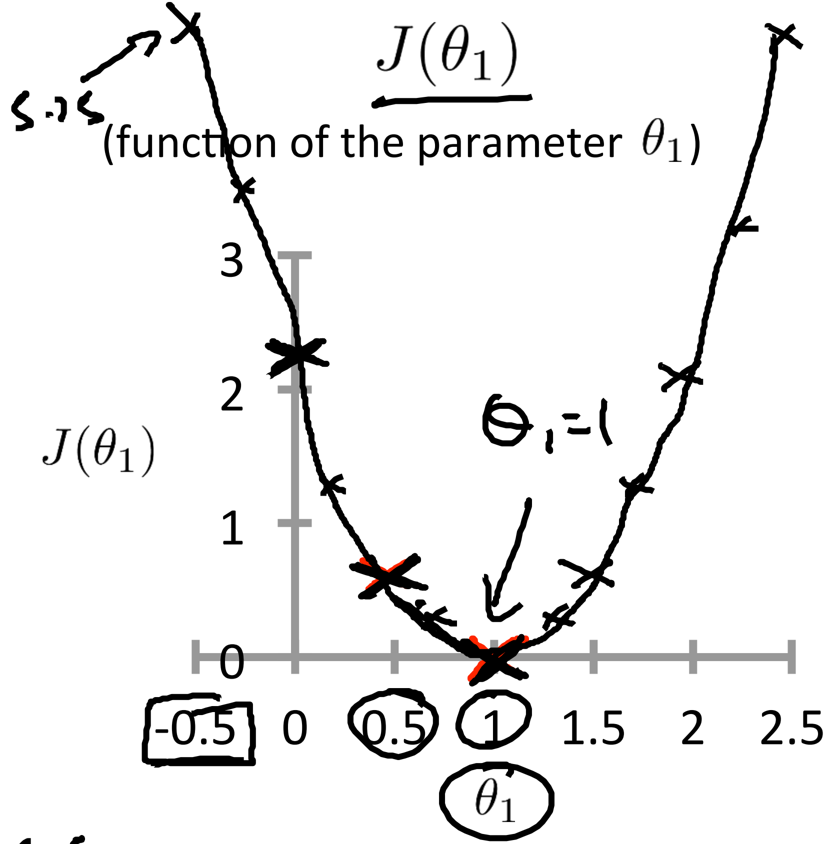


$J(0) = \frac{1}{2m}(1^2 + 2^2 + 3^2)$

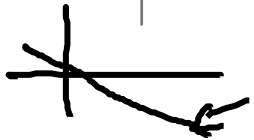
$= \frac{1}{6} \cdot 14 \approx 2.3$

$J(\theta_1)$

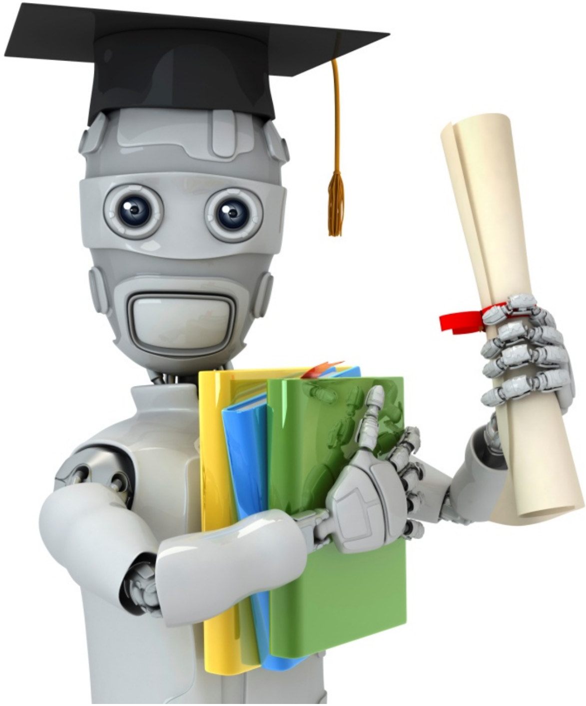
(function of the parameter θ_1)



$h(x) = -0.5x$



$\boxed{\underset{\theta_1}{\text{minimize}}\ J(\theta_1)}$



Machine Learning

Linear regression with one variable

Cost function intuition II

Hypothesis: $h_\theta(x) = \theta_0 + \theta_1 x$

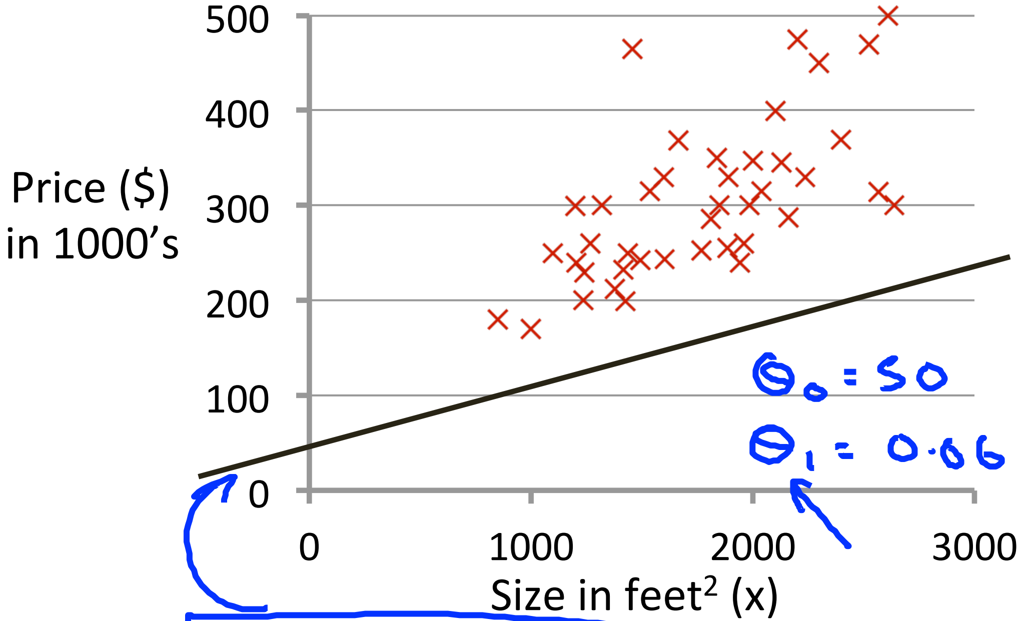
Parameters: $\underline{\theta_0, \theta_1}$

Cost Function: $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$

Goal: $\underset{\theta_0, \theta_1}{\text{minimize}}\ J(\theta_0, \theta_1)$

$h_\theta(x)$

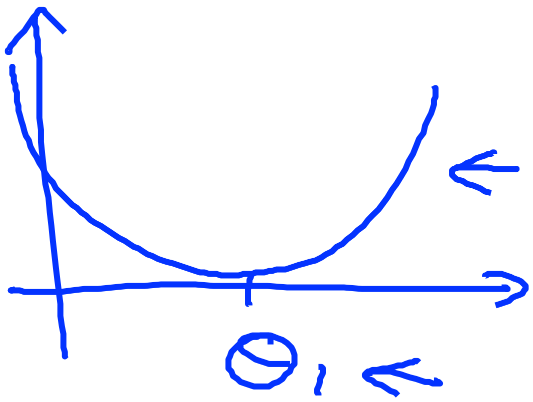
(for fixed θ_0, θ_1, this is a function of x)



$$\boxed{h_\theta(x) = 50 + 0.06x}$$

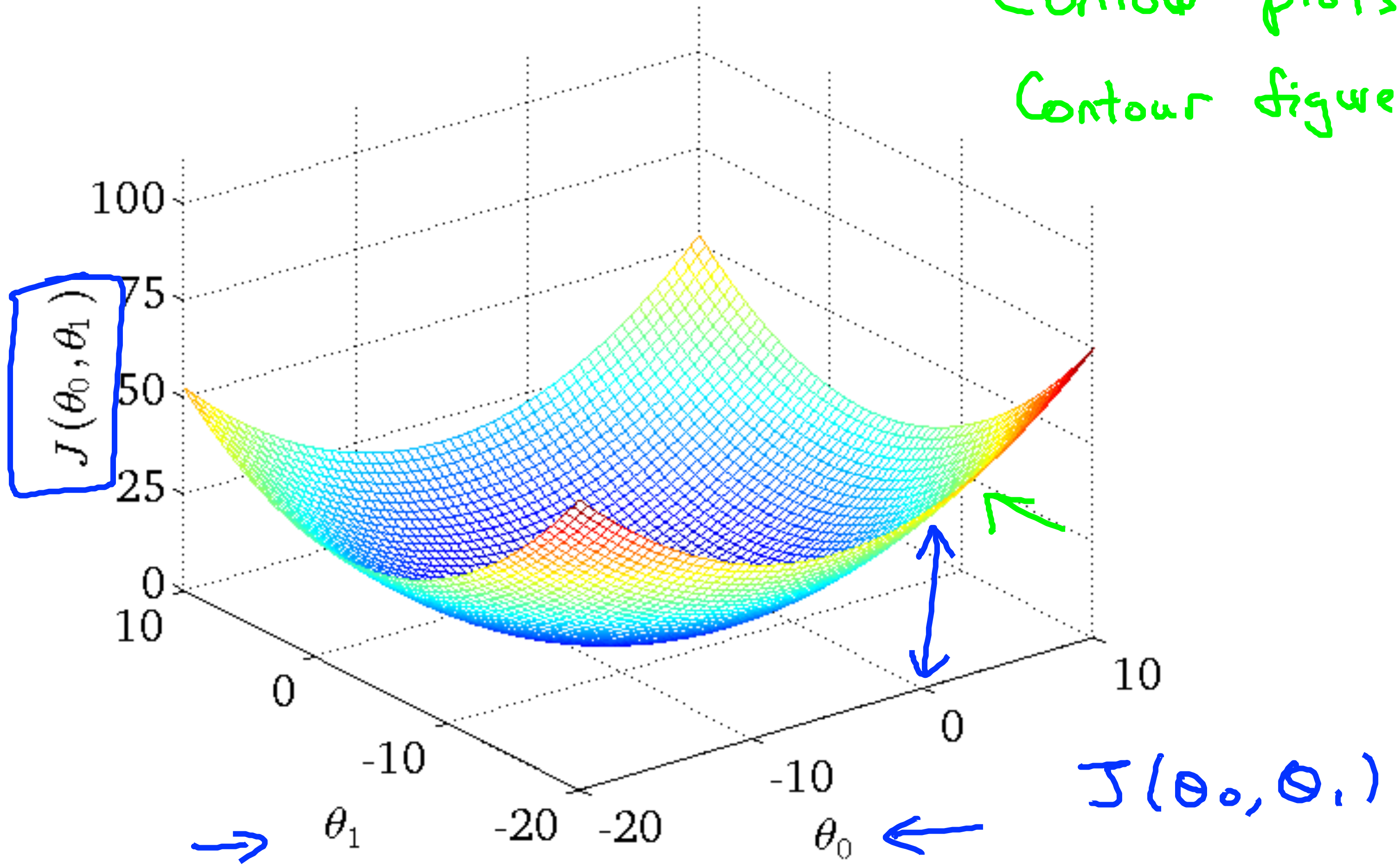
$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



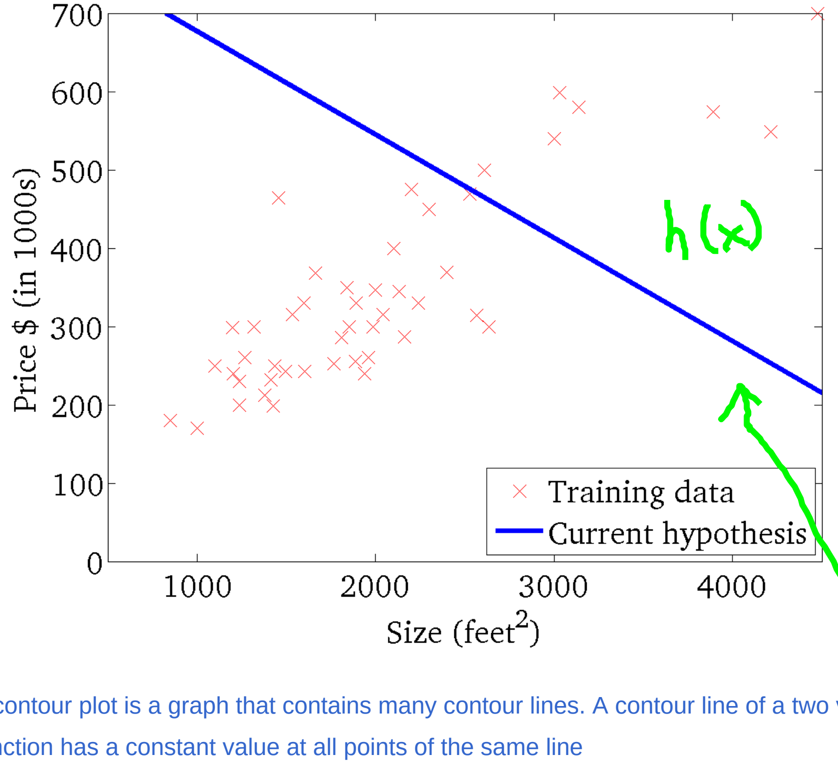
$$\boxed{\theta_0, \theta_1}$$

Contour plots
Contour figures.



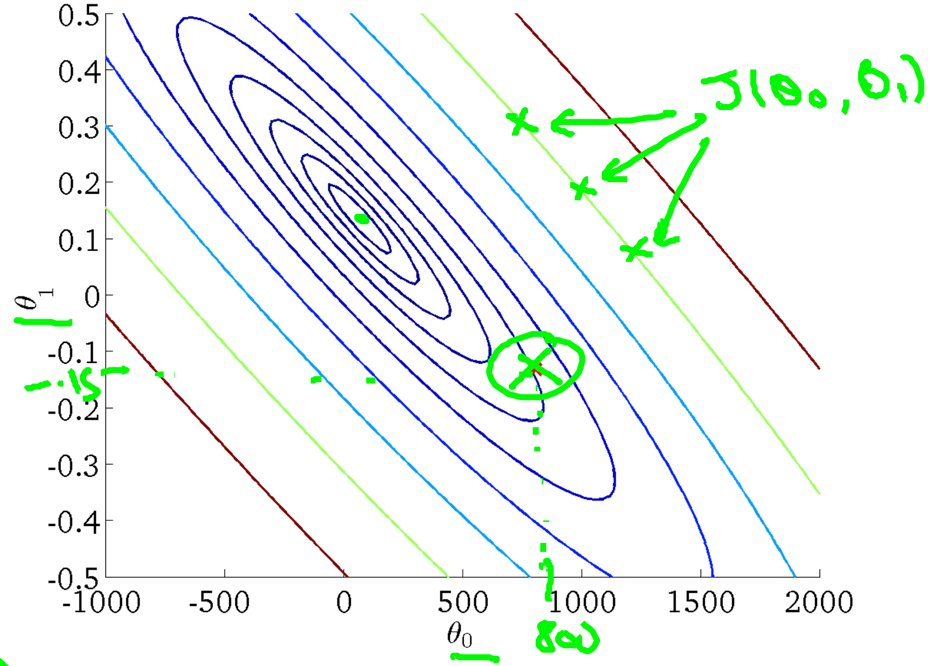
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)

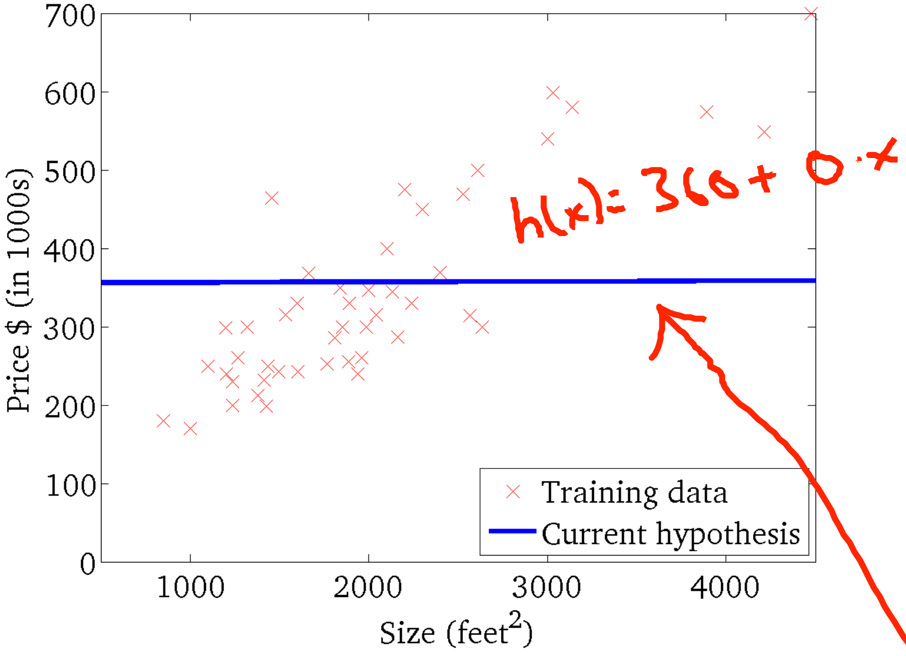


A contour plot is a graph that contains many contour lines. A contour line of a two variable function has a constant value at all points of the same line

Andrew Ng

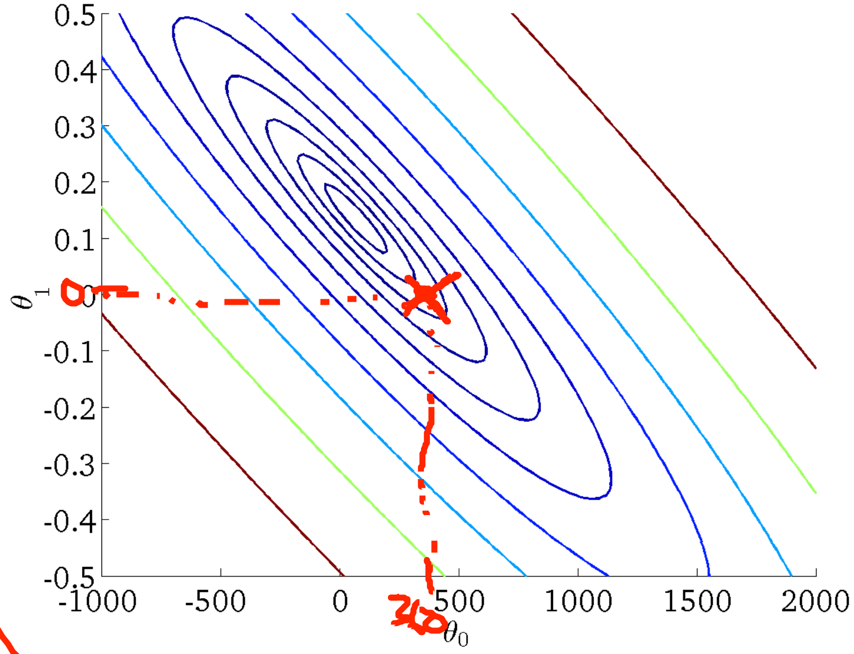
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



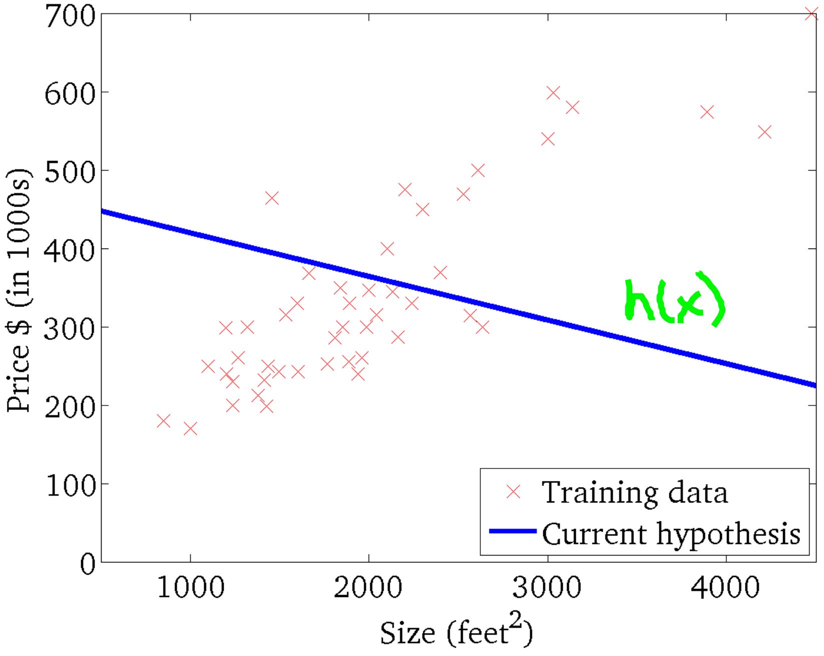
$\theta_0 = 360$

$\theta_1 = 0$

Andrew Ng

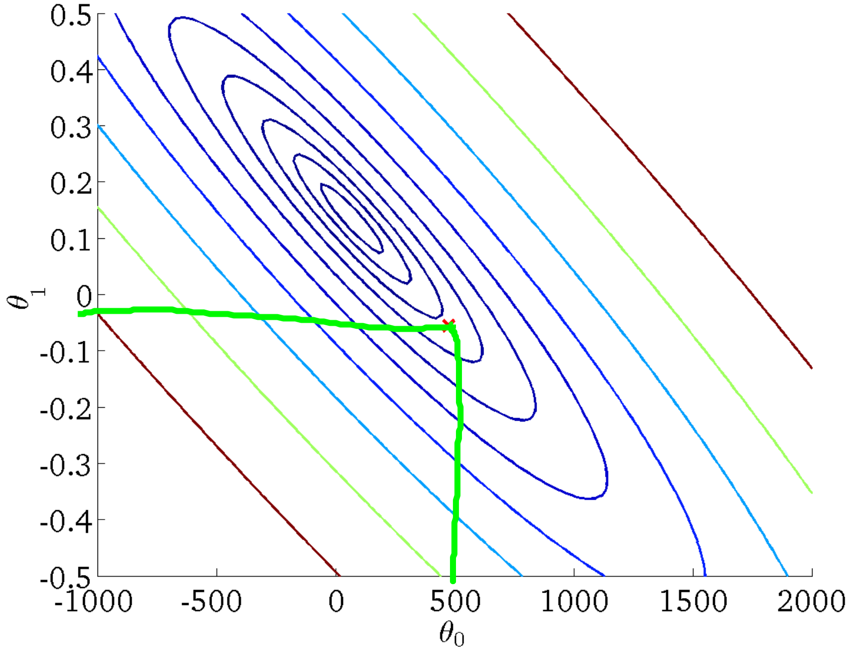
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



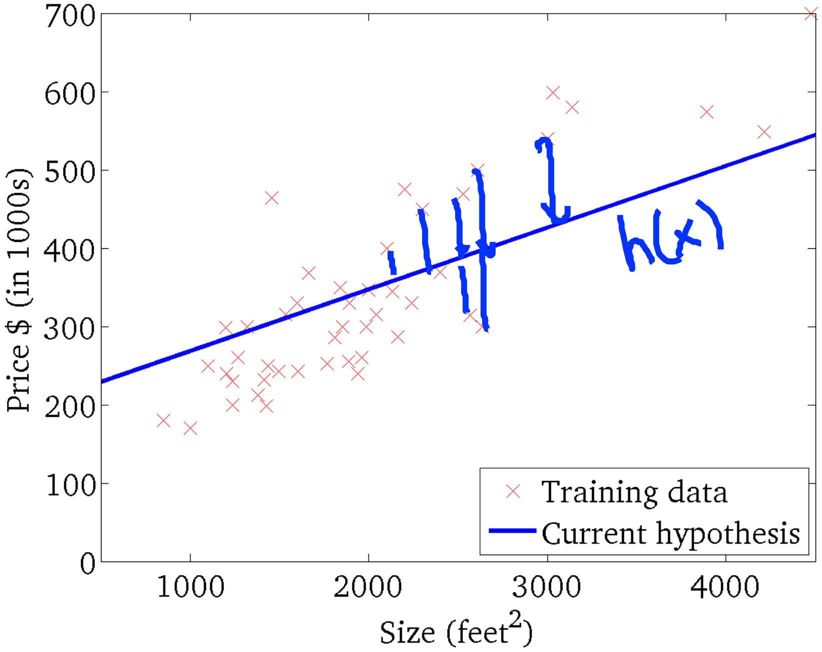
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



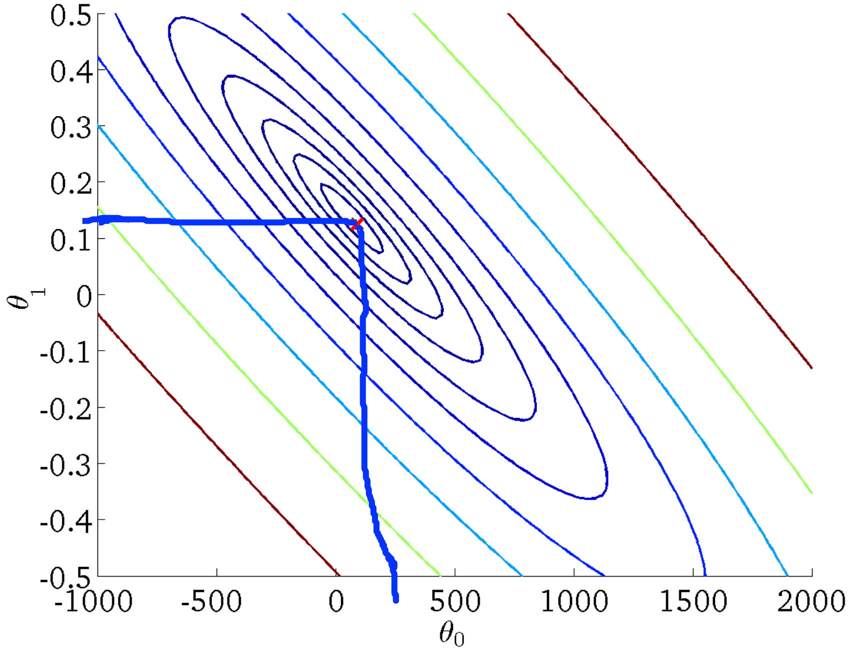
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



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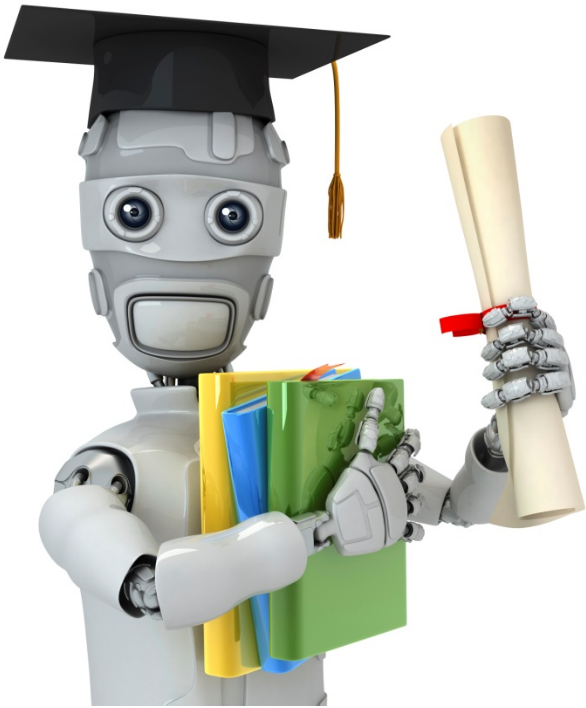


Machine Learning

Linear regression with one variable

Gradient descent

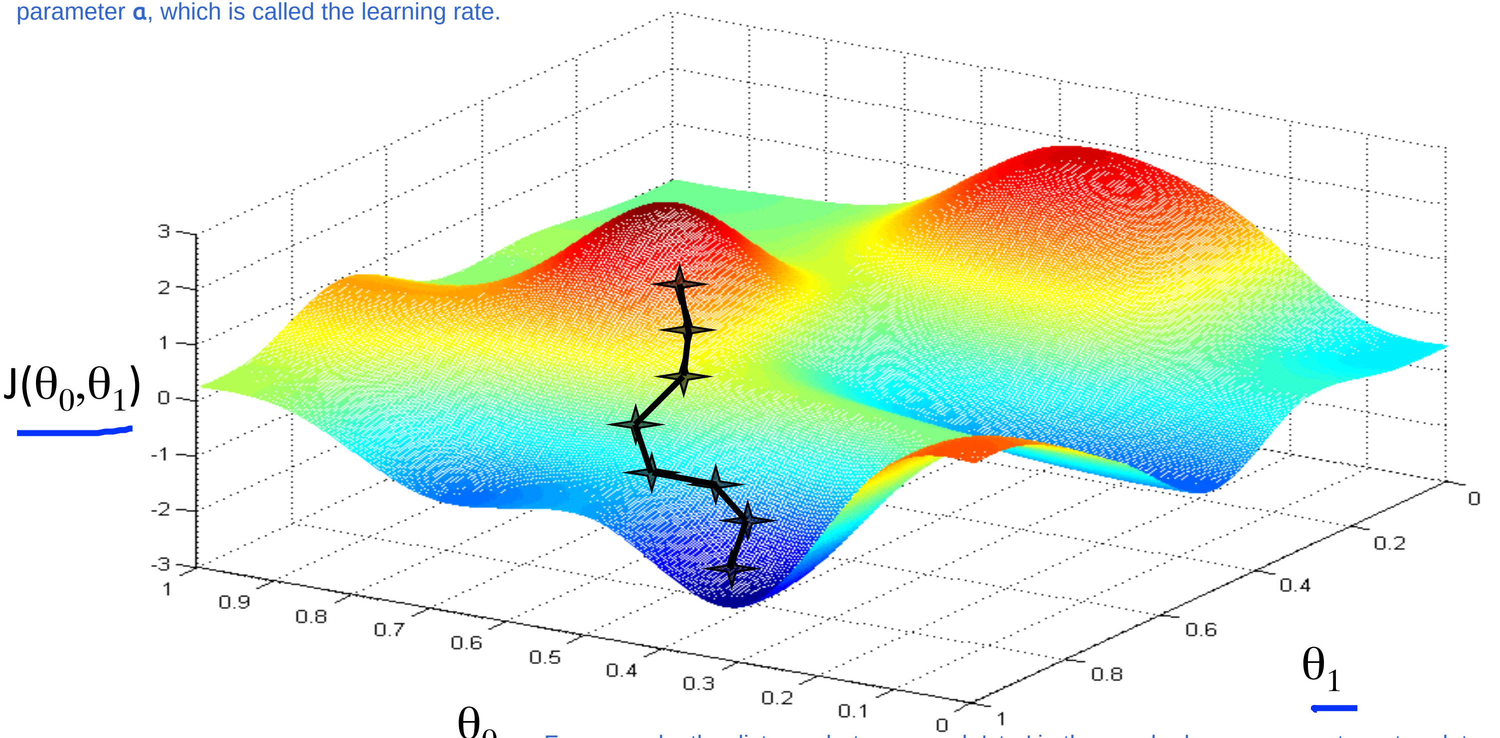
Have some function $J(\theta_0, \theta_1)$ $J(\theta_0, \theta_1, \theta_2, \ldots, \theta_n)$

Want $\min_{\theta_0, \theta_1} J(\theta_0, \theta_1)$ $\min_{\theta_0, \ldots, \theta_n} J(\theta_0, \ldots, \theta_n)$

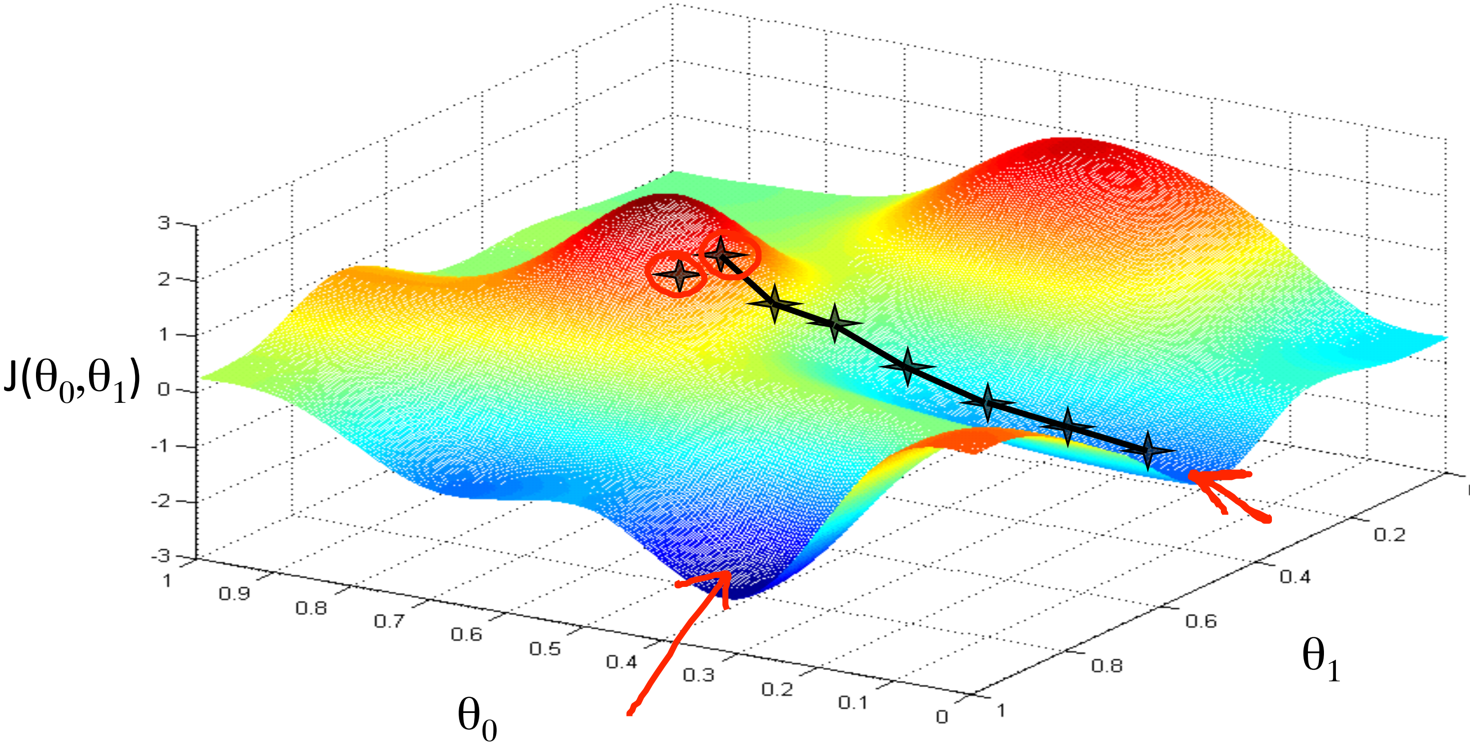
Outline:

- Start with some θ_0, θ_1 (say $\theta_0 = 0, \theta_1 = 0$)
- Keep changing θ_0, θ_1 to reduce $J(\theta_0, \theta_1)$ until we hopefully end up at a minimum

The way we do this is by taking the derivative (the tangential line to a function) of our cost function. The slope of the tangent is the derivative at that point and it will give us a direction to move towards. We make steps down the cost function in the direction with the steepest descent. The size of each step is determined by the parameter **α**, which is called the learning rate.



For example, the distance between each 'star' in the graph above represents a step determined by our parameter **α**. A smaller **α** would result in a smaller step and a larger **α** results in a larger step. The direction in which the step is taken is determined by the partial derivative of J(**θ** 0 ,**θ** 1).



3
2
1
0
-1
-2
-3
$J(\theta_0,\theta_1)$
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
θ_0
0
0.2
0.4
0.6
0.8
1
θ_1

Gradient descent algorithm

Assignment | Truth assertion

$a := b$

$a := a + 1$

$a = b$

$a = a + 1$ X

Like Comparison operator not assignment

θ_0, θ_1

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \qquad (\text{for } j = 0 \text{ and } j = 1)$$

}

learning rate

Simultaneously update θ_0 and θ_1

القدام بعد كده theta0 & theta1 إستخدم

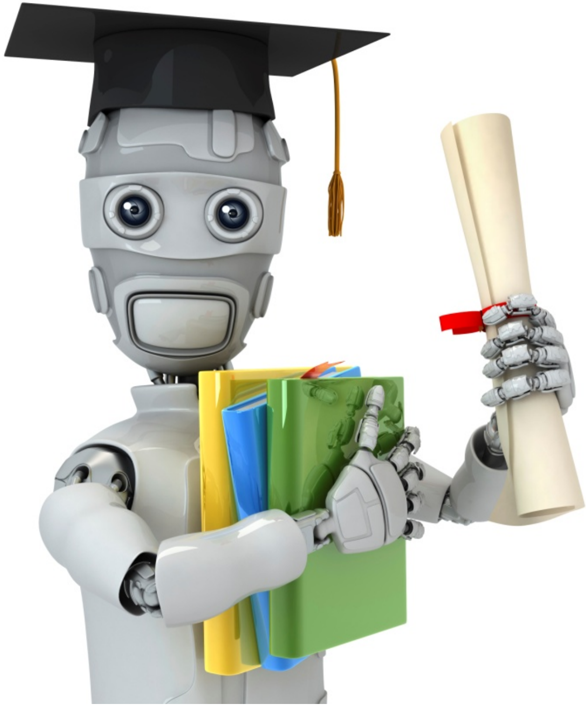
ليهم update عمل

Correct: Simultaneous update

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$
$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$
$$\theta_0 := \text{temp0}$$
$$\theta_1 := \text{temp1}$$

Incorrect:

$$\text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$
$$\theta_0 := \text{temp0}$$
$$\text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$
$$\theta_1 := \text{temp1}$$



Machine Learning

Linear regression with one variable

Gradient descent intuition

Gradient descent algorithm

repeat until convergence {

$$\theta_j := \theta_j - \alpha \boxed{\frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)} \quad \text{(simultaneously update } j = 0 \text{ and } j = 1\text{)}$$

Partial Derivative

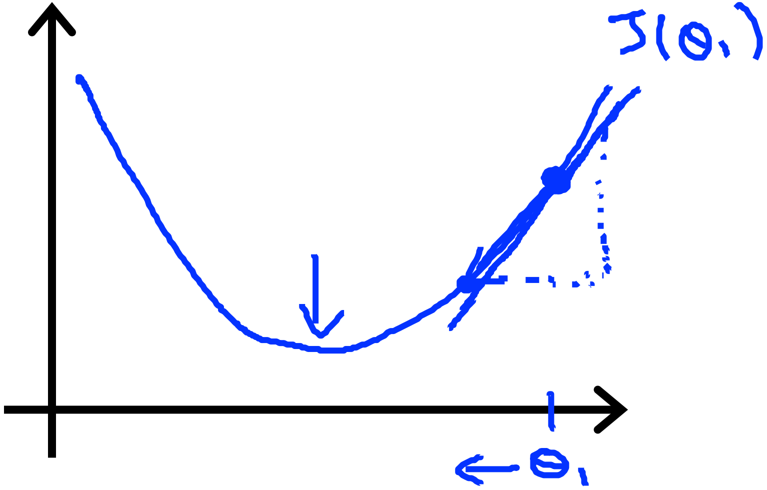
}

learning rate

Derivative

$\min_{\theta_1} J(\theta_1)$

$\theta_1 \in \mathbb{R}$.



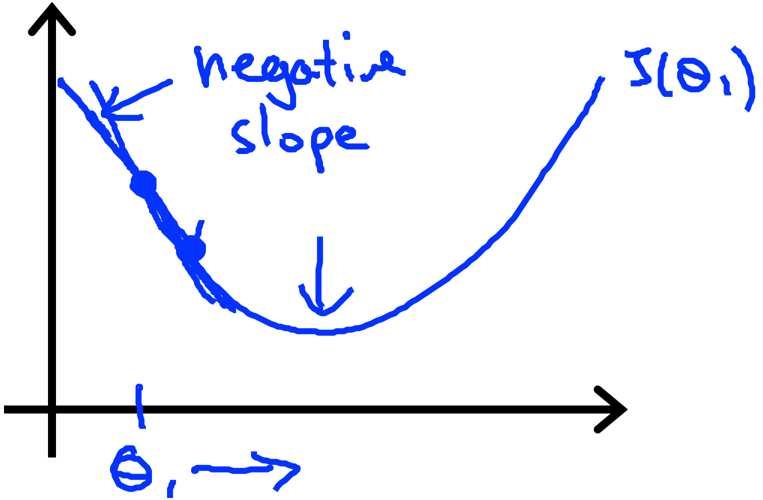
$(\theta_1 \in \mathbb{R})$

$$\frac{\partial}{\partial \theta_1}$$

$$\theta_1 := \theta_1 - \alpha \boxed{\frac{d}{d\theta_1} J(\theta_1)}$$

≥ 0

$$\theta_1 := \theta_1 - \underline{\alpha} \cdot (\text{positive number})$$



$$\underline{\frac{d}{d\theta_1} J(\theta_1)}$$

≤ 0

$$\theta_1 := \underline{\theta_1} - \alpha\,(\text{negative number})$$

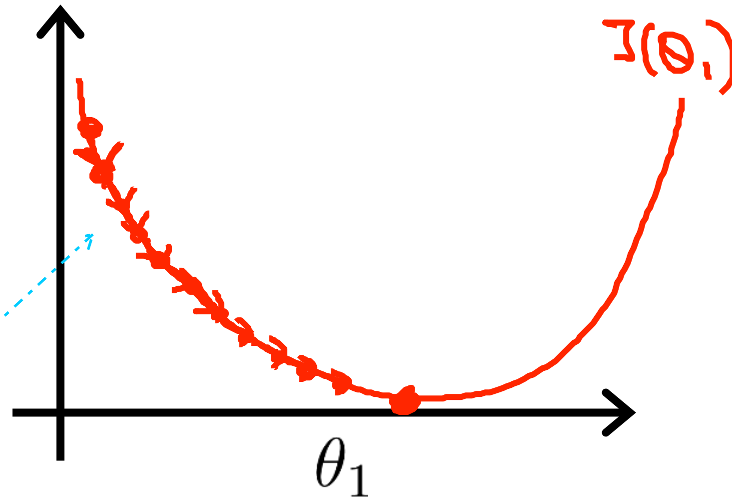
we should adjust our parameter \alpha$\alpha$ to ensure that the gradient descent algorithm converges in a reasonable time. Failure to converge or too much time to obtain the minimum value imply that our step size is wrong.

$$\boxed{\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)}$$

If α is too small, gradient descent can be slow.

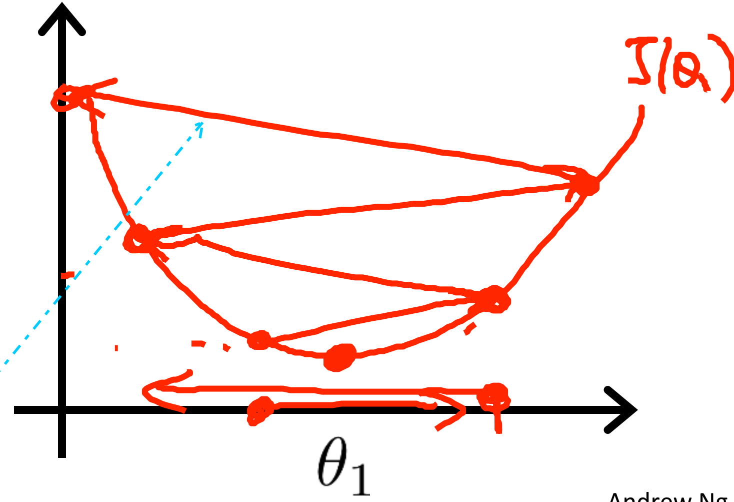
Steps will be too small

baby step



If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.

Overshooting



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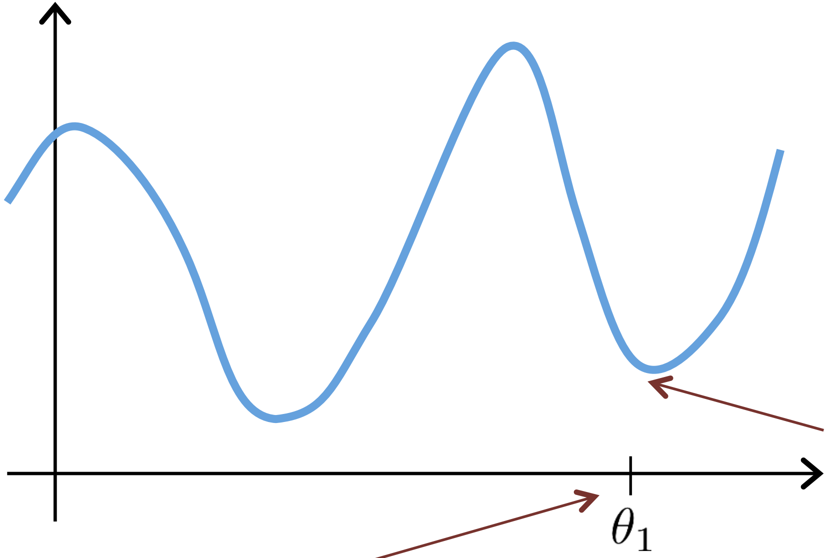


At local min; the derivative is equal to zero

θ_1 at local optima

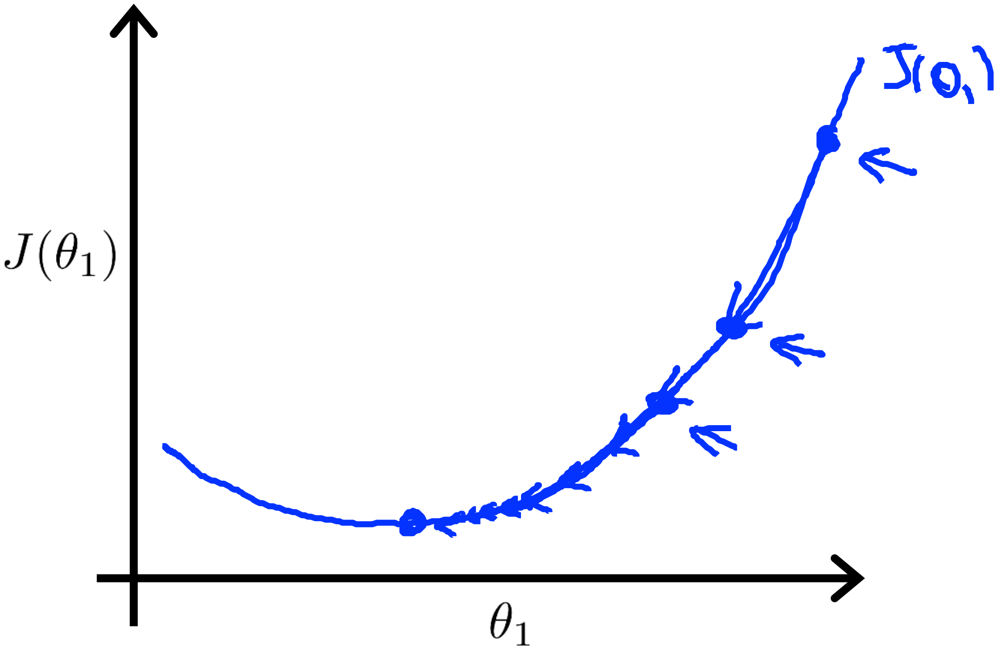
Current value of θ_1

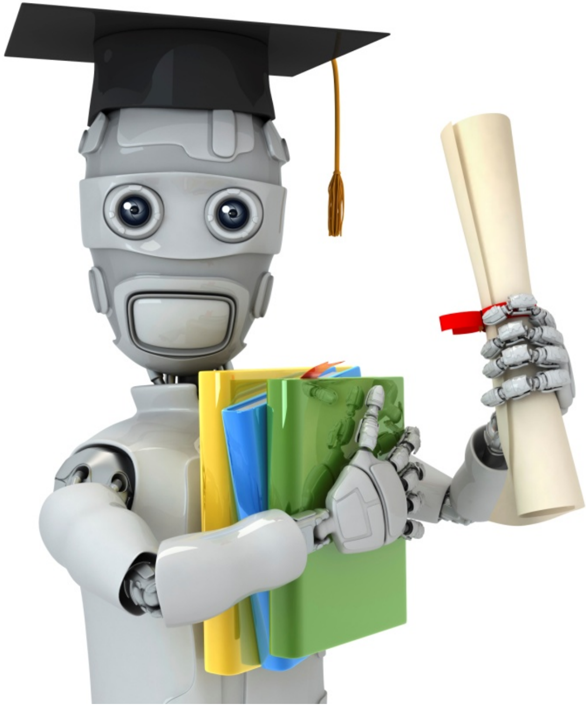
$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$

Gradient descent can converge to a local minimum, even with the learning rate α fixed.

$$\theta_1 := \theta_1 - \alpha \boxed{\frac{d}{d\theta_1} J(\theta_1)}$$

As we approach a local minimum, gradient descent will automatically take smaller steps. So, no need to decrease α over time.





Machine Learning

Linear regression with one variable

Gradient descent for linear regression

Gradient descent algorithm

$$\text{repeat until convergence } \{$$

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$$

$$(\text{for } j = 1 \text{ and } j = 0)$$

$$\}$$

Linear Regression Model

$$h_\theta(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

$$\frac{\partial}{\partial\theta_j} \underline{J(\theta_0, \theta_1)} = \frac{\partial}{\partial\theta_j} \underline{\frac{1}{2m} \sum_{i=1}^{m} \left(\underline{h_\theta(x^{(i)}} - y^{(i)}\right)^2}$$

$$= \frac{\partial}{\partial\theta_j} \frac{1}{2m} \sum_{i=1}^{m} \left(\underline{\theta_0 + \theta_1 x^{(i)}} - y^{(i)}\right)^2$$

$$j = 0 : \underline{\frac{\partial}{\partial\theta_0} J(\theta_0, \theta_1)} = \frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)$$

$$j = 1 : \underline{\frac{\partial}{\partial\theta_1} J(\theta_0, \theta_1)} = \frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right) \cdot x^{(i)}$$

Gradient descent algorithm

$\frac{\partial}{\partial\theta_0} J(\theta_0, \theta_1)$

repeat until convergence {

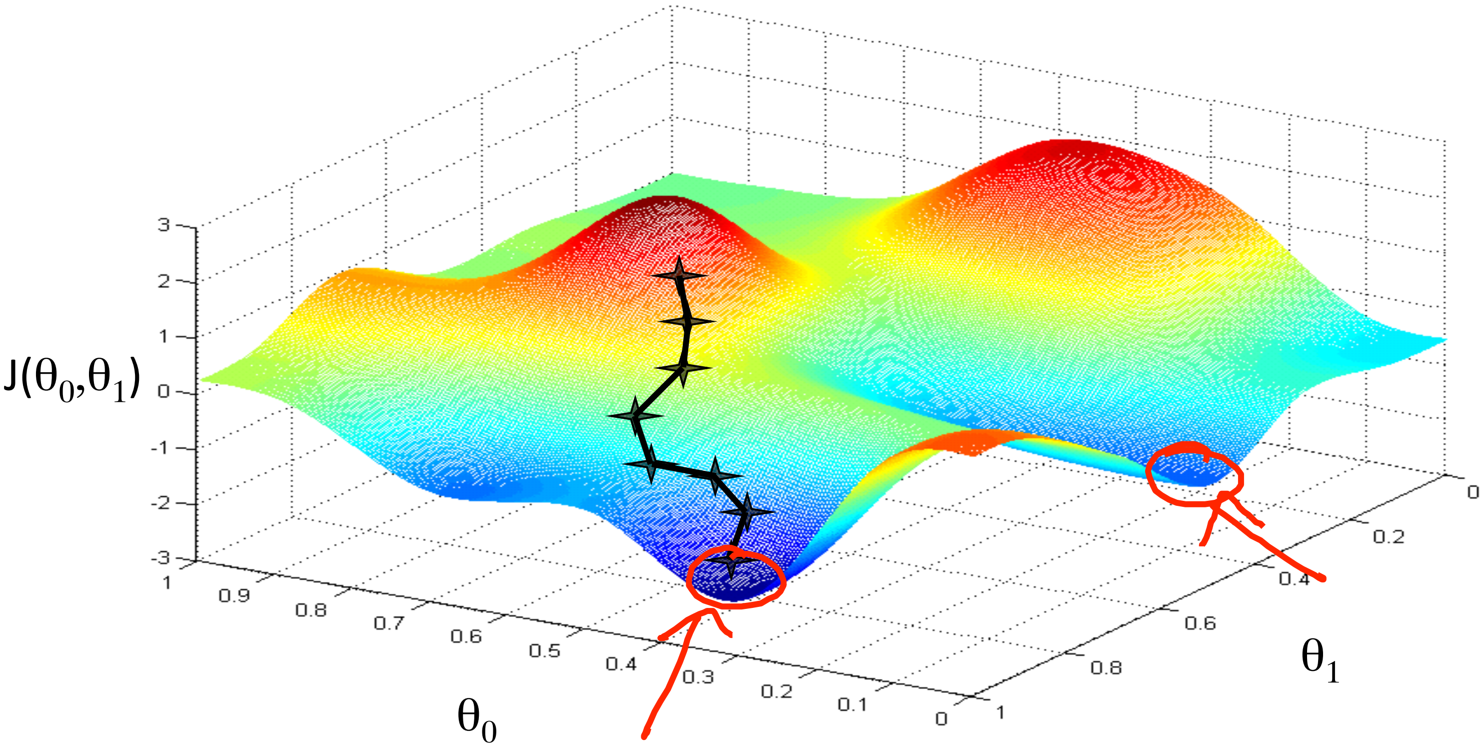
$$\theta_0 := \theta_0 - \alpha \boxed{\frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right)}$$

$$\theta_1 := \theta_1 - \alpha \boxed{\frac{1}{m} \sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)}\right) \cdot x^{(i)}}$$

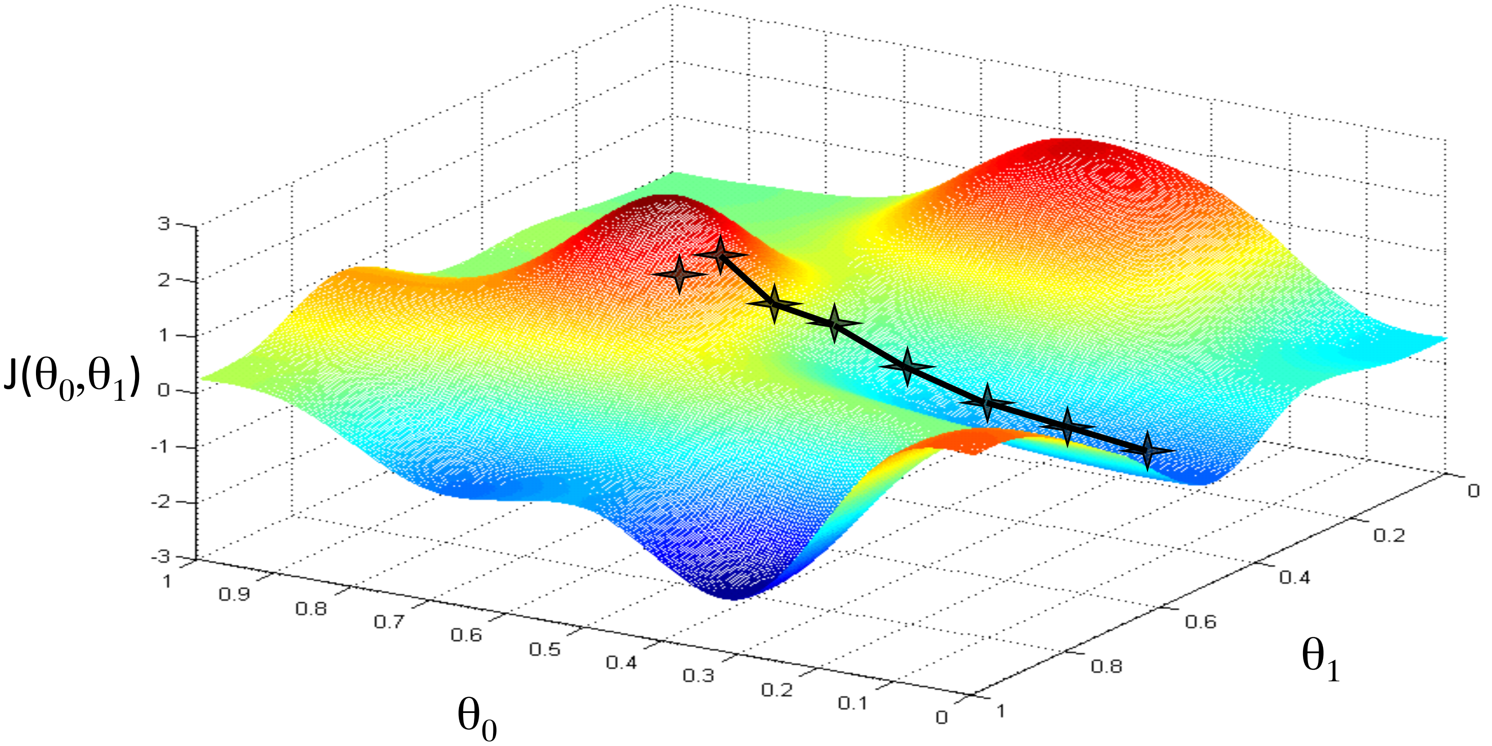
}

$\frac{\partial}{\partial\theta_1} J(\theta_0, \theta_1)$

update
θ_0 and θ_1
simultaneously



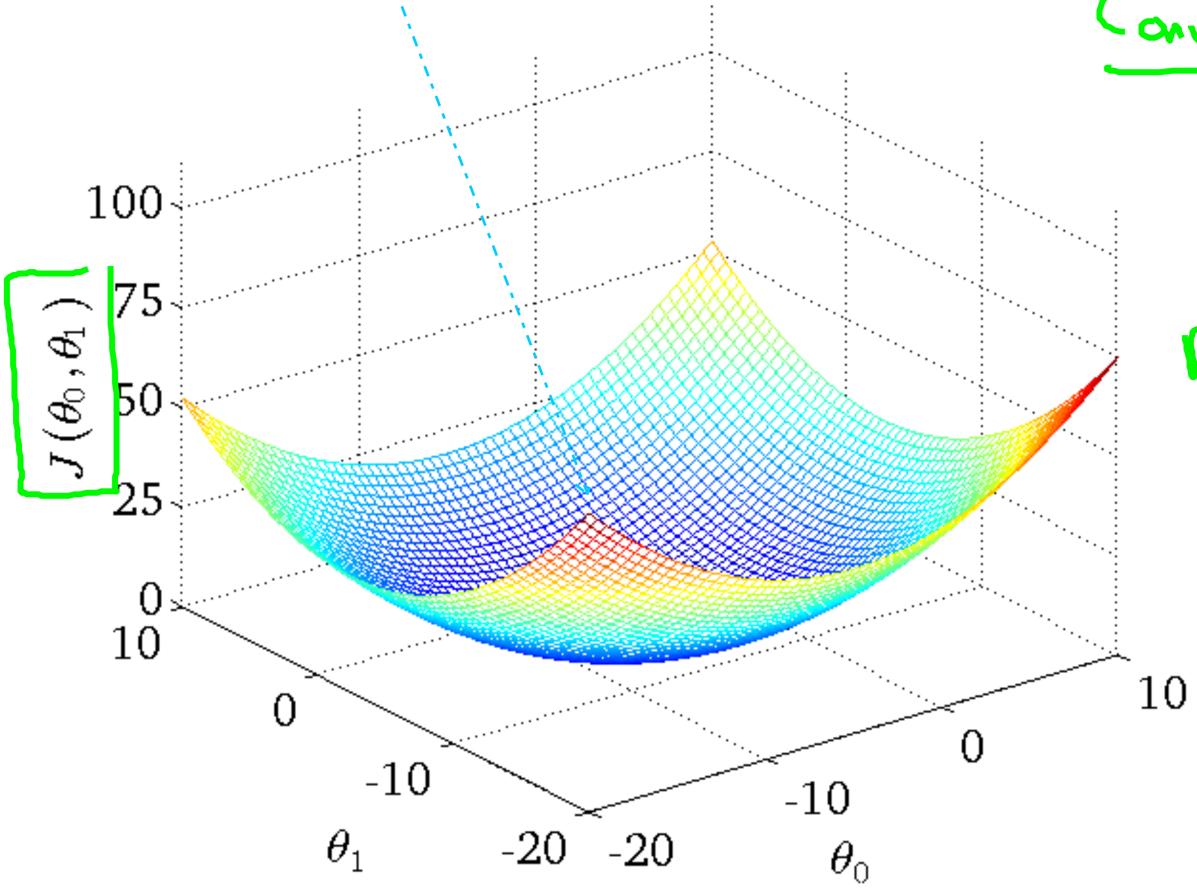
J(θ0,θ1)
θ0
θ1
3
2
1
0
-1
-2
-3
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
0
0.2
0.4
0.6
0.8
1



3
2
1
0
-1
-2
-3
$J(\theta_0,\theta_1)$
1
0.9
0.8
0.7
0.6
0.5
0.4
0.3
0.2
0.1
0
θ_0
0
0.2
0.4
0.6
0.8
1
θ_1

Only 1 local minimum

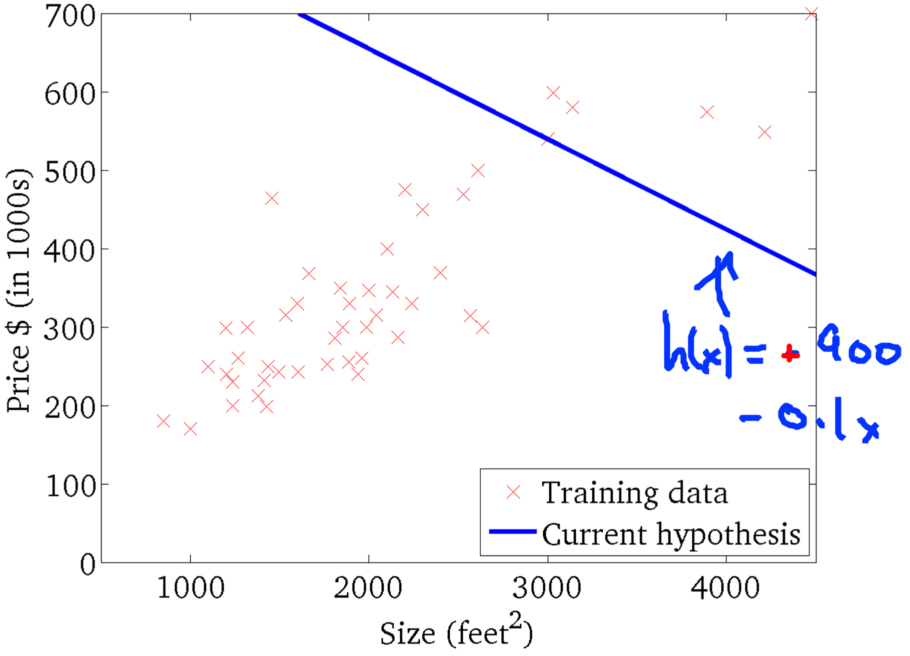
"Convex function"



Bowl-shaped

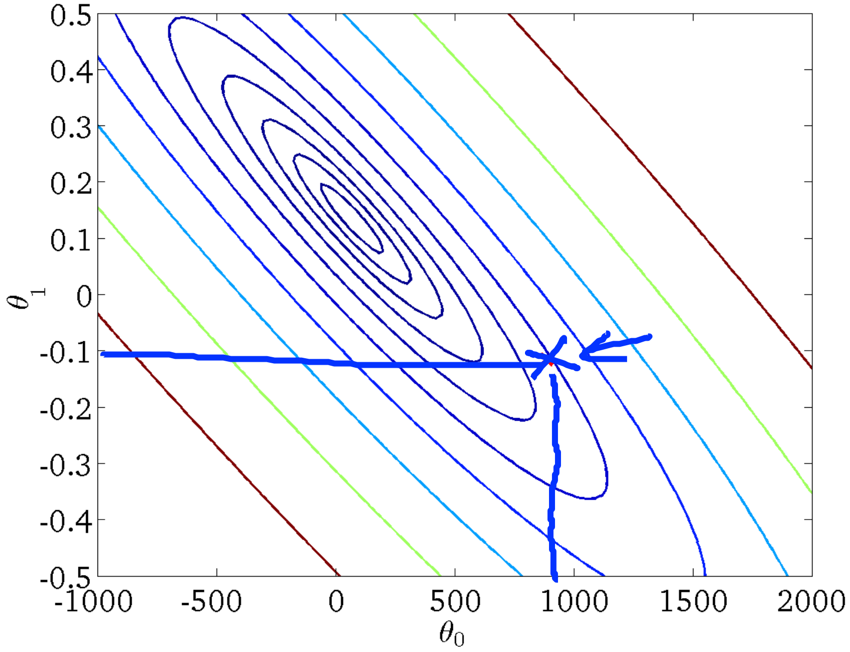
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



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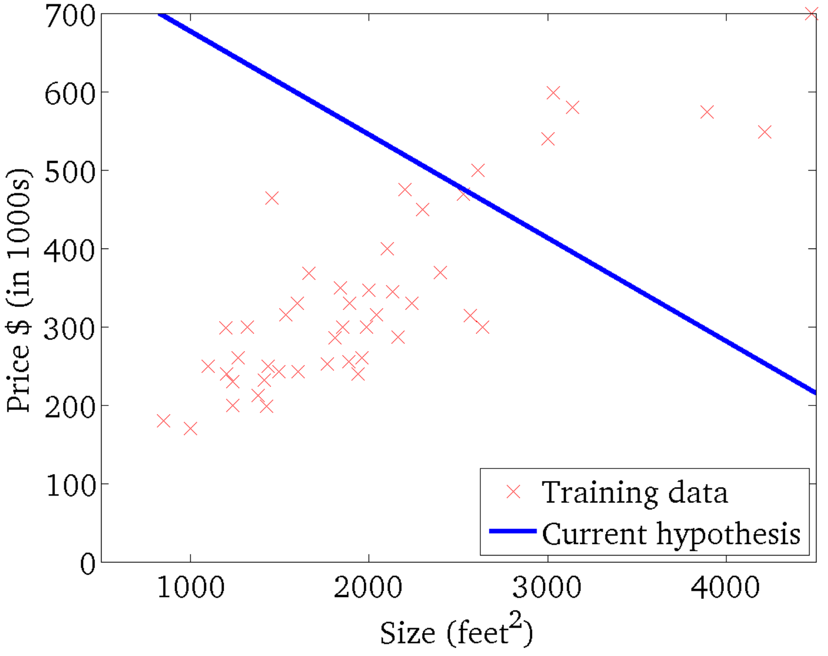
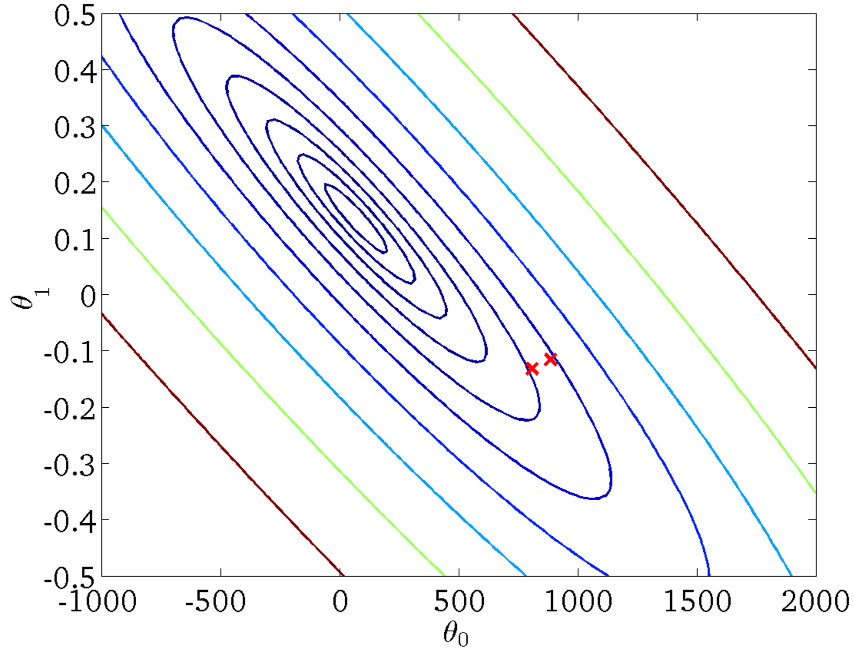
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



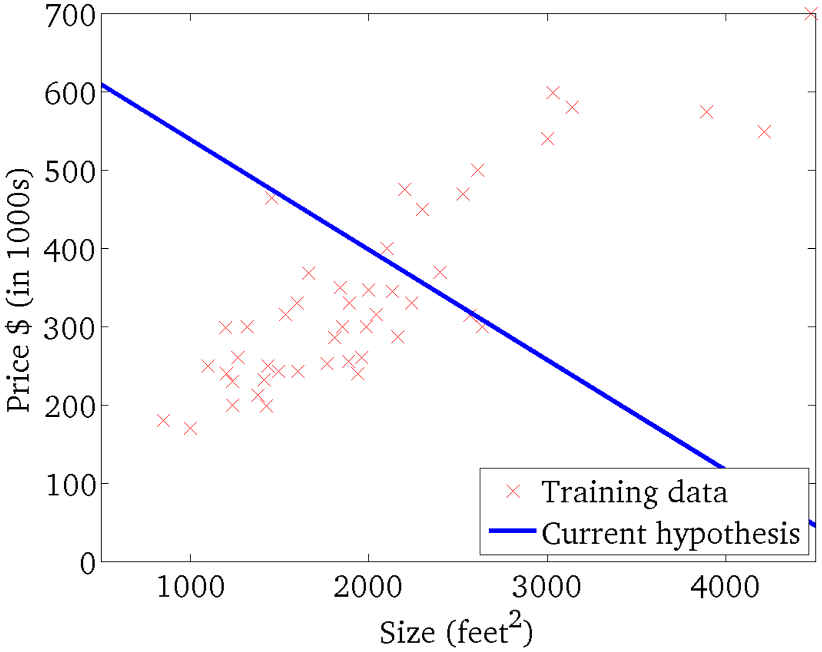
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



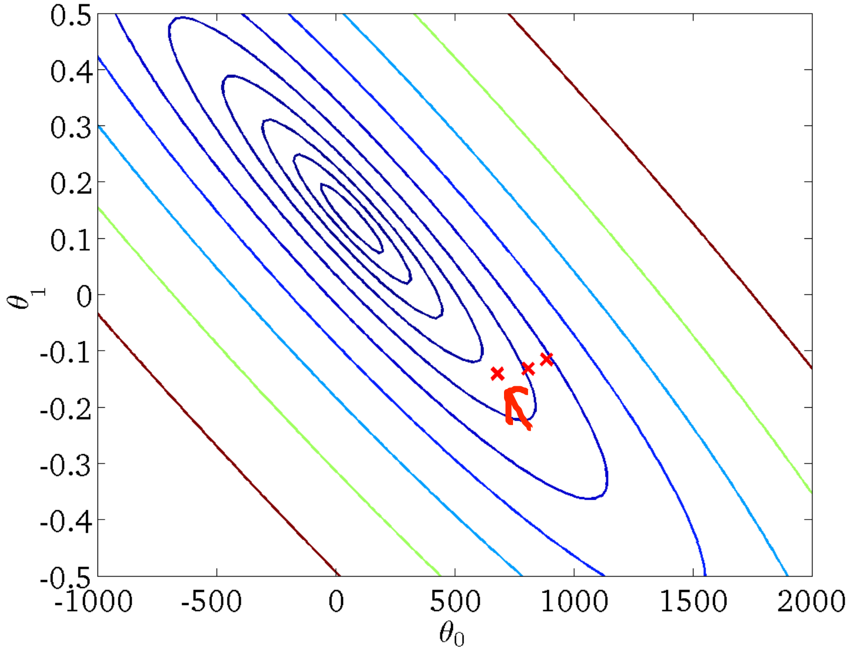
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



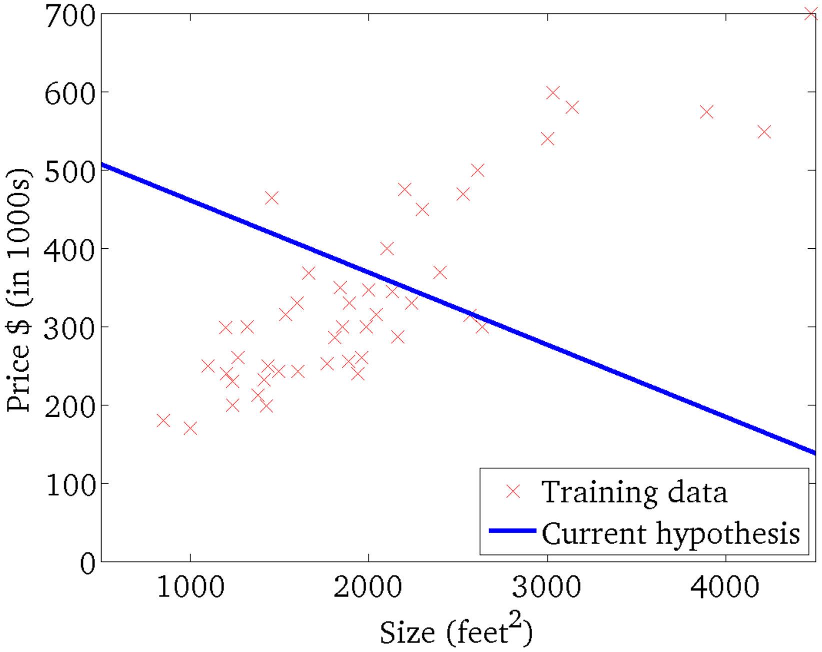
$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



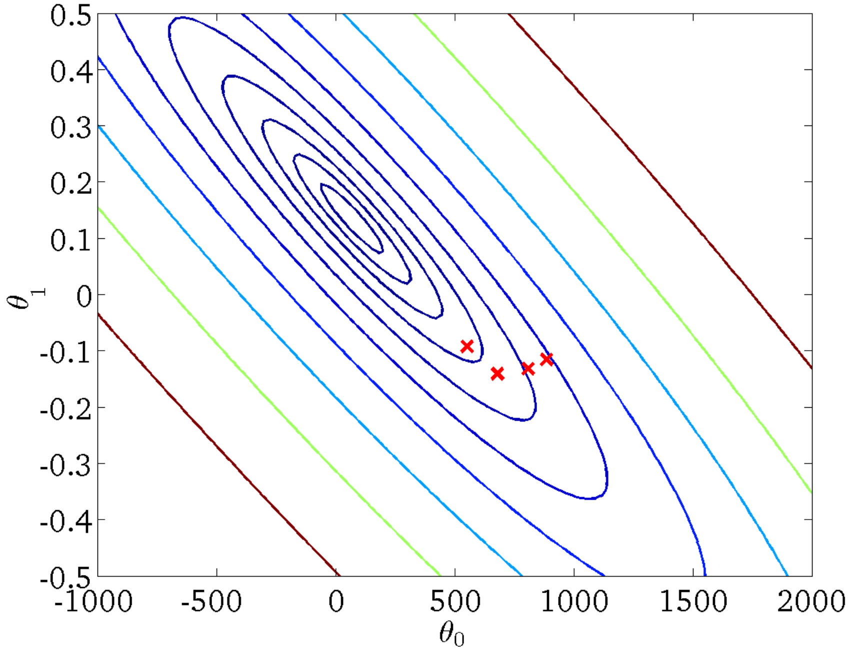
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



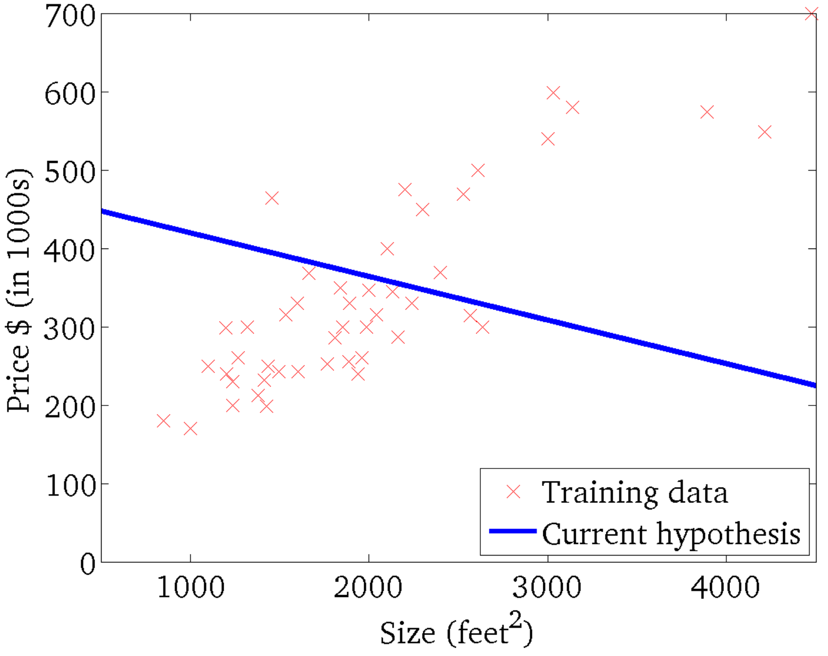
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



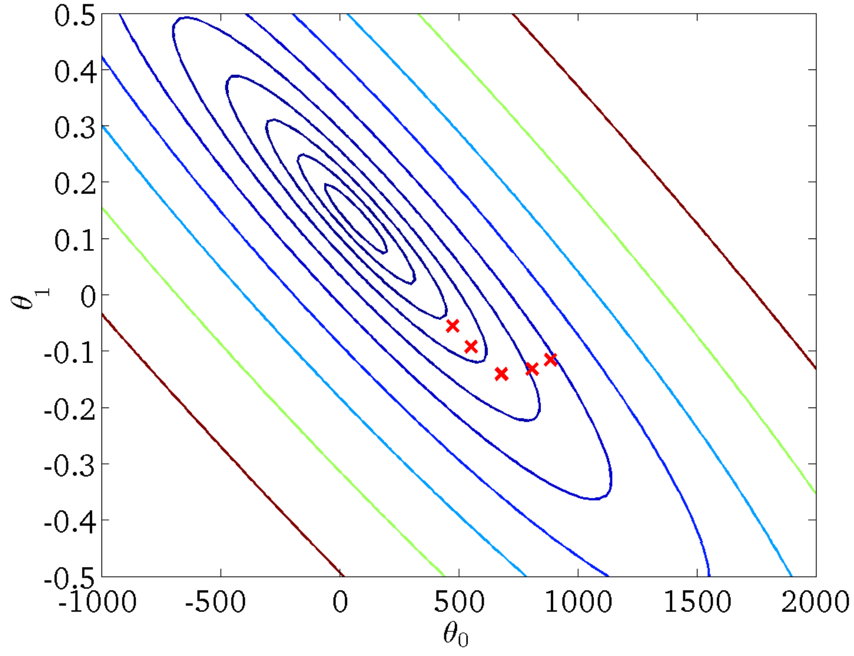
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)



$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)



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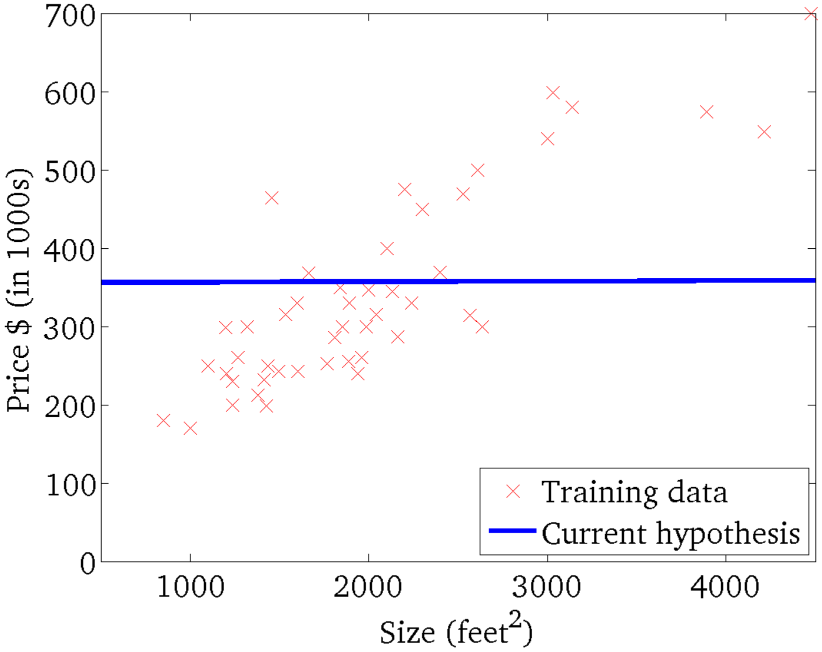
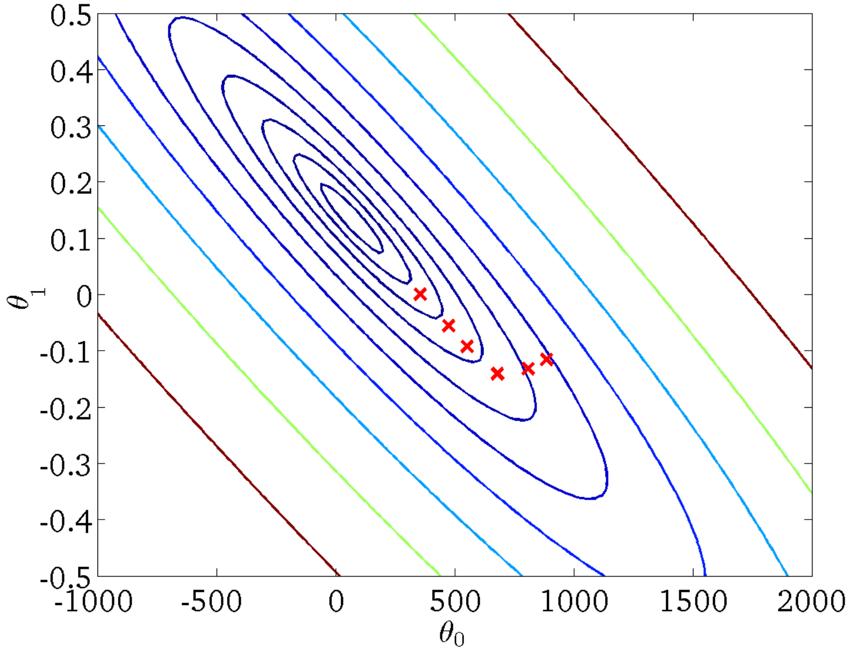
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)

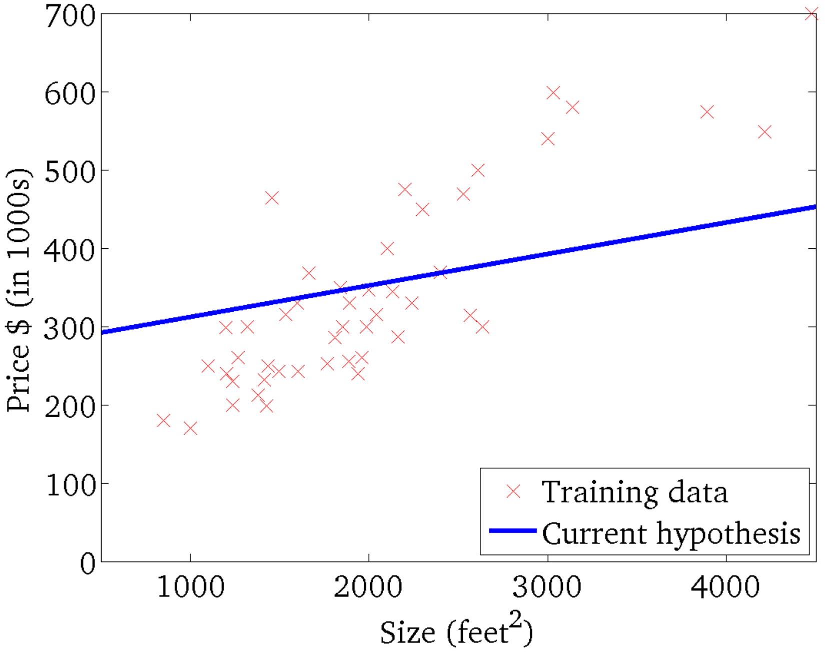


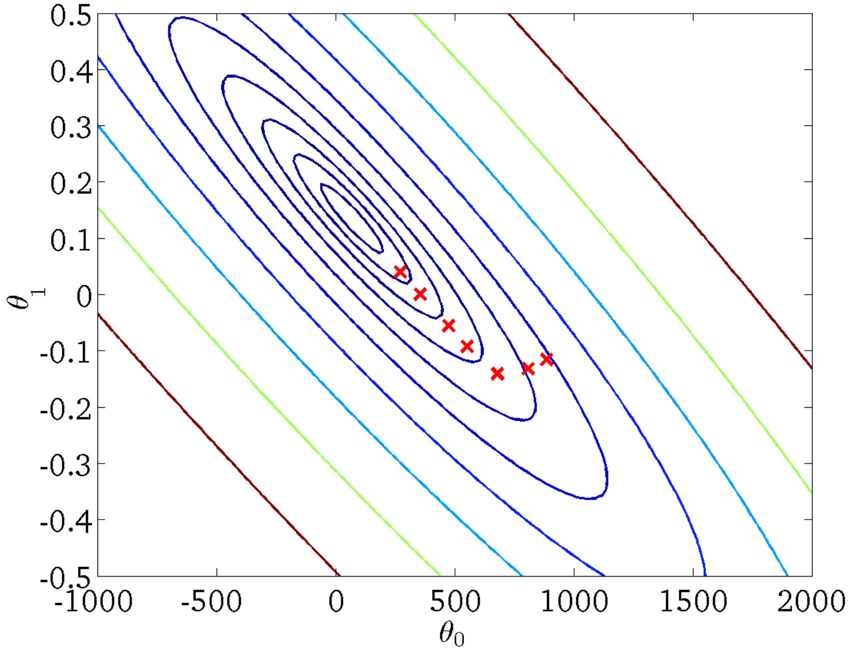
$h_\theta(x)$

(for fixed θ_0, θ_1, this is a function of x)

$J(\theta_0, \theta_1)$

(function of the parameters θ_0, θ_1)





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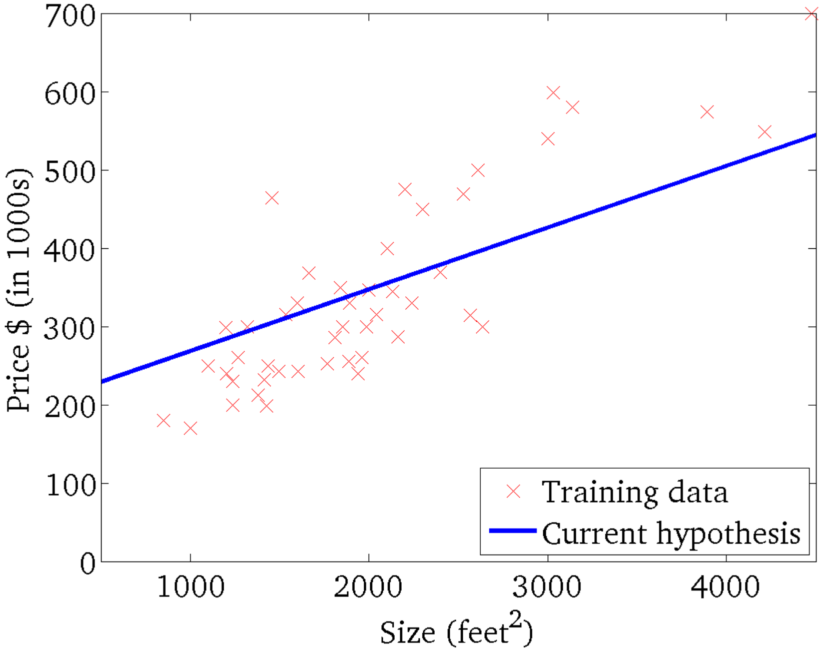
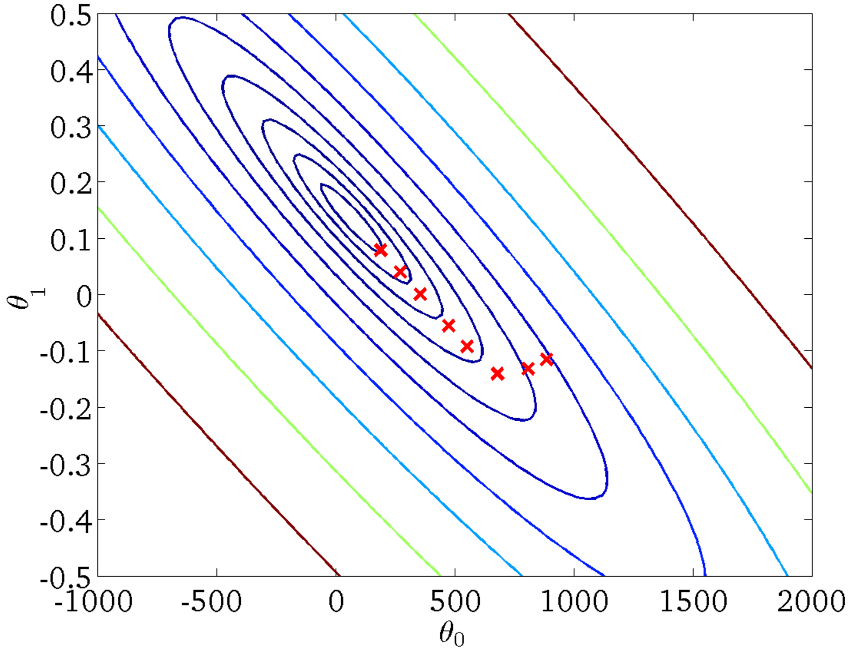
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



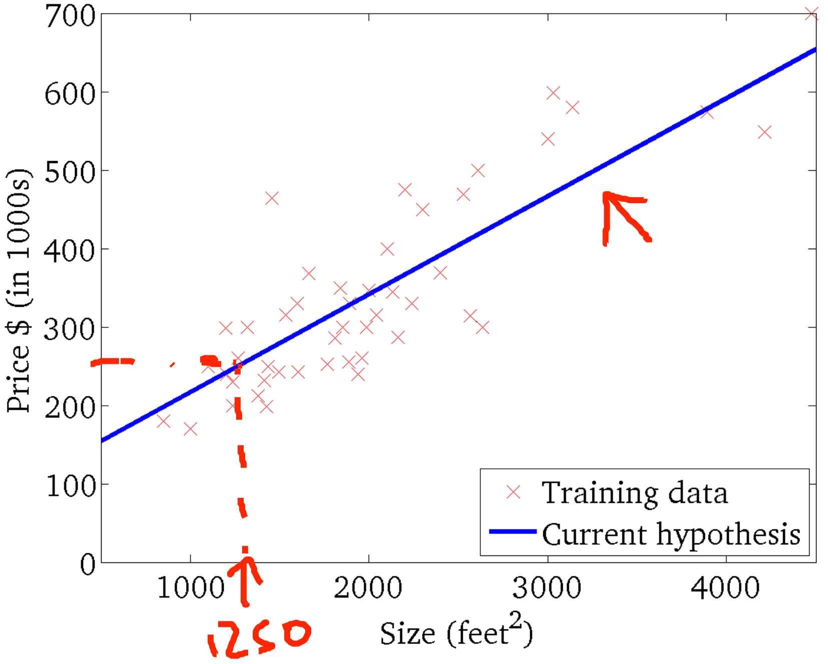
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



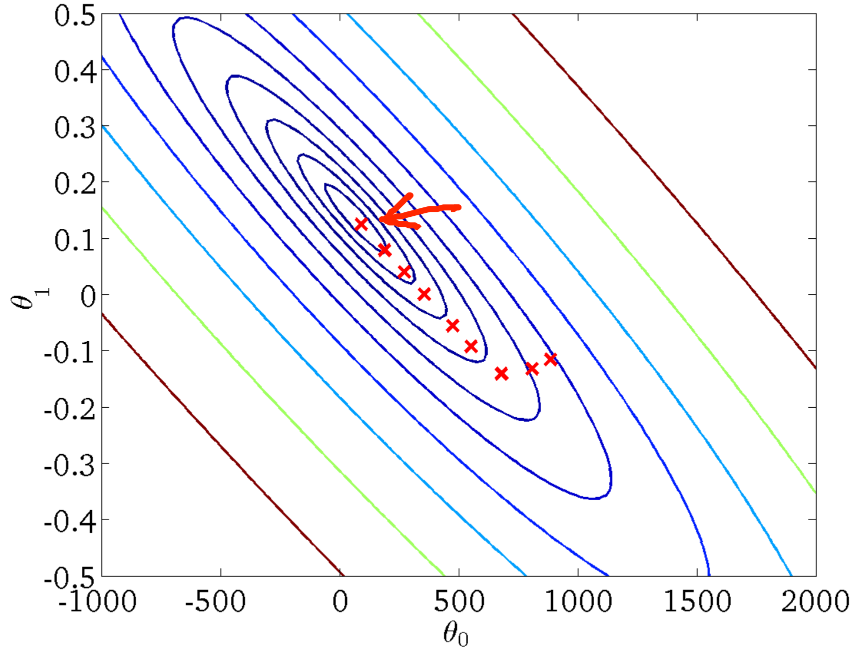
$$h_\theta(x)$$

(for fixed θ_0, θ_1, this is a function of x)



$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



Algorithm is sometimes called batch

"Batch" Gradient Descent

"Batch": Each step of gradient descent uses all the training examples.

$$\sum_{i=1}^{m} \left(h_\theta(x^{(i)}) - y^{(i)} \right)$$

This method looks at every example in the entire training set on every step, and is called batch gradient descent. Note that, while gradient descent can be susceptible to local minima in general, the optimization problem we have posed here for linear regression has only one global, and no other local, optimum