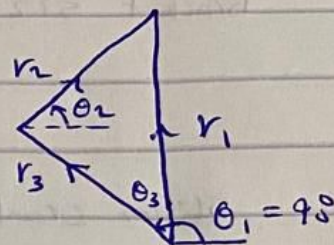
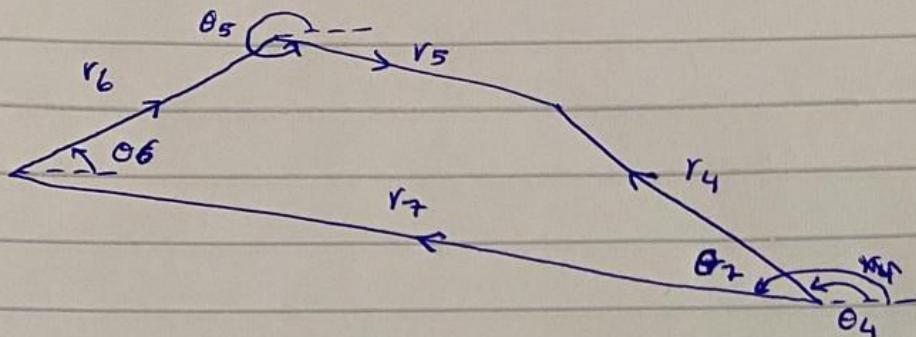


# Position Analysis



$$\vec{r}_1 = \vec{r}_2 + \vec{r}_3$$

$$r_1 = 67 \text{ mm}, r_2 = 20 \text{ mm}, r_3 = 90 \text{ mm}$$

$$r_5 = 70 \text{ mm}, r_6 = 120 \text{ mm}, r_7 = 163 \text{ mm}$$

$$\theta_7 = 155.75$$

$$RE: 0 = r_2 \cos \theta_2 + r_3 \cos \theta_3$$

$$\theta_3 = \theta_4$$

$$IM: r_1 = r_2 \sin \theta_2 + r_3 \sin \theta_3$$

$$\vec{r}_4 = \vec{r}_5 + \vec{r}_6 + \vec{r}_7$$

$$RE: r_4 \cos \theta_3 = r_5 \cos \theta_5 + r_6 \cos \theta_6 + r_7 \cos \theta_7$$

$$IM: r_4 \sin \theta_3 = r_5 \sin \theta_5 + r_6 \sin \theta_6 + r_7 \sin \theta_7$$

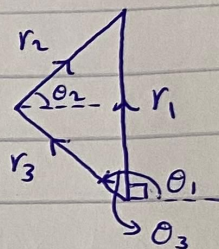
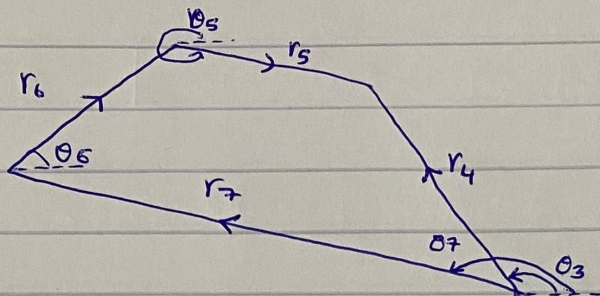
input :  $r_2$

outputs :  $r_3, \theta_3, \theta_5, \theta_6$



$$r_1 = 67 \text{ cm}, r_2 = 20 \text{ cm}, r_4 = 90 \text{ cm}, r_5 = 70 \text{ cm}, r_6 = 120 \text{ cm}, r_7 = 163 \text{ cm}, \theta_7 = 155.7^\circ$$

$$\omega_2 = 20 \text{ rad/s}$$



### Velocity Analysis

$$\vec{v}_1 = \vec{v}_2 + \vec{v}_3$$

$$\vec{v}_1 = \vec{v}_2 + \vec{v}_3$$

$$\dot{r}_1 = \dot{r}_2 = \dot{r}_4 = \dot{r}_5 = \dot{r}_6 = \dot{r}_7 = \omega_1 = \omega_7 = 0$$

$$\omega_3 = \omega_4$$

$$RE: 0 = -\omega_2 r_2 \sin \theta_2 + \dot{r}_3 \cos \theta_3 + \omega_3 r_3 \sin \theta_3$$

$$IM: 0 = \omega_2 r_2 \cos \theta_2 + \dot{r}_3 \sin \theta_3 + \omega_3 r_3 \cos \theta_3$$

$$\vec{r}_4 = \vec{r}_5 + \vec{r}_6 + \vec{r}_7 = 0$$

$$\text{outputs: } \dot{r}_3, \omega_3, \omega_5, \omega_6$$

$$RE: -\omega_3 r_4 \sin \theta_3 = -\omega_5 r_5 \sin \theta_5 - \omega_6 r_6 \sin \theta_6$$

$$IM: \omega_3 r_4 \cos \theta_3 = \omega_5 r_5 \cos \theta_5 + \omega_6 r_6 \cos \theta_6$$

### Acceleration Analysis

$$\ddot{r}_1 = \ddot{r}_2 = \ddot{r}_4 = \ddot{r}_5 = \ddot{r}_6 = \ddot{r}_7 = \alpha_1 = \alpha_2 = \alpha_7 = 0$$

$$RE: 0 = -\omega_2^2 r_2 \cos \theta_2 + (\ddot{r}_3 - \omega_3^2 r_3) \cos \theta_3 + (\alpha_3 r_3 + 2\omega_3 \dot{r}_3) \sin \theta_3$$

$$IM: 0 = -\omega_2^2 r_2 \sin \theta_2 + (\ddot{r}_3 - \omega_3^2 r_3) \sin \theta_3 + (\alpha_3 r_3 + 2\omega_3 \dot{r}_3) \cos \theta_3$$

$$RE: -\omega_3^2 r_4 \cos \theta_3 = \alpha_3 r_4 \sin \theta_3 = -\omega_5^2 r_5 \cos \theta_5 - \alpha_5 r_5 \sin \theta_5 - \omega_6^2 r_6 \cos \theta_6 - \alpha_6 r_6 \sin \theta_6$$

$$\alpha_3 = \alpha_4$$

$$IM: -\omega_3^2 r_4 \sin \theta_3 + \alpha_3 r_4 \cos \theta_3 = -\omega_5^2 r_5 \sin \theta_5 + \alpha_5 r_5 \cos \theta_5 - \omega_6^2 r_6 \sin \theta_6 + \alpha_6 r_6 \cos \theta_6$$

$$\text{outputs: } \ddot{r}_3, \alpha_3, \alpha_5, \alpha_6$$



# Velocity Analysis @ $\theta_2 = 66.5^\circ$

$$\omega_2 = 2 \text{ rad/s CCW}$$

$$V_A = \omega_2 r_2 = 2 \times 20 = 40 \text{ mm/s} = 4 \text{ cm/s}, \quad \mu_v = 1$$

$$\vec{V}_C = \vec{V}_F + \vec{V}_{C/F}$$

$$\vec{V}_A_{\text{abs}} = \vec{V}_A_{\text{base}} + \vec{V}_A_{\text{relative}}$$

$$3.3 \text{ cm} \rightarrow 2.2$$

$$5.85 \text{ cm} \rightarrow 3.9$$

$$V_F = 5.8 \text{ cm/s}$$

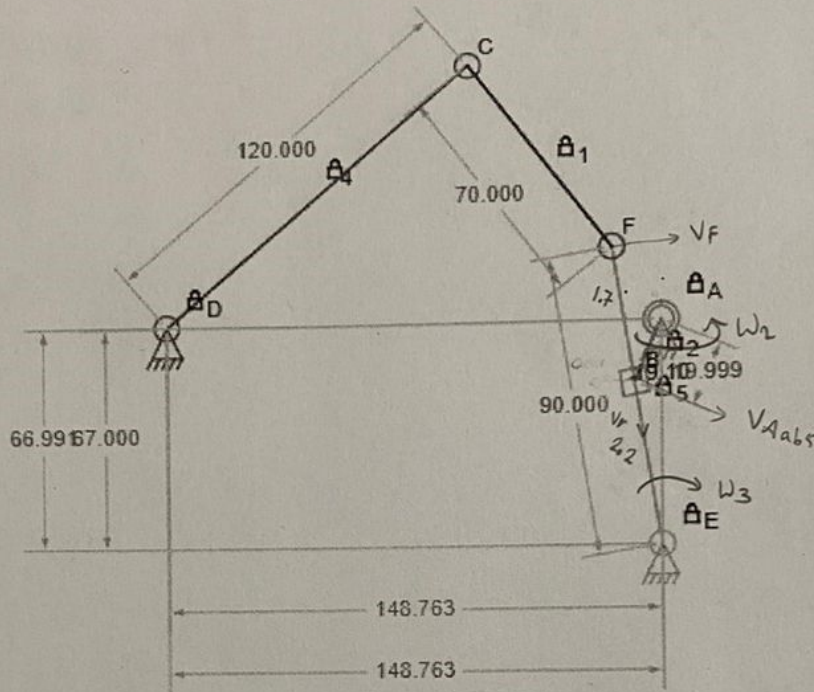
$$\omega_3 = \frac{5.8}{9 \text{ cm}} = 0.644 \text{ rad/s}$$

CW

$$\omega_3 = -0.644 \text{ rad/s}$$

$$\omega_3 = -0.6816 \text{ rad/s}$$

actual



$$V_{C/F} = 5 \text{ cm/s}$$

$$\omega_5 = \frac{5}{7 \text{ cm}} = 0.714 \text{ rad/s}$$

CW

$$\omega_5 = 0.714 \text{ rad/s}$$

$$\omega_5 = 0.753 \text{ rad/s}$$

actual

$$V_C = 2.8 \text{ cm}$$

$$\omega_6 = \frac{2.8}{12 \text{ cm}} = 0.233 \text{ rad/s}$$

CW

$$\omega_6 = -0.233 \text{ rad/s}$$

$$\omega_6 = -0.241 \text{ rad/s}$$

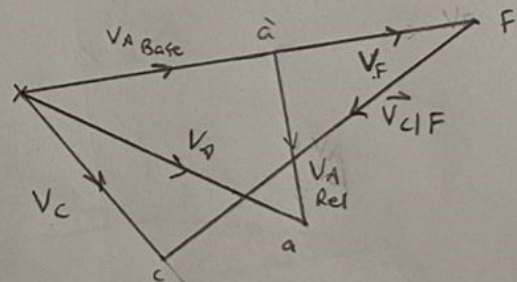
actual

$$V_A_{\text{relative}} = -2.2 \text{ cm/s} = -22 \text{ mm/s}$$

$$\dot{r}_3 = -22 \text{ mm/s}$$

$$\dot{r}_3 = 21.67 \text{ mm/s}$$

actual





# Acceleration Analysis @ $\theta_2 = 66.5^\circ$

$$\alpha_2 = 0$$

$$a_{abs}^A = \underbrace{\hat{a}_A^n}_{\omega_2^2 r_2} + \underbrace{\hat{a}_A^t}_{d_2 r_2} \rightarrow 0$$

$$a_{abs}^A = 2^2 \times 2\text{cm} = 8\text{cm/s}^2, m_a = 2$$

$\hookrightarrow 4\text{cm}$

$$\vec{a}_F = \underbrace{\hat{a}_F^n}_{\omega_3^2 r_4} + \underbrace{\hat{a}_F^t}_{d_3 r_4}$$

$$\hat{a}_F^n = 0.644^2 \times 9 = 3.73\text{cm/s}^2$$

$\hookrightarrow 1.85\text{cm}$

$$a_{cor} = 2 \omega_3 v_r$$

$$a_{cor} = 2 \times 0.644 \times 2.2$$

$$a_{cor} = 2.83\text{cm/s}^2$$

$\hookrightarrow 1.4\text{cm}$

$$\hat{a}_F^n \rightarrow 1.85 \rightarrow 3.9\text{cm}$$

$\hookrightarrow 1 \rightarrow 2.2\text{cm}$

$\hookrightarrow a_{A, base}$

$$\hat{a}_F^t = 6.6 \times 2 = d_3 \times 9\text{cm}$$

$$d_3 = 1.467\text{rad/s}^2 \text{ CW}$$

$$d_3 = -1.467\text{rad/s}^2$$

$$d_3 = -1.478\text{rad/s}^2 \text{ actual}$$

$$\hat{a}_{C/F}^t = 4.9 \times 2 = d_5 \times 7\text{cm}$$

$$d_5 = 1.4\text{rad/s}^2 \text{ CCW}$$

$$d_5 = 1.4\text{rad/s}^2$$

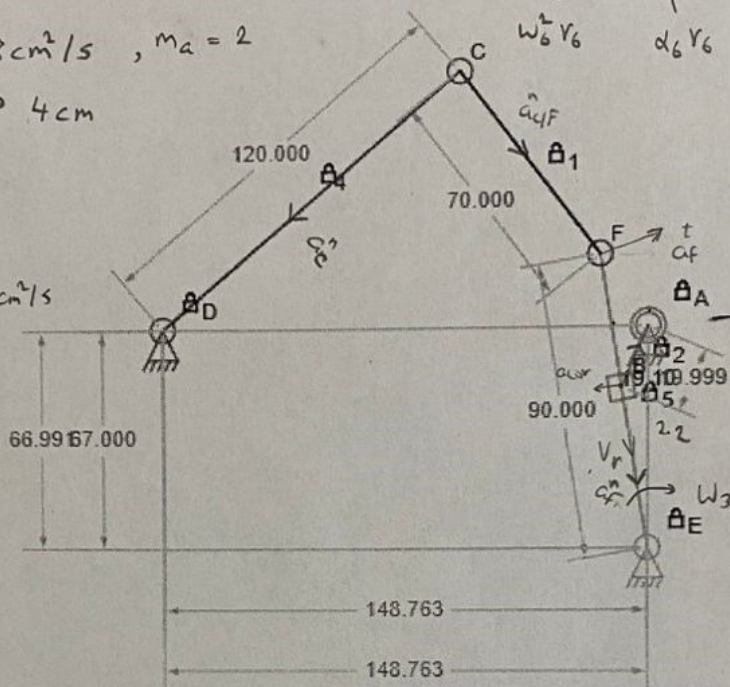
$$d_5 = 1.398\text{rad/s}^2 \text{ actual}$$

$$\hat{a}_C^t = 6.5 \times 2 = d_6 \times 12\text{cm}$$

$$d_6 = 1.083\text{rad/s}^2 \text{ CW}$$

$$d_6 = -1.083\text{rad/s}^2$$

$$d_6 = -1.159\text{rad/s}^2 \text{ actual}$$



$$a_c = a_F + a_{C/F}$$

$$\hat{a}_C^n = 0.233^2 \times 12\text{cm} = 0.651$$

$\hookrightarrow 0.33\text{cm}$

$$\hat{a}_{C/F}^t = 0.714^2 \times 7\text{cm} = 3.57\text{cm/s}^2$$

$\hookrightarrow 1.8\text{cm}$

$$a_{A, relative} = 44\text{mm} \times 2 = 88\text{mm/s}^2$$

$$\ddot{r}_3 = .88\text{mm/s}^2$$

$$\ddot{r}_3 = 90.157\text{mm/s}^2 \text{ actual}$$

