



Product Data Sheet

Range: Precision Haptic
Title: 6mm Vibration Motor

Type: Undefined Model: 306-109

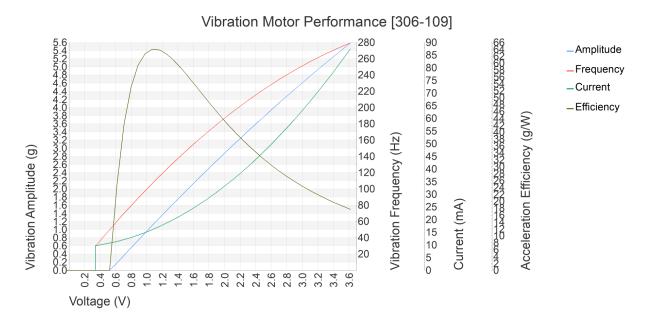
6mm Vibration Motor 12mm Type

Shown on 6mm Isometric Grid



| KEY FEATURES | |
|---------------------------------|------------------------|
| Body Diameter | 6 mm [+/- 0.1] |
| Body Length | 12.2 mm [+/- 0.2] |
| Ecc. Weight Radius | 2.9 mm [+/- 0.1] |
| Ecc. Weight Length | 4.5 mm [+/- 0.1] |
| Rated Operating Voltage | 3 V |
| Rated Vibration Speed | 14,300 rpm [+/- 3,500] |
| Typical Rated Operating Current | 66 mA |
| Typical Norm. Amplitude | 4.51 G |

TYPICAL DC MOTOR PERFORMANCE CHARACTERISTICS



ORDERING INFORMATION

The model number fully defines the model, variant and additional features of the product. Please quote this number when ordering. For stocked types, testing and evaluation samples can be ordered directly through our online store.

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS



Looking for the perfect design? We can help.



Precision Microdrives is an ISO 9001:2015 trusted designer and manufacturer of miniature, cost-effective, and well engineered motors and mechanisms. We are specialists in,

- Trusted precision motor design
- Flexible motor & mechanism manufacturing
- Dependable quality control & after-sales support
- Industry leading motor testing and validation

Our UK based motor design engineers, will support you through the complex process of specifying, developing, validating, and mass manufacturing, a custom motor or mechanism. The result? A part perfect for your application.

Delivered, On-Time & To Spec.

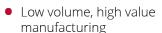
SPEAK TO OUR DESIGN ENGINEERS TODAY

Email: enquiries@precisionmicrodrives.com Call: +44 (0) 1932 252482

DESIGN FOR APPLICATION CASE STUDIES



VIBRATION MOTOR HIGHLY OPTIMISED FOR DUGGEDISED FIRE AND



ENCAPSULATED VIBRATION

MOTOR FOR A CPR TRAINING

- Custom CNC machined enclosure
- Optimised haptic performance

DUMMY

- Custom PCB including FMI filters
- Part no. 334-401.001



OPTIMISED FOR RUGGEDISED FIRE AND POLICE EMERGENCY RADIOS

- High volume production
- Optimised for emergency services application
- Ruggedised design with custom rubber 'suspension' cover
- Custom PCB with spring legs for simplified production assembly times
- Part no. 308-104.001



PRECISION SPEED AND TORQUE CONTROLLED SERVO WITH INTEGRATED TUNABLE PID LOOP FOR SINGLE-USE SCIENTIFIC INSTRUMENT.

- Medium volume, high value assembly
- Proprietary PID controller converts cost-effective motor design into a precision servo
- Adapted control software including digital IO (to customer's specification)
- Part no. 132-100.001



CUSTOMISED PRECISION GEAR MOTOR WITH ROBUST OPTICAL ENCODER

- High volume production
- Application specific output shaft
- Tailored motor performance curves
- Rear motor shaft with noise resistant optical encoder
- Part no. 212-116.001



PHYSICAL SPECIFICATION

| PARAMETER | CONDITIONS | SPECIFICATION |
|----------------------|--|-------------------|
| Body Diameter | Max body diameter or max face dimension where non-circular | 6 mm [+/- 0.1] |
| Body Length | Excl. shafts, leads and terminals | 12.2 mm [+/- 0.2] |
| Unit Weight | | 2.7 g |
| No. of Output Shafts | | 1 |
| Ecc. Weight Radius | Radius from shaft for non-cylindrical weights | 2.9 mm [+/- 0.1] |
| Ecc. Weight Length | | 4.5 mm [+/- 0.1] |

CONSTRUCTION SPECIFICATION

| PARAMETER | CONDITIONS | SPECIFICATION |
|--------------------|------------|----------------------|
| Motor Construction | | Coreless |
| Commutation | | Precious Metal Brush |
| No. of Poles | | 3 |
| Bearing Type | | Sintered Bronze |

LEADS & CONNECTORS SPECIFICATION

| PARAMETER | CONDITIONS | SPECIFICATION |
|--------------------|---|----------------|
| Lead Length | Lead lengths defined as total length or between motor and connector | 45 mm [+/- 2] |
| Lead Strip Length | | 2 mm [+/- 0.5] |
| Lead Wire Gauge | | 32 AWG |
| Lead Configuration | | Straight |

OPERATIONAL SPECIFICATION

| PARAMETER | CONDITIONS | SPECIFICATION |
|---------------------------------|--|------------------------|
| Rated Operating Voltage | | 3 V |
| Rated Vibration Speed | At rated voltage using the inertial test load | 14,300 rpm [+/- 3,500] |
| Max. Rated Operating Current | At rated voltage using the inertial test load | 117 mA |
| Max. Start Voltage | With the inertial test load | 1.4 V |
| Rated Inertial Test Load | Mass of standard test sled | 100 g |
| Max. Operating Voltage | | 3.6 V |
| Min. Vibration Amplitude | Peak-to-peak value at rated voltage using the inertial test load | 2.8 G |
| Max. Start Current | At rated voltage | 250 mA |
| Min. Insulation Resistance | At 50V DC between motor terminal and case | 1 MOhm |

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS



Important: The characteristics of the motor is the typical operating parameters of the product. The data herein offers design guidance information only and supplied batches are validated for conformity against the specifications on the previous page.

TYPICAL PERFORMANCE CHARACTERISTICS

| PARAMETER | CONDITIONS | SPECIFICATION |
|---|--|---------------|
| Typical Rated Load Power Consumption | At rated voltage and load | 225 mW |
| Typical Rated Operating Current | At rated voltage using the inertial test load | 66 mA |
| Typical Vibration Amplitude | Peak-to-peak value at rated voltage using the inertial test load | 4.51 G |
| Typical Start Current | At rated voltage | 170 mA |
| Typical Vibration Efficiency | At rated voltage using the inertial test load | 22.93 G/W |
| Typical Norm. Amplitude | Peak-to-peak vibration amplitude normalised by the inertial test load at rated voltage | 4.51 G |
| Typical Start Voltage | With the inertial test load | 0.4 V |
| Typical Terminal Resistance | | 16 Ohm |
| Typical Terminal Inductance | | 90 uH |

TYPICAL HAPTIC CHARACTERISTICS

| PARAMETER | CONDITIONS | SPECIFICATION |
|---------------------------|--|---------------|
| Typical Lag Time | At rated voltage using the inertial test load | 8 ms |
| Typical Rise Time | At rated voltage using the inertial test load | 35 ms |
| Typical Stop Time | At rated voltage using the inertial test load | 80 ms |
| Typical Active Brake Time | Time taken from steady-state to 0.04 G under inverse polarity at max. voltage $$ | 20 ms |

TYPICAL DURABILITY CHARACTERISTICS

| PARAMETER | CONDITIONS | SPECIFICATION |
|---------------------------------------|--|---------------|
| Typical Min. Counterweight Pullout | | 9.8 N |
| Mean Time to Failure | Typical rated lifetime. Actual operating life depends on application | 216 hours |

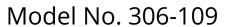
ENVIRONMENTAL CHARACTERISTICS

| PARAMETER | CONDITIONS | SPECIFICATION |
|-------------------------------------|------------|---------------|
| Max. Operating Temp. | | 60 Deg.C |
| Min. Operating Temp. | | -20 Deg.C |
| Max. Storage & Transportation Temp. | | 80 Deg.C |
| Min. Storage & Transportation Temp. | | -20 Deg.C |

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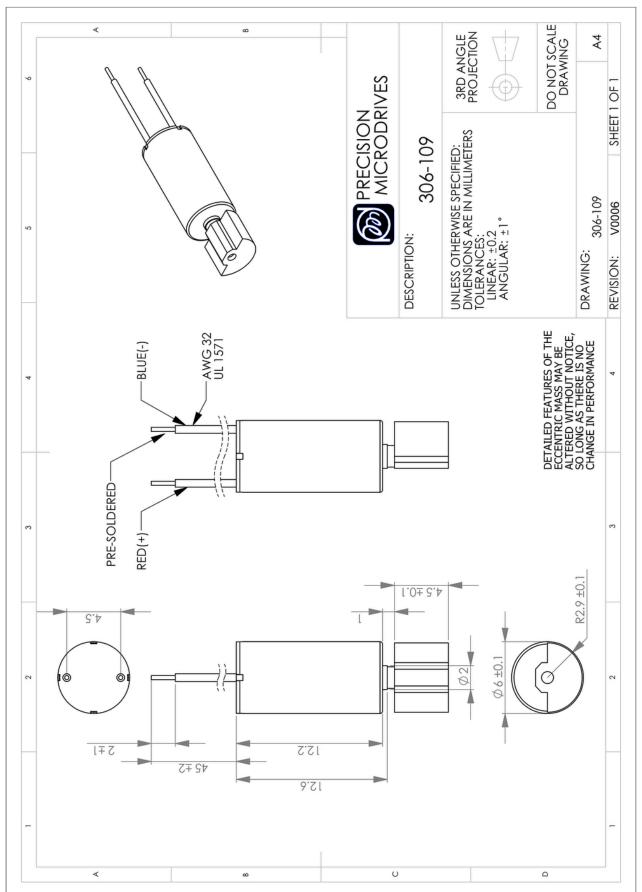


TYPICAL PACKING CONDITIONS

| PARAMETER | CONDITIONS | SPECIFICATION |
|-------------|------------|---------------|
| Carton Type | | Boxed trays |



PRODUCT DIMENSIONAL SPECIFICATION



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Haptic Characteristics

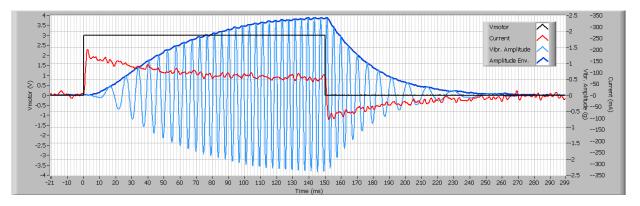
This section presents information regarding the performance of the motor for haptic feedback applications. The tests performed are equivalent to Immersion's TS2000 Actuator Performance Test for certified actuators.

Step Response applies the motor's rated voltage for set time - operating current, vibration amplitude are measured. The haptic parameters are calculated from the results. The negative current is a result of back EMF from the motor.

Overdrive Step Response is similar, but includes a period of overdrive (using the motor's maximum voltage instead of rated voltage) before falling to the rated voltage once vibration amplitude reaches 90% of rated amplitude. Concludes with active brake period where the maximum voltage is applied with reversed polarity until the vibration amplitude is less than 0.04 G.

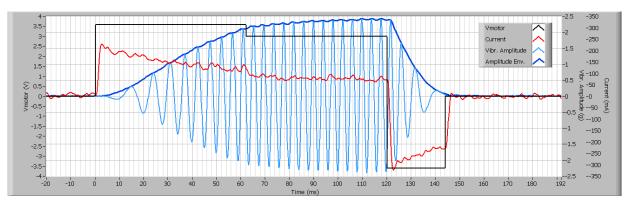
Step Response

| PARAMETER | CONDITIONS | SPECIFICATION |
|--------------------------|--|---------------|
| Typical Rise Time to 50% | Time to get to 50% of the rated amplitude at rated voltage | 42 ms |
| Typical Rise Time to 90% | Time to get to 90% of the rated amplitude at rated voltage | 92 ms |
| Typical Stop Time | Time to stop the motor when the voltage is removed | 104 ms |



Overdrive Step Response

| PARAMETER | CONDITIONS | SPECIFICATION |
|------------------------------------|---|---------------|
| Typical Overdrive Rise Time to 50% | Time to get to 50% of the rated amplitude at maximum voltage | 33 ms |
| Typical Overdrive Rise Time to 90% | Time to get to 90% of the rated amplitude at maximum voltage | 60 ms |
| Typical Brake Time | Time to stop the motor when the voltage is reversed to negative maximum voltage | 25 ms |



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Reliability Analysis

This section presents information regarding the longevity test performed on the motor. The Mean Time to Failure reported in this page should not be interpreted as a guaranteed lifetime. Please check our Application Notes for further information.

Our longevity test consists of powering the motors at their rated voltage for 2 seconds, then turning them off for 2 seconds. This cycle is repeated over the total test time.

The test is performed by our custom longevity machine which drives the motors and collects performance data. The test parameters and results can be seen below.



Test Parameters

- Motors tested: 48
- Test time: 720 hours
- Cycle period: 4 seconds
- Duty cycle: 50%
- Test voltage: 3.0 V
- Temperature: 33 °C

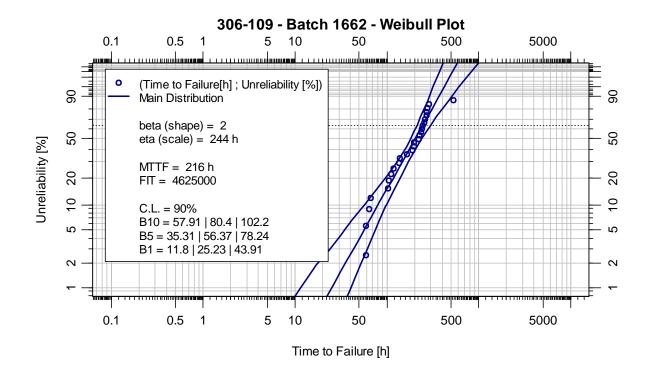
Formulas to derive the key reliability figures from a Weibull distribution:

$$MTTF = \eta * \Gamma \left(1 + \frac{1}{\beta} \right)$$

$$FIT = 10^9 / MTTF$$

Test Result

The results for the longevity test are presented in a Weibull plot. From the fitting distribution it is possible to obtain an estimate of the Mean Time to Failure.



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HOW TO ORDER

Call or email us with your order requirements at:

Email: enquiries@precisionmicrodrives.com

Phone: +44 (0) 1932 252482

Please quote the full part number when ordering or making an enquiry. Some products can be ordered in smaller volumes directly from our website: **www.precisionmicrodrives.com**

DATASHEET REVISION AND VERSION NUMBERING

We aim to provide ou customer with the most detailed product information available. Sometimes changes are necessary, and these will be controlled by our engineering change request and notification process. To track datasheet versions we use both a 'production revision number' and a 'document version number'. These can be found at the bottom of every page. Inc some cases, such as documentation errors, the document version number can increase without triggering a product revision.

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- 2. A critical component is any component of a life support device or any other system or machine whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

BATCH NUMBERING, MANUFACTURING, TRACEABILITY AND LABELLING

Every part of manufactured by Precision Microdrives is at minimum identified and traced via a batch number. Where physically practical, we try to make each part with a batch number. In addition, some parts carry a lot code or barcode serial numbers. If traceability is a core requirement for your purchase, let us know and we'll outline the production options for you.

STANDARD QUALITY CONTROLS AND ISO 9001

Precision quality control is one of our 3 key competitive advantages. All motors that we produce undergo 100% line inspection followed by strict and detailed batch sample testing in accordance with ISO 2859. All of the processes operated at Precision Microdrives are managed within our ISO 9001 quality system.



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