

# Computer Vision HW10

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## Homework 10

Zero Crossing Edge Detection

Step:

1. 依照 mask 大小 padding 後，跟 mask 相乘並相加，如圖所示(有 1/3 的話就將 temp0/3)

```
for(int i = 0 ; i < x ; i++){
    for(int j = 0 ; j < y ; j++){
        int temp0 = 0;
        for(int a = -5 ; a < 6 ; a++){
            for(int b = -5 ; b < 6 ; b++){
                temp0 += pic[i + 5 + a][j + 5 + b] * mask[a+5][b+5];
            }
        }
        if (temp0 >= threshold) temp[i+1][j+1] = 1;
        else if (temp0 <= -threshold) temp[i+1][j+1] = -1;
        else temp[i+1][j+1] = 0;
    }
}
```

2. 求出之結果進行 zero crossing edge detection，先將 step1 求出之 temp padding，然後進行計算如圖

```
Mat lena_Difference_of_Gaussian(512, 512, CV_8UC1, Scalar(0));

for(int i = 0 ; i < x ; i++){
    for(int j = 0 ; j < y ; j++){
        bool flag = 0;
        if(temp[i+1][j+1] == 1){
            for(int a = -1 ; a < 2 ; a++){
                for(int b = -1 ; b < 2 ; b++){
                    if(temp[i+1+a][j+1+b] == -1){
                        lena_Difference_of_Gaussian.at<uchar>(i,j) = 0;
                        flag = 1;
                        break;
                    }
                }
            }
            if(flag == 1) break;
            if(flag == 0) lena_Difference_of_Gaussian.at<uchar>(i,j) = 255;
        }
        else lena_Difference_of_Gaussian.at<uchar>(i,j) = 255;
    }
}
```

Result:

(a) Laplace Mask1:

thresholds : 15

Mask:

```
int mask[3][3] = {0, 1, 0,  
                  1, -4, 1,  
                  0, 1, 0};
```



(b) Laplace Mask2:

thresholds : 15

Mask:

```
int mask[3][3] = {1, 1, 1,  
                  1, -8, 1,  
                  1, 1, 1};
```







(e) Difference of Gaussian:

thresholds : 1

Mask:

```
int mask[11][11] = {-1, -3, -4, -6, -7, -8, -7, -6, -4, -3, -1,
-3, -5, -8, -11, -13, -13, -13, -11, -8, -5, -3,
-4, -8, -12, -16, -17, -17, -17, -16, -12, -8, -4,
-6, -11, -16, -16, 0, 15, 0, -16, -16, -11, -6,
-7, -13, -17, 0, 85, 160, 85, 0, -17, -13, -7,
-8, -13, -17, 15, 160, 283, 160, 15, -17, -13, -8,
-7, -13, -17, 0, 85, 160, 85, 0, -17, -13, -7,
-6, -11, -16, -16, 0, 15, 0, -16, -16, -11, -6,
-4, -8, -12, -16, -17, -17, -17, -16, -12, -8, -4,
-3, -5, -8, -11, -13, -13, -13, -11, -8, -5, -3,
-1, -3, -4, -6, -7, -8, -7, -6, -4, -3, -1};
```

